

Simulink® Coder™

Reference



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R2022b



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Simulink[®] *Coder*[™] *Reference*

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Revision History

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Check Bug Reports for Issues and Fixes

Software is inherently complex and is not free of errors. The output of a code generator might contain bugs, some of which are not detected by a compiler. MathWorks reports critical known bugs brought to its attention on its Bug Report system at www.mathworks.com/support/bugreports/. In the search bar, type the phrase "Incorrect Code Generation" to obtain a report of known bugs that produce code that might compile and execute, but still produce wrong answers. To save a search, click Save Search.

The bug reports are an integral part of the documentation for each release. Examine periodically all bug reports for a release, as such reports may identify inconsistencies between the actual behavior of a release you are using and the behavior described in this documentation.

In addition to reviewing bug reports, you should implement a verification and validation strategy to identify potential bugs in your design, code, and tools.

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Simulink Code Generation Limitations

Simulink Code Generation Limitations

The following topics identify Simulink code generation limitations:

- “C++ Language Support Limitations”
- “Limitations”
- “Tunable Expression Limitations”
- “Generate Reentrant Code from Subsystems”
- “Code Generation Limitations for Model Reference”
- “TCP/IP and Serial External Mode Limitations”
- “Noninlined S-Function Parameter Type Limitations”
- “S-Function Target Limitations”
- “Rapid Simulation Target Limitations”
- “Asynchronous Support Limitations”
- “C API Limitations”
- “Use Blocks and Products Supported for Code Generation”

Apps

Simulink Coder

Generate and execute C and C++ code from Simulink models, Stateflow charts, and MATLAB functions for use in applications such as simulation acceleration, rapid prototyping, and hardware-in-the-loop (HIL) simulations

Description

To generate C or C++ code from a model that represents a discrete-time system, use the **Simulink Coder** app. When you open the app, a **C Code** tab is added to the Simulink Editor toolstrip. The **C Code** tab contains sections that represent steps of the Simulink Coder workflow. You can iterate through model preparation for code generation, code generation and builds, and code verification by using the editor window panels.

Use the app to:

- Learn product basics while quickly configuring a model for code generation. If you are new to Simulink Coder, use the Simulink Coder Quick Start to prepare a model for code generation. The Simulink Coder Quick Start chooses fundamental code generation settings based on your goals and application. To open the Simulink Coder Quick Start, click **Quick Start**.
- Set code generation objectives and prepare a model for code generation. Click **C/C++ Code Advisor**.
- Configure model-wide code generation parameter settings. Click **Settings**.
- Configure data. Select **Code Interface > Default Code Mappings** or **Code Interface > Individual Element Code Mappings**, which open the Code Mappings editor and Property Inspector.
- Generate code or build an executable program. Select **Build > Generate Code** or **Build > Build**.
- Review generated code. Click **Open Report**.
- Create a protected model for simulation and code generation to share with a third party. Select **Share > Generate Protected Model**.
- Package generated code and artifacts for deployment to another computer system. Select **Share > Generate Code and Package**.

The screenshot displays the Simulink Coder application window for the project 'rtwdemo_configrpinterface'. The interface is divided into several sections:

- Top Bar:** Contains tabs for SIMULATION, DEBUG, MODELING, FORMAT, APPS, and C CODE. The 'C CODE' tab is currently selected.
- Toolbar:** Includes icons for Generic C Code, Quick Start, C/C++ Code Advisor, Settings, Code Interface, Generate Code, Open Report, Verify Code, and Share. A text field shows 'Code for rtwdemo_configrpinterface'.
- Model View:** Shows a Simulink block diagram with inputs 1, 2, 3, and 4. The diagram includes blocks for 'UPPER', 'LOWER', 'RelOp1', 'RelOp2', 'OR', 'LogOp', 'mode', '1-D T(u)' (Table1), 'K1', 'u1', 'u2' (Table2), 'Delay', and a switch block.
- Property Inspector:** Located on the right, it shows properties for 'In1'. Under 'Design', it lists Data Type (double), Min (-20), Max (20), Dimensions (1), Complexity (real), Sample Time (1), and Unit (inherit). Under 'Code', it shows Storage Class (ImportedExtern) and Identifier (input1).
- Code Mappings - C:** A table at the bottom showing the mapping between source code and storage classes.

Source	Storage Class
In1	ImportedExtern
In2	Model default: ImportedExternPointer
In3	Model default: ImportedExternPointer
In4	Model default: ImportedExternPointer

Open the Simulink Coder App

In the **Apps** gallery, under **Code generation**, click **Simulink Coder**. The **C Code** tab opens.

Examples

- “Generate Code by Using the Quick Start Tool”
- “Generate Code Using Simulink Coder”
- “Design Models for Rapid Prototyping Deployment”

Tips

- If you are working with a model hierarchy, open the **Simulink Coder** app in the Simulink Editor window for the top model of the hierarchy that you are generating code for. On the **C Code** tab, the functionalities apply to the top model of the hierarchy that is open in the editor.
- To configure data for a referenced model, navigate to the model in the hierarchy. Open the Code Mappings editor and Property Inspector by selecting **Code Interface > Default Code Mappings** or **Code Interface Individual Element Code Mappings**. These tools apply to the active model, which can be the top model or a referenced model.

Version History

Introduced in R2019b

See Also

Topics

“Generate Code by Using the Quick Start Tool”

“Generate Code Using Simulink Coder”

“Design Models for Rapid Prototyping Deployment”

Run on Custom Hardware

Run external mode simulations

Description

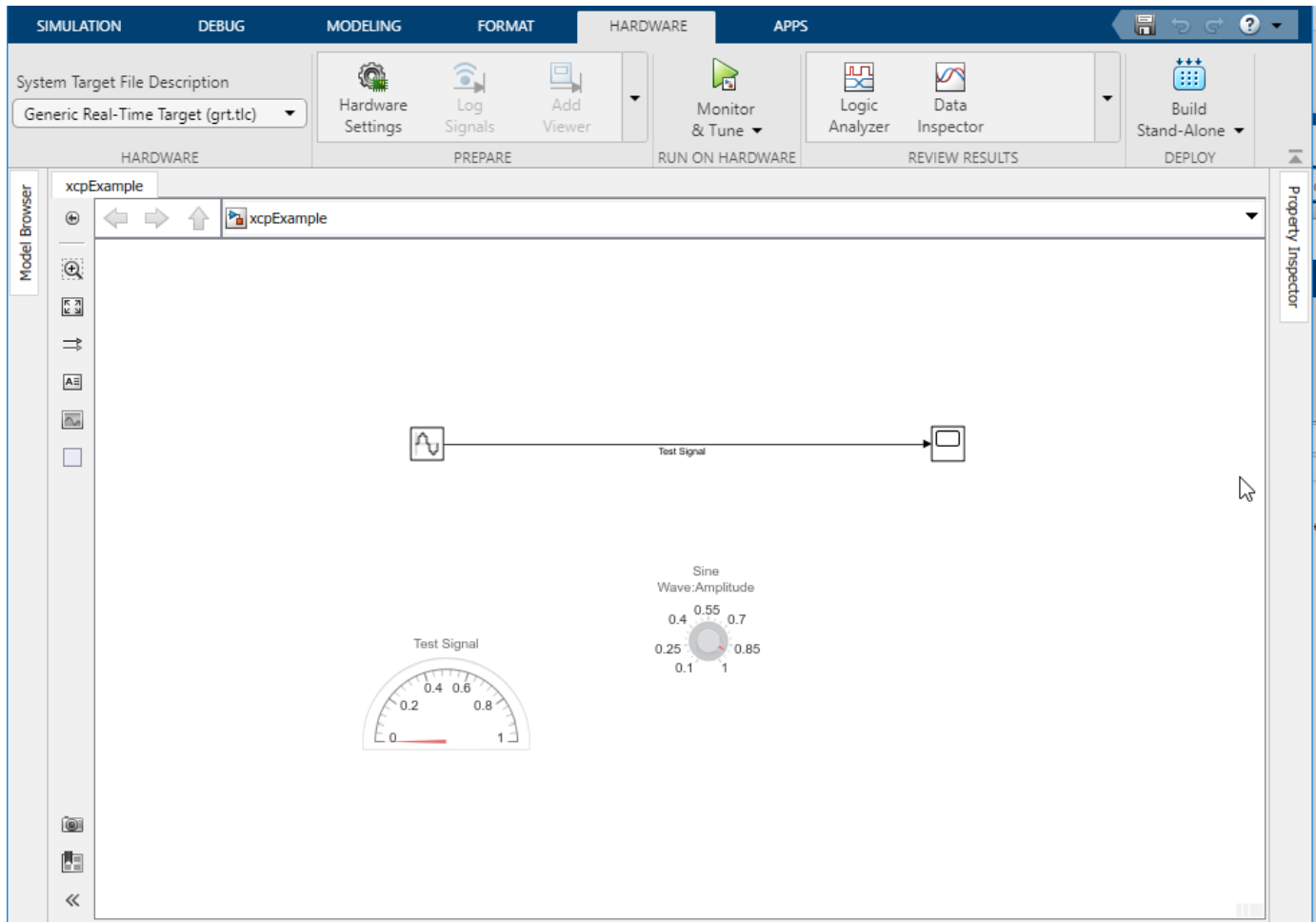
The **Run on Custom Hardware** app enables you to run external mode simulations on your development computer or other target hardware. In an external mode simulation, you can tune parameters in real time and monitor target application signals.

To run an external mode simulation, you:

- 1 Build the target application on your development computer.
- 2 Deploy the target application to the target hardware.
- 3 Connect Simulink to the target application that runs on the target hardware.
- 4 Start execution of generated code on the target hardware.

Using the app, you can:

- Perform the steps separately or with one click.
- Register custom launchers that deploy the target application.



Open the Run on Custom Hardware App

On the **Apps** tab, click **Run on Custom Hardware**. Or, on the **C Code** tab, select **Verify Code > Run on Custom Hardware**.

Examples

Run XCP External Mode Simulation

For an example that uses the **Run on Custom Hardware** app, see “Run XCP External Mode Simulation on Development Computer”.

Version History

Introduced in R2019b

See Also

Topics

[“External Mode Simulation by Using XCP Communication”](#)

[“External Mode Simulation with TCP/IP or Serial Communication”](#)

Simulink Coder Functions

addCompileFlags

Package: RTW

Add compiler options to build information

Syntax

```
addCompileFlags(buildinfo,options,groups)
```

Description

`addCompileFlags(buildinfo,options,groups)` specifies the compiler options to add to the build information.

The function requires the *buildinfo* and *options* arguments. You can use an optional *groups* argument to group your options.

The code generator stores the compiler options in a build information object. The function adds options to the object based on the order in which you specify them.

Examples

Add Compiler Flags to OPTS Group

Add the compiler option `-O3` to the build information `myBuildInfo` and place the option in the group `OPTS`.

```
myBuildInfo = RTW.BuildInfo;  
addCompileFlags(myBuildInfo,'-O3','OPTS');
```

Add Compiler Flags to OPT_OPTS Group

Add the compiler options `-Zi` and `-Wall` to the build information `myBuildInfo` and place the options in the group `OPT_OPTS`.

```
myBuildInfo = RTW.BuildInfo;  
addCompileFlags(myBuildInfo,'-Zi -Wall','OPT_OPTS');
```

Add Compiler Flags to Build Information

For a non-makefile build environment, add the compiler options `-Zi`, `-Wall`, and `-O3` to the build information `myBuildInfo`. Place the options `-Zi` and `-Wall` in the group `Debug` and the option `-O3` in the group `MemOpt`.

```
myBuildInfo = RTW.BuildInfo;
addCompileFlags(myBuildInfo,{'-Zi -Wall' '-03'}, ...
    {'Debug' 'MemOpt'});
```

Input Arguments

buildinfo — Build information object

object

RTW.BuildInfo object that contains information for compiling and linking generated code.

options — List of compiler options to add to build information

character vector | array of character vectors | string

You can specify the *options* argument as a character vector, as an array of character vectors, or as a string. You can specify the *options* argument as multiple compiler flags within a single character vector, for example `'-Zi -Wall'`. If you specify the *options* argument as multiple character vectors, for example, `'-Zi -Wall'` and `'-03'`, the *options* argument is added to the build information as an array of character vectors.

Example: `{'-Zi -Wall' '-03'}`

groups — Optional group name for the added compiler options

character vector | array of character vectors | string

You can specify the *groups* argument as a character vector, as an array of character vectors, or as a string. If you specify multiple *groups*, for example, `'Debug' 'MemOpt'`, the function relates the *groups* to the *options* in order of appearance. For example, the *options* argument `{'-Zi -Wall' '-03'}` is an array of character vectors with two elements. The first element is in the `'Debug'` group and the second element is in the `'MemOpt'` group.

Note The template makefile-based build process considers only compiler flags in the `'OPTS'`, `'OPT_OPTS'`, and `'OPTIMIZATION_FLAGS'` groups when generating the makefile.

For the build process to consider compiler flags in other groups, the template makefile must contain the token `|>COMPILE_FLAGS_OTHER<|`.

Example: `{'Debug' 'MemOpt'}`

Version History

Introduced in R2006a

See Also

`addDefines` | `addLinkFlags` | `getCompileFlags`

Topics

“Customize Post-Code-Generation Build Processing”

“Customize Template Makefiles”

addDefines

Package: RTW

Add preprocessor macro definitions to build information

Syntax

```
addDefines(buildinfo,macrodefs,groups)
```

Description

`addDefines(buildinfo,macrodefs,groups)` specifies the preprocessor macro definitions to add to the build information.

The function requires the *buildinfo* and *macrodefs* arguments. You can use an optional *groups* argument to group your options.

The code generator stores the definitions in a build information object. The function adds definitions to the object based on the order in which you specify them.

Examples

Add Macro Definitions to OPTS Group

Add the macro definition `-DPRODUCTION` to the build information `myBuildInfo` and place the definition in the group `OPTS`.

```
myBuildInfo = RTW.BuildInfo;  
addDefines(myBuildInfo,'-DPRODUCTION','OPTS');
```

Add Macro Definitions to OPT_OPTS Group

Add the macro definitions `-DPROTO` and `-DDEBUG` to the build information `myBuildInfo` and place the definitions in the group `OPT_OPTS`.

```
myBuildInfo = RTW.BuildInfo;  
addDefines(myBuildInfo, ...  
    '-DPROTO -DDEBUG','OPT_OPTS');
```

Add Macro Definitions to Build Information

For a non-makefile build environment, add the macro definitions `-DPROTO`, `-DDEBUG`, and `-DPRODUCTION` to the build information `myBuildInfo`. Place the definitions `-DPROTO` and `-DDEBUG` in the group `Debug` and the definition `-DPRODUCTION` in the group `Release`.

```
myBuildInfo = RTW.BuildInfo;  
addDefines(myBuildInfo, ...
```



```
{'-DPROTO -DDEBUG' '-DPRODUCTION'}, ...
{'Debug' 'Release'});
```

Input Arguments

buildinfo — Name of build information object returned by `RTW.BuildInfo` object

Object contains information for compiling and linking generated code.

macrodefs — List of macro definitions to add to build information
character vector | array of character vectors | string

You can specify the *macrodefs* argument as a character vector, as an array of character vectors, or as a string. You can specify the *macrodefs* argument as multiple definitions within a single character vector, for example `'-DRT -DDEBUG'`. If you specify the *macrodefs* argument as multiple character vectors, for example `'-DPROTO -DDEBUG'` and `'-DPRODUCTION'`, the *macrodefs* argument is added to the build information as an array of character vectors.

Example: `{'-DPROTO -DDEBUG' '-DPRODUCTION'}`

groups — Optional group name for the added compiler options
character vector | array of character vectors | string

You can specify the *groups* argument as a character vector, as an array of character vectors, or as a string. If you specify multiple *groups*, for example `'Debug' 'Release'`, the function relates the *groups* to the *macrodefs* in order of appearance. For example, the *macrodefs* argument `{'-DPROTO -DDEBUG' '-DPRODUCTION'}` is an array of character vectors with two elements. The first element is in the `'Debug'` group and the second element is in the `'Release'` group.

Note The template makefile-based build process considers only macro definitions in the `'OPTS'`, `'OPT_OPTS'`, `'OPTIMIZATION_FLAGS'`, and `'Custom'` groups when generating the makefile.

For the build process to consider definitions in other groups, the template makefile must contain the token `|>DEFINES_OTHER<|`.

Example: `{'Debug' 'Release'}`

Version History

Introduced in R2006a

See Also

`addCompileFlags` | `getDefines` | `addLinkFlags`

Topics

“Customize Post-Code-Generation Build Processing”

“Customize Template Makefiles”

addIncludeFiles

Package: RTW

Add include files to build information

Syntax

```
addIncludeFiles(buildinfo,filenames,paths,groups)
```

Description

`addIncludeFiles(buildinfo,filenames,paths,groups)` specifies included files and paths to add to the build information.

The function requires the *buildinfo* and *filenames* arguments. You can use an optional *paths* argument to specify the included file paths and use an optional *groups* argument to group your options.

The code generator stores the included file and path options in a build information object. The function adds options to the object based on the order in which you specify them.

Note The function does **not**:

- Add the file paths to the compiler search path. See `addIncludePaths`.
 - Produce `#include` directives in the generated code
-

Examples

Add Included File to SysFiles Group

Add the include file `mytypes.h` to the build information `myBuildInfo` and place the file in the group `SysFiles`.

```
myBuildInfo = RTW.BuildInfo;  
addIncludeFiles(myBuildInfo, ...  
    'mytypes.h', '/proj/src', 'SysFiles');
```

Add Included Files to AppFiles Group

Add the include files `etc.h` and `etc_private.h` to the build information `myBuildInfo`, and place the files in the group `AppFiles`.

```
myBuildInfo = RTW.BuildInfo;  
addIncludeFiles(myBuildInfo, ...
```

```
{'etc.h' 'etc_private.h'}, ...
'/proj/src', 'AppFiles');
```

Add Included Files to SysFiles and AppFiles Groups

Add the include files `etc.h`, `etc_private.h`, and `mytypes.h` to the build information `myBuildInfo`. Group the files `etc.h` and `etc_private.h` with the character vector `AppFiles` and the file `mytypes.h` with the character vector `SysFiles`.

```
myBuildInfo = RTW.BuildInfo;
addIncludeFiles(myBuildInfo, ...
{'etc.h' 'etc_private.h' 'mytypes.h'}, ...
    '/proj/src', ...
    {'AppFiles' 'AppFiles' 'SysFiles'});
```

Add Included Files with Wildcard to HFiles Group

Add the include files (`.h` files identified with a wildcard character) in a specified folder to the build information `myBuildInfo`, and place the files in the group `HFiles`.

```
myBuildInfo = RTW.BuildInfo;
addIncludeFiles(myBuildInfo, ...
    '*.h', '/proj/src', 'HFiles');
```

Input Arguments

buildinfo — Name of build information object returned by `RTW.BuildInfo`

object

Object provides information for compiling and linking generated code.

filenames — List of included files to add to build information

character vector | array of character vectors | string

You can specify the *filenames* argument as a character vector, as an array of character vectors, or as a string. If you specify the *filenames* argument as multiple character vectors, for example, `'etc.h' 'etc_private.h'`, the *filenames* argument is added to the build information as an array of character vectors.

If the dot delimiter (`.`) is present, the file name text can include wildcard characters. Examples are `'*.h'`, `'*.h'`, and `'*.h*'`.

The function removes duplicate included file entries with an exact match of a path and file name to a previously defined entry in the build information object.

Example: `'*.h'`

paths — List of included file paths to add to build information

character vector | array of character vectors | string

You can specify the *paths* argument as a character vector, as an array of character vectors, or as a string. If you specify a single path as a character vector, the function uses that path for all files. If you

specify the *paths* argument as multiple character vectors, for example, `'/proj/src'` and `'/proj/inc'`, the *paths* argument is added to the build information as an array of character vectors.

Example: `'/proj/src'`

groups — Optional group name for the added included files

character vector | array of character vectors | string

You can specify the *groups* argument as a character vector, as an array of character vectors, or as a string. If you specify multiple *groups*, for example, `'AppFiles'` `'AppFiles'` `'SysFiles'`, the function relates the *groups* to the *filenames* in order of appearance. For example, the *filenames* argument `'etc.h'` `'etc_private.h'` `'mytypes.h'` is an array of character vectors with three elements. The first element is in the `'AppFiles'` group, the second element is in the `'AppFiles'` group, and the third element is in the `'SysFiles'` group.

Example: `'AppFiles'` `'AppFiles'` `'SysFiles'`

Version History

Introduced in R2006a

See Also

`addIncludePaths` | `addSourceFiles` | `addSourcePaths` | `findIncludeFiles` | `getIncludeFiles` | `updateFilePathsAndExtensions` | `updateFileSeparator`

Topics

“Customize Post-Code-Generation Build Processing”

addIncludePaths

Package: RTW

Add include paths to build information

Syntax

```
addIncludePaths(buildinfo,paths,groups)
```

Description

`addIncludePaths(buildinfo,paths,groups)` specifies included file paths to add to the build information.

The function requires the *buildinfo* and *paths* arguments. You can use an optional *groups* argument to group your options.

The code generator stores the included file path options in a build information object. The function adds options to the object based on the order in which you specify them.

The function adds the file paths to the compiler search path.

The code generator does not check whether a specified path is valid.

Examples

Add Include File Path to Build Information

Add the include path `/etcproj/etc/etc_build` to the build information `myBuildInfo`.

```
myBuildInfo = RTW.BuildInfo;  
addIncludePaths(myBuildInfo,...  
    '/etcproj/etc/etc_build');
```

Add Include File Paths to a Group

Add the include paths `/etcproj/etclib` and `/etcproj/etc/etc_build` to the build information `myBuildInfo` and place the files in the group `etc`.

```
myBuildInfo = RTW.BuildInfo;  
addIncludePaths(myBuildInfo,...  
    {'/etcproj/etclib' '/etcproj/etc/etc_build'}, 'etc');
```

Add Include File Paths to Groups

Add the include paths `/etcproj/etclib`, `/etcproj/etc/etc_build`, and `/common/lib` to the build information `myBuildInfo`. Group the paths `/etc/proj/etclib` and `/etcproj/etc/`

`etc_build` with the character vector `etc` and the path `/common/lib` with the character vector `shared`.

```
myBuildInfo = RTW.BuildInfo;
addIncludePaths(myBuildInfo,...
    {'/etc/proj/etclib' '/etcproj/etc/etc_build'...
    '/common/lib'}, {'etc' 'etc' 'shared'});
```

Input Arguments

buildinfo — Name of build information object returned by `RTW.BuildInfo`
object

paths — List of included file paths to add to build information
character vector | array of character vectors | string

You can specify the *paths* argument as a character vector, as an array of character vectors, or as a string. If you specify a single path as a character vector, the function uses that path for all files. If you specify the *paths* argument as multiple character vectors, for example, `'/proj/src'` and `'/proj/inc'`, the *paths* argument is added to the build information as an array of character vectors.

The function removes duplicate include file path entries with an exact match of a path and file name to a previously defined entry in the build information object.

Example: `'/proj/src'`

groups — Optional group name for the added included files
character vector | array of character vectors | string

You can specify the *groups* argument as a character vector, as an array of character vectors, or as a string. If you specify multiple *groups*, for example, `'etc' 'etc' 'shared'`, the function relates the *groups* to the *paths* in order of appearance. For example, the *paths* argument `'/etc/proj/etclib' '/etcproj/etc/etc_build' '/common/lib'` is an array of character vectors with three elements. The first element is in the `'etc'` group, the second element is in the `'etc'` group, and the third element is in the `'shared'` group.

Example: `'etc' 'etc' 'shared'`

Version History

Introduced in R2006a

See Also

`addIncludeFiles` | `addSourceFiles` | `addSourcePaths` | `getIncludePaths` | `updateFilePathsAndExtensions` | `updateFileSeparator`

Topics

“Customize Post-Code-Generation Build Processing”

addLinkFlags

Package: RTW

Add link options to build information

Syntax

```
addLinkFlags(buildinfo,options,groups)
```

Description

`addLinkFlags(buildinfo,options,groups)` specifies the linker options to add to the build information.

The function requires the *buildinfo* and *options* arguments. You can use an optional *groups* argument to group your options.

The code generator stores the linker options in a build information object. The function adds options to the object based on the order in which you specify them.

Examples

Add Linker Flags to OPTS Group

Add the linker `-T` option to the build information `myBuildInfo` and place the option in the group `OPTS`.

```
myBuildInfo = RTW.BuildInfo;  
addLinkFlags(myBuildInfo,'-T','OPTS');
```

Add Linker Flags to OPT_OPTS Group

Add the linker options `-MD` and `-Gy` to the build information `myBuildInfo` and place the options in the group `OPT_OPTS`.

```
myBuildInfo = RTW.BuildInfo;  
addLinkFlags(myBuildInfo,'-MD -Gy','OPT_OPTS');
```

Add Linker Flags to Build Information

For a non-makefile build environment, add the linker options `-MD`, `-Gy`, and `-T` to the build information `myBuildInfo`. Place the options `-MD` and `-Gy` in the group `Debug` and the option `-T` in the group `Temp`.

```
myBuildInfo = RTW.BuildInfo;  
addLinkFlags(myBuildInfo, {'-MD -Gy' '-T'}, ...  
    {'Debug' 'Temp'});
```

Input Arguments

buildinfo — Name of build information object returned by `RTW.BuildInfo`
object

options — List of linker options to add to build information
character vector | array of character vectors | string

You can specify the *options* argument as a character vector, as an array of character vectors, or as a string. You can specify the *options* argument as multiple compiler flags within a single character vector, for example `'-MD -Gy'`. If you specify the *options* argument as multiple character vectors, for example, `'-MD -Gy'` and `'-T'`, the *options* argument is added to the build information as an array of character vectors.

Example: `{'-MD -Gy' '-T'}`

groups — Optional group name for the added linker options
character vector | array of character vectors | string

You can specify the *groups* argument as a character vector, as an array of character vectors, or as a string. If you specify multiple *groups*, for example, `'Debug' 'Temp'`, the function relates the *groups* to the *options* in order of appearance. For example, the *options* argument `{'-MD -Gy' '-T'}` is an array of character vectors with two elements. The first element is in the `'Debug'` group and the second element is in the `Temp` group.

Example: `{'Debug' 'Temp'}`

Version History

Introduced in R2006a

See Also

`addCompileFlags` | `addDefines` | `getLinkFlags`

Topics

“Customize Post-Code-Generation Build Processing”

addLinkObjects

Package: RTW

Add link objects to build information

Syntax

```
addLinkObjects(buildinfo,linkobjs,paths,priority,precompiled,linkonly,groups)
```

Description

`addLinkObjects(buildinfo,linkobjs,paths,priority,precompiled,linkonly,groups)` specifies included files and paths to add to the build information.

The function requires the *buildinfo*, *linkobjs*, and *paths* arguments. You can optionally select *priority* for link objects, select whether the objects are *precompiled*, select whether the objects are *linkonly* objects, and apply a *groups* argument to group your options.

The code generator stores the included link object and path options in a build information object. The function adds options to the object based on the order in which you specify them.

Examples

Add Link Objects to Build Information

Add the linkable objects `libobj1` and `libobj2` to the build information `myBuildInfo`. Mark both objects as link-only. Since individual priorities are not specified, the function adds the objects to the vector in the order specified.

```
myBuildInfo = RTW.BuildInfo;
addLinkObjects(myBuildInfo,{'libobj1' 'libobj2'}, ...
    {'/proj/lib/lib1' '/proj/lib/lib2'},1000, ...
    false,true);
```

Add Prioritized Link-Only Link Objects to Build Information

Add the linkable objects `libobj1` and `libobj2` to the build information `myBuildInfo`. Set the priorities of the objects to 26 and 10, respectively. Because `libobj2` is assigned the lower numeric priority value and has the higher priority, the function orders the objects such that `libobj2` precedes `libobj1` in the vector.

```
myBuildInfo = RTW.BuildInfo;
addLinkObjects(myBuildInfo, {'libobj1' 'libobj2'}, ...
    {'/proj/lib/lib1' '/proj/lib/lib2'},[26 10]);
```

Add Precompiled Link Objects to MyTest Group

Add the linkable objects `libobj1` and `libobj2` to the build information `myBuildInfo`. Set the priorities of the objects to 26 and 10, respectively. Mark both objects as precompiled. Group them under the name `MyTest`.

```
myBuildInfo = RTW.BuildInfo;
addLinkObjects(myBuildInfo,{'libobj1' 'libobj2'}, ...
    {'/proj/lib/lib1' '/proj/lib/lib2'},[26 10], ...
    true,false,'MyTest');
```

Input Arguments

buildinfo — Name of build information object returned by `RTW.BuildInfo`
object

linkobjs — List of linkable object files to add to build information
character vector | array of character vectors | string

You can specify the *linkobjs* argument as a character vector, as an array of character vectors, or as a string. If you specify the *linkobjs* argument as multiple character vectors, for example, `'libobj1' 'libobj2'`, the *linkobjs* argument is added to the build information as an array of character vectors.

The function removes duplicate linkable object entries with an exact match of a path and file name to a previously defined entry in the build information object.

Example: `'libobj1'`

paths — List of included file paths to add to build information
character vector | array of character vectors | string

You can specify the *paths* argument as a character vector, as an array of character vectors, or as a string. If you specify a single path as a character vector, the function uses that path for all files. If you specify the *paths* argument as multiple character vectors, for example, `'/proj/lib/lib1' and '/proj/lib/lib2'`, the *paths* argument is added to the build information as an array of character vectors. The number of elements in *paths* must match the number of elements in the *linkobjs* argument.

Example: `'/proj/lib/lib1'`

priority — List of priority values for link objects to add to build information
1000 (default) | numeric value | array of numeric values

A numeric value or an array of numeric values that indicates the relative priority of each specified link object. Lower values have higher priority.

Example: `1000`

precompiled — List of precompiled indicators for link objects to add to build information
false (default) | true | array of logical values

A logical value or an array of logical values that indicates whether each specified link object is precompiled. The logical value `true` indicates precompiled.

Example: `false`

linkonly — List of link-only indicators for link objects to add to build information`false` (default) | `true`

A logical value or an array of logical values that indicates whether each specified link object is link-only (not precompiled). The logical value `true` indicates link-only. If *linkonly* is `true`, the value of the *precompiled* argument is ignored.

Example: `false`

groups — Optional group name for the added link object files`character vector` | `array of character vectors` | `string`

You can specify the *groups* argument as a character vector, as an array of character vectors, or as a string. If you specify multiple *groups*, for example, `'MyTest1' 'MyTest2'`, the function relates the *groups* to the *linkobjs* in order of appearance. For example, the *linkobjs* argument `'libobj1' 'libobj2'` is an array of character vectors with two elements. The first element is in the `'MyTest1'` group, and the second element is in the `'MyTest2'` group.

Example: `'MyTest1' 'MyTest2'`

Version History

Introduced in R2006a

See Also

`addIncludePaths` | `addSourceFiles` | `addSourcePaths` | `findIncludeFiles` | `getIncludeFiles` | `updateFilePathsAndExtensions` | `updateFileSeparator`

Topics

“Customize Post-Code-Generation Build Processing”

addNonBuildFiles

Package: RTW

Add nonbuild-related files to build information

Syntax

```
addNonBuildFiles(buildinfo,filenames,paths,groups)
```

Description

`addNonBuildFiles(buildinfo,filenames,paths,groups)` specifies nonbuild-related files and paths to add to the build information.

The function requires the *buildinfo* and *filenames* arguments. You can use an optional *paths* argument to specify the included file paths and use an optional *groups* argument to group your options.

The code generator stores the nonbuild-related file and path options in a build information object. The function adds options to the object based on the order in which you specify them.

Examples

Add Nonbuild File to DocFiles Group

Add the nonbuild-related file `readme.txt` to the build information `myBuildInfo`, and place the file in the group `DocFiles`.

```
myBuildInfo = RTW.BuildInfo;  
addNonBuildFiles(myBuildInfo, ...  
    'readme.txt', '/proj/docs', 'DocFiles');
```

Add Nonbuild Files to DLLFiles Group

Add the nonbuild-related files `myutility1.dll` and `myutility2.dll` to the build information `myBuildInfo`, and place the files in the group `DLLFiles`.

```
myBuildInfo = RTW.BuildInfo;  
addNonBuildFiles(myBuildInfo, ...  
    {'myutility1.dll' 'myutility2.dll'}, ...  
    '/proj/dlls', 'DLLFiles');
```

Add Nonbuild Files with Wildcard to DLLFiles Group

Add nonbuild-related files (`.dll` files identified with a wildcard character) in a specified folder to the build information `myBuildInfo`, and place the files in the group `DLLFiles`.

```
myBuildInfo = RTW.BuildInfo;
addNonBuildFiles(myBuildInfo, ...
    '*.dll', '/proj/dlls', 'DLLFiles');
```

Input Arguments

buildinfo — Name of build information object returned by `RTW.BuildInfo` object

filenames — List of nonbuild-related files to add to build information
character vector | array of character vectors | string

You can specify the *filenames* argument as a character vector, as an array of character vectors, or as a string. If you specify the *filenames* argument as multiple character vectors, for example, 'etc.dll' 'etc_private.dll', the *filenames* argument is added to the build information as an array of character vectors.

If the dot delimiter (.) is present, the file name text can include wildcard characters. Examples are '*.*', '*.dll', and '*.d*'.

The function removes duplicate nonbuild-related file entries with an exact match of a path and file name to a previously defined entry in the build information object.

Example: '*.dll'

paths — List of nonbuild-related file paths to add to build information
character vector | array of character vectors | string

You can specify the *paths* argument as a character vector, as an array of character vectors, or as a string. If you specify a single path as a character vector, the function uses that path for all files. If you specify the *paths* argument as multiple character vectors, for example, '/proj/dll' and '/proj/docs', the *paths* argument is added to the build information as an array of character vectors.

Example: '/proj/dll'

groups — Optional group name for the added nonbuild-related files
character vector | array of character vectors | string

You can specify the *groups* argument as a character vector, as an array of character vectors, or as a string. If you specify multiple *groups*, for example, 'DLLFiles' 'DLLFiles' 'DocFiles', the function relates the *groups* to the *filenames* in order of appearance. For example, the *filenames* argument 'myutility1.dll' 'myutility2.dll' 'readme.txt' is an array of character vectors with three elements. The first element is in the 'DLLFiles' group, the second element is in the 'DLLFiles' group, and the third element is in the 'DocFiles' group.

Example: 'DLLFiles' 'DLLFiles' 'DocFiles'

Version History

Introduced in R2008a

See Also

getNonBuildFiles

Topics

“Customize Post-Code-Generation Build Processing”

addSourceFiles

Package: RTW

Add source files to build information

Syntax

```
addSourceFiles(buildinfo,filenames,paths,groups)
```

Description

`addSourceFiles(buildinfo,filenames,paths,groups)` specifies source files and paths to add to the build information.

The function requires the *buildinfo* and *filenames* arguments. You can use an optional *groups* argument to group your options.

The code generator stores the source file and path options in a build information object. The function adds options to the object based on the order in which you specify them.

Examples

Add Source File to Drivers Group

Add the source file `driver.c` to the build information `myBuildInfo` and place the file in the group `Drivers`.

```
myBuildInfo = RTW.BuildInfo;  
addSourceFiles(myBuildInfo,'driver.c', ...  
    '/proj/src', 'Drivers');
```

Add Source Files to a Group

Add the source files `test1.c` and `test2.c` to the build information `myBuildInfo` and place the files in the group `Tests`.

```
myBuildInfo = RTW.BuildInfo;  
addSourceFiles(myBuildInfo, ...  
    {'test1.c' 'test2.c'}, ...  
    '/proj/src', 'Tests');
```

Add Source Files to Groups

Add the source files `test1.c`, `test2.c`, and `driver.c` to the build information `myBuildInfo`. Group the files `test1.c` and `test2.c` with the character vector `Tests`. Group the file `driver.c` with the character vector `Drivers`.

```
myBuildInfo = RTW.BuildInfo;
addSourceFiles(myBuildInfo, ...
    {'test1.c' 'test2.c' 'driver.c'}, ...
    '/proj/src', ...
    {'Tests' 'Tests' 'Drivers'});
```

Add Source Files with Wildcard to CFiles Group

Add the .c files in a specified folder to the build information myBuildInfo and place the files in the group CFiles.

```
myBuildInfo = RTW.BuildInfo;
addIncludeFiles(myBuildInfo, ...
    '*.c', '/proj/src', 'CFiles');
```

Input Arguments

buildinfo — Build information object

object

RTW.BuildInfo object that holds information for compiling and linking generated code.

Example: myBuildInfo

filenames — List of source files to add to build information

character vector | array of character vectors | string

You can specify the *filenames* argument as a character vector, as an array of character vectors, or as a string. If you specify the *filenames* argument as multiple character vectors, for example, 'etc.c' 'etc_private.c', the *filenames* argument is added to the build information as an array of character vectors.

If the dot delimiter (.) is present, the file name text can include wildcard characters. Examples are '*.*', '*.c', and '*.c*'.

The function removes duplicate included file entries with an exact match of a path and file name to a previously defined entry in the build information object.

Example: '*.c'

paths — List of source file paths to add to build information

character vector | array of character vectors | string

You can specify the *paths* argument as a character vector, as an array of character vectors, or as a string. If you specify a single path as a character vector, the function uses that path for all files. If you specify the *paths* argument as multiple character vectors, for example, '/proj/src' and '/proj/inc', the *paths* argument is added to the build information as an array of character vectors.

Example: '/proj/src'

groups — Optional group name for the added source files

character vector | array of character vectors | string

You can specify the *groups* argument as a character vector, as an array of character vectors, or as a string. If you specify multiple *groups*, for example, 'Tests' 'Tests' 'Drivers', the function

relates the *groups* to the *filenames* in order of appearance. For example, the *filenames* argument 'test1.c' 'test2.c' 'driver.c' is an array of character vectors with three elements. The first element is in the 'Tests' group, and the second element is in the 'Tests' group, and the third element is in the 'Drivers' group.

Example: 'Tests' 'Tests' 'Drivers'

Version History

Introduced in R2006a

See Also

[addIncludeFiles](#) | [addIncludePaths](#) | [addSourcePaths](#) | [getSourceFiles](#) | [removeSourceFiles](#) | [updateFilePathsAndExtensions](#) | [updateFileSeparator](#)

Topics

“Customize Post-Code-Generation Build Processing”

addSourcePaths

Package: RTW

Add source paths to build information

Syntax

```
addSourcePaths(buildinfo,paths,groups)
```

Description

`addSourcePaths(buildinfo,paths,groups)` specifies source file paths to add to the build information.

The function requires the *buildinfo* and *paths* arguments. You can use an optional *groups* argument to group your options.

The code generator stores the source file path options in a build information object. The function adds options to the object based on the order in which you specify them.

The code generator does not check whether a specified path is valid.

Note If you want to add source files and the corresponding file paths to build information, use the `addSourceFiles` function. Do not use `addSourcePaths`.

Examples

Add Source File Path to Build Information

Add the source path `/etcproj/etc/etc_build` to the build information `myBuildInfo`.

```
myBuildInfo = RTW.BuildInfo;  
addSourcePaths(myBuildInfo, ...  
    '/etcproj/etc/etc_build');
```

Add Source File Paths to a Group

Add the source paths `/etcproj/etclib` and `/etcproj/etc/etc_build` to the build information `myBuildInfo` and place the files in the group `etc`.

```
myBuildInfo = RTW.BuildInfo;  
addSourcePaths(myBuildInfo, ...  
    {'/etcproj/etclib' '/etcproj/etc/etc_build'}, 'etc');
```

Add Source File Paths to Groups

Add the source paths `/etcproj/etclib`, `/etcproj/etc/etc_build`, and `/common/lib` to the build information `myBuildInfo`. Group the paths `/etcproj/etclib` and `/etcproj/etc/etc_build` with the character vector `etc` and the path `/common/lib` with the character vector `shared`.

```
myBuildInfo = RTW.BuildInfo;
addSourcePaths(myBuildInfo,...
    {'/etcproj/etclib' '/etcproj/etc/etc_build'...
    '/common/lib'}, {'etc' 'etc' 'shared'});
```

Input Arguments

buildinfo — Name of build information object returned by `RTW.BuildInfo`

object

paths — List of source file paths to add to build information

character vector | array of character vectors | string

You can specify the *paths* argument as a character vector, as an array of character vectors, or as a string. If you specify a single path as a character vector, the function uses that path for all files. If you specify the *paths* argument as multiple character vectors, for example, `'/proj/src'` and `'/proj/inc'`, the *paths* argument is added to the build information as an array of character vectors.

The function removes duplicate source file path entries with an exact match of a path and file name to a previously defined entry in the build information object.

Example: `'/proj/src'`

groups — Optional group name for the added source files

character vector | array of character vectors | string

You can specify the *groups* argument as a character vector, as an array of character vectors, or as a string. If you specify multiple *groups*, for example, `'etc' 'etc' 'shared'`, the function relates the *groups* to the *paths* in order of appearance. For example, the *paths* argument `'/etcproj/etclib' '/etcproj/etc/etc_build' '/common/lib'` is an array of character vectors with three elements. The first element is in the `'etc'` group, the second element is in the `'etc'` group, and the third element is in the `'shared'` group.

Example: `'etc' 'etc' 'shared'`

Version History

Introduced in R2006a

See Also

`addIncludeFiles` | `addIncludePaths` | `addSourceFiles` | `getSourcePaths` | `updateFilePathsAndExtensions` | `updateFileSeparator`

Topics

“Customize Post-Code-Generation Build Processing”

addTMFTokens

Package: RTW

Add template makefile (TMF) tokens to build information

Syntax

```
addTMFTokens(buildinfo, tokennames, tokenvalues, groups)
```

Description

`addTMFTokens(buildinfo, tokennames, tokenvalues, groups)` specifies TMF tokens and values to add to the build information.

To provide build-time information to help customize makefile generation, call the `addTMFTokens` function inside a post-code-generation command. The tokens specified in the `addTMFTokens` function call must be handled in the template makefile (TMF) for the target selected for your project. For example, you can call `addTMFTokens` in a post-code-generation command to add a TMF token named `|>CUSTOM_OUTNAME<|` with a token value that specifies an output file name for the build. To achieve the result you want, the TMF must apply an action with the value of `|>CUSTOM_OUTNAME<|`. (See “Examples” on page 3-0 .)

The `addTMFTokens` function adds specified TMF token names and values to the build information. The code generator stores the TMF tokens in a vector. The function adds the tokens to the end of the vector in the order that you specify them.

The function requires the *buildinfo*, *tokennames*, and *tokenvalues* arguments. You can use an optional *groups* argument to group your options. You can specify *groups* as a character vector or as an array of character vectors.

Examples

Add TMF Tokens to Build Information

Inside a post-code-generation command, add the TMF token `|>CUSTOM_OUTNAME<|` and its value to build information `myBuildInfo`, and place the token in the group `LINK_INFO`.

```
myBuildInfo = RTW.BuildInfo;  
addTMFTokens(myBuildInfo, ...  
             '|>CUSTOM_OUTNAME<|', 'foo.exe', 'LINK_INFO');
```

Apply Build Information as Tokens in TMF Build

In the TMF for the target selected for your project, this code uses the token value to achieve the result that you want:

```
CUSTOM_OUTNAME = |>CUSTOM_OUTNAME<|  
...
```

```
target:
$(LD) -o $(CUSTOM_OUTNAME) ...
```

Input Arguments

buildinfo — Name of build information object returned by `RTW.BuildInfo` object

tokennames — Specifies names of TMF tokens to add to the build information
character vector | array of character vectors | string

You can specify the *tokennames* argument as a character vector, as an array of character vectors, or as a string. If you specify the *tokennames* argument as multiple character vectors, for example, '|>CUSTOM_OUTNAME<|' '|>COMPUTER<|', the *tokennames* argument is added to the build information as an array of character vectors.

Example: '|>CUSTOM_OUTNAME<|' '|>COMPUTER<|'

tokenvalues — Specifies TMF token values (for the added tokens) to add to the build information

character vector | array of character vectors | string

You can specify the *tokenvalues* argument as a character vector, as an array of character vectors, or as a string. If you specify the *tokenvalues* argument as multiple character vectors, for example, '|>CUSTOM_OUTNAME<|' 'PCWIN64', the *tokennames* argument is added to the build information as an array of character vectors.

Example: 'foo.exe' 'PCWIN64'

groups — Optional group name for the added TMF tokens

character vector | array of character vectors | string

You can specify the *groups* argument as a character vector, as an array of character vectors, or as a string. If you specify multiple *groups*, for example, 'LINK_INFO' 'COMPUTER_INFO', the function relates the *groups* to the *tokennames* in order of appearance. For example, the *tokennames* argument '|>CUSTOM_OUTNAME<|' '|>COMPUTER<|' is an array of character vectors with two elements. The first element is in the 'LINK_INFO' group, and the second element is in the 'COMPUTER_INFO' group.

Example: 'LINK_INFO' 'COMPUTER_INFO'

Version History

Introduced in R2009b

See Also

Topics

“Customize Post-Code-Generation Build Processing”

buildStandaloneCoderAssumptions

Create application to check code generator assumptions

Syntax

```
buildStandaloneCoderAssumptions(buildFolder)
```

Description

`buildStandaloneCoderAssumptions(buildFolder)` creates an application for your target hardware to check code generator assumptions. The application checks that code generator assumptions based on model parameter settings or build configuration settings are correct with reference to the target hardware.

The function creates the target application in the `buildFolder\coderassumptions\standalone` subfolder.

Examples

Create Application to Check Code Generator Assumptions

For an example that shows how to create an application to check code generator assumptions, see “Check Code Generator Assumptions for Development Computer” (Embedded Coder).

Input Arguments

buildFolder — Build folder

character vector | string scalar

Path to the build folder that contains the generated code.

Version History

Introduced in R2018b

See Also

Topics

“Check Code Generation Assumptions” (Embedded Coder)

codebuild

Compile and link generated code

Syntax

```
buildResults = codebuild(buildFolder)
codebuild(buildFolder, Name,Value)
codebuild(buildInfo, Name,Value)
```

Description

`buildResults = codebuild(buildFolder)` loads data from the `buildInfo.mat` file in `buildFolder`, generates a makefile in `buildFolder`, and uses the specified toolchain or template makefile to compile source code that is registered in the `RTW.BuildInfo` object. If the object is at the top of a hierarchy, the function performs the process for each object in the hierarchy.

The function saves compilation artifacts, including object code files, in `buildFolder`.

The function returns an object that contains the display output. To view the output, run `disp(buildResults)`.

`codebuild(buildFolder, Name,Value)` specifies additional options using one or more name-value pairs.

`codebuild(buildInfo, Name,Value)` compiles the code specified in `buildInfo` using one or more name-value pairs.

Examples

Relocate and Compile Generated Code

For an example that shows how to relocate and compile generated code in another development environment, see [Compile Code in Another Development Environment](#).

Input Arguments

buildFolder — Build folder

character vector | string

Path to the build folder, which typically contains the generated source code. The folder must contain the `buildInfo.mat` file.

Example: `codebuild(pathToCodeFolder, 'BuildMethod', myToolchain)`

buildInfo — Build information object

object

`RTW.BuildInfo` object that contains information for compiling and linking generated code.

Example: `codebuild(myBuildInfo, 'BuildMethod', 'CMake')`

Name-Value Pair Arguments

Specify optional pairs of arguments as `Name1=Value1, . . . , NameN=ValueN`, where `Name` is the argument name and `Value` is the corresponding value. Name-value arguments must appear after other arguments, but the order of the pairs does not matter.

Before R2021a, use commas to separate each name and value, and enclose `Name` in quotes.

Example: `codebuild(pathToCodeFolder, 'BuildMethod', myToolchain)`

BuildMethod — Build method

character vector | string

Use one these build methods:

- **Toolchain** — Specify the name of the toolchain, for example, `'GNU gcc/g++ | gmake (64-bit Linux)'`.
- **Template makefile** — Specify the path to the template makefile.
- **CMake** — Specify `'cmake'`, which generates `CMakeLists.txt` configuration files for the CMake build system. The argument value is case-insensitive. For example, you can also specify `'Cmake'` or `'CMake'`.

Example: `codebuild(pathToCodeFolder, 'BuildMethod', 'CMake')`

BuildVariant — Build variant

'STANDALONE_EXECUTABLE' | 'MODEL_REFERENCE_CODER' | 'MEX_FILE' | 'SHARED_LIBRARY' | 'STATIC_LIBRARY'

Specify the type of build output:

- `'STANDALONE_EXECUTABLE'` -- Generates a standalone, executable file.
- `'MODEL_REFERENCE_CODER'` -- Generates a static library.
- `'MEX_FILE'` -- Generates a MEX file. Use this value only for building a simulation target, for example, model reference simulation target (`ModelReferenceSimTarget`) and accelerator mode.
- `'SHARED_LIBRARY'` -- Generates a dynamic library.
- `'STATIC_LIBRARY'` -- Generates a static library.

Example: `codebuild(pathToCodeFolder, 'BuildVariant', 'SHARED_LIBRARY')`

Output Arguments

buildResults — Build results

object

Capture display output from build process. To view the display output, in the Command Window, run `disp(buildResults)`.

Version History

Introduced in R2020b

See Also

`slbuild` | `RTW.BuildInfo`

Topics

Compile Code in Another Development Environment

coder.buildstatus.close

Close Build Status window

Syntax

```
coder.buildstatus.close()  
coder.buildstatus.close(model)  
coder.buildstatus.close(subsystem)
```

Description

`coder.buildstatus.close()` closes Build Status windows.

The Build Status window supports parallel builds of referenced model hierarchies. Do not use the Build Status window for serial builds.

`coder.buildstatus.close(model)` closes the Build Status window for `model`.

`coder.buildstatus.close(subsystem)` closes the Build Status window for `subsystem`.

Examples

Close Build Status Windows

Close Build Status windows that are open.

```
coder.buildstatus.close()
```

Close Build Status Window for a Model

After generating code for `rtwdemo_counter`, close the Build Status window for the model.

```
coder.buildstatus.close('rtwdemo_counter')
```

Close Build Status Window for a Subsystem

Close the Build Status window for the subsystem 'Amplifier' in model 'rtwdemo_counter'.

```
coder.buildstatus.close('rtwdemo_counter/Amplifier')
```

Input Arguments

model — Model name

character vector

Model name specified as a character vector

Example: 'rtwdemo_counter'

Data Types: char

subsystem – Subsystem name

character vector

Subsystem name specified as a character vector

Example: 'rtwdemo_counter/Amplifier'

Data Types: char

Version History

Introduced in R2018a

See Also

`coder.buildstatus.open` | `coder.report.close` | `slbuild`

Topics

"Monitor Parallel Building of Referenced Models"

coder.buildstatus.open

Open Build Status window

Syntax

```
coder.buildstatus.open(model)
coder.buildstatus.open(model,systemTarget)
```

Description

`coder.buildstatus.open(model)` opens the Build Status window for `model`.

The Build Status window supports parallel builds of referenced model hierarchies. Do not use the Build Status window for serial builds.

If the current working folder is the model build folder and the folder contains information from a previous parallel build, opening the Build Status window displays the previous build information. When you start a model parallel build, the current build information replaces the previous build information in the window.

`coder.buildstatus.open(model,systemTarget)` opens the Build Status window for `model` and displays the `model` tab. The available tabs are **Simulation Targets** and **Code Generation Targets**

Examples

Open Build Status Window for a Model

After generating code for model 'rtwdemo_parabuild_a_1', open the Build Status window for the model.

```
coder.buildstatus.open('rtwdemo_parabuild_a_1')
```

Open Build Status Window with Simulation Targets

Open the Build Status window for the model 'rtwdemo_parabuild_a_1' and display the **Simulation Targets** tab.

```
coder.buildstatus.open('rtwdemo_parabuild_a_1','sim')
```

Input Arguments

model — Model name

character vector | string scalar

Model name specified as a character vector or a string scalar

Example: 'rtwdemo_parabuild_a_1'

Data Types: char | string

systemTarget — System targets name

sim | rtw

System targets tab name specified as a character vector or string scalar, `sim` for **Simulation Targets** and `rtw` for **Code Generation Targets**. When build information is available for a system target from a previous build, the `systemTarget` argument directs the **Build Status** dialog box to display the tab for the system target. If this optional argument is omitted, when build information is available, dialog opens both the **Simulation Targets** tab and **Code Generation Targets** tab. If build information for a target is not available, the dialog does not open the corresponding system targets tab.

Example: 'rtw'

Data Types: char | string

Version History

Introduced in R2018a

See Also

`coder.buildstatus.close` | `coder.report.open` | `slbuild`

Topics

“Monitor Parallel Building of Referenced Models”

coder.codedescriptor.CodeDescriptor class

Package: coder.codedescriptor

Return information about generated code

Description

Create a `coder.codedescriptor.CodeDescriptor` object to access all the methods defined within the code descriptor API. The `coder.codedescriptor.CodeDescriptor` object describes the data interfaces, function interfaces, global data stores, local and global parameters in the generated code.

Creation

`codeDescObj = coder.getCodeDescriptor(model)` creates a `coder.codedescriptor.CodeDescriptor` object for the specified model.

`codeDescObj = coder.getCodeDescriptor(folder)` creates a `coder.codedescriptor.CodeDescriptor` object for the model in the build folder specified in `folder`.

Properties

ModelName — Name of the model

character vector (default)

Name of the model for which the code descriptor object is invoked.

Example: 'rtwdemo_comments'

Attributes:

GetAccess public

BuildDir — Build folder

character vector (default)

Path of the build folder where the model is built.

Example: 'C:\Users\Desktop\Work\rtwdemo_comments_ert_rtw'

Attributes:

GetAccess public

Methods

Public Methods

<code>getAllDataInterfaceTypes</code>	Return data interface types
<code>getAllFunctionInterfaceTypes</code>	Return function interface types

getArrayLayout	Return array layout of the generated code
getDataInterfaceTypes	Return data interface types in the generated code
getDataInterfaces	Return information of the specified data interface
getFunctionInterfaceTypes	Return function interface types in the generated code
getFunctionInterfaces	Return information of the specified function interface
getReferencedModelCodeDescriptor	Return coder.codedescriptor.CodeDescriptor object for the specified referenced model
getReferencedModelNames	Return names of the referenced models

Examples

Create coder.codedescriptor.CodeDescriptor Object

- 1 Build the model.

```
slbuild('rtwdemo_comments')
```

- 2 Create a coder.codedescriptor.CodeDescriptor object for the required model.

```
codeDescObj = coder.getCodeDescriptor('rtwdemo_comments')
```

```
    ModelName: 'rtwdemo_comments'
```

```
    BuildDir: 'C:\Users\Desktop\Work\rtwdemo_comments_ert_rtw'
```

- 3 Return a list of all available function interface types.

```
allFunctionInterfaceTypes = getAllFunctionInterfaceTypes(codeDescObj)
```

```
    {'Initialize'}
    {'Output'    }
    {'Update'    }
    {'Terminate' }
```

Version History

Introduced in R2018a

See Also

getCodeDescriptor | coder.descriptor.DataInterface |
coder.descriptor.FunctionInterface

Topics

“Get Code Description of Generated Code”

coder.descriptor.BreakpointDataInterface class

Package: coder.descriptor

Superclasses: coder.descriptor.DataInterface

Return information about tunable breakpoint set data for a lookup table that has tunable parameters

Description

The `coder.descriptor.BreakpointDataInterface` object describes various properties for breakpoint set data for these Lookup Table blocks that have tunable parameters in the generated code:

- 1-D Lookup Table
- 2-D Lookup Table
- n-D Lookup Table
- Interpolation Using Prelookup
- Direct Lookup Table (n-D)
- Sine
- Cosine

Creation

`params = getDataInterfaces(codeDescObj, dataInterfaceName)` creates a `coder.descriptor.BreakpointDataInterface` object for each dimension in the lookup table. The `codeDescObj` object is the `coder.codedescriptor.CodeDescriptor` object created for the model by using the `getCodeDescriptor` function.

The `coder.descriptor.LookupTableDataInterface` and `coder.descriptor.BreakpointDataInterface` objects are created if these conditions are true:

- Lookup table data is tunable.
- One of these conditions is true:
 - Breakpoint set data is tunable.
 - Breakpoint set data is nontunable and the block does not use a `Simulink.LookupTable` object.
 - The block uses a `Simulink.LookupTable` object.

Input Arguments

dataInterfaceName — Name of data interface

Parameters

Specify the Parameters data interface type.

Example: Parameters

Properties

Type — Type of data

`coder.descriptor.types` object

The data type associated with the data such as `integer`, `double`, `matrix`, and its properties.

Attributes:

GetAccess	public
SetAccess	public

SID — Simulink identifier

character vector

The Simulink identifier (SID) is a unique number within the model that Simulink assigns to a block.

Attributes:

GetAccess	public
SetAccess	public

GraphicalName — Name of the tunable parameter for the breakpoints

character vector

The name of the associated tunable parameter for the breakpoints.

Attributes:

GetAccess	public
SetAccess	public

VariantInfo — Variant conditions in the model

`coder.descriptor.VariantInfo` object

The variant conditions in the model that interact with the data interface.

Attributes:

GetAccess	public
SetAccess	public

Implementation — Description of implementation of data

`coder.descriptor.DataImplementation` object

Description of how the data in the generated code is implemented. This property describes characteristics such as data type and size. It also describes how the data is accessed or declared in the code. The property describes if the data is declared as a variable or structure member.

Attributes:

GetAccess	public
SetAccess	public

Timing — Data access rate in run-time environment

`coder.descriptor.TimingInterface` object

The rate at which data is accessed in a run-time environment.

Attributes:

GetAccess	public
SetAccess	public

Unit — Physical unit as attribute on signals

character vector

Specified physical units as attributes on signals at the boundaries of model components.

Attributes:

GetAccess	public
SetAccess	public

Range — Range of output value

coder.descriptor.Range object

The range of valid values for the block output signals.

Attributes:

GetAccess	public
SetAccess	public

OperatingPoint — Input value to the lookup table relative to each breakpoint

coder.descriptor.DataInterface object

To find the input value in the table, the operating point uses relative breakpoint set data.

Attributes:

GetAccess	public
SetAccess	public

SupportTunableSize — Option to generate code that enables tunability of table size

1 (default) | 0

Option to generate code that enables tunability of the effective size of the table, specified as 0 or 1.

Attributes:

GetAccess	public
SetAccess	public

Data Types: logical

FixAxisMetadata — Description of breakpoint set data

coder.descriptor.FixAxisMetadata

Description of breakpoint set data that is either evenly spaced or non-evenly spaced. The coder.descriptor.FixAxisMetadata object is created only if the lookup table data is tunable and the breakpoint set data is not tunable.

Attributes:

GetAccess	public
SetAccess	public

Methods**Public Methods**

`isBreakpointDataInterface` Determine whether object is a `coder.descriptor.BreakpointDataInterface` object

Examples**Get breakpoint data set information**

- 1 Build the model.

```
slbuild('rtwdemo_asap2')
```

- 2 Create a `coder.codedescriptor.CodeDescriptor` object for the model.

```
codeDescObj = coder.getCodeDescriptor('rtwdemo_asap2')
```

- 3 Return properties of the Lookup Table parameters in the model.

```
params = getDataInterfaces(codeDescObj, 'Parameters')
```

The `params` variable is an array of `coder.descriptor.DataInterface` and `coder.descriptor.LookupTableDataInterface` objects. The model `rtwdemo_asap2` contains three Lookup Table blocks. Only two of them have tunable breakpoint set data. The code generator creates only two corresponding `coder.descriptor.LookupTableDataInterface` objects.

Obtain the details of the `Standard_Axis` block by accessing the sixth location in the array.

```
params(6)
```

The `coder.descriptor.LookupTableDataInterface` object with properties is returned.

```

Type: [1x1 coder.descriptor.types.Type]
SID: 'rtwdemo_asap2:14'
GraphicalName: 'tabledata'
VariantInfo: [1x0 coder.descriptor.VariantInfo]
Implementation: [1x1 coder.descriptor.DataImplementation]
Timing: [1x0 coder.descriptor.TimingInterface]
Unit: ''
Range: [1x0 coder.descriptor.Range]
SupportTunableSize: 0
BreakpointSpecification: 'Explicit values'
Output: [1x1 coder.descriptor.DataInterface]
Breakpoints: [1x2 coder.descriptor.BreakpointDataInterface Sequence]

```

- 4 The `Breakpoints` property of the `coder.descriptor.LookupTableDataInterface` object holds a vector of `coder.descriptor.BreakpointDataInterface` objects. Obtain the details of the breakpoint set attached to the model Lookup Table block by accessing the first location in the array.

```
params(6).Breakpoints(1)
```

The `coder.descriptor.BreakpointDataInterface` object with properties is returned.

```
    Type: [1x1 coder.descriptor.types.Type]
      SID: 'rtwdemo_asap2:14'
  GraphicalName: 'tabledata'
    VariantInfo: [1x0 coder.descriptor.VariantInfo]
  Implementation: [1x1 coder.descriptor.DataImplementation]
    Timing: [1x0 coder.descriptor.TimingInterface]
    Unit: ''
    Range: [1x0 coder.descriptor.Range]
  OperatingPoint: [1x1 coder.descriptor.DataInterface]
  SupportTunableSize: 0
  FixAxisMetadata: [1x0 coder.descriptor.FixAxisMetadata]
```

Version History

Introduced in R2020a

See Also

[coder.codedescriptor.CodeDescriptor](#) | [coder.descriptor.DataInterface](#) |
[coder.descriptor.LookupTableDataInterface](#) | [coder.descriptor.FixAxisMetadata](#)

coder.descriptor.DataInterface class

Package: coder.descriptor

Return information about different types of data interfaces

Description

The `coder.descriptor.DataInterface` object describes various properties for a specified data interface in the generated code. The different types of data interfaces are:

- Root-level inports and outports: An interface between the model and external models or systems, for exchanging data.
- Parameters: Local and global parameters that describe the data for the block, lookup table, and the associated breakpoint set data.
- Data Stores: A repository to store global and shared data that can be written and read.
- Internal data: Internal data structures including DWork vectors, block I/O, and zero-crossings.

Creation

`dataInterface = getDataInterfaces(codeDescObj, dataInterfaceName)` creates a `coder.descriptor.DataInterface` object. The `codeDescObj` object is the `coder.codedescriptor.CodeDescriptor` object created for the model by using the `getCodeDescriptor` function.

Input Arguments

dataInterfaceName — Name of data interface

Inports | Outports | Parameters | GlobalDataStores | SharedLocalDataStores | ExternalParameterObjects | ModelParameters | InternalData

Name of the specified data interface.

Example: 'Inports'

Data Types: string

Properties

Type — Type of data

`coder.descriptor.types` object

The data type associated with the data such as `integer`, `double`, `matrix`, and its properties.

Attributes:

GetAccess	public
SetAccess	public

SID — Simulink identifier

character vector

The Simulink identifier (SID) is a unique number within the model that Simulink assigns to the block.

Attributes:

GetAccess	public
SetAccess	public

GraphicalName — Name of graphical entity

character vector

The name of the associated graphical entity.

Attributes:

GetAccess	public
SetAccess	public

VariantInfo — Variant conditions in the model

`coder.descriptor.VariantInfo` object

The variant conditions in the model that interact with the data interface.

Attributes:

GetAccess	public
SetAccess	public

Implementation — Description of implementation of data

`coder.descriptor.DataImplementation` object

The description of how the data in the generated code is implemented. This property describes characteristics such as data type and size. In addition, it describes how the data is accessed or declared in the code. The property describes if the data is declared as a variable or structure member.

Attributes:

GetAccess	public
SetAccess	public

Timing — Data access rate in run-time environment

`coder.descriptor.TimingInterface` object

The rate at which data is accessed in a run-time environment.

Attributes:

GetAccess	public
SetAccess	public

Unit — Physical unit as attribute on signals

character vector

Specified physical units as attributes on signals at the boundaries of model components.

Attributes:

GetAccess	public
SetAccess	public

Range — Range of output value

coder.descriptor.Range object

The range of valid values for the block output signals.

Attributes:

GetAccess	public
SetAccess	public

Limitations

A bitfield data structure is generated if you select these configuration parameters:

- **Pack Boolean data into bitfields**
- **Use bitset for storing state configuration**
- **Use bitset for storing Boolean data**

If the coder.descriptor.DataInterface represents a bitfield data structure, the Implementation property of the coder.descriptor.DataInterface object is empty.

Examples**Get All Data Interface Types**

- 1 Build the model.

```
slbuild('rtwdemo_comments')
```

- 2 Create a coder.CodeDescriptor.CodeDescriptor object for the required model.

```
codeDescObj = coder.getCodeDescriptor('rtwdemo_comments')
```

- 3 Return a list of all data interface types in the generated code.

```
dataInterfaceTypes = getDataInterfaceTypes(codeDescObj)
```

```
{'Inports'      }
{'Outports'     }
{'Parameters'   }
{'ExternalParameterObjects'}
{'InternalData' }
```

- 4 Return properties of a specified data interface in the generated code.

```
dataInterface = getDataInterfaces(codeDescObj, 'Inports')
```

dataInterface is an array of coder.descriptor.DataInterface objects. Obtain the details of the first Inport block of the model by accessing the first location in the array.

```
dataInterface(1)
```

The first coder.descriptor.DataInterface object with properties is returned.

```
        Type: [1x1 coder.descriptor.types.Double]
          SID: 'rtwdemo_comments:1'
  GraphicalName: 'In1'
    VariantInfo: [0x0 coder.descriptor.VariantInfo]
  Implementation: [1x1 coder.descriptor.StructExpression]
        Timing: [1x1 coder.descriptor.TimingInterface]
```

Version History

Introduced in R2018a

See Also

`coder.codedescriptor.CodeDescriptor` | `getAllDataInterfaceTypes` | `getDataInterfaceTypes` | `getDataInterfaces`

Topics

“Get Code Description of Generated Code”

coder.descriptor.EvenSpacingMetadata class

Package: coder.descriptor

Superclasses: coder.descriptor.FixAxisMetadata

Return information about evenly spaced breakpoint set data

Description

The `coder.descriptor.EvenSpacingMetadata` object describes breakpoint set data that is evenly spaced, such as starting point, breakpoint step size, and number of points.

Creation

`params = getDataInterfaces(codeDescObj, dataInterfaceName)` creates a `coder.descriptor.BreakpointDataInterface` object for each dimension in the lookup table. The `codeDescObj` object is the `coder.codedescriptor.CodeDescriptor` object created for the model by using the `getCodeDescriptor` function.

The `coder.descriptor.BreakpointDataInterface` object has property `FixAxisMetadata` that contains a `coder.descriptor.FixAxisMetadata` object. The `coder.descriptor.FixAxisMetadata` contains a `coder.descriptor.EvenSpacingMetadata` object if the breakpoint set data is evenly spaced.

Input Arguments

dataInterfaceName — Name of data interface

Parameters

Specify the Parameters data interface type.

Example: Parameters

Properties

StartingValue — Starting value in the breakpoint set data

character vector

The first point in evenly spaced breakpoint set data.

Attributes:

GetAccess	public
SetAccess	public

StepValue — Spacing between evenly spaced breakpoints

character vector

The spacing between points in evenly spaced breakpoint set data. This value represents a power of 2 if the `IsPow2` returns 1.

Attributes:

GetAccess public
SetAccess public

NumPoints — Total number of breakpoint values
character vector

Total number of points in evenly spaced breakpoint set data.

Attributes:

GetAccess public
SetAccess public

IsPow2 — Power of 2
1 | 0

Returns 1 if the value in StepValue is a power of 2.

Attributes:

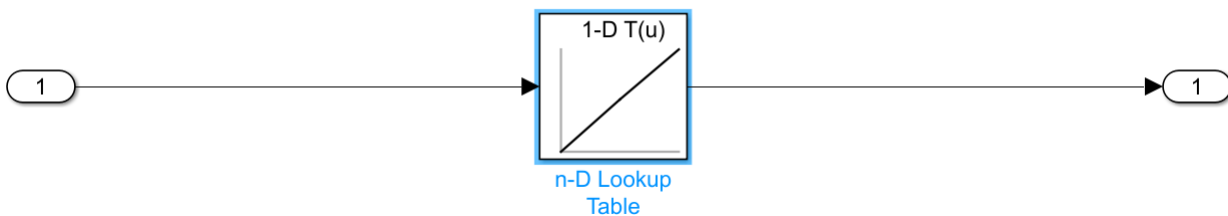
GetAccess public
SetAccess public

Data Types: logical

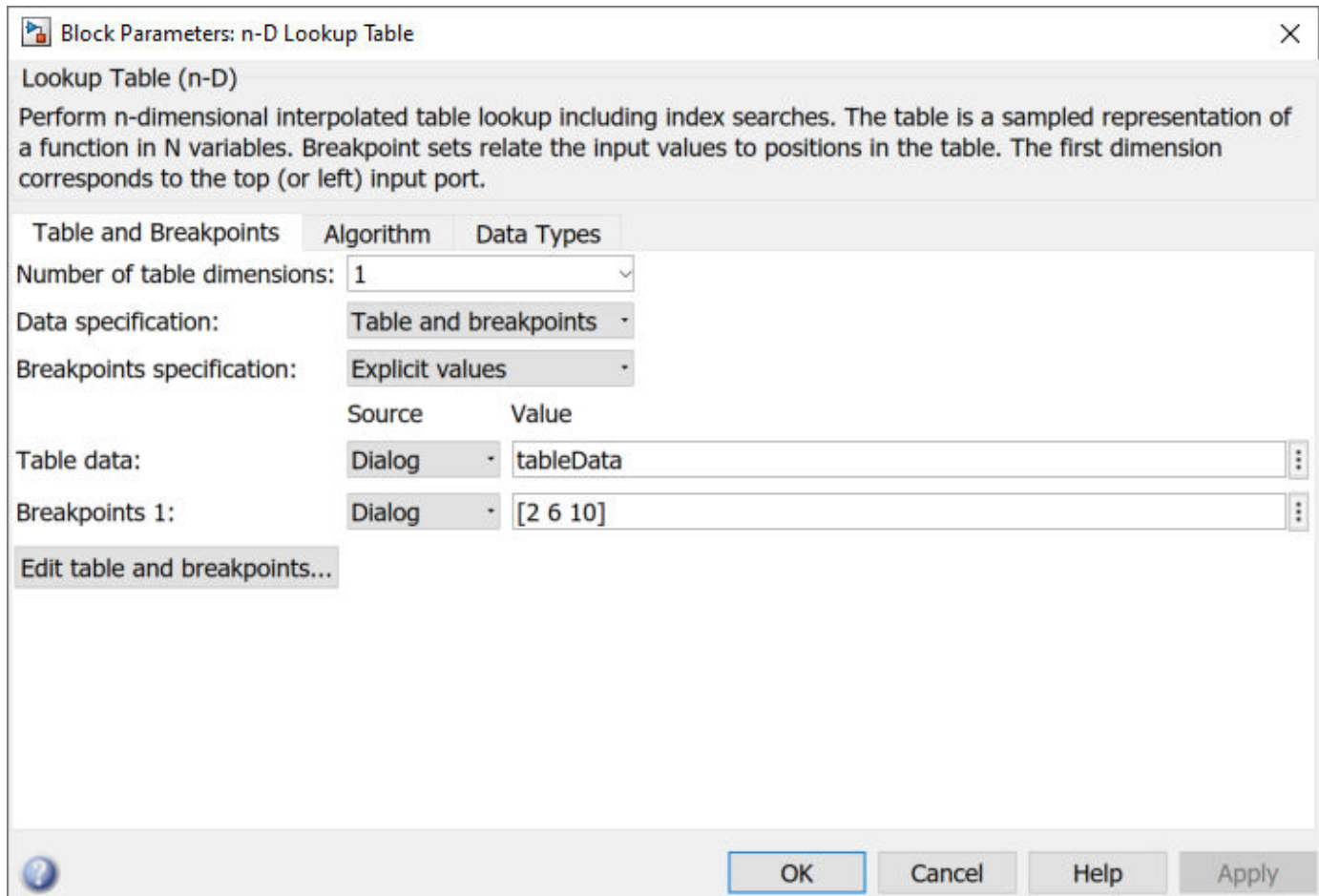
Examples

Get evenly spaced breakpoint set data information

Consider creating model codeDescDemo or a model with similar specifications.



The model contains a n-D Lookup Table. The n-D Lookup Table block takes table data from a model workspace variable named `tableData` with value `[4 5 6]`. The `tableData` is a `Simulink.Parameter` object with non-Auto storage class. The breakpoint set data is specified as `[2 6 10]`.



The model configuration parameter **Default parameter behavior** is set to Inlined.

- 1 Build the model and create a `coder.codedescriptor.CodeDescriptor` object for the model.

```
codeDescObj = coder.getCodeDescriptor('codeDescDemo')
```

- 2 Retrieve properties of the Lookup Table block and breakpoint set in the generated code.

```
params = getDataInterfaces(codeDescObj, 'Parameters')
```

The `params` variable is an array of `coder.descriptor.LookupTableDataInterface` and `coder.descriptor.BreakpointDataInterface` objects.

```
LookupTableDataInterface with properties:
    Type: [1x1 coder.descriptor.types.Type]
    SID: 'demoModel:22'
    GraphicalName: 'tableData'
    VariantInfo: [1x0 coder.descriptor.VariantInfo]
    Implementation: [1x1 coder.descriptor.DataImplementation]
    Timing: [1x0 coder.descriptor.TimingInterface]
    Unit: ''
    Range: [1x1 coder.descriptor.Range]
    SupportTunableSize: 0
    BreakpointSpecification: 'Even spacing'
    Output: [1x1 coder.descriptor.DataInterface]
    Breakpoints: [1x1 coder.descriptor.BreakpointDataInterface Sequence]
```

- 3 The `Breakpoints` property of the `coder.descriptor.LookupTableDataInterface` object holds a vector of `coder.descriptor.BreakpointDataInterface` objects. Obtain the details

of the breakpoint set attached to the Lookup Table block by accessing the first location in the array.

```
params.Breakpoints(1)
```

```
BreakpointDataInterface with properties:  
    Type: [1x1 coder.descriptor.types.Type]  
    SID: 'demoModel:22'  
    GraphicalName: 'n-D Lookup Table'  
    VariantInfo: [1x0 coder.descriptor.VariantInfo]  
    Implementation: [1x0 coder.descriptor.DataImplementation]  
    Timing: [1x0 coder.descriptor.TimingInterface]  
    Unit: ''  
    Range: [1x1 coder.descriptor.Range]  
    OperatingPoint: [1x1 coder.descriptor.DataInterface]  
    SupportTunableSize: 0  
    FixAxisMetadata: [1x1 coder.descriptor.FixAxisMetadata]
```

- 4** The new `coder.descriptor.FixAxisMetadata` object provides more information about whether the breakpoint set data is evenly spaced or not.

```
params.Breakpoints(1).FixAxisMetadata
```

The information is returned as a new `coder.descriptor.EvenSpacingMetadata` object with these properties:

```
EvenSpacingMetadata with properties:  
    StartingValue: 2  
    StepValue: 2  
    NumPoints: 3  
    IsPow2: 1
```

Version History

Introduced in R2020b

See Also

`coder.codedescriptor.CodeDescriptor` | `coder.descriptor.DataInterface` |
`coder.descriptor.FixAxisMetadata` | `coder.descriptor.BreakpointDataInterface` |
`coder.descriptor.NonEvenSpacingMetadata`

coder.descriptor.FixAxisMetadata class

Package: coder.descriptor

Abstract class to get breakpoint set data information

Description

Abstract base class to get breakpoint set data information. Based on the breakpoint set data, you can get either a `coder.descriptor.EvenSpacingMetadata` object or a `coder.descriptor.NonEvenSpacingMetadata` object. To get breakpoint set data information, use the `coder.descriptor.BreakpointDataInterface` object.

You can get a `coder.descriptor.FixAxisMetadata` object if the model meets these conditions:

- Table data is tunable.

Table data is tunable if the Lookup Table block uses a `Simulink.Parameter` object that has a non-Auto storage class or the model configuration parameter **Default parameter behavior** is Tunable.

- Breakpoint set data is not tunable.

Breakpoint set data is tunable if the Lookup Table block uses a `Simulink.Parameter` object that has a non-Auto storage class or the model configuration parameter **Default parameter behavior** is Tunable.

Creation

`params = getDataInterfaces(codeDescObj, dataInterfaceName)` creates a `coder.descriptor.BreakpointDataInterface` object for each dimension in the lookup table. The `codeDescObj` object is the `coder.codedescriptor.CodeDescriptor` object created for the model by using the `getCodeDescriptor` function.

The `coder.descriptor.BreakpointDataInterface` object has property `FixAxisMetadata` that contains a `coder.descriptor.FixAxisMetadata` object.

Input Arguments

dataInterfaceName — Name of data interface

Parameters

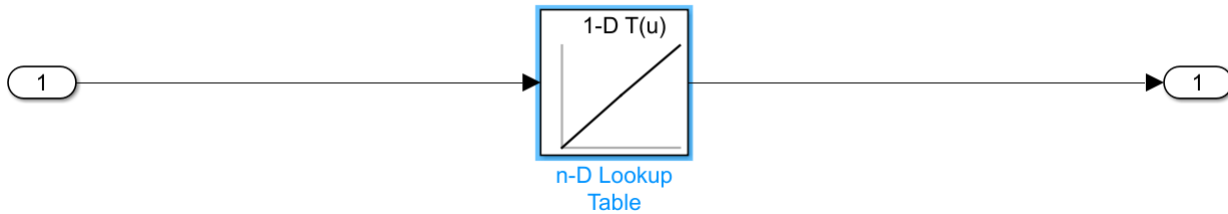
Specify the Parameters data interface type.

Example: Parameters

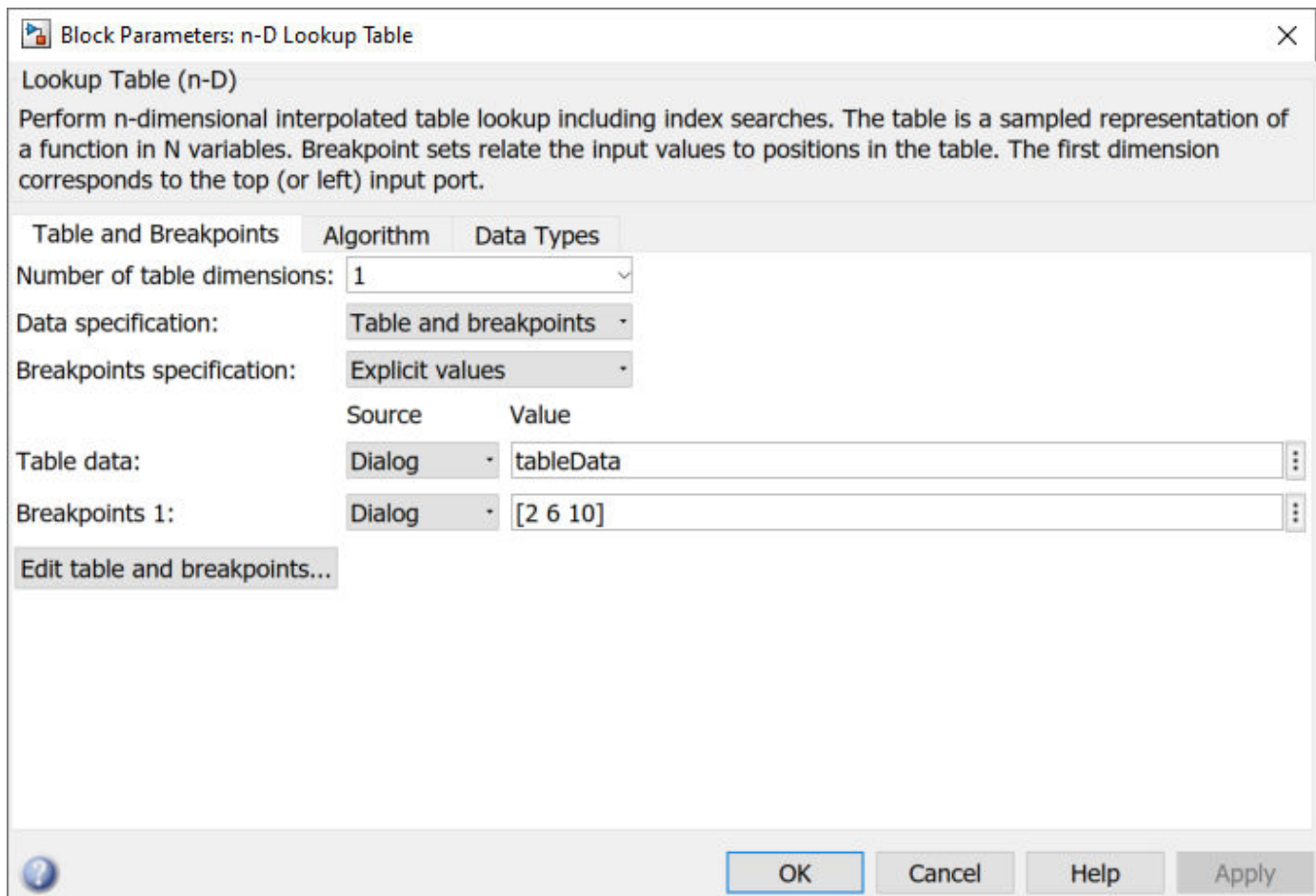
Examples

Get breakpoint set data information

Consider creating model `codeDescDemo` or a model with similar specifications.



The model contains an n-D Lookup Table. The n-D Lookup Table block takes table data from a model workspace variable named `tableData` that has a value of `[4 5 6]`. The `tableData` is a `Simulink.Parameter` object that has a non-Auto storage class. The breakpoint set data is specified as `[2 6 10]`.



The model configuration parameter **Default parameter behavior** is set to `Inlined`.

- 1 Build the model and create a `coder.codedescriptor.CodeDescriptor` object for the model.

```
codeDescObj = coder.getCodeDescriptor('codeDescDemo')
```

- 2 Retrieve properties of the Lookup Table block and breakpoint set in the generated code.

```
params = getDataInterfaces(codeDescObj, 'Parameters')
```

The `params` variable is an array of `coder.descriptor.LookupTableDataInterface` and `coder.descriptor.BreakpointDataInterface` objects.

```
LookupTableDataInterface with properties:
    Type: [1x1 coder.descriptor.types.Type]
    SID: 'demoModel:22'
    GraphicalName: 'tableData'
    VariantInfo: [1x0 coder.descriptor.VariantInfo]
    Implementation: [1x1 coder.descriptor.DataImplementation]
    Timing: [1x0 coder.descriptor.TimingInterface]
    Unit: ''
    Range: [1x1 coder.descriptor.Range]
    SupportTunableSize: 0
    BreakpointSpecification: 'Even spacing'
    Output: [1x1 coder.descriptor.DataInterface]
    Breakpoints: [1x1 coder.descriptor.BreakpointDataInterface Sequence]
```

- 3 The `Breakpoints` property of the `coder.descriptor.LookupTableDataInterface` object holds a vector of `coder.descriptor.BreakpointDataInterface` objects. Obtain the details of the breakpoint set attached to the Lookup Table block by accessing the first location in the array.

```
params.Breakpoints(1)
```

```
BreakpointDataInterface with properties:
    Type: [1x1 coder.descriptor.types.Type]
    SID: 'demoModel:22'
    GraphicalName: 'n-D Lookup Table'
    VariantInfo: [1x0 coder.descriptor.VariantInfo]
    Implementation: [1x0 coder.descriptor.DataImplementation]
    Timing: [1x0 coder.descriptor.TimingInterface]
    Unit: ''
    Range: [1x1 coder.descriptor.Range]
    OperatingPoint: [1x1 coder.descriptor.DataInterface]
    SupportTunableSize: 0
    FixAxisMetadata: [1x1 coder.descriptor.FixAxisMetadata]
```

- 4 The new `coder.descriptor.FixAxisMetadata` object provides more information about whether the breakpoint set data is evenly spaced or not.

```
params.Breakpoints(1).FixAxisMetadata
```

The information is returned as a new `coder.descriptor.EvenSpacingMetadata` object that has these properties:

```
EvenSpacingMetadata with properties:
    StartingValue: 2
    StepValue: 2
    NumPoints: 3
    IsPow2: 1
```

- 5 If the breakpoint set data value is changed to `[1 5 10]`, the information is returned as a new `coder.descriptor.NonEvenSpacingMetadata` object that has these properties:

```
NonEvenSpacingMetadata with properties:
    AllPoints: [1x3 Real Sequence]
```

Version History

Introduced in R2020b

See Also

`coder.codedescriptor.CodeDescriptor` | `coder.descriptor.DataInterface` |
`coder.descriptor.BreakpointDataInterface` | `coder.descriptor.EvenSpacingMetadata`
| `coder.descriptor.NonEvenSpacingMetadata`

coder.descriptor.FunctionInterface class

Package: coder.descriptor

Return information about entry-point functions

Description

The function interfaces are the entry-point functions in the generated code. The `coder.descriptor.FunctionInterface` object describes various properties for a specified function interface. The different types of function interfaces are:

- **Allocation:** Contains memory allocation code based on the target of the model. See `model_initialize`.
- **Initialize:** Contains initialization code for the model and is called once at the start of your application code. See `model_initialize`.
- **Output:** Contains the output code for the blocks in the model. See `model_step`.
- **Update:** Contains the update code for the blocks in the model. See `model_step`.
- **Terminate:** Contains the termination code for the model and is called as part of a system shutdown. See `model_terminate`.

Creation

`functionInterface = getFunctionInterfaces(codeDescObj, functionInterfaceName)` creates a `coder.descriptor.FunctionInterface` object. `codeDescObj` is the `coder.codedescriptor.CodeDescriptor` object created for the model by using the `getCodeDescriptor` function.

Input Arguments

functionInterfaceName — Name of function interface

Allocation | Initialize | Output | Update | Terminate

Name of the specified function interface

Example: 'Output'

Data Types: string

Properties

Prototype — Description of function prototype

`coder.descriptor.Prototype` object

Description of the function prototype, including the function return value, name, arguments, header, and source file, specified as a `coder.descriptor.Prototype` object.

Attributes:

GetAccess	public
SetAccess	public

ActualReturn — Return arguments from function`coder.descriptor.DataInterface` object

Return arguments from the function, specified as a `coder.descriptor.DataInterface` object. When the function returns no data, this field is empty.

Attributes:

GetAccess	public
SetAccess	public

VariantInfo — Variant conditions in model`coder.descriptor.VariantInfo` object

Variant conditions in the model that interact with the function interface, specified as a `coder.descriptor.VariantInfo` object.

Attributes:

GetAccess	public
SetAccess	public

FunctionOwner — Function owner`coder.descriptor.TypedRegion` object

Function owner of the class that the function belongs to, specified as a `coder.descriptor.TypedRegion` object. For C code generation, this property is empty.

Attributes:

GetAccess	public
SetAccess	public

Timing — Function access rate in target environment`coder.descriptor.TimingInterface` object

Function access rate in the target environment, specified as a `coder.descriptor.TimingInterface` object.

Attributes:

GetAccess	public
SetAccess	public

ActualArgs — Input arguments to the function`coder.descriptor.DataInterfaceList` object

Input arguments to the function, specified as a `coder.descriptor.DataInterfaceList` object. When there is no data passed as an argument to the function, this property is empty.

Attributes:

GetAccess public

Examples**Get All Function Interface Types**

- 1 Build the model.

```
slbuild('rtwdemo_comments')
```

- 2 Create a `coder.codedescriptor.CodeDescriptor` object for the required model.

```
codeDescObj = coder.getCodeDescriptor('rtwdemo_comments')
```

- 3 Return a list of all function interface types in the generated code.

```
functionInterfaceTypes = getFunctionInterfaceTypes(codeDescObj)
```

```
    {'Initialize'}
    {'Output'     }
```

- 4 Return properties of a specified function interface in the generated code.

```
functionInterface = getFunctionInterfaces(codeDescObj, 'Output')
```

```
    Prototype: [1x1 coder.descriptor.types.Prototype]
    ActualReturn: [0x0 coder.descriptor.DataInterface]
    VariantInfo: [0x0 coder.descriptor.VariantInfo]
    Timing: [1x1 coder.descriptor.TimingInterface]
    ActualArgs: [1x0 coder.descriptor.DataInterface List]
```

Version History

Introduced in R2018a

See Also

`coder.codedescriptor.CodeDescriptor` | `getAllFunctionInterfaceTypes` | `getFunctionInterfaceTypes` | `getFunctionInterfaces`

Topics

“Get Code Description of Generated Code”

coder.descriptor.LookupTableDataInterface class

Package: coder.descriptor

Superclasses: coder.descriptor.DataInterface

Return information about Lookup Table blocks that have tunable parameters

Description

The `coder.descriptor.LookupTableDataInterface` object describes various properties for these Lookup Table blocks that have tunable parameters in the generated code:

- 1-D Lookup Table
- 2-D Lookup Table
- n-D Lookup Table
- Interpolation Using Prelookup
- Direct Lookup Table (n-D)
- Sine
- Cosine

Creation

`params = getDataInterfaces(codeDescObj, dataInterfaceName)` creates a `coder.descriptor.LookupTableDataInterface` object if the model has a Lookup Table block that has tunable parameters. The `codeDescObj` object is the `coder.codedescriptor.CodeDescriptor` object created for the model by using the `getCodeDescriptor` function.

Input Arguments

dataInterfaceName — Name of data interface

Parameters

Specify the Parameters data interface type.

Example: Parameters

Properties

Type — Type of data

`coder.descriptor.types` object

The data type associated with the data such as `integer`, `double`, `matrix`, and its properties.

Attributes:

GetAccess	public
SetAccess	public

SID — Simulink identifier

character vector

The Simulink identifier (SID) is a unique number within the model that Simulink assigns to the block.

Attributes:

GetAccess	public
SetAccess	public

GraphicalName — Name of the tunable parameter for the table data

character vector

The name of the associated tunable parameter for the table data.

Attributes:

GetAccess	public
SetAccess	public

VariantInfo — Variant conditions in the model

coder.descriptor.VariantInfo object

The variant conditions in the model that interact with the data interface.

Attributes:

GetAccess	public
SetAccess	public

Implementation — Description of implementation of data

coder.descriptor.DataImplementation object

Description of how the data in the generated code is implemented. This property describes characteristics such as data type and size. It also describes how the data is accessed or declared in the code. The property describes if the data is declared as a variable or structure member.

Attributes:

GetAccess	public
SetAccess	public

Timing — Data access rate in run-time environment

coder.descriptor.TimingInterface object

The rate at which data is accessed in a run-time environment.

Attributes:

GetAccess	public
SetAccess	public

Unit — Physical unit as attribute on signals

character vector

Specified physical units as attributes on signals at the boundaries of model components.

Attributes:

GetAccess	public
SetAccess	public

Range — Range of output value
`coder.descriptor.Range` object

The range of valid values for the block output signals.

Attributes:

GetAccess	public
SetAccess	public

SupportTunableSize — Tunability of table size
`1 (default) | 0`

Value that represents whether table is enabled for tunability of the effective size of the table, specified as `0` or `1`.

Attributes:

GetAccess	public
SetAccess	public

Data Types: `logical`

BreakpointSpecification — Source of breakpoint set information in ASAP2 specification
`'Explicit values' (default) | 'Reference' | 'Even spacing'`

Source of the breakpoint set information, specified as `'Explicit values'` (default), `'Even spacing'`, or `'Reference'`. The breakpoint specification is mapped as:

- `Explicit values` — `STD_AXIS`
- `Reference` — `COM_AXIS`
- `Even spacing` — `FIX_AXIS`

For more information on ASAP2 lookup tables, see “Define ASAP2 Information for Lookup Tables”.

Attributes:

GetAccess	public
SetAccess	public

Data Types: `char`

Output — Data interface for the output of Lookup Table block
`coder.descriptor.DataInterface` object

Return value of the lookup table operation.

Attributes:

GetAccess	public
SetAccess	public

Breakpoints — Breakpoint set data

coder.descriptor.BreakpointDataInterface object

Vector of coder.descriptor.BreakpointDataInterface objects that are used in the Lookup Table block. These objects contain the breakpoint set data.

Attributes:

GetAccess public

Methods**Public Methods**

isLookupTableDataInterface Determine whether object is a coder.descriptor.LookupTableDataInterface object

getAllParameters Return all associated coder.descriptor.LookupTableDataInterface and coder.descriptor.BreakpointDataInterface objects

Examples**Get Lookup Table block information**

- 1 Build the model.

```
slbuild('rtwdemo_asap2')
```

- 2 Create a coder.codeDescriptor.CodeDescriptor object for the model.

```
codeDescObj = coder.getCodeDescriptor('rtwdemo_asap2')
```

- 3 Return properties of the Lookup Table parameters in the model.

```
params = getDataInterfaces(codeDescObj, 'Parameters')
```

The params variable is an array of coder.descriptor.DataInterface and coder.descriptor.LookupTableDataInterface objects. The model rtwdemo_asap2 contains three Lookup Table blocks. Only two of them have tunable breakpoint set data. The code generator creates only two corresponding coder.descriptor.LookupTableDataInterface objects.

Obtain the details of the Standard_Axis block by accessing the sixth location in the array.

```
params(6)
```

The coder.descriptor.LookupTableDataInterface object with properties is returned.

```

Type: [1x1 coder.descriptor.types.Type]
SID: 'rtwdemo_asap2:14'
GraphicalName: 'tabledata'
VariantInfo: [1x0 coder.descriptor.VariantInfo]
Implementation: [1x1 coder.descriptor.DataImplementation]
Timing: [1x0 coder.descriptor.TimingInterface]
Unit: ''
Range: [1x0 coder.descriptor.Range]
SupportTunableSize: 0
BreakpointSpecification: 'Explicit values'
Output: [1x1 coder.descriptor.DataInterface]
Breakpoints: [1x2 coder.descriptor.BreakpointDataInterface Sequence]
```

Version History

Introduced in R2020a

See Also

`coder.codedescriptor.CodeDescriptor` | `coder.descriptor.DataInterface` |
`coder.descriptor.BreakpointDataInterface`

coder.descriptor.NonEvenSpacingMetadata class

Package: coder.descriptor

Superclasses: coder.descriptor.FixAxisMetadata

Return information about non-evenly spaced breakpoint set data

Description

The `coder.descriptor.NonEvenSpacingMetadata` object describes the points in breakpoint set data that are non-evenly spaced.

Creation

`params = getDataInterfaces(codeDescObj, dataInterfaceName)` creates a `coder.descriptor.BreakpointDataInterface` object for each dimension in the lookup table. The `codeDescObj` object is the `coder.codedescriptor.CodeDescriptor` object created for the model by using the `getCodeDescriptor` function.

The `coder.descriptor.BreakpointDataInterface` object has property `FixAxisMetadata` that contains a `coder.descriptor.FixAxisMetadata` object. The `coder.descriptor.FixAxisMetadata` further contains a `coder.descriptor.NonEvenSpacingMetadata` object if the breakpoint set data is non-evenly spaced.

Input Arguments

dataInterfaceName — Name of data interface

Parameters

Specify the Parameters data interface type.

Example: Parameters

Properties

AllPoints — All values in the breakpoint set

double vector

All values that are in the non-evenly spaced breakpoint set data.

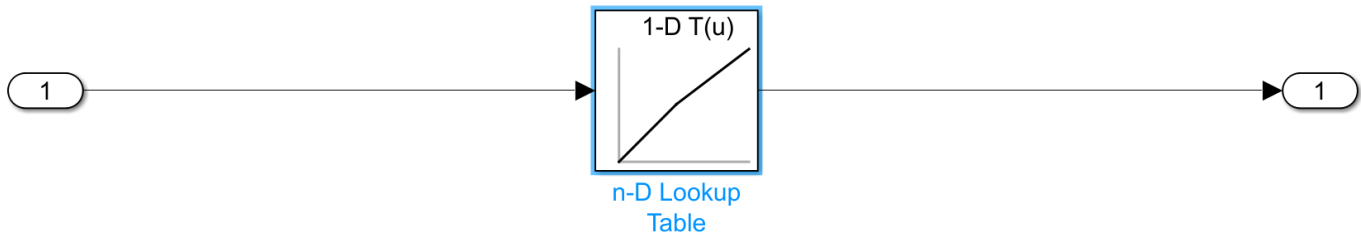
Attributes:

GetAccess public

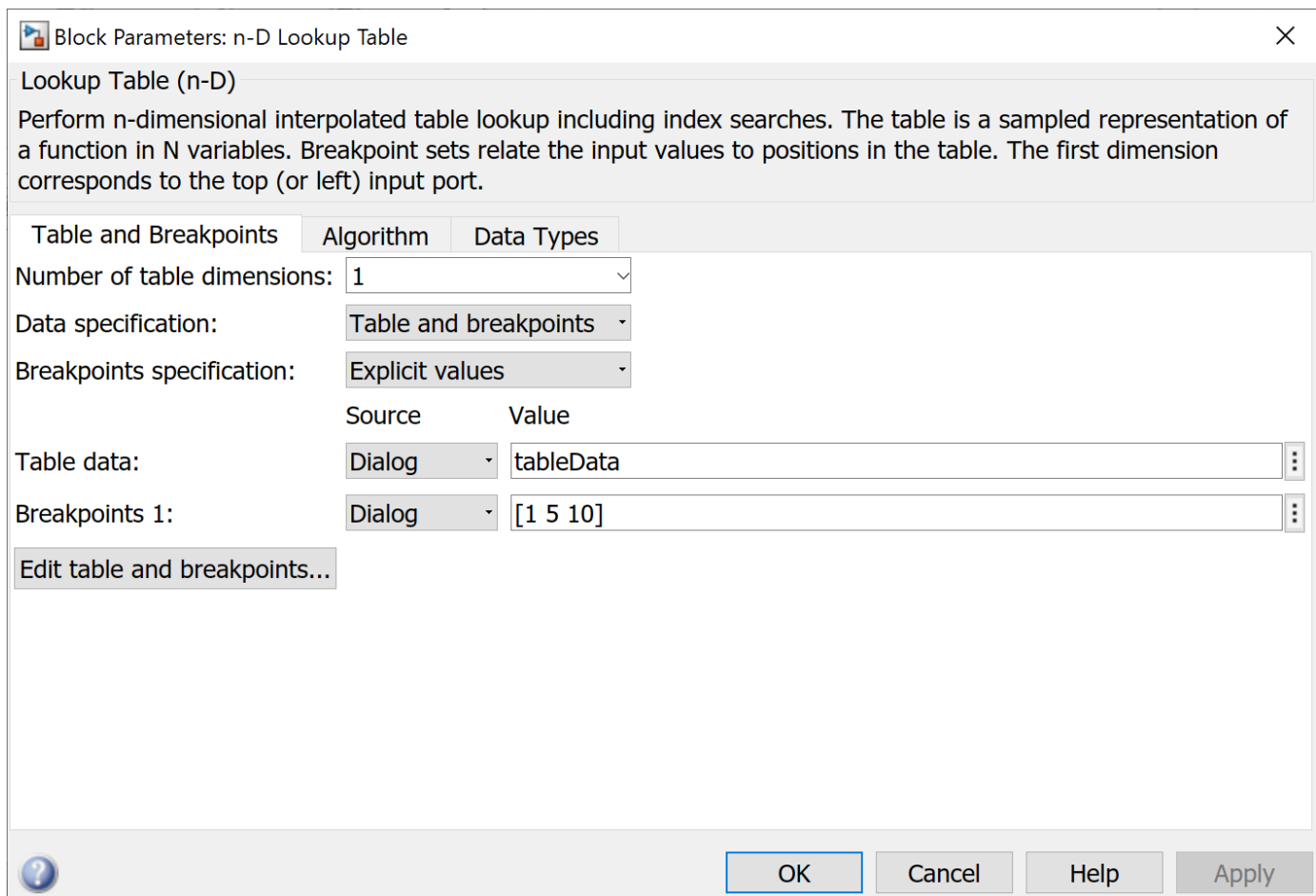
Examples

Get non-evenly spaced breakpoint set data information

Consider creating model `codeDescDemo` or a model with similar specifications.



The model contains an n-D Lookup Table. The n-D Lookup Table block takes table data from a model workspace variable named `tableData` that has a value of `[4 5 6]`. The `tableData` is a `Simulink.Parameter` object with a non-Auto storage class. The breakpoint set data is specified as `[1 5 10]`.



The model configuration parameter **Default parameter behavior** is set to Inlined.

- 1 Build the model and create a `coder.codescriptor.CodeDescriptor` object for the model.


```
codeDescObj = coder.getCodeDescriptor('codeDescDemo')
```
- 2 Retrieve properties of the Lookup Table block and breakpoint set in the generated code.


```
params = getDataInterfaces(codeDescObj, 'Parameters')
```

The `params` variable is an array of `coder.descriptor.LookupTableDataInterface` and `coder.descriptor.BreakpointDataInterface` objects.

```
LookupTableDataInterface with properties:
    Type: [1x1 coder.descriptor.types.Type]
    SID: 'demoModel:22'
    GraphicalName: 'tableData'
    VariantInfo: [1x0 coder.descriptor.VariantInfo]
    Implementation: [1x1 coder.descriptor.DataImplementation]
    Timing: [1x0 coder.descriptor.TimingInterface]
    Unit: ''
    Range: [1x1 coder.descriptor.Range]
    SupportTunableSize: 0
    BreakpointSpecification: 'Even spacing'
    Output: [1x1 coder.descriptor.DataInterface]
    Breakpoints: [1x1 coder.descriptor.BreakpointDataInterface Sequence]
```

- 3 The `Breakpoints` property of the `coder.descriptor.LookupTableDataInterface` object holds a vector of `coder.descriptor.BreakpointDataInterface` objects. Obtain the details of the breakpoint set attached to the Lookup Table block by accessing the first location in the array.

```
params.Breakpoints(1)
```

```
BreakpointDataInterface with properties:
    Type: [1x1 coder.descriptor.types.Type]
    SID: 'demoModel:22'
    GraphicalName: 'n-D Lookup Table'
    VariantInfo: [1x0 coder.descriptor.VariantInfo]
    Implementation: [1x0 coder.descriptor.DataImplementation]
    Timing: [1x0 coder.descriptor.TimingInterface]
    Unit: ''
    Range: [1x1 coder.descriptor.Range]
    OperatingPoint: [1x1 coder.descriptor.DataInterface]
    SupportTunableSize: 0
    FixAxisMetadata: [1x1 coder.descriptor.FixAxisMetadata]
```

- 4 The new `coder.descriptor.FixAxisMetadata` object gives you more information about whether the breakpoint set data is evenly spaced or not.

```
params.Breakpoints(1).FixAxisMetadata
```

The information is returned as a new `coder.descriptor.NonEvenSpacingMetadata` object that has these properties:

```
NonEvenSpacingMetadata with properties:
    AllPoints: [1x3 Real Sequence]
```

Version History

Introduced in R2020b

See Also

`coder.codedescriptor.CodeDescriptor` | `coder.descriptor.DataInterface` |
`coder.descriptor.FixAxisMetadata` | `coder.descriptor.BreakpointDataInterface` |
`coder.descriptor.EvenSpacingMetadata`

isBreakpointDataInterface

Determine whether object is a `coder.descriptor.BreakpointDataInterface` object

Syntax

```
breakpointTableDataInterface = isBreakpointDataInterface(parameterObj)
```

Description

`breakpointTableDataInterface = isBreakpointDataInterface(parameterObj)` returns a logical value indicating whether the object is a `coder.descriptor.BreakpointDataInterface` object or not.

Input Arguments

parameterObj — `coder.descriptor.BreakpointDataInterface` object

`coder.descriptor.BreakpointDataInterface`

`coder.descriptor.BreakpointDataInterface` object that represents a breakpoint set in the model.

Data Types: `string`

Output Arguments

breakpointTableDataInterface — logical value

1 | 0

Logical value indicating whether the object is a `coder.descriptor.BreakpointDataInterface`.

Data Types: `logical`

Examples

Determine if the object is a `coder.descriptor.BreakpointDataInterface` object

1 Build the model.

```
slbuild('rtwdemo_asap2')
```

2 Create a `coder.codeDescriptor.CodeDescriptor` object for the model.

```
codeDescObj = coder.getCodeDescriptor('rtwdemo_asap2')
```

3 Return properties of the breakpoint set data in the model.

```
params = getDataInterfaces(codeDescObj, 'Parameters')
```

The `params` variable is an array of `coder.descriptor.DataInterface`, `coder.descriptor.LookupTableDataInterface`, and `coder.descriptor.BreakpointDataInterface` objects.

- 4 Obtain the details of the breakpoint set attached to the model Lookup Table block by accessing the first location in the array.

```
parameterObj = params(6).Breakpoints(1)
```

- 5 Determine if the object stored in `parameterObj` variable is a `coder.descriptor.BreakpointDataInterface` object.

```
breakpointDataInterface = isBreakpointDataInterface(parameterObj)
```

```
lookupTableDataInterface =
```

```
    logical
```

```
    1
```

The code generator returns a logical value of 1 indicating if `parameterObj` is a `coder.descriptor.BreakpointDataInterface` object. Otherwise, the code generator returns a logical value of 0.

Version History

Introduced in R2020a

See Also

`isLookupTableDataInterface` | `coder.descriptor.BreakpointDataInterface`

getAllDataInterfaceTypes

Class: `coder.codedescriptor.CodeDescriptor`

Package: `coder.codedescriptor`

Return data interface types

Syntax

```
allDataInterfaceTypes = getAllDataInterfaceTypes(codeDescObj)
```

Description

`allDataInterfaceTypes = getAllDataInterfaceTypes(codeDescObj)` returns a list of the data interface types. This list is not specific to any model.

Input Arguments

codeDescObj — Code Descriptor object

`coder.codedescriptor.CodeDescriptor` object

`coder.codedescriptor.CodeDescriptor` object for which you want to retrieve the information about generated code.

Output Arguments

allDataInterfaceTypes — Data interface types available

cell array of character vectors

A list of available data interface types.

Examples

Create a `coder.codedescriptor.CodeDescriptor` object for the required model that is built, then list the available data interface types.

- 1 Build the model.

```
slbuild('rtwdemo_comments')
```

- 2 Create a `coder.codedescriptor.CodeDescriptor` object for the required model.

```
codeDescObj = coder.getCodeDescriptor('rtwdemo_comments')
```

- 3 Return a list of available data interface types.

```
allDataInterfaceTypes = getAllDataInterfaceTypes(codeDescObj)
```

`allDataInterfaceTypes` has these values:

```
{'Inports'           }  
{'Outports'         }  
{'Parameters'       }
```

```

{'GlobalDataStores'      }
{'SharedLocalDataStores'}
{'ExternalParameterObjects' }
{'ModelParameters'      }
{'InternalData'         }

```

Inports and **Outports** represent root-level inports and outports, not the inports and outports of subsystems.

Parameters includes all parameters in the model. **ExternalParameterObjects** and **ModelParameters** are subsets of **Parameters**. **ModelParameters** represents parameters that you define within a model, such as parameters in the model workspace. **ExternalParameterObjects** represents parameters that you define in the base workspace or in a data dictionary.

GlobalDataStores represents data stores that are defined by a signal object in the base workspace or in a data dictionary. **SharedLocalDataStores** represents Data Store Memory blocks that have the block parameter **Share across model instances** selected.

InternalData represents data elements that are internal to the model, such as block output signals, discrete block states, data stores, and zero-crossing signals.

For more information, see “C Code Generation Configuration for Model Interface Elements”.

Version History

Introduced in R2018a

See Also

`coder.codedescriptor.CodeDescriptor` | `coder.descriptor.DataInterface` | `getDataInterfaceTypes` | `getDataInterfaces` | `getCodeDescriptor`

Topics

“Get Code Description of Generated Code”

getAllFunctionInterfaceTypes

Class: `coder.codedescriptor.CodeDescriptor`

Package: `coder.codedescriptor`

Return function interface types

Syntax

```
allFunctionInterfaceTypes = getAllFunctionInterfaceTypes(codeDescObj)
```

Description

`allFunctionInterfaceTypes = getAllFunctionInterfaceTypes(codeDescObj)` returns a list of the function interface types. The returned list is not specific to any model.

Input Arguments

codeDescObj — Code Descriptor object

`coder.codedescriptor.CodeDescriptor` object

`coder.codedescriptor.CodeDescriptor` object for which you want to retrieve the information about generated code.

Output Arguments

allFunctionInterfaceTypes — Function interface types available

cell array of character vectors

A list of the available function interface types.

Examples

Create a `coder.codedescriptor.CodeDescriptor` object for the required model which is built, then list the available function interface types.

- 1 Build the model.

```
slbuild('rtwdemo_comments')
```

- 2 Create a `coder.codedescriptor.CodeDescriptor` object for the required model.

```
codeDescObj = coder.getCodeDescriptor('rtwdemo_comments')
```

- 3 Return a list of available function interface types.

```
allFunctionInterfaceTypes = getAllFunctionInterfaceTypes(codeDescObj)
```

`allFunctionInterfaceTypes` has these values:

```
{'Allocation'}  
{'Initialize'}  
{'Output' }
```



```
{'Update'   }  
{'Terminate'}  
}
```

Version History

Introduced in R2018a

See Also

`coder.codedescriptor.CodeDescriptor` | `getAllFunctionInterfaceTypes` |
`getAllFunctionInterfaces` | `getCodeDescriptor` | `coder.descriptor.FunctionInterface`

Topics

“Get Code Description of Generated Code”

“Configure Generated C Function Interface for Model Entry-Point Functions”

getArrayLayout

Class: `coder.codedescriptor.CodeDescriptor`

Package: `coder.codedescriptor`

Return array layout of the generated code

Syntax

```
arrayLayout = getArrayLayout(codeDescObj)
```

Description

`arrayLayout = getArrayLayout(codeDescObj)` returns the array layout of the model for which the code is generated.

Input Arguments

codeDescObj — Code Descriptor object

`coder.codedescriptor.CodeDescriptor` object

`coder.codedescriptor.CodeDescriptor` object for which you want to retrieve the information about generated code.

Output Arguments

arrayLayout — Array layout of the generated code

character vectors

Array layout specified for the model by using the model configuration parameter **Array layout** on page 12-46.

Examples

Create a `coder.codedescriptor.CodeDescriptor` object for the model that is built, then list the array layout of the generated code.

- 1 Open a model.

```
rtwdemo_comments
```

- 2 Specify the model configuration parameter **Array layout** as Row-major. Alternatively, in the command window, use these commands:

```
set_param('rtwdemo_comments', 'ArrayLayout', 'Row-major');
```

- 3 Build the model.

```
slbuild('rtwdemo_comments')
```

- 4 Create a `coder.codedescriptor.CodeDescriptor` object for the model.

```
codeDescObj = coder.getCodeDescriptor('rtwdemo_comments')
```

- 5** Return the array layout of the generated code.

```
arrayLayout = getArrayLayout(codeDescObj)
```

arrayLayout has this value:

```
'Row-major'
```

Version History

Introduced in R2018b

See Also

`coder.codescriptor.CodeDescriptor` | `getCodeDescriptor`

Topics

“Get Code Description of Generated Code”

“Code Generation of Matrices and Arrays”

getDataInterfaces

Class: `coder.codedescriptor.CodeDescriptor`

Package: `coder.codedescriptor`

Return information of the specified data interface

Syntax

```
dataInterface = getDataInterfaces(codeDescObj, dataInterfaceName)
```

Description

`dataInterface = getDataInterfaces(codeDescObj, dataInterfaceName)` returns the type of data, SID, graphical name, timing, implementation, and variant information on the data interface that `dataInterfaceName` specifies.

Input Arguments

codeDescObj — Code Descriptor object

`coder.codedescriptor.CodeDescriptor` object

`coder.codedescriptor.CodeDescriptor` object for which you want to retrieve the information about generated code.

dataInterfaceName — Name of data interface

Inports | Outports | Parameters | GlobalDataStores | SharedLocalDataStores | ExternalParameterObjects | ModelParameters | InternalData

`dataInterfaceName` specifies the name of a data interface. To get a list of all the data interfaces in the generated code, call `getDataInterfaceTypes()`.

Data Types: `string`

Output Arguments

dataInterface — `coder.descriptor.DataInterface` object with properties of specified data interface type

`coder.descriptor.DataInterface` object | array of `coder.descriptor.DataInterface` objects

The `coder.descriptor.DataInterface` object describes information about the specified data interface such as type of data, SID, graphical name, timing, implementation, and variant information.

Examples

- 1 Build the model.

```
slbuild('rtwdemo_comments')
```
- 2 Create a `coder.codedescriptor.CodeDescriptor` object for the required model.

- `codeDescObj = coder.getCodeDescriptor('rtwdemo_comments')`
- 3** Return a list of all data interface types in the generated code.

```
dataInterfaceTypes = getDataInterfaceTypes(codeDescObj)
```

`dataInterfaceTypes` has these values:

```
{'Inports'      }
{'Outports'     }
{'Parameters'   }
{'ExternalParameterObjects'}
{'InternalData' }
```

- 4** Return properties of Inport blocks in the generated code.

```
dataInterface = getDataInterfaces(codeDescObj, 'Inports')
```

`dataInterface` is an array of `coder.descriptor.DataInterface` objects. Obtain the details of the first Inport block of the model by accessing the first location in the array.

```
dataInterface(1)
```

The first `coder.descriptor.DataInterface` object with properties is returned.

```
      Type: [1x1 coder.descriptor.types.Type]
      SID: 'rtwdemo_comments:99'
  GraphicalName: 'In1'
    VariantInfo: [1x0 coder.descriptor.VariantInfo]
  Implementation: [1x1 coder.descriptor.DataImplementation]
      Timing: [1x1 coder.descriptor.TimingInterface]
      Unit: ''
      Range: [1x0 coder.descriptor.Range]
```

Version History

Introduced in R2018a

See Also

`coder.codedescriptor.CodeDescriptor` | `getAllDataInterfaceTypes` | `getDataInterfaceTypes` | `coder.descriptor.DataInterface`

Topics

“Get Code Description of Generated Code”

getDataInterfaceTypes

Class: `coder.codedescriptor.CodeDescriptor`

Package: `coder.codedescriptor`

Return data interface types in the generated code

Syntax

```
dataInterfaceTypes = getDataInterfaceTypes(codeDescObj)
```

Description

`dataInterfaceTypes = getDataInterfaceTypes(codeDescObj)` returns a list of the data interface types in the generated code. To get a list of the available data interfaces, call `getAllDataInterfaceTypes()`.

Input Arguments

codeDescObj — Code Descriptor object

`coder.codedescriptor.CodeDescriptor` object

`coder.codedescriptor.CodeDescriptor` object for which you want to retrieve the information about generated code.

Output Arguments

dataInterfaceTypes — Data interface types in the generated code

cell array of character vectors

A list of the data interface types in the generated code.

Examples

1 Build the model.

```
slbuild('rtwdemo_counter')
```

2 Create a `coder.codedescriptor.CodeDescriptor` object for the required model.

```
codeDescObj = coder.getCodeDescriptor('rtwdemo_counter')
```

3 Return a list of data interface types in the generated code.

```
dataInterfaceTypes = getDataInterfaceTypes(codeDescObj)
```

`dataInterfaceTypes` has these values for model `rtwdemo_counter`:

```
{'Inports'      }  
{'Outports'     }  
{'InternalData' }
```

Version History

Introduced in R2018a

See Also

`coder.codedescriptor.CodeDescriptor` | `getAllDataInterfaceTypes` | `getDataInterfaces` | `getCodeDescriptor`

Topics

"Get Code Description of Generated Code"

getFunctionInterfaces

Class: `coder.codedescriptor.CodeDescriptor`

Package: `coder.codedescriptor`

Return information of the specified function interface

Syntax

```
functionInterface = getFunctionInterfaces(codeDescObj, functionInterfaceName)
```

Description

`functionInterface = getFunctionInterfaces(codeDescObj, functionInterfaceName)` returns the function prototype, input arguments, return arguments, variant conditions, and timing information of the function interface that `functionInterfaceName` specifies.

Input Arguments

codeDescObj — Code Descriptor object

`coder.codedescriptor.CodeDescriptor` object

`coder.codedescriptor.CodeDescriptor` object for which you want to retrieve the information about generated code.

functionInterfaceName — Name of function interface

`Allocation` | `Initialize` | `Output` | `Update` | `Terminate`

`functionInterfaceName` specifies the name of a function interface. A list of all the function interfaces in the generated code is returned by `getFunctionInterfaceTypes()`.

Data Types: `string`

Output Arguments

functionInterface — `coder.descriptor.FunctionInterface` object with properties of specified function interface type

`coder.descriptor.FunctionInterface` object | array of `coder.descriptor.FunctionInterface` objects

The `coder.descriptor.FunctionInterface` object describes information about the specified function interface such as function prototype, input arguments, return arguments, variant conditions, and timing information.

Examples

- 1 Build the model.

```
slbuild('rtwdemo_comments')
```
- 2 Create a `coder.codedescriptor.CodeDescriptor` object for the required model.

- ```
codeDescObj = coder.getCodeDescriptor('rtwdemo_comments')
```
- 3** Return a list of all function interface types in the generated code.

```
functionInterfaceTypes = getFunctionInterfaceTypes(codeDescObj)
```

These are the function interface types in the generated code of model `rtwdemo_comments`:

```
{'Initialize'}
{'Output' }
```

- 4** Return properties of a specified function interface in the generated code.

```
functionInterface = getFunctionInterfaces(codeDescObj, 'Output')
```

`functionInterface` is a `coder.descriptor.FunctionInterface` object.

```
Prototype: [1x1 coder.descriptor.types.Prototype]
ActualReturn: [0x0 coder.descriptor.DataInterface]
VariantInfo: [0x0 coder.descriptor.VariantInfo]
Timing: [1x1 coder.descriptor.TimingInterface]
ActualArgs: [1x0 coder.descriptor.DataInterface List]
```

## Version History

Introduced in R2018a

### See Also

`coder.codedescriptor.CodeDescriptor` | `getAllFunctionInterfaceTypes` | `getFunctionInterfaceTypes` | `coder.descriptor.FunctionInterface`

### Topics

“Get Code Description of Generated Code”

## getFunctionInterfaceTypes

**Class:** `coder.codedescriptor.CodeDescriptor`

**Package:** `coder.codedescriptor`

Return function interface types in the generated code

### Syntax

```
functionInterfaceTypes = getFunctionInterfaceTypes(codeDescObj)
```

### Description

`functionInterfaceTypes = getFunctionInterfaceTypes(codeDescObj)` returns a list of the function interface types in the generated code. To get a list of the available function interfaces, call `getAllFunctionInterfaceTypes()`.

### Input Arguments

**codeDescObj** — Code Descriptor object

`coder.codedescriptor.CodeDescriptor` object

`coder.codedescriptor.CodeDescriptor` object for which you want to retrieve the information about generated code.

### Output Arguments

**functionInterfaceTypes** — Function interface types in the generated code

cell array of character vectors

A list of the data interface types in the generated code.

### Examples

- 1 Build the model.

```
slbuild('rtwdemo_counter')
```

- 2 Create a `coder.codedescriptor.CodeDescriptor` object for the required model.

```
codeDescObj = coder.getCodeDescriptor('rtwdemo_counter')
```

- 3 Return a list of function interface types in the generated code.

```
functionInterfaceTypes = getFunctionInterfaceTypes(codeDescObj)
```

`functionInterfaceTypes` has these values for model `rtwdemo_counter`:

```
{'Initialize'}
{'Output' }
```

## **Version History**

**Introduced in R2018a**

### **See Also**

`coder.codedescriptor.CodeDescriptor` | `getAllFunctionInterfaceTypes` |  
`getFunctionInterfaces` | `getCodeDescriptor`

### **Topics**

“Get Code Description of Generated Code”

## getReferenceModelCodeDescriptor

**Class:** `coder.codedescriptor.CodeDescriptor`

**Package:** `coder.codedescriptor`

Return `coder.codedescriptor.CodeDescriptor` object for the specified referenced model

### Syntax

```
refCodeDescriptor = getReferencedModelCodeDescriptor(codeDescObj,
refModelName)
```

### Description

`refCodeDescriptor = getReferencedModelCodeDescriptor(codeDescObj, refModelName)` returns the `coder.codedescriptor.CodeDescriptor` object for the referenced model specified in `refModelName`.

### Input Arguments

**codeDescObj — Code Descriptor object**

`coder.codedescriptor.CodeDescriptor` object

`coder.codedescriptor.CodeDescriptor` object for which you want to retrieve the information about generated code.

**refModelName — Name of referenced model**

string

`refModelName` can take any name from the list of referenced models returned by `getReferenceModelNames()`.

### Output Arguments

**refCodeDescriptor — `coder.codedescriptor.CodeDescriptor` object for the specified referenced model**

`coder.codedescriptor.CodeDescriptor` object

`coder.codedescriptor.CodeDescriptor` object for the specified referenced model.

### Examples

- 1 Build the model.  

```
slbuild('rtwdemo_async_mdltreftop')
```
- 2 Create a `coder.codedescriptor.CodeDescriptor` object for the required model.  

```
codeDescObj = coder.getCodeDescriptor('rtwdemo_async_mdltreftop')
```
- 3 Return a list of referenced models.  

```
refModels = getReferencedModelNames(codeDescObj)
```

`refModels` contains the list of referenced models for `rtwdemo_async_mdltreftop`.

```
{'rtwdemo_async_mdltreftop'}
```

Obtain the `coder.CodeDescriptor` object for any of the referenced models.

```
refCodeDescriptorObj = getReferencedModelCodeDescriptor(codeDescObj, 'rtwdemo_async_mdltreftop')
```

`refCodeDescriptorObj` is the `coder.CodeDescriptor` object for `rtwdemo_async_mdltreftop` model.

```
ModelName: 'rtwdemo_async_mdltreftop'
BuildDir: 'C:\Users\Desktop\Work\slprj\tornado\rtwdemo_async_mdltreftop'
```

## Version History

Introduced in R2018a

### See Also

`coder.CodeDescriptor` | `getReferencedModelNames` | `getCodeDescriptor`

### Topics

“Get Code Description of Generated Code”

## getReferenceModelNames

**Class:** `coder.codedescriptor.CodeDescriptor`

**Package:** `coder.codedescriptor`

Return names of the referenced models

### Syntax

```
refModels = getReferencedModelNames(codeDescObj)
```

### Description

`refModels = getReferencedModelNames(codeDescObj)` returns a list of referenced models for a `coder.codedescriptor.CodeDescriptor` object. The list includes only the models that the `CodeDescriptor` object directly references. For example, if `model1` references `model2` and `model2` references `model3`, then running `getReferenceModelNames` from the `model1` `CodeDescriptor` object returns only `model2`, not `model3`.

### Input Arguments

**codeDescObj** — Code Descriptor object

`coder.codedescriptor.CodeDescriptor` object

`coder.codedescriptor.CodeDescriptor` object for which you want to retrieve the information about generated code.

### Output Arguments

**refModels** — Names of referenced models

cell array of character vectors

A list of referenced models.

### Examples

1 Build the model.

```
slbuild('rtwdemo_async_mdltreftop')
```

2 Create a `coder.codedescriptor.CodeDescriptor` object for the required model.

```
codeDescObj = coder.getCodeDescriptor('rtwdemo_async_mdltreftop')
```

3 Return a list of referenced models.

```
refModels = getReferencedModelNames(codeDescObj)
```

`refModels` has the list of referenced models.

```
{'rtwdemo_async_mdltreftop'}
```

## **Version History**

**Introduced in R2018a**

### **See Also**

`coder.codedescriptor.CodeDescriptor` | `getReferencedModelCodeDescriptor`

### **Topics**

“Get Code Description of Generated Code”

## getAllParameters

Return all associated `coder.descriptor.LookupTableDataInterface` and `coder.descriptor.BreakpointDataInterface` objects

### Syntax

```
dataInterface = getAllParameters(parameterObj)
```

### Description

`dataInterface = getAllParameters(parameterObj)` returns all associated `coder.descriptor.LookupTableDataInterface` and `coder.descriptor.BreakpointDataInterface` objects.

### Input Arguments

**parameterObj** — `coder.descriptor.LookupTableDataInterface` object

`coder.descriptor.LookupTableDataInterface` object

The `coder.descriptor.LookupTableDataInterface` object that represents a Lookup Table block in the model.

Data Types: `string`

### Output Arguments

**dataInterface** — array of `coder.descriptor.LookupTableDataInterface` and/or `coder.descriptor.BreakpointDataInterface` objects

`coder.descriptor.LookupTableDataInterface` object | array of `coder.descriptor.LookupTableDataInterface` and/or `coder.descriptor.BreakpointDataInterface` objects

The `coder.descriptor.LookupTableDataInterface` object represents a Lookup Table block in the model. The `coder.descriptor.BreakpointDataInterface` object represents the breakpoint set data associated with the Lookup Table block.

### Examples

**Return all associated `coder.descriptor.LookupTableDataInterface` and `coder.descriptor.BreakpointDataInterface` objects**

- 1 Build the model.  

```
slbuild('rtwdemo_asap2')
```
- 2 Create a `coder.codeDescriptor.CodeDescriptor` object for the required model.  

```
codeDescObj = coder.getCodeDescriptor('rtwdemo_asap2')
```
- 3 Return properties of the Lookup Table parameters in the model.



```
params = getDataInterfaces(codeDescObj, 'Parameters')
```

The `params` variable is an array of `coder.descriptor.DataInterface`, `coder.descriptor.LookupTableDataInterface`, and `coder.descriptor.BreakpointDataInterface` objects.

- 4 Obtain the details of the model Lookup Table block by accessing the sixth location in the array.

```
parameterObj = params(6)
```

- 5 Retrieve all the associated `coder.descriptor.LookupTableDataInterface` and `coder.descriptor.BreakpointDataInterface` objects by using the `parameterObj`.

```
dataInterface = getAllParameters(parameterObj)
```

The code generator returns an array of `coder.descriptor.LookupTableDataInterface` and `coder.descriptor.BreakpointDataInterface` objects.

1×3 heterogeneous `DataInterface` (`LookupTableDataInterface`, `BreakpointDataInterface`) array with properties:

```
Type
SID
GraphicalName
VariantInfo
Implementation
Timing
Unit
Range
```

## Version History

**Introduced in R2020a**

### See Also

`coder.descriptor.LookupTableDataInterface` (Embedded Coder) |  
`coder.descriptor.BreakpointDataInterface` (Embedded Coder) |  
`coder.descriptor.DataInterface` (Embedded Coder)

## isLookupTableDataInterface

Determine whether object is a `coder.descriptor.LookupTableDataInterface` object

### Syntax

```
lookupTableDataInterface = isLookupTableDataInterface(parameterObj)
```

### Description

`lookupTableDataInterface = isLookupTableDataInterface(parameterObj)` returns a logical value indicating whether the object is a `coder.descriptor.LookupTableDataInterface` object.

### Input Arguments

**parameterObj** — `coder.descriptor.LookupTableDataInterface` object

`coder.descriptor.LookupTableDataInterface` object

`coder.descriptor.LookupTableDataInterface` object that represents a Lookup Table block in the model.

Data Types: `string`

### Output Arguments

**lookupTableDataInterface** — logical value

1 | 0

Logical value indicating whether the object is a `coder.descriptor.LookupTableDataInterface`.

Data Types: `logical`

### Examples

**Determine if the object is a `coder.descriptor.LookupTableDataInterface` object**

- 1 Build the model.  

```
slbuild('rtwdemo_asap2')
```
- 2 Create a `coder.codeDescriptor.CodeDescriptor` object for the model.  

```
codeDescObj = coder.getCodeDescriptor('rtwdemo_asap2')
```
- 3 Return properties of the Lookup Table parameters in the model.  

```
params = getDataInterfaces(codeDescObj, 'Parameters')
```

The `params` variable is an array of `coder.descriptor.DataInterface`, `coder.descriptor.LookupTableDataInterface`, and `coder.descriptor.BreakpointDataInterface` objects.

- 4 Obtain the details of the model Lookup Table block by accessing the sixth location in the array.

```
parameterObj = params(6)
```

- 5 Determine if the object stored in `parameterObj` variable is a `coder.descriptor.LookupTableDataInterface` object.

```
lookupTableDataInterface = isLookupTableDataInterface(parameterObj)
```

```
lookupTableDataInterface =
```

```
 logical
```

```
 1
```

The code generator returns a logical value of 1 if `parameterObj` is a `coder.descriptor.LookupTableDataInterface` object. Otherwise, the code generator returns a logical value of 0.

## Version History

Introduced in R2020a

### See Also

`coder.descriptor.LookupTableDataInterface` (Embedded Coder) |  
`isBreakpointDataInterface` (Embedded Coder)

## coder.mapping.api.CodeMapping

Model data and function interface configuration for C code generation

### Description

A code mappings object and related functions enable you to configure C code generation for data of a Simulink model. For model data elements, code mappings associate data elements with configurations that consist of a storage class and storage class properties. Reduce the effort of preparing a model for C code generation by specifying default configurations for categories of data elements across a model. Override default configurations by configuring data elements individually. For smaller models, you can choose to configure each data element individually.

### Creation

When you select a code generation app from the Apps tab in the Simulink Editor, such as the **Simulink Coder** or **Embedded Coder** app, the app creates a `coder.mapping.api.CodeMapping` object if code mappings do not already exist. The app creates code mappings based on code customization settings stored in the model active configuration set object. The configuration set object can specify memory sections for data and functions.

Create a `coder.mapping.api.CodeMapping` object programmatically by calling the function `coder.mapping.utils.create`.

### Object Functions

|                                         |                                                                                                       |
|-----------------------------------------|-------------------------------------------------------------------------------------------------------|
| <code>addSignal</code>                  | Add block output signal to model code mappings                                                        |
| <code>coder.mapping.api.get</code>      | Get code mappings for model                                                                           |
| <code>coder.mapping.utils.create</code> | Create code mappings object for configuring data and function interface for C and C++ code generation |
| <code>find</code>                       | Get model elements for the category of model code mappings                                            |
| <code>getDataDefault</code>             | Get default storage class or storage class property setting for model data category                   |
| <code>getDataStore</code>               | Get code and calibration configuration from code mappings for local or shared local data store        |
| <code>getInport</code>                  | Get code and calibration configuration from code mappings for root-level inport                       |
| <code>getModelParameter</code>          | Get code and calibration configuration from code mappings for model parameters                        |
| <code>getOutport</code>                 | Get code and calibration configuration from code mappings for root-level outport                      |
| <code>getSignal</code>                  | Get code and calibration configuration from code mappings for block output signal                     |
| <code>getState</code>                   | Get code and calibration configuration from code mappings for block state                             |
| <code>removeSignal</code>               | Remove block output signal from model code mappings                                                   |
| <code>setDataDefault</code>             | Set default storage class and storage class property values for model data category                   |

|                   |                                                                                           |
|-------------------|-------------------------------------------------------------------------------------------|
| setDataStore      | Configure local or shared local data store for code and calibration file (a2l) generation |
| setInport         | Configure root-level inports for code and calibration file (a2l) generation               |
| setModelParameter | Configure model parameter for code and calibration file (a2l) generation                  |
| setOutport        | Configure root-level outport for code and calibration file (a2l) generation               |
| setSignal         | Configure block signal data for code and calibration file (a2l) generation                |
| setState          | Configure block states for code and calibration file (a2l) generation                     |

## Examples

### Create Environment to Configure Code Mappings for Model

For model `myConfigModel`, create the environment for configuring model data and functions for code generation. After calling this function, use calls to other functions listed under Object Functions to configure aspects of code generation for model interface elements.

```
coder.mapping.utils.create('myConfigModel');
```

## Version History

Introduced in R2020b

### See Also

`coder.mapping.api.get` | `coder.mapping.utils.create` |  
`coder.mapping.api.CoderDictionary` | `coder.mapping.api.CodeMappingCPP`

### Topics

“C Code Generation Configuration for Model Interface Elements”  
 “Programmatically Configure C++ Interface” (Embedded Coder)  
 “Service Interfaces” (Embedded Coder)

## addSignal

Add block output signal to model code mappings

### Syntax

```
addSignal(myCodeMappingObj, portHandle)
addSignal(myCodeMappingObj, portHandle, Name, Value)
```

### Description

`addSignal(myCodeMappingObj, portHandle)` adds signals specified by the block output port handles to the specified model code mappings.

This function does not apply to signals that originate from root-level Inport blocks.

`addSignal(myCodeMappingObj, portHandle, Name, Value)` adds signals specified by the block output port handles to the model code mappings. It configures the storage class and values of storage class properties that the code generator uses to produce C code for the signal data. For models linked to a service interface configuration, you can also configure measurement interface properties.

### Examples

#### Add Block Output Signals to Model Code Mappings

For model `myConfigModel`, add the output signals of lookup table blocks `Table1D` and `Table2D` to the model code mappings. After creating the object `cm` by calling function `coder.mapping.api.get`, get handles to the output ports for lookup table blocks. Add the output signals to the code mappings with a call to `addSignal`.

```
cm = coder.mapping.api.get('myConfigModel');
lut1D_ports = get_param('myConfigModel/Table1D', 'PortHandles');
lut2D_ports = get_param('myConfigModel/Table2D', 'PortHandles');
lut1D_outPort = lut1D_ports.Outputport;
lut2D_outPort = lut2D_ports.Outputport;
addSignal(cm, [lut1D_outPort, lut2D_outPort]);
```

#### Add Block Output Signals to Model Code Mappings and Configure Storage Class for Signals

For model `myConfigModel`, add the output signals of lookup table blocks `Table1D` and `Table2D` to the model code mappings. After creating the object `cm` by calling function `coder.mapping.api.get`, get handles to the output ports for lookup table blocks. Add the output signals to the code mappings and set the storage class for the signals to `ExportedGlobal` with a call to `addSignal`.

```
cm = coder.mapping.api.get('myConfigModel');
lut1D_ports = get_param('myConfigModel/Table1D', 'PortHandles');
lut2D_ports = get_param('myConfigModel/Table2D', 'PortHandles');
lut1D_outPort = lut1D_ports.Outputport;
```

```
lut2D_outPort = lut2D_ports.Outport;
addSignal(cm,[lut1D_outPort,lut2D_outPort],'StorageClass','ExportedGlobal');
```

## Input Arguments

### **myCodeMappingObj** — Code mapping object

CodeMapping object

Code mapping object (model code mappings) returned by a call to function `coder.mapping.api.get`.

Example: `myCM`

### **portHandle** — Output port handle of signal source block

port handle | array of port handles

Signal to add to the code mappings, specified as a handle of an output port of the source block of the signal. To specify multiple port handles, use an array.

Example: `portHandle`

Data Types: `port_handle` | array

## Name-Value Pair Arguments

Specify comma-separated pairs of `Name`, `Value` arguments. `Name` is the argument name and `Value` is the corresponding value. `Name` must appear inside quotes. You can specify several name and value pair arguments as `Name1, Value1, ..., NameN, ValueN`. The order of the name and value pair arguments does not matter.

Example: `'StorageClass' 'ExportedGlobal'`

### **StorageClass** — Name of storage class

`Auto` | `Dictionary default` | `ExportedGlobal` | `ImportedExtern` | `ImportedExternPointer` | `Model default`

Storage class to set for the specified signals. The name of a predefined storage class or a storage class that is defined in the Embedded Coder Dictionary associated with the model. See “Configure Signal Data for C Code Generation”

### **Identifier** — Name of variable

character vector | string scalar

Name for the variable that represents the signal data in the generated code.

Data Types: `char` | `string`

## Version History

Introduced in R2020b

## See Also

`coder.mapping.api.CodeMapping` | `coder.mapping.api.get` | `find` | `getDataDefault` | `getSignal` | `removeSignal` | `setDataDefault` | `setSignal`

**Topics**

“Configure Signal Data for C Code Generation”

“C Code Generation Configuration for Model Interface Elements”



# find

**Package:** `coder.mapping.api`

Get model elements for the category of model code mappings

## Syntax

```
modelElementsFound= find(myCodeMappingObj,category)
modelElementsFound= find(myCodeMappingObj,category,Name,Value)
```

## Description

`modelElementsFound= find(myCodeMappingObj,category)` returns the elements in the model code mappings of the specified category as an array of objects.

`modelElementsFound= find(myCodeMappingObj,category,Name,Value)` returns the elements in the model code mappings of the specified category that match specified property and value criteria.

## Examples

### Find Model Parameters in Code Mappings

In the model code mappings for model `myConfigModel`, find model workspace parameters.

```
cm = coder.mapping.api.get('myConfigModel');
modelParams = find(cm,'ModelParameters');
```

### Find Inport Blocks That Have Storage Class Set to Auto

For model `myConfigModel`, find Inport blocks that have storage class set to Auto. For each Inport block found, change the storage class setting to Model default.

```
cm = coder.mapping.api.get('myConfigModel');
inportBlkHandles = find(cm,'Inports','StorageClass','Auto');
setInport(cm,inportBlkHandles,'StorageClass','Model default');
```

## Input Arguments

### `myCodeMappingObj` — Code mapping object

CodeMapping object

Code mapping object returned by a call to function `coder.mapping.api.get`.

Example: `myCM`

**category — Model element category**

DataStores | DataTransfers | Inports | ModelParameters | ModelParameterArguments | Outports | Signals | States

Category of model elements that you search for in the model code mappings.

Example: 'Inports'

**Name-Value Pair Arguments**

Specify optional comma-separated pairs of Name, Value arguments. Name is the argument name and Value is the corresponding value. Name must appear inside quotes. You can specify several name and value pair arguments as Name1, Value1, ..., NameN, ValueN. The order of the name and value pair arguments does not matter.

Example: 'Identifier','mp\_table1'

**Data Interfaces**

**StorageClass — Name of storage class**

Auto | Dictionary default | ExportedGlobal | ImportedExtern | ImportedExternPointer | Model default

Data element storage class to include in code mappings search criteria. The name of a predefined storage class or storage class that is defined in the Embedded Coder Dictionary associated with the model. Values that you can specify vary depending on the category that you specify.

**Identifier — Code identifier**

character vector | string scalar

Name that the code generator uses to identify a data element in generated code. Applies to storage classes other than Auto.

Data Types: char | string

**Output Arguments**

**modelElementsFound — Model elements found**

array | string vector

Model elements found, returned as an array or string vector of objects. Each object identifies a model element of the specified category. If you specify additional search criteria, the array or string vector includes objects for model elements of the specified category that meet the additional search criteria. The object returned for an element depends on the category that you specify.

| Category                      | Type of Object Returned       |
|-------------------------------|-------------------------------|
| Inports, Outports, and States | Block handle                  |
| Signals                       | Port handle                   |
| DataStores                    | Block handle                  |
| ModelParameters               | Model parameter name          |
| ModelParameterArguments       | Model parameter argument name |

## Version History

Introduced in R2020b

### Model parameters and parameter arguments returned separately by find function

*Behavior changed in R2022b*

The `find` function now returns model parameter arguments separately from model parameters.

Starting in R2022b, to return all elements in the model code mappings that are model parameter arguments, enter the following.

```
cm = coder.mapping.api.get('myConfigModel');
modelParamArgs = find(cm, 'ModelParameterArguments');
```

To return all elements in the model code mappings that are model parameters, enter the following.

```
cm = coder.mapping.api.get('myConfigModel');
modelParams = find(cm, 'ModelParameters');
```

In previous releases, specifying `ModelParameters` as the category argument returned both model parameters and model parameter arguments.

### See Also

`coder.mapping.api.get`

### Topics

“C Code Generation Configuration for Model Interface Elements”

## coder.mapping.api.get

Get code mappings for model

### Syntax

```
myCodeMappingObj = coder.mapping.api.get(model)
myCodeMappingObj = coder.mapping.api.get(dictionary)
myCodeMappingObj = coder.mapping.api.get(model,codeMappingType)
```

### Description

`myCodeMappingObj = coder.mapping.api.get(model)` returns the active code mappings for the specified model as object `myCodeMappingObj`. Code mappings associate model data elements with configurations for code generation. If a model has multiple code mappings, the active code mappings are the mappings associated with the active system target file.

If code mappings do not exist, Simulink returns an error. Simulink creates a code mappings object when you open a model in a coder app. If you have not opened a model in a coder app, you can create a code mappings object with a call to `coder.mapping.util.create`.

`myCodeMappingObj = coder.mapping.api.get(dictionary)` returns the active code mappings for the specified dictionary as object `myCodeMappingObj`. Code mappings associate data elements in the data dictionary with configurations for code generation.

If code mappings do not exist, Simulink returns an error. Simulink creates a code mappings object when you open a model in a coder app. If you have not opened a model in a coder app, you can create a code mappings object with a call to `coder.mapping.util.create`.

`myCodeMappingObj = coder.mapping.api.get(model,codeMappingType)` returns the code mappings for your model that correspond to the specified code mapping type as object `myCodeMappingObj`. Code mappings enable you to associate a model with code generation configurations for C rapid prototyping (Simulink Coder and C language) and C production (Embedded Coder® and C language) platforms. The code mappings type specifies your platform of interest. If a code mapping of the specified type does not exist, Simulink returns an error.

### Examples

#### Get Code Mappings for Model

For model `myConfigModel`, return the code mappings to object `myCodeMappingObj`. Specify the returned object as the first argument in subsequent calls to other code mappings API functions. This example specifies the returned object in a call to `getInport`.

```
myCodeMappingObj = coder.mapping.api.get('myConfigModel');
myInput = getInport(myCodeMappingObj, 'In1', 'myConfigModel');
```

## Create and Get Code Mappings for Model

In this example, for model `myConfigModel`, create the code mappings object `myCodeMappingObj` by calling `coder.mapping.util.create`. Then, return the object with a call to `coder.mapping.api.get`. This example specifies the returned object in a call to `getInport`.

```
myCodeMappingObj = coder.mapping.utils.create('myConfigModel');
cm = coder.mapping.api.get(myCodeMappingObj);
myInput = getInport(cm, 'In1', 'myConfigModel');
```

## Get Simulink Coder C Code Mappings for Model

For model `myConfigModel`, return the Simulink Coder C language code mappings to object `mySCCodeMappingObj`. Specify the returned object as the first argument in subsequent calls to other code mappings API functions. This example specifies the returned object in a call to `getInport`.

```
mySCCodeMappingObj = coder.mapping.api.get('myConfigModel','SimulinkCoderC');
myInput = getInport(mySCCodeMappingObj, 'In1', 'myConfigModel');
```

## Input Arguments

### **model** — Name of model

handle | character vector | string scalar

Model for which to return code mappings object, specified as a handle or a character vector or string scalar representing the model name. The model must be loaded (for example, by using `load_system`) or open. Omit the `.slx` file extension.

Example: `'myConfigModel'`

Data Types: `char` | `string` | `model_handle`

### **dictionary** — Name of data dictionary

character vector | string scalar

Data dictionary for which to return code mappings object, specified as a character vector or string scalar representing the dictionary name.

Example: `'exCodeDefs.slidd'`

Data Types: `char` | `string`

### **codeMappingType** — Type of code mapping

`SimulinkCoderC` | `EmbeddedCoderC` | `EmbeddedCoderCPP`

The type of code mappings to return for the specified model or dictionary. Code mappings enable you to associate a model with code generation configurations for C rapid prototyping (Simulink Coder and C language) and C and C++ production (Embedded Coder and C and C++ language) platforms. The code mappings type specifies your platform of interest, `SimulinkCoderC`, `EmbeddedCoderC`, or `EmbeddedCoderCPP`. If a code mapping of the specified type does not exist, Simulink returns an error.

Example: `'SimulinkCoderC'`

## Output Arguments

### **myCodeMappingObj** — Code mapping object

CodeMapping object | CodeMappingCPP object | CoderDictionary object

The model or dictionary code mappings, returned as a CodeMapping object, a CodeMappingCPP object, or a CoderDictionary object.

| Output                                         | Input Object             | Code Mapping Type                |
|------------------------------------------------|--------------------------|----------------------------------|
| <code>coder.mapping.api.CodeMapping</code>     | Simulink model           | SimulinkCoderC or EmbeddedCoderC |
| <code>coder.mapping.api.CodeMappingCPP</code>  | Simulink model           | EmbeddedCoderCPP                 |
| <code>coder.mapping.api.CoderDictionary</code> | Simulink data dictionary | N/A                              |

## Version History

Introduced in R2020b

### See Also

`coder.mapping.api.CodeMapping` | `coder.mapping.utils.create` |  
`coder.mapping.api.CoderDictionary` | `coder.mapping.api.CodeMappingCPP`

### Topics

“C Code Generation Configuration for Model Interface Elements”  
 “Programmatically Configure C++ Interface” (Embedded Coder)

# getDataDefault

Get default storage class or storage class property setting for model data category

## Syntax

```
propertyValue = getDataDefault(myCodeMappingObj, category, property)
```

## Description

`propertyValue = getDataDefault(myCodeMappingObj, category, property)` returns the value from the code mappings of the specified property for the specified data category.

Default data configurations cannot be specified for models linked to a service interface configuration.

## Examples

### Get Default Storage Class Setting for Root-Level Inports

From the model code mappings for model `myConfigModel`, get the default storage class setting for root-level inports.

```
cm = coder.mapping.api.get('myConfigModel');
defaultStorageClass = getDataDefault(cm, 'Inports', 'StorageClass');
```

## Input Arguments

### **myCodeMappingObj** — Code mapping object

CodeMapping object

Code mapping object (model code mappings) returned by a call to function `coder.mapping.api.get`.

Example: `myCM`

### **category** — Model data element category

ExternalParameterObjects | GlobalDataStores | Inports | InternalData | ModelParameters | Outports | SharedLocalDataStores

Category of model data elements that you return a property value for.

Example: `'Inports'`

### **property** — Code mapping property value to return

StorageClass | Identifier

Code mapping property that you return a value for. Specify one of these property names.

| Information to Return                                   | Property Name |
|---------------------------------------------------------|---------------|
| Name of storage class                                   | StorageClass  |
| Name of variable for data element in the generated code | Identifier    |

Example: 'Identifier'

## Output Arguments

### propertyValue — Name of storage class or value of storage class property

character vector | string scalar | Auto | Dictionary default | ExportedGlobal | ImportedExtern | ImportedExternPointer | Model default

The property value is one of these values depending on the category and property that you specify.

| Property     | Value Returned                                                                                            |
|--------------|-----------------------------------------------------------------------------------------------------------|
| StorageClass | One of these values: Auto, , Dictionary default, ExportedGlobal, , ImportedExtern, ImportedExternPointer, |

Data Types: char | string

## Version History

Introduced in R2020b

### See Also

coder.mapping.api.CodeMapping | coder.mapping.api.get | setDataDefault

### Topics

- “C Code Generation Configuration for Model Interface Elements”
- “Configure Root-Level Inport Blocks for C Code Generation”
- “Configure Root-Level Outport Blocks for C Code Generation”
- “Configure Signal Data for C Code Generation”
- “Configure Parameters for C Code Generation”
- “Configure Block States for C Code Generation”
- “Configure Data Stores for C Code Generation”



# getDataStore

Get code and calibration configuration from code mappings for local or shared local data store

## Syntax

```
propertyValue = getDataStore(myCodeMappingObj,dataStore,property)
```

## Description

`propertyValue = getDataStore(myCodeMappingObj,dataStore,property)` returns the value of a code mapping property or calibration property for the specified local or shared local data store. For example, use this function to return the storage class or the calibration access of a measurement property configured for a local or shared local data store in a model.

## Examples

### Get Storage Class Configured for Local Data Store

From the model code mappings for model `rtwdemo_configrpinterface`, get the name of the storage class that is configured for local data store mode.

```
open_system('rtwdemo_configrpinterface');
cm = coder.mapping.api.get('rtwdemo_configrpinterface');
scMode = getDataStore(cm,'mode','StorageClass');
```

### Get Code Identifier Configured for Local Data Store

From the model code mappings for model `rtwdemo_configrpinterface`, get the code identifier configured for the local data store mode.

```
open_system('rtwdemo_configrpinterface');
cm = coder.mapping.api.get('rtwdemo_configrpinterface');
idDSMmode = getDataStore(cm,'mode','Identifier');
```

### Get Calibration Properties Configured for Local Data Store

From the model code mappings for model `rtwdemo_configrpinterface`, get the calibration properties such as calibration access and display identifier configured for local data store mode.

```
open_system('rtwdemo_configrpinterface');
cm = coder.mapping.api.get('rtwdemo_configrpinterface');
prop_export = getDataStore(cm,'mode','Export');
prop_bitmask = getDataStore(cm,'mode','BitMask');
prop_calaccess = getDataStore(cm,'mode','CalibrationAccess');
prop_compname = getDataStore(cm,'mode','CompuMethod');
```

```
prop_dispid = getDataStore(cm, 'mode', 'DisplayIdentifier');
prop_format = getDataStore(cm, 'mode', 'Format');
```

## Input Arguments

### **myCodeMappingObj** — Code mapping object

CodeMapping object

Code mapping object (model code mappings) returned by a call to function `coder.mapping.api.get`.

Example: `myCM`

### **dataStore** — Block path, block handle, or name of data store

character vector | string scalar | block handle

Path of the Data Store Memory block for which to return the code mapping information, specified as a character vector or string scalar. Alternatively, you can specify a block handle or the name of the data store. If you specify the name of a data store and that name is not unique within the model, Simulink returns an error that instructs you to specify the block path or handle.

Example: `blockHandle`

Data Types: `char` | `string` | `block_handle`

### **property** — Code mapping property value to return

`StorageClass` | `Identifier` | `Export` | `BitMask` | `CalibrationAccess` | `CompuMethod` | `DisplayIdentifier` | `Format` | `MeasurementService`

Code mapping property for which to return a value. For a storage class defined in the Embedded Coder Dictionary associated with the model, specify a property name or one of these property names.

| Information to Return                                                                                                                                                                                                                                                                                                   | Property Name                  |
|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|--------------------------------|
| Name of storage class                                                                                                                                                                                                                                                                                                   | <code>StorageClass</code>      |
| Name of variable for data store in the generated code                                                                                                                                                                                                                                                                   | <code>Identifier</code>        |
| Boolean value indicating whether to export the selected data store to a calibration file (a2l)                                                                                                                                                                                                                          | <code>Export</code>            |
| Mask value in hexadecimal format to extract single bits from the data store in a calibration tool                                                                                                                                                                                                                       | <code>BitMask</code>           |
| Enumeration value indicating the access of calibration. <code>Calibration</code> for a data store indicates that the data store can be calibrated. <code>NoCalibration</code> indicates that the data store can be read-only and cannot be calibrated. <code>NoCalibration</code> is the default value for the property | <code>CalibrationAccess</code> |
| Name of the conversion method used during the calibration                                                                                                                                                                                                                                                               | <code>CompuMethod</code>       |

| Information to Return                                                               | Property Name      |
|-------------------------------------------------------------------------------------|--------------------|
| Optional display name of the data store for calibration                             | DisplayIdentifier  |
| Specifies the display format of the data store being measured in a calibration tool | Format             |
| Name of measurement service defined in Embedded Coder Dictionary                    | MeasurementService |

Example: 'StorageClass '

Example: 'CalibrationAccess '

## Output Arguments

**propertyValue** — Name of storage class or value of storage class property

character vector

Name of the storage class or value of the specified storage class property configured for the specified data store.

Data Types: char

## Version History

Introduced in R2020b

## See Also

`coder.mapping.api.CodeMapping` | `coder.mapping.api.get` | `find` | `getDataDefault` | `setDataDefault` | `setDataStore`

## Topics

“Configure Data Stores for C Code Generation”

“C Code Generation Configuration for Model Interface Elements”

## getFunction

Get code configuration from code mappings for model function

### Syntax

```
propertyValue = getFunction(myCodeMappingObj, function, property)
```

### Description

`propertyValue = getFunction(myCodeMappingObj, function, property)` returns the value of a property for the specified model function. Use this function to return the function customization template or memory section configured for a model function. For single-tasking periodic functions for which you previously set an argument specification and for Simulink functions, use this function to return the argument specification.

### Examples

#### Get Function Name Configured for Initialize Function

For model `myConfigModel`, get the function name that is configured for the model initialize function from the model code mappings.

```
cm = coder.mapping.api.get('myConfigModel');
initFunctionName = getFunction(cm, 'Initialize', 'FunctionName');
```

#### Get Memory Section Configured for Periodic Single-Tasking Function

For model `myConfigModel`, get the memory section that is configured for the model periodic single-tasking function from the model code mappings.

```
cm = coder.mapping.api.get('myConfigModel');
periodicFunctionMemSec = getFunction(cm, 'Periodic', 'MemorySection');
```

#### Get Function Customization Template Configured for Periodic Multitasking Function for Sample Time D2

For model `myConfigModel`, get the function customization template that is configured for the model periodic multitasking function that corresponds to sample time D2 from the model code mappings.

```
cm = coder.mapping.api.get('myConfigModel');
periodicD2FunctionTemp = getFunction(cm, 'Periodic:D2', 'FunctionCustomizationTemplate');
```

## Get Argument Specification Configured for Simulink Function

For model `myConfigModel`, get the function argument specification (names, port type, qualifiers, and order) that is configured for the model Simulink function `mySLFunc` from the model code mappings.

```
cm = coder.mapping.api.get('myConfigModel');
mySLFuncArgs = getFunction(cm, 'SimulinkFunction:mySLFunc', 'Arguments');
```

## Input Arguments

### `myCodeMappingObj` — Code mapping object

CodeMapping object

Code mapping object (model code mappings) returned by a call to function `coder.mapping.api.get`.

Example: `myCM`

### function — Model function

`Initialize` | `Terminate` | `Periodic:sIdentifier` | `Partition:sIdentifier` | `PeriodicUpdate:sIdentifier` | `PartitionUpdate:sIdentifier` | `Reset:sIdentifier` | `ExportedFunction:sIdentifier` | `SimulinkFunction:sIdentifier`

Model function for which to return a code mapping property value. Specify one of the values listed in this table. If model configuration parameter **Single output/update function** is cleared, you can specify the update version of a partition, periodic multi-tasking, or periodic singletasking function.

| Type of Model Function                | Value                                                                                                                                                                                                                                              |
|---------------------------------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Exported function                     | <code>ExportedFunction:sIdentifier</code> , where <i>sIdentifier</i> is the name of the function-call Inport block in the model                                                                                                                    |
| Initialize function                   | <code>Initialize</code>                                                                                                                                                                                                                            |
| Partition function                    | <code>Partition:sIdentifier</code> , where <i>sIdentifier</i> is a partition that was created explicitly from a block in the model and shown in the Simulink Schedule Editor (for example, P1), or a task name in the Concurrent Execution dialog. |
| Partition update function             | <code>PartitionUpdate:sIdentifier</code> , is a partition that was created explicitly from a block in the model and shown in the Simulink Schedule Editor (for example, P1), or a task name in the Concurrent Execution dialog.                    |
| Periodic multitasking function        | <code>Periodic:sIdentifier</code> , where <i>sIdentifier</i> is an annotation that corresponds to the sample time period for a periodic or continuous rate of a multi-tasking model (for example, D1)                                              |
| Periodic multitasking update function | <code>PeriodicUpdate:sIdentifier</code> , where <i>sIdentifier</i> is an annotation that corresponds to the sample time period for a periodic or continuous rate of a multi-tasking model (for example, D1)                                        |

| Type of Model Function                  | Value                                                                                                               |
|-----------------------------------------|---------------------------------------------------------------------------------------------------------------------|
| Periodic single-tasking function        | Periodic                                                                                                            |
| Periodic single-tasking update function | PeriodicUpdate                                                                                                      |
| Reset function                          | Reset: <i>slIdentifier</i> , where <i>slIdentifier</i> is the name of the reset function in the model               |
| Simulink function                       | SimulinkFunction: <i>slIdentifier</i> , where <i>slIdentifier</i> is the name of the Simulink function in the model |
| Terminate function                      | Terminate                                                                                                           |

For information about model partitioning, see “Create Partitions”.

Example: 'Periodic:D1'

**property — Code mapping property value to return**

FunctionCustomizationTemplate | MemorySection | FunctionName | Arguments | TimerService

Code mapping property value to return. Specify one of the property names listed in this table.

| Information to Return                                                                                                                                                           | Property Name                 |
|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-------------------------------|
| Function customization template setting for the specified function                                                                                                              | FunctionCustomizationTemplate |
| Memory section associated with the specified function                                                                                                                           | MemorySection                 |
| Name to use for the function in the generated code                                                                                                                              | FunctionName                  |
| For periodic, single-tasking functions and Simulink functions, a string that shows the names, type qualifiers, and order of arguments as they will appear in the generated code | Arguments                     |
| Name of timer service defined in Embedded Coder Dictionary                                                                                                                      | TimerService                  |

Example: 'FunctionCustomizationTemplate'

**Output Arguments**

**propertyValue — Name of function customization template, memory section, function, or argument specification**

character vector | string scalar

Name of the function customization template, memory section, function, or argument specification returned as a character vector or string scalar.

Data Types: char | string

## Version History

Introduced in R2020b

### See Also

`coder.mapping.api.CodeMapping` | `coder.mapping.api.get` | `getFunctionDefault` | `setFunction` | `setFunctionDefault`

### Topics

“Configure Names for Individual C Entry-Point Functions” (Embedded Coder)

“Configure Name and Arguments for Individual Step Functions” (Embedded Coder)

“Configure Default C Code Generation for Categories of Data Elements and Functions” (Embedded Coder)

“C Code Generation Configuration for Model Interface Elements” (Embedded Coder)

“Configure Timer Service Interfaces for Aperiodic Export Functions” (Embedded Coder)

## getFunctionDefault

Get default function customization template or memory section for model functions category

### Syntax

```
propertyValue = getFunctionDefault(myCodeMappingObj, category, property)
```

### Description

`propertyValue = getFunctionDefault(myCodeMappingObj, category, property)` returns the value of the specified property for the specified function category.

Default function configurations cannot be specified for models linked to a service interface configuration.

### Examples

#### Get Default Function Customization Template Setting for Execution Functions

For model `myConfigModel`, get the default function customization template for execution functions from the model code mappings.

```
cm = coder.mapping.api.get('myConfigModel');
defaultFuncTemplateExe = getFunctionDefault(cm, 'Execution', 'FunctionCustomizationTemplate');
```

#### Get Default Memory Section Setting for Initialize and Terminate Functions

For model `myConfigModel`, get the default function customization template for initialize and terminate functions from the model code mappings.

```
cm = coder.mapping.api.get('myConfigModel');
defaultMemSecExe = getFunctionDefault(cm, 'InitializeTerminate', 'MemorySection');
```

### Input Arguments

#### **myCodeMappingObj** — Code mapping object

CodeMapping object

Code mapping object (model code mappings) returned by a call to function `coder.mapping.api.get`.

Example: `myCM`

#### **category** — Model function category

`InitializeTerminate` | `Execution` | `SharedUtility`

Category of model entry-point functions for which to return the default function customization template or memory section.



Example: 'Execution'

**property — Function customization template or memory section**

FunctionCustomizationTemplate | MemorySection

FunctionCustomizationTemplate or MemorySection for which to return a value.

Example: 'FunctionCustomizationTemplate'

## Output Arguments

**propertyValue — Name of function customization template or memory section**

character vector | string scalar

Name of the function customization template or memory section.

Data Types: char | string

## Version History

**Introduced in R2020b**

### See Also

coder.mapping.api.CodeMapping | coder.mapping.api.get | getFunction | setFunction | setFunctionDefault

### Topics

“Configure Default C Code Generation for Categories of Data Elements and Functions” (Embedded Coder)

“C Code Generation Configuration for Model Interface Elements” (Embedded Coder)

## getInport

Get code and calibration configuration from code mappings for root-level inport

### Syntax

```
propertyValue = getInport(myCodeMappingObj,inportBlock,property)
```

### Description

`propertyValue = getInport(myCodeMappingObj,inportBlock,property)` returns the value of a code mapping property or calibration property for the specified root-level Inport block. For example, use this function to return the storage class or the value of a storage class property configured for a root-level inport in a model, or to return the calibration access of the inport.

### Examples

#### Get Storage Class Configured for Root-Level Inport

From the model code mappings for model `rtwdemo_configrpinterface`, get the name of the storage class that is configured for root-level inport `In1`.

```
open_system('rtwdemo_configrpinterface');
cm = coder.mapping.api.get('rtwdemo_configrpinterface');
scIn1 = getInport(cm,'In1','StorageClass');
```

#### Get Code Identifier Configured for Root-Level Inport

From the model code mappings for model `rtwdemo_configrpinterface`, get the code identifier configured for root-level inport `In1`.

```
open_system('rtwdemo_configrpinterface');
cm = coder.mapping.api.get('rtwdemo_configrpinterface');
idIn1 = getInport(cm,'In1','Identifier');
```

#### Get Calibration Properties Configured for Root-Level Inport

From the model code mappings for model `rtwdemo_configrpinterface`, get the calibration properties such as calibration access and display identifier configured for root-level inport `In1`.

```
open_system('rtwdemo_configrpinterface');
cm = coder.mapping.api.get('rtwdemo_configrpinterface');
prop_export = getInport(cm,'In1','Export');
prop_bitmask = getInport(cm,'In1','BitMask');
prop_calaccess = getInport(cm,'In1','CalibrationAccess');
prop_compname = getInport(cm,'In1','CompuMethod');
```

```
prop_dispid = getInport(cm, 'In1', 'DisplayIdentifier');
prop_format = getInport(cm, 'In1', 'Format');
```

## Input Arguments

### **myCodeMappingObj** — Code mapping object

CodeMapping object

Code mapping object (model code mappings) returned by a call to function `coder.mapping.api.get`.

Example: myCM

### **inportBlock** — Name, path, or handle of root-level inport

character vector | string scalar | block handle

Name, path, or handle of the root-level inport for which to return the code mapping information.

Example: 'In1'

Data Types: char | string | block\_handle

### **property** — Code mapping property value to return

StorageClass | Identifier | Export | BitMask | CalibrationAccess | CompuMethod | DisplayIdentifier | Format

Code mapping property for which to return a value. For a storage class defined in the Embedded Coder Dictionary associated with the model, specify a property name or one of these property names.

| Information to Return                                                                                                                                                                                                                                                                                        | Property Name     |
|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-------------------|
| Name of storage class                                                                                                                                                                                                                                                                                        | StorageClass      |
| Name of variable for inport in the generated code                                                                                                                                                                                                                                                            | Identifier        |
| Boolean value indicating whether to export the selected inport to a calibration file (a2l)                                                                                                                                                                                                                   | Export            |
| Mask value in hexadecimal format to extract single bits from the inport in a calibration tool                                                                                                                                                                                                                | BitMask           |
| Enumeration value indicating the access of calibration. <code>Calibration</code> for an inport indicates that the inport can be calibrated. <code>NoCalibration</code> indicates that the inport can be read-only but cannot be calibrated. <code>NoCalibration</code> is the default value for the property | CalibrationAccess |
| Name of the conversion method used during the calibration                                                                                                                                                                                                                                                    | CompuMethod       |
| Optional display name of the inport for calibration                                                                                                                                                                                                                                                          | DisplayIdentifier |
| Specifies the display format of the inport being measured in a calibration tool                                                                                                                                                                                                                              | Format            |
|                                                                                                                                                                                                                                                                                                              |                   |

Example: 'StorageClass'

Example: 'CalibrationAccess'

## Output Arguments

**propertyValue** — Name or value of the property returned

character vector | boolean

Name or value of the property configured for the specified root-level inport.

Data Types: char | logical

## Version History

**Introduced in R2020b**

### See Also

`coder.mapping.api.CodeMapping` | `coder.mapping.api.get` | `find` | `getDataDefault` | `setDataDefault` | `setInport`

### Topics

“Configure Root-Level Inport Blocks for C Code Generation”

“C Code Generation Configuration for Model Interface Elements”

# getModelParameter

Get code and calibration configuration from code mappings for model parameters

## Syntax

```
propertyValue = getModelParameter(myCodeMappingObj,modelParameter,property)
```

## Description

`propertyValue = getModelParameter(myCodeMappingObj,modelParameter,property)` returns the value of a code mapping property or calibration property for the specified model workspace parameter. For example, use this function to return the storage class or the calibration access of a calibration property configured for the parameter.

## Examples

### Get Storage Class Configured for Model Parameter

From the model code mappings for model `rtwdemo_configrpinterface`, get the name of the storage class that is configured for model parameter `K1`.

```
open_system('rtwdemo_configrpinterface');
cm = coder.mapping.api.get('rtwdemo_configrpinterface');
sck1 = getModelParameter(cm,'K1','StorageClass');
```

### Get Identifier Configured for Model Parameter

From the model code mappings for model `rtwdemo_configrpinterface`, configure the storage class and identifier for model parameter `Table1`. To access the identifier configured for a model parameter, use the `getModelParameter` function.

```
open_system('rtwdemo_configrpinterface');
cm = coder.mapping.api.get('rtwdemo_configrpinterface');
setModelParameter(cm,'Table1','StorageClass','ExportedGlobal',...
'Identifier','mp_Table1')
idTable1 = getModelParameter(cm,'Table1','Identifier');

idTable1 =

 'mp_Table1'
```

### Get Calibration Properties Configured for Model Parameter

From the model code mappings for model `rtwdemo_configrpinterface`, get the calibration properties such as calibration access and display identifier configured for model parameter `LOWER`.

```
open_system('rtwdemo_configrpinterface');
cm = coder.mapping.api.get('rtwdemo_configrpinterface');
```

```

prop_export = getModelParameter(cm, 'LOWER', 'Export');
prop_bitmask = getModelParameter(cm, 'LOWER', 'BitMask');
prop_calaccess = getModelParameter(cm, 'LOWER', 'CalibrationAccess');
prop_compname = getModelParameter(cm, 'LOWER', 'CompuMethod');
prop_dispid = getModelParameter(cm, 'LOWER', 'DisplayIdentifier');
prop_format = getModelParameter(cm, 'LOWER', 'Format');

```

## Input Arguments

### **myCodeMappingObj** — Code mapping object

CodeMapping object

Code mapping object (model code mappings) returned by a call to function `coder.mapping.api.get`.

Example: `myCM`

### **modelParameter** — Name of model parameter

character vector | string scalar

Name of the model workspace parameter for which to return the code mapping information.

Example: `'Table1'`

Data Types: `char` | `string`

### **property** — Code mapping property value to return

`StorageClass` | `Identifier` | `Export` | `BitMask` | `CalibrationAccess` | `CompuMethod` | `DisplayIdentifier` | `Format`

Code mapping property for which to return a value. For a storage class defined in the Embedded Coder Dictionary associated with the model, specify a property name or one of these property names.

| Information to Return                                                                                                                                                                                                                                                                          | Property Name                  |
|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|--------------------------------|
| Name of storage class                                                                                                                                                                                                                                                                          | <code>StorageClass</code>      |
| Name of variable for the parameter in the generated code                                                                                                                                                                                                                                       | <code>Identifier</code>        |
| Boolean value indicating whether to export the selected model parameter to a calibration file (a2l)                                                                                                                                                                                            | <code>Export</code>            |
| Mask value in hexadecimal format to extract single bits from the model parameter in a calibration tool                                                                                                                                                                                         | <code>BitMask</code>           |
| Enumeration value indicating the access of calibration. <code>Calibration</code> for an parameter indicates that the parameter can be calibrated and is the default value for the property. <code>NoCalibration</code> indicates that the parameter can be read-only and cannot be calibrated. | <code>CalibrationAccess</code> |
| Name of the conversion method used during the calibration                                                                                                                                                                                                                                      | <code>CompuMethod</code>       |
| Optional display name of the model parameter for calibration                                                                                                                                                                                                                                   | <code>DisplayIdentifier</code> |

| Information to Return                                                                      | Property Name |
|--------------------------------------------------------------------------------------------|---------------|
| Specifies the display format of the model parameter being calibrated in a calibration tool | Format        |
|                                                                                            |               |
|                                                                                            |               |

Example: 'StorageClass '

Example: 'CalibrationAccess '

## Output Arguments

**propertyValue** — Name of storage class or value of storage class property

character vector

Name of the storage class or value of the specified storage class property configured for model parameter.

Data Types: char

## Version History

Introduced in R2020b

## See Also

`coder.mapping.api.CodeMapping` | `coder.mapping.api.get` | `find` | `getDataDefault` | `setDataDefault` | `setModelProperty`

## Topics

“Configure Parameters for C Code Generation”

“C Code Generation Configuration for Model Interface Elements”

## getOutputport

Get code and calibration configuration from code mappings for root-level outputport

### Syntax

```
propertyValue = getOutputport(myCodeMappingObj,outputBlock,property)
```

### Description

`propertyValue = getOutputport(myCodeMappingObj,outputBlock,property)` returns the value of a code mapping property or calibration property for the specified root-level Outputport block. For example, use this function to return the storage class or the value of a storage class property configured for a root-level outputport in a model, or to return the calibration access of the outputport.

### Examples

#### Get Storage Class Configured for Root-Level Outputport

From the model code mappings for model `rtwdemo_configrpinterface`, get the name of the storage class that is configured for root-level outputport `Out1`.

```
open_system('rtwdemo_configrpinterface');
cm = coder.mapping.api.get('rtwdemo_configrpinterface');
scOut1 = getOutputport(cm,'Out1','StorageClass');
```

#### Get Code Identifier Configured for Root-Level Outputport

From the model code mappings for model `rtwdemo_configrpinterface`, get the code identifier configured for root-level outputport `Out1`.

```
open_system('rtwdemo_configrpinterface');
cm = coder.mapping.api.get('rtwdemo_configrpinterface');
idOut1 = getOutputport(cm,'Out1','Identifier');
```

#### Get Calibration Properties Configured for Root-Level Outputport

From the model code mappings for model `rtwdemo_configrpinterface`, get the calibration properties such as calibration access and display identifier configured for root-level outputport `Out1`.

```
open_system('rtwdemo_configrpinterface');
cm = coder.mapping.api.get('rtwdemo_configrpinterface');
prop_export = getOutputport(cm,'Out1','Export');
prop_bitmask = getOutputport(cm,'Out1','BitMask');
prop_calaccess = getOutputport(cm,'Out1','CalibrationAccess');
prop_compname = getOutputport(cm,'Out1','CompuMethod');
```



```
prop_dispid = getOutport(cm, 'Out1', 'DisplayIdentifier');
prop_format = getOutport(cm, 'Out1', 'Format');
```

## Input Arguments

### **myCodeMappingObj** — Code mapping object

CodeMapping object

Code mapping object (model code mappings) returned by a call to function `coder.mapping.api.get`.

Example: `myCM`

### **outportBlock** — Name, path, or handle of root-level outport

character vector | string scalar | block handle

Name, path, or handle of the root-level outport for which to return the code mapping information.

Example: `'Out1'`

Data Types: `char` | `string`

### **property** — Code mapping property value to return

`StorageClass` | `Identifier` | `Export` | `BitMask` | `CalibrationAccess` | `CompuMethod` | `DisplayIdentifier` | `Format`

Code mapping property for which to return a value. For a storage class defined in the Embedded Coder Dictionary associated with the model, specify a property name or one of these property names.

| Information to Return                                                                                                                                                                                                                                                                                           | Property Name                  |
|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|--------------------------------|
| Name of storage class                                                                                                                                                                                                                                                                                           | <code>StorageClass</code>      |
| Name of variable for root-level outport in the generated code                                                                                                                                                                                                                                                   | <code>Identifier</code>        |
| Boolean value indicating whether to export the selected outport to a calibration file (a2l)                                                                                                                                                                                                                     | <code>Export</code>            |
| Mask value in hexadecimal format to extract single bits from the outport in a calibration tool                                                                                                                                                                                                                  | <code>BitMask</code>           |
| Enumeration value indicating the access of calibration. <code>Calibration</code> for an outport indicates that the outport can be calibrated. <code>NoCalibration</code> indicates that the outport can be read-only but cannot be calibrated. <code>NoCalibration</code> is the default value for the property | <code>CalibrationAccess</code> |
| Name of the conversion method used during the calibration                                                                                                                                                                                                                                                       | <code>CompuMethod</code>       |
| Optional display name of the outport for calibration                                                                                                                                                                                                                                                            | <code>DisplayIdentifier</code> |
| Specifies the display format of the outport being measured in a calibration tool                                                                                                                                                                                                                                | <code>Format</code>            |

| Information to Return | Property Name |
|-----------------------|---------------|
|                       |               |

Example: 'StorageClass'

Example: 'CalibrationAccess'

## Output Arguments

**propertyValue** — Name or value of the property returned

character vector | boolean

Name or value of the property configured for the specified root-level outport.

Data Types: char | logical

## Version History

**Introduced in R2020b**

### See Also

`coder.mapping.api.CodeMapping` | `coder.mapping.api.get` | `find` | `getDataDefault` | `setDataDefault` | `setOutport`

### Topics

“Configure Root-Level Outport Blocks for C Code Generation”

“C Code Generation Configuration for Model Interface Elements”

# getSignal

Get code and calibration configuration from code mappings for block output signal

## Syntax

```
propertyValue = getSignal(myCodeMappingObj, portHandle, property)
```

## Description

`propertyValue = getSignal(myCodeMappingObj, portHandle, property)` returns the value of a code mapping property or calibration property for the signal specified by a block output port handle. For example, use this function to return the name of the storage class or calibration access of a measurement property configured for a signal.

This function does not apply to signals that originate from root-level Inport blocks. For signals that originate from root-level Inport blocks, see `getInport`.

## Examples

### Get Storage Class Configured for Block Output Signal

From the model code mappings for model `rtwdemo_configrpinterface`, get the name of the storage class that is configured for the output signal of lookup table block `Table1`. After creating the object `cm` by calling function `coder.mapping.api.get`, get the handle to the output signals for the lookup table block. Get the storage class configured for the output port by calling `getSignal`.

```
open_system('rtwdemo_configrpinterface');
cm = coder.mapping.api.get('rtwdemo_configrpinterface');
lut1_ports = get_param('rtwdemo_configrpinterface/Table1', 'PortHandles');
lut1_outPort = lut1_ports.Outport;
addSignal(cm, lut1_outPort);
scTable1ID = getSignal(cm, lut1_outPort, 'StorageClass');
```

### Get Code Identifiers Configured for Block Output Signals

From the model code mappings for model `rtwdemo_configrpinterface`, get the code identifiers that are configured for output signals of lookup table blocks `Table1` and `Table2`. After creating the object `cm` by calling function `coder.mapping.api.get`, get the handles to the output ports for the lookup table blocks. Get the code identifiers configured for the output ports by calling `getSignal`.

```
open_system('rtwdemo_configrpinterface');
cm = coder.mapping.api.get('rtwdemo_configrpinterface');
lut1_ports = get_param('rtwdemo_configrpinterface/Table1', 'PortHandles');
lut2_ports = get_param('rtwdemo_configrpinterface/Table2', 'PortHandles');
lut1_outPort = lut1_ports.Outport;
lut2_outPort = lut2_ports.Outport;
addSignal(cm, lut1_outPort);
addSignal(cm, lut2_outPort);
setSignal(cm, lut1_outPort, 'StorageClass', 'ExportedGlobal');
setSignal(cm, lut2_outPort, 'StorageClass', 'ExportedGlobal');
```

```
idTable1 = getSignal(cm,lut1_outPort,'Identifier');
idTable2 = getSignal(cm,lut2_outPort,'Identifier');
```

### Get Calibration Properties Configured for Signal

From the model code mappings for model `rtwdemo_configrpinterface`, get the calibration properties configured for signal `Signal_1`.

```
open_system('rtwdemo_configrpinterface');
cm = coder.mapping.api.get('rtwdemo_configrpinterface');
port_handles = get_param('rtwdemo_configrpinterface/Table1','PortHandles');
Signal_1 = port_handles.Outport;
addSignal(cm, Signal_1);
prop_export = getSignal(cm,Signal_1,'Export');
prop_bitmask = getSignal(cm,Signal_1,'BitMask');
prop_calaccess = getSignal(cm,Signal_1,'CalibrationAccess');
prop_compname = getSignal(cm,Signal_1,'CompuMethod');
prop_dispid = getSignal(cm,Signal_1,'DisplayIdentifier');
prop_format = getSignal(cm,Signal_1,'Format');
```

## Input Arguments

### `myCodeMappingObj` — Code mapping object

CodeMapping object

Code mapping object (model code mappings) returned by a call to function `coder.mapping.api.get`.

Example: `myCM`

### `portHandle` — Output port handle of signal source block

port handle

Block output signals for which to return signal code mapping information.

Example: `portHandle`

Data Types: `port_handle`

### `property` — Code mapping property value to return

StorageClass | Identifier | Export | BitMask | CalibrationAccess | CompuMethod | DisplayIdentifier | Format | MeasurementService

Code mapping property for which to return a value. For a storage class defined in the Embedded Coder Dictionary associated with the model, specify a property name or one of these property names.

| Information to Return                                                                         | Property Name |
|-----------------------------------------------------------------------------------------------|---------------|
| Name of storage class                                                                         | StorageClass  |
| Name of variable for signal data in the generated code                                        | Identifier    |
| Boolean value indicating whether to export the selected signal to a calibration file (a2l)    | Export        |
| Mask value in hexadecimal format to extract single bits from the signal in a calibration tool | BitMask       |

| Information to Return                                                                                                                                                                                                                                                                                       | Property Name                   |
|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|---------------------------------|
| Enumeration value indicating the access of calibration. <code>Calibration</code> for a signal indicates that the signal can be calibrated. <code>NoCalibration</code> indicates that the signal can be read-only but cannot be calibrated. <code>NoCalibration</code> is the default value for the property | <code>CalibrationAccess</code>  |
| Name of the conversion method used during the calibration                                                                                                                                                                                                                                                   | <code>CompuMethod</code>        |
| Optional display name of the signal for calibration                                                                                                                                                                                                                                                         | <code>DisplayIdentifier</code>  |
| Specifies the display format of the signal being measured in a calibration tool                                                                                                                                                                                                                             | <code>Format</code>             |
| Name of measurement service defined in Embedded Coder Dictionary                                                                                                                                                                                                                                            | <code>MeasurementService</code> |

Example: `'StorageClass'`

Example: `'CalibrationAccess'`

## Output Arguments

**propertyValue** — Name of storage class or value of storage class property

character vector

Name of the storage class or value of the specified storage class property configured for the specified signal.

Data Types: `char`

## Version History

Introduced in R2020b

## See Also

`addSignal` | `coder.mapping.api.CodeMapping` | `coder.mapping.api.get` | `find` | `getDataDefault` | `removeSignal` | `setDataDefault` | `setSignal`

## Topics

“Configure Signal Data for C Code Generation”

“C Code Generation Configuration for Model Interface Elements”

## getState

Get code and calibration configuration from code mappings for block state

### Syntax

```
propertyValue = getState(myCodeMappingObj,block,property)
```

### Description

`propertyValue = getState(myCodeMappingObj,block,property)` returns the value of a code mapping property or calibration property for the state of the specified block. For example, use this function to return the storage class or calibration access of a measurement property configured for a block state.

### Examples

#### Get Storage Class Configured for Block State

From the model code mappings for model `rtwdemo_configrpinterface`, get the name of the storage class that is configured for state X of Unit Delay block Delay.

```
open_system('rtwdemo_configrpinterface');
cm = coder.mapping.api.get('rtwdemo_configrpinterface');
state = find(cm,'State');
scX = getState(cm,state,'StorageClass');
```

#### Get Calibration Properties Configured for State of Unit Delay Block

From the model code mappings for model `rtwdemo_configrpinterface`, get the calibration properties configured for state X of Unit Delay block Delay.

```
open_system('rtwdemo_configrpinterface');
cm = coder.mapping.api.get('rtwdemo_configrpinterface');
state = find(cm,'State');
prop_export = getState(cm,state,'Export');
prop_bitmask = getState(cm,state,'BitMask');
prop_calaccess = getState(cm,state,'CalibrationAccess');
prop_compname = getState(cm,state,'CompuMethod');
prop_dispid = getState(cm,state,'DisplayIdentifier');
prop_format = getState(cm,state,'Format');
```

### Input Arguments

#### **myCodeMappingObj** — Code mapping object

CodeMapping object

Code mapping object (model code mappings) returned by a call to function `coder.mapping.api.get`.

Example: myCM

### **block — Path or handle of block**

character vector | string scalar | block handle

Path of the block for which to return the state code mapping information, specified as a character vector or string scalar. Alternatively, you can specify a block handle.

Example: blockHandle

Data Types: char | string | block\_handle

### **property — Code mapping property value to return**

StorageClass | Identifier | | | | Export | BitMask | CalibrationAccess | CompuMethod | DisplayIdentifier | Format | MeasurementService

Code mapping property for which to return a value. For a storage class defined in the Embedded Coder Dictionary associated with the model, specify a property name or one of these property names.

| Information to Return                                                                                                                                                                                                                                                                                    | Property Name      |
|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|--------------------|
| Name of storage class                                                                                                                                                                                                                                                                                    | StorageClass       |
| Name of variable for state in the generated code                                                                                                                                                                                                                                                         | Identifier         |
| Boolean value indicating whether to export the selected state to a calibration file (a2l)                                                                                                                                                                                                                | Export             |
| Mask value in hexadecimal format to extract single bits from the state in a calibration tool                                                                                                                                                                                                             | BitMask            |
| Enumeration value indicating the access of calibration. <code>Calibration</code> for a state indicates that the state can be calibrated. <code>NoCalibration</code> indicates that the state can be read-only but cannot be calibrated. <code>NoCalibration</code> is the default value for the property | CalibrationAccess  |
| Name of the conversion method used during the calibration                                                                                                                                                                                                                                                | CompuMethod        |
| Optional display name of the state for calibration                                                                                                                                                                                                                                                       | DisplayIdentifier  |
| Specifies the display format of the state being measured in a calibration tool                                                                                                                                                                                                                           | Format             |
| Name of the measurement service                                                                                                                                                                                                                                                                          | MeasurementService |

Example: 'StorageClass'

Example: 'CalibrationAccess'

## **Output Arguments**

### **propertyValue — Name of storage class or value of storage class property**

character vector

Name of the storage class or value of the specified storage class property configured for the specified block state, returned as a character vector.

Data Types: char

## **Version History**

**Introduced in R2020b**

### **See Also**

`coder.mapping.api.CodeMapping` | `coder.mapping.api.get` | `find` | `getDataDefault` | `setDataDefault` | `setState`

### **Topics**

“Configure Block States for C Code Generation”

“C Code Generation Configuration for Model Interface Elements”



# removeSignal

Remove block output signal from model code mappings

## Syntax

```
removeSignal(myCodeMappingObj, portHandle)
```

## Description

`removeSignal(myCodeMappingObj, portHandle)` removes signals specified by the block output port handles from the specified model code mappings.

This function does not apply to signals that originate from root-level Inport blocks.

## Examples

### Remove Block Output Signals from Model Code Mappings

From the model code mappings for model `myConfigModel`, remove the output signals of lookup table blocks `Table1D` and `Table2D`. After creating the object `cm` by calling function `coder.mapping.api.get`, get handles to the output ports for lookup table blocks. Remove the output signals from the code mappings by calling `removeSignal`.

```
cm = coder.mapping.api.get('myConfigModel');
lut1D_ports = get_param('myConfigModel/Table1D', 'PortHandles');
lut2D_ports = get_param('myConfigModel/Table2D', 'PortHandles');
lut1D_outPort = lut1D_ports.Outport;
lut2D_outPort = lut2D_ports.Outport;
removeSignal(cm, [lut1D_outPort, lut2D_outPort]);
```

## Input Arguments

### **myCodeMappingObj** — Code mapping object

CodeMapping object

Code mapping object (model code mappings) returned by a call to function `coder.mapping.api.get`.

Example: `myCM`

### **portHandle** — Output port handle of signal source block

port handle | cell array of port handles

Signal to remove from the code mappings, specified as a handle of an output port of the source block of the signal. To specify multiple port handles, use a cell array.

Example: `portHandle`

Data Types: `port_handle` | `cell`

## **Version History**

**Introduced in R2020b**

### **See Also**

`addSignal` | `coder.mapping.api.CodeMapping` | `coder.mapping.api.get` | `find` | `getDataDefault` | `getSignal` | `removeSignal` | `setDataDefault` | `setSignal`

### **Topics**

“Configure Signal Data for C Code Generation”

“C Code Generation Configuration for Model Interface Elements”

# setDataDefault

Set default storage class and storage class property values for model data category

## Syntax

```
setDataDefault(myCodeMappingObj, category, Name, Value)
```

## Description

`setDataDefault(myCodeMappingObj, category, Name, Value)` sets the default storage class and storage class property values in the code mappings for the specified category of model data.

Default data configurations cannot be specified for models linked to a service interface configuration.

## Examples

### Configure Default Representation for Model Workspace Parameters in Generated Code as Unstructured Global Variables

In the model code mappings for model `myConfigModel`, configure the default representation of model workspace parameters in generated code as unstructured global variables by setting the default storage class to `ExportedGlobal`.

```
cm = coder.mapping.api.get('myConfigModel');
setDataDefault(cm, 'ModelParameters', 'StorageClass', 'ExportedGlobal');
```

## Input Arguments

### `myCodeMappingObj` — Code mapping object

CodeMapping object

Code mapping object (model code mappings) returned by a call to function `coder.mapping.api.get`.

Example: `myCM`

### `category` — Model element category

`ExternalParameterObjects` | `GlobalDataStores` | `Inports` | `InternalData` | `ModelParameters` | `Outports` | `SharedLocalDataStores`

Category of model data element for which to set the storage class and storage class properties.

Example: `'Inports'`

### Name-Value Pair Arguments

Specify comma-separated pairs of `Name`, `Value` arguments. `Name` is the argument name and `Value` is the corresponding value. `Name` must appear inside quotes. You can specify several name and value pair arguments as `Name1, Value1, ..., NameN, ValueN`. The order of the name and value pair arguments does not matter.

Example: 'StorageClass','ExportedGlobal'

**StorageClass — Name of storage class**

Auto | Dictionary default | ExportedGlobal | ImportedExtern | ImportedExternPointer  
| Model default

Storage class to set for the specified data element category. The name of a predefined storage class or storage class that is defined in the Embedded Coder Dictionary associated with the model. Values that you can specify vary depending on the category that you specify. See “Choose Storage Class for Controlling Data Representation in Generated Code”.

Example: 'StorageClass','ImportedExtern'

## Version History

**Introduced in R2020b**

### See Also

`coder.mapping.api.CodeMapping` | `coder.mapping.api.get` | `getDataDefault`

### Topics

“C Code Generation Configuration for Model Interface Elements”

“Configure Root-Level Inport Blocks for C Code Generation”

“Configure Root-Level Outport Blocks for C Code Generation”

“Configure Signal Data for C Code Generation”

“Configure Parameters for C Code Generation”

“Configure Block States for C Code Generation”

“Configure Data Stores for C Code Generation”

## setDataStore

Configure local or shared local data store for code and calibration file (a2l) generation

### Syntax

```
setDataStore(myCodeMappingObj, dataStore, Name, Value)
```

### Description

`setDataStore(myCodeMappingObj, dataStore, Name, Value)` configures the specified local or shared local data store for code and calibration file (a2l) generation. Use this function to map a local or shared local data store to the storage class and storage class property settings that the code generator uses to produce C code. Or, set the calibration access for that data store.

### Examples

#### Configure Storage Class for Local Data Store

In the model code mappings for model `rtwdemo_configrpinterface`, set the storage class for local data store mode to `ExportedGlobal`.

```
open_system('rtwdemo_configrpinterface');
cm = coder.mapping.api.get('rtwdemo_configrpinterface');
setDataStore(cm, 'mode', 'StorageClass', 'ExportedGlobal');
```

#### Configure Storage Class for Local and Shared Local Data Stores in Model to Model default

In the model code mappings for model `rtwdemo_configrpinterface`, set the storage class for local and shared local data stores throughout the model to `Model default`.

```
open_system('rtwdemo_configrpinterface');
cm = coder.mapping.api.get('rtwdemo_configrpinterface');
dsmHandles = find(cm, 'DataStores')
setDataStore(cm, dsmHandles, 'StorageClass', 'Model default');
```

#### Configure Code Identifier for Local Data Store

In the model code mappings, for model `rtwdemo_configrpinterface`, set the code identifier for local data store mode to `ds_mode`.

```
open_system('rtwdemo_configrpinterface');
cm = coder.mapping.api.get('rtwdemo_configrpinterface');
setDataStore(cm, 'mode', 'Identifier', 'ds_mode');
```

### Configure Calibration Properties for Local Data Store

From the model code mappings for model `rtwdemo_configrpinterface`, set the calibration properties configured for the local data store mode.

```
open_system('rtwdemo_configrpinterface');
cm = coder.mapping.api.get('rtwdemo_configrpinterface');
setDataStore(cm, 'mode', 'Export', true);
setDataStore(cm, 'mode', 'CalibrationAccess', 'Calibration');
setDataStore(cm, 'mode', 'CompuMethod', 'CM_state');
setDataStore(cm, 'mode', 'DisplayIdentifier', 'state_X');
setDataStore(cm, 'mode', 'Format', '%4.2');
```

## Input Arguments

### `myCodeMappingObj` — Code mapping object

CodeMapping object

Code mapping object (model code mappings) returned by a call to function `coder.mapping.api.get`.

Example: `myCM`

### `dataStore` — Block path, block handle, or name of data store

character vector | string scalar | block handle | array of character vectors | array of string scalars | array of block handles

Path of the Data Store Memory block for which to return the code mapping information, specified as a character vector or string scalar. Alternatively, you can specify a block handle or the name of the data store. If you specify the name of a data store and that name is not unique within the model, Simulink returns an error that instructs you to specify the block path or handle. To specify multiple data stores, use an array.

Example: `blockHandle`

Data Types: `char` | `string` | `block_handle` | `array`

### Name-Value Pair Arguments

Specify comma-separated pairs of `Name`, `Value` arguments. `Name` is the argument name and `Value` is the corresponding value. `Name` must appear inside quotes. You can specify several name and value pair arguments as `Name1, Value1, ..., NameN, ValueN`. The order of the name and value pair arguments does not matter.

Example: `'StorageClass' 'ExportedGlobal'`

### `StorageClass` — Name of storage class

`Auto` | `Dictionary default` | `ExportedGlobal` | `ImportedExtern` | `ImportedExternPointer` | `Model default`

Storage class to set for the specified data store. The name of a predefined storage class or storage class that is defined in the Embedded Coder Dictionary associated with the model. See “Configure Data Stores for C Code Generation”.

### `Identifier` — Name of variable

character vector | string scalar

Name for the variable that represents the local data store in the generated code.

Data Types: `char` | `string`

**Export — Enable or disable generation of the data store to calibration file (a2I)**

`true` (default) | `false`

Enable this property to generate the data store to calibration file (a2I).

**BitMask — Extract single bits from the data store value**

hexadecimal value

Mask value in hexadecimal format to extract single bits from the data store during calibration. This property is applicable only for integers.

Data Types: `hexadecimal`

**CalibrationAccess — Enable or disable calibration of the data store**

`NoCalibration` (default) | `Calibration`

Select `Calibration` for the data store to enable the calibration. Select `NoCalibration` to view the value of the data store and disable the calibration.

**CompuMethod — Name of conversion method**

character vector | string scalar

Name of the method for converting the ECU-internal value to a physical value for easy readability.

Data Types: `char` | `string`

**DisplayIdentifier — Display name of the data store**

character vector | string scalar

Optional display name of the data store for the measurement purpose in the calibration tool, which is different than the data store name in the Simulink model.

Data Types: `char` | `string`

**Format — Display format of the data store value**

`%[length].[layout]`

Special display format to be specified for measurement in the calibration tool. This format specification overrules the display format specified in `CompuMethod` of the data store.

## Version History

Introduced in R2020b

### See Also

`coder.mapping.api.CodeMapping` | `coder.mapping.api.get` | `find` | `getDataDefault` | `getDataStore` | `setDataDefault`

### Topics

“Configure Data Stores for C Code Generation”

“C Code Generation Configuration for Model Interface Elements”

## setFunction

Set code mapping information for model function

### Syntax

```
setFunction(myCodeMappingObj, function, Name, Value)
```

### Description

`setFunction(myCodeMappingObj, function, Name, Value)` sets code mapping information for the specified model function. Use this function to set the function customization template, memory section, or function name for a model function. For single-tasking periodic functions and Simulink functions, you can use this function to set the argument specification, including argument names, type qualifiers, and argument order.

### Examples

#### Configure Function Name for Model Initialize Function

In the model code mappings for model `myConfigModel`, configure the name of the generated C initialize function as `myInitFunction`.

```
cm = coder.mapping.api.get('myConfigModel');
setFunction(cm, 'Initialize', 'FunctionName', 'myInitFunction');
```

#### Configure Memory Section for Periodic Single-Tasking Function

In the model code mappings for model `myInitFunction`, configure the memory section for the periodic single-tasking function as `None`.

```
cm = coder.mapping.api.get('myInitFunction');
setFunction(cm, 'Periodic', 'MemorySection', 'None');
```

#### Configure Function Customization Template for Periodic Multitasking Function for Sample Time D2

In the model code mappings for model `myInitFunction`, configure the function customization template for the periodic multitasking function for sample time `D2` as `FastFcn`.

```
cm = coder.mapping.api.get('myInitFunction');
setFunction(cm, 'Periodic:D2', 'FunctionCustomizationTemplate', 'FastFcn');
```



## Configure Argument Specification for Simulink Function

In the model code mappings for model `myInitFunction`, configure the argument specification for Simulink function `mySLFunc` as `y=(u1, const *u2)`.

```
cm = coder.mapping.api.get('myInitFunction');
setFunction(cm, 'mySLFunc', 'Arguments', 'y=(u1, const *u2)');
```

## Input Arguments

### `myCodeMappingObj` — Code mapping object

CodeMapping object

Code mapping object (model code mappings) returned by a call to function `coder.mapping.api.get`.

Example: `myCM`

### function — Model function

Initialize | Terminate | Periodic:*slIdentifier* | Partition:*slIdentifier* |  
 PeriodicUpdate:*slIdentifier* | PartitionUpdate:*slIdentifier* | Reset:*slIdentifier* |  
 ExportedFunction:*slIdentifier* | SimulinkFunction:*slIdentifier*

Model function for which to return a code mapping property value. Specify one of the values listed in this table. If model configuration parameter **Single output/update function** is cleared, you can specify the update version of a partition, periodic multi-tasking, or periodic singletasking function.

| Type of Model Function                | Value                                                                                                                                                                                                                                          |
|---------------------------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Exported function                     | ExportedFunction: <i>slIdentifier</i> , where <i>slIdentifier</i> is the name of the function-call Inport block in the model                                                                                                                   |
| Initialize function                   | Initialize                                                                                                                                                                                                                                     |
| Partition function                    | Partition: <i>slIdentifier</i> , where <i>slIdentifier</i> is a partition that was created explicitly from a block in the model and shown in the Simulink Schedule Editor (for example, P1), or a task name in the Concurrent Execution dialog |
| Partition update function             | PartitionUpdate: <i>slIdentifier</i> , is a partition that was created explicitly from a block in the model and shown in the Simulink Schedule Editor (for example, P1), or a task name in the Concurrent Execution dialog                     |
| Periodic multitasking function        | Periodic: <i>slIdentifier</i> , where <i>slIdentifier</i> is an annotation that corresponds to the sample time period for a periodic or continuous rate of a multi-tasking model (for example, D1)                                             |
| Periodic multitasking update function | PeriodicUpdate: <i>slIdentifier</i> , where <i>slIdentifier</i> is an annotation that corresponds to the sample time period for a periodic or continuous rate of a multi-tasking model (for example, D1)                                       |
| Periodic single-tasking function      | Periodic                                                                                                                                                                                                                                       |

| Type of Model Function                  | Value                                                                                                               |
|-----------------------------------------|---------------------------------------------------------------------------------------------------------------------|
| Periodic single-tasking update function | PeriodicUpdate                                                                                                      |
| Reset function                          | Reset: <i>slIdentifier</i> , where <i>slIdentifier</i> is the name of the reset function in the model               |
| Simulink function                       | SimulinkFunction: <i>slIdentifier</i> , where <i>slIdentifier</i> is the name of the Simulink function in the model |
| Terminate function                      | Terminate                                                                                                           |

For information about model partitioning, see “Create Partitions”.

Example: 'Periodic:D1'

### Name-Value Pair Arguments

Specify comma-separated pairs of `Name`, `Value` arguments. `Name` is the argument name and `Value` is the corresponding value. `Name` must appear inside quotes. You can specify several name and value pair arguments as `Name1, Value1, ..., NameN, ValueN`. The order of the name and value pair arguments does not matter.

Example: 'FunctionCustomizationTemplate' 'exFastFunction'

### FunctionCustomizationTemplate — Name of function customization template

character vector | string scalar

Name of a function customization template defined in the Embedded Coder Dictionary associated with the model, specified as a character vector or string scalar. If you set the default function customization template for a category of functions to `Default`, you can specify a memory section for the functions category.

Data Types: char | string

### MemorySection — Name of memory section

character vector | string scalar

Name of a memory section that is defined in the Embedded Coder Dictionary associated with the model, specified as a character vector or string scalar.

Data Types: char | string

### FunctionName — Name of function

character vector | string scalar

Name for the entry-point function in the generated C code, specified as a character vector or string scalar.

Data Types: char | string

### Arguments — Argument specification

character vector | string scalar

Argument specification for the entry-point function in the generated C code, specified as a character vector or string scalar. The specification is a function prototype that shows argument names, type qualifiers, and argument order (for example, `y=(u1, const *u2)`).

Data Types: char | string

## Version History

Introduced in R2020b

### See Also

`coder.mapping.api.CodeMapping` | `coder.mapping.api.get` | `getFunction` | `getFunctionDefault` | `setFunctionDefault`

### Topics

“Configure Names for Individual C Entry-Point Functions” (Embedded Coder)

“Configure Name and Arguments for Individual Step Functions” (Embedded Coder)

“Configure Default C Code Generation for Categories of Data Elements and Functions” (Embedded Coder)

“C Code Generation Configuration for Model Interface Elements” (Embedded Coder)

## setFunctionDefault

Set default function customization template and memory section for model functions category

### Syntax

```
setFunctionDefault(myCodeMappingObj, category, Name, Value)
```

### Description

`setFunctionDefault(myCodeMappingObj, category, Name, Value)` sets the default function customization template and memory section for the specified category of model entry-point functions.

Default function configurations cannot be specified for models linked to a service interface configuration.

### Examples

#### Configure Default Memory Section for Model Execution Functions

For model `myConfigModel`, configure the code generator to use memory section `functionFastMem` for generating code for model execution functions in the model code mappings.

```
cm = coder.mapping.api.get('myConfigModel');
setFunctionDefault(cm, 'Execution', 'MemorySection', 'FunctionFastMem');
```

### Input Arguments

#### **myCodeMappingObj** — Code mapping object

CodeMapping object

Code mapping object (model code mappings) returned by a call to function `coder.mapping.api.get`.

Example: `myCM`

#### **category** — Model function category

`InitializeTerminate` | `Execution` | `SharedUtility`

Category of model entry-point functions for which to set the function customization template and memory section.

Example: `'Execution'`

#### **Name-Value Pair Arguments**

Specify comma-separated pairs of `Name`, `Value` arguments. `Name` is the argument name and `Value` is the corresponding value. `Name` must appear inside quotes. You can specify several name and value pair arguments as `Name1, Value1, ..., NameN, ValueN`. The order of the name and value pair arguments does not matter.

Example: 'FunctionCustomizationTemplate' 'exFastFunction'

### **FunctionCustomizationTemplate** — Name of function customization template

character vector | string scalar

Name of a function customization template defined in the Embedded Coder Dictionary associated with the model. If you set the default function customization template for a category of functions to `Default`, you can specify a memory section for the category of functions.

Data Types: char | string

### **MemorySection** — Name of memory section

character vector | string scalar

Name of a memory section that is defined in the Embedded Coder Dictionary associated with the model.

Data Types: char | string

## **Version History**

**Introduced in R2020b**

### **See Also**

`coder.mapping.api.CodeMapping` | `coder.mapping.api.get` | `getFunction` | `getFunctionDefault` | `setFunction`

### **Topics**

“Configure Default C Code Generation for Categories of Data Elements and Functions” (Embedded Coder)

“C Code Generation Configuration for Model Interface Elements” (Embedded Coder)

## setInport

Configure root-level inports for code and calibration file (a2l) generation

### Syntax

```
setInport(myCodeMappingObj, inport, Name, Value)
```

### Description

`setInport(myCodeMappingObj, inport, Name, Value)` configures specified root-level Inport blocks for code and calibration file (a2l) generation. For example, use this function to map specified root-level inports to the storage class and storage class property settings that the code generator uses to produce C code for the inports. Or, set the calibration access for the inport.

### Examples

#### Configure Storage Class for Root-Level Inports in Model to Model default

In the model code mappings for model `rtwdemo_configrpinterface`, set the storage class for root-level inports throughout the model to `Model default`.

```
open_system('rtwdemo_configrpinterface');
cm = coder.mapping.api.get('rtwdemo_configrpinterface');
inBlockHandles = find(cm, 'Inports');
setInport(cm, inBlockHandles, 'StorageClass', 'Model default');
```

#### Configure Calibration Properties for Root-Level Inports

In the model code mappings for model `rtwdemo_configrpinterface`, set the calibration properties for root-level Inport block `In1`.

```
open_system('rtwdemo_configrpinterface');
cm = coder.mapping.api.get('rtwdemo_configrpinterface');
setInport(cm, 'In1', 'Export', true);
setInport(cm, 'In1', 'CalibrationAccess', 'Calibration');
setInport(cm, 'In1', 'CompuMethod', 'CM_Inport');
setInport(cm, 'In1', 'DisplayIdentifier', 'inport_display_name');
setInport(cm, 'In1', 'Format', '%4.2');
```

### Input Arguments

#### **myCodeMappingObj** — Code mapping object

CodeMapping object

Code mapping object (model code mappings) returned by a call to function `coder.mapping.api.get`.

Example: `myCM`

**inport — Name, path, or handle of root-level inport**

character vector | string scalar | block handle | cell array of character vectors | cell array of string scalars | cell array of handles

Name, path, or handle of root-level inport to configure. To specify multiple inports, use a cell array.

Example: 'In1'

Data Types: char | string | cell

**Name-Value Pair Arguments**

Specify comma-separated pairs of Name, Value arguments. Name is the argument name and Value is the corresponding value. Name must appear inside quotes. You can specify several name and value pair arguments as Name1, Value1, ..., NameN, ValueN. The order of the name and value pair arguments does not matter.

Example: 'StorageClass' 'ExportedGlobal'

**StorageClass — Name of storage class**

Auto | Dictionary default | ExportedGlobal | ImportedExtern | ImportedExternPointer | Model default

Storage class to set for the specified root Inport block. The name of a predefined storage class or storage class that is defined in the Embedded Coder Dictionary associated with the model. See “Configure Root-Level Inport Blocks for C Code Generation”.

**Identifier — Name of variable**

character vector | string scalar

Name for the variable that represents the inport in the generated code.

Data Types: char | string

**Export — Enable or disable generation of the inport to calibration file (a2I)**

true (default) | false

Enable this property to generate the inport to calibration file (a2I).

**BitMask — Extract single bits from the inport value**

hexadecimal value

Mask value in hexadecimal format to extract single bits from the inport during calibration. This property is applicable only for integers.

Data Types: hexadecimal

**CalibrationAccess — Enable or disable calibration of the inport**

NoCalibration (default) | Calibration

Select Calibration for the inport to enable the calibration. Select NoCalibration to view the value of the inport and disable the calibration.

**CompuMethod — Name of conversion method**

character vector | string scalar

Name of the method for converting the ECU-internal value to a physical value for easy readability.

Data Types: `char` | `string`

**DisplayIdentifier** — Display name of the inport

character vector | string scalar

Optional display name of the inport for the measurement purpose in the calibration tool, which is different than the inport name in the Simulink model.

Data Types: `char` | `string`

**Format** — Display format of the inport value

`%[length].[layout]`

Special display format to be specified for measurement in the calibration tool. This format specification overrides the display format specified in `CompuMethod` of the inport.

## Version History

**Introduced in R2020b**

**See Also**

`coder.mapping.api.CodeMapping` | `coder.mapping.api.get` | `find` | `getDataDefault` | `getInport` | `setDataDefault`

**Topics**

“Configure Root-Level Inport Blocks for C Code Generation”

“C Code Generation Configuration for Model Interface Elements”



# setModelParameter

Configure model parameter for code and calibration file (a2l) generation

## Syntax

```
setModelParameter(myCodeMappingObj,modelParameter,Name,Value)
```

## Description

setModelParameter(myCodeMappingObj,modelParameter,Name,Value) configures the specified model parameter for code and calibration file (a2l) generation. Use this function to map the specified model parameter to the storage class and storage class property settings that the code generator uses to produce C code. Or, set the calibration access for the parameter.

## Examples

### Configure Storage Class for Model Parameter

In the model code mappings for model rtwdemo\_configrpinterface, set the storage class for model parameter K1 to ExportedGlobal.

```
open_system('rtwdemo_configrpinterface');
cm = coder.mapping.api.get('rtwdemo_configrpinterface');
setModelParameter(cm,'K1','StorageClass','ExportedGlobal');
```

### Configure Storage Class for Model Parameters in Model to Model default

In the model code mappings for model rtwdemo\_configrpinterface, set the storage class for model parameters throughout the model to Model default.

```
open_system('rtwdemo_configrpinterface');
cm = coder.mapping.api.get('rtwdemo_configrpinterface');
paramHandles = find(cm,'ModelParameters')
setModelParameter(cm,paramHandles,'StorageClass','Model default');
```

### Configure Storage Class for Model Parameters

In the model code mappings for model rtwdemo\_configrpinterface, set the storage class for model parameters Table1 and Table2 to ExportedGlobal.

```
open_system('rtwdemo_configrpinterface');
cm = coder.mapping.api.get('rtwdemo_configrpinterface');
setModelParameter(cm,'Table1','StorageClass','ExportedGlobal',...
 'Identifier','mp_Table1');
```

```
setModelParameter(cm, 'Table2', 'StorageClass', 'ExportedGlobal', ...
 'Identifier', 'mp_Table2');
```

### Configure Calibration Properties for Model Parameter

From the model code mappings for model `rtwdemo_configrpinterface`, set the calibration properties configured for the mode parameter argument `LOWER`.

```
open_system('rtwdemo_configrpinterface');
cm = coder.mapping.api.get('rtwdemo_configrpinterface');
setModelParameter(cm, 'LOWER', 'Export', true);
setModelParameter(cm, 'LOWER', 'CalibrationAccess', 'Calibration');
setModelParameter(cm, 'LOWER', 'CompuMethod', 'CM_param');
setModelParameter(cm, 'LOWER', 'DisplayIdentifier', 'param_lower');
setModelParameter(cm, 'LOWER', 'Format', '%4.2');
```

## Input Arguments

### **myCodeMappingObj** — Code mapping object

CodeMapping object

Code mapping object (model code mappings) returned by a call to function `coder.mapping.api.get`.

Example: `myCM`

### **modelParameter** — Name of model parameter

character vector | string | cell array of character vectors | cell array of string scalars

Name of the model workspace parameter to configure.

Example: `'Table1'`

Data Types: `char` | `string`

### **Name-Value Pair Arguments**

Specify comma-separated pairs of `Name`, `Value` arguments. `Name` is the argument name and `Value` is the corresponding value. `Name` must appear inside quotes. You can specify several name and value pair arguments as `Name1, Value1, ..., NameN, ValueN`. The order of the name and value pair arguments does not matter.

Example: `'StorageClass' 'ExportedGlobal'`

### **StorageClass** — Name of storage class

`Auto` | `Dictionary default` | `ExportedGlobal` | `ImportedExtern` | `ImportedExternPointer` | `Model default`

Storage class to set for the specified model parameter. The name of a predefined storage class or storage class that is defined in the Embedded Coder Dictionary associated with the model. See “Configure Parameters for C Code Generation”.

### **Identifier** — Name of variable

character vector | string scalar

Name for the variable that represents the model parameter in the generated code.

Data Types: char | string

**Export — Enable or disable generation of the model parameter to calibration file (a2l)**

true (default) | false

Enable this property to generate the model parameter to calibration file (a2l).

**BitMask — Extract single bits from the model parameter value**

hexadecimal value

Mask value in hexadecimal format to extract single bits from the model parameter during calibration. This property is applicable only for integers.

Data Types: hexadecimal

**CalibrationAccess — Enable or disable calibration of the model parameter**

Calibration (default) | NoCalibration

Select Calibration for the model parameter to enable the calibration. Select NoCalibration to view the value of the model parameter and disable the calibration.

**CompuMethod — Name of conversion method**

character vector | string scalar

Name of the method for converting the ECU-internal value to a physical value for easy readability.

Data Types: char | string

**DisplayIdentifier — Display name of the model parameter**

character vector | string scalar

Optional display name of the model parameter for measurement purpose in the calibration tool, which is different than the model parameter name in the Simulink model.

Data Types: char | string

**Format — Display format of the model parameter value**

%[length].[layout]

Special display format to be specified for measurement in the calibration tool. This format specification overrides the display format specified in CompuMethod of the model parameter.

## Version History

Introduced in R2020b

### See Also

coder.mapping.api.CodeMapping | coder.mapping.api.get | find | getDataDefault | getModelParameter | setDataDefault

### Topics

“Configure Parameters for C Code Generation”

“C Code Generation Configuration for Model Interface Elements”

## setOutputport

Configure root-level outputport for code and calibration file (a2l) generation

### Syntax

```
setOutputport(myCodeMappingObj, outputport, Name, Value)
```

### Description

`setOutputport(myCodeMappingObj, outputport, Name, Value)` configures specified root-level Outputport blocks for code and calibration file (a2l) generation. Use this function to map specified root-level outputports to the storage class and storage class property settings that the code generator uses to produce C code. Or, set the calibration access for the outputport.

### Examples

#### Configure Storage Class for Root-Level Outputports in Model to Model default

In the model code mappings for model `rtwdemo_configrpinterface`, set the storage class for root Outputport blocks throughout the model to `Model default`.

```
open_system('rtwdemo_configrpinterface');
cm = coder.mapping.api.get('rtwdemo_configrpinterface');
outBlockHandles = find(cm, 'Outputports');
setOutputport(cm, outBlockHandles, 'StorageClass', 'Model default');
```

#### Configure Calibration Properties for Root-Level Outputports

In the model code mappings for model `rtwdemo_configrpinterface`, set the calibration properties for root-level Outputport block `Out1`.

```
open_system('rtwdemo_configrpinterface');
cm = coder.mapping.api.get('rtwdemo_configrpinterface');
setOutputport(cm, 'Out1', 'Export', true);
setOutputport(cm, 'Out1', 'CalibrationAccess', 'Calibration');
setOutputport(cm, 'Out1', 'CompuMethod', 'CM_Outputport');
setOutputport(cm, 'Out1', 'DisplayIdentifier', 'output_display_name');
setOutputport(cm, 'Out1', 'Format', '%4.2');
```

### Input Arguments

#### **myCodeMappingObj** — Code mapping object

CodeMapping object

Code mapping object (model code mappings) returned by a call to function `coder.mapping.api.get`.

Example: `myCM`

**output** — Name, path, or handle of root-level output

character vector | string scalar | block handle | cell array of character vectors | cell array of string scalars | cell array of handles

Name, path, or handle of root-level output to configure. To specify multiple outputs, use a cell array.

Example: 'Out1'

Data Types: char | string | cell

**Name-Value Pair Arguments**

Specify comma-separated pairs of Name, Value arguments. Name is the argument name and Value is the corresponding value. Name must appear inside quotes. You can specify several name and value pair arguments as Name1, Value1, ..., NameN, ValueN. The order of the name and value pair arguments does not matter.

Example: 'StorageClass' 'ExportedGlobal'

**StorageClass** — Name of storage class

Auto | Dictionary default | ExportedGlobal | ImportedExtern | ImportedExternPointer | Model default

Storage class to set for the specified root Output block. The name of a predefined storage class or storage class that is defined in the Embedded Coder Dictionary associated with the model. See “Configure Root-Level Output Blocks for C Code Generation”.

**Identifier** — Name of variable

character vector | string scalar

Name for the variable that represents the output in the generated code.

Data Types: char | string

**Export** — Enable or disable generation of the output to calibration file (a2I)

true (default) | false

Enable this property to generate the output to calibration file (a2I).

**BitMask** — Extract single bits from the output value

hexadecimal value

Mask value in hexadecimal format to extract single bits from the output during calibration. This property is applicable only for integers.

Data Types: hexadecimal

**CalibrationAccess** — Enable or disable calibration of the output

NoCalibration (default) | Calibration

Select Calibration for the output to enable the calibration. Select NoCalibration to view the value of the output and disable the calibration.

**CompuMethod** — Name of conversion method

character vector | string scalar

Name of the method for converting the ECU-internal value to a physical value for easy readability.

Data Types: `char` | `string`

**DisplayIdentifier** – Display name of the outport

character vector | string scalar

Optional display name of the outport for the measurement purpose in the calibration tool, which is different than the outport name in the Simulink model.

Data Types: `char` | `string`

**Format** – Display format of the outport value

`%[length].[layout]`

Special display format to be specified for measurement in the calibration tool. This format specification overrides the display format specified in `CompuMethod` of the outport.

## Version History

**Introduced in R2020b**

### See Also

`coder.mapping.api.CodeMapping` | `coder.mapping.api.get` | `find` | `getDataDefault` | `getOutport` | `setDataDefault`

### Topics

“Configure Root-Level Outport Blocks for C Code Generation”

“C Code Generation Configuration for Model Interface Elements”

# setSignal

Configure block signal data for code and calibration file (a2l) generation

## Syntax

```
setSignal(myCodeMappingObj, portHandle, Name, Value)
```

## Description

`setSignal(myCodeMappingObj, portHandle, Name, Value)` configures signals specified by block output ports for code and calibration file (a2l) generation. Use this function to map specified block output ports to the storage class and storage class property settings that the code generator uses to produce C code. Or, set the calibration access for the corresponding signal data.

This function does not apply to signals that originate from root-level Inport blocks. For signals that originate from root-level Inport blocks, see `setInport`.

## Examples

### Configure Storage Class for Block Output Signals

In the model code mappings for model `rtwdemo_configrpinterface`, set the storage class for output signals of lookup table blocks `Table1` and `Table2D` to `ExportedGlobal`. After creating the object `cm` by calling function `coder.mapping.api.get`, get handles to the output ports for lookup table blocks. Set the storage class for the output signals by calling `setSignal`.

```
open_system('rtwdemo_configrpinterface');
cm = coder.mapping.api.get('rtwdemo_configrpinterface');
lut1_ports = get_param('rtwdemo_configrpinterface/Table1', 'PortHandles');
lut2_ports = get_param('rtwdemo_configrpinterface/Table2', 'PortHandles');
lut1_outPort = lut1_ports.Outport;
lut2_outPort = lut2_ports.Outport;
addSignal(cm, [lut1_outPort, lut2_outPort]);
setSignal(cm, [lut1_outPort, lut2_outPort], 'StorageClass', 'ExportedGlobal');
```

### Configure Storage Class for Signal Data in Model Code Mappings to Model default

In the model code mappings for model `rtwdemo_configrpinterface`, set the storage class for block output signals to `Model default`. After creating the object `cm` by calling function `coder.mapping.api.get`, get the port handles of the signal data in the code mappings. Set the storage class for the signals by calling `setSignal`.

```
open_system('rtwdemo_configrpinterface');
cm = coder.mapping.api.get('rtwdemo_configrpinterface');
portHandles = find(cm, 'Signals')
setSignal(cm, portHandles, 'StorageClass', 'Model default');
```

### Configure Code Identifiers for Block Output Signals

In the model code mappings for model `rtwdemo_configrpinterface`, set the code identifiers for output signals of lookup table blocks `Table1` and `Table2` to `dout_Table1` and `dout_Table2`. After creating the object `cm` by calling function `coder.mapping.api.get`, get handles to the output ports for lookup table blocks. Set the code identifiers for the output signals by calling `setSignal`.

```
open_system('rtwdemo_configrpinterface');
cm = coder.mapping.api.get('rtwdemo_configrpinterface');
lut1_ports = get_param('rtwdemo_configrpinterface/Table1','PortHandles');
lut2_ports = get_param('rtwdemo_configrpinterface/Table2','PortHandles');
lut1_outPort = lut1_ports.Outport;
lut2_outPort = lut2_ports.Outport;
addSignal(cm,[lut1_outPort,lut2_outPort]);
setSignal(cm,lut1_outPort,'Identifier','dout_Table1D');
setSignal(cm,lut2_outPort,'Identifier','dout_Table2D');
```

### Configure Calibration Properties for Signal

In the model code mappings for model `rtwdemo_configrpinterface`, configure the calibration properties for signal `Signal_1`.

```
open_system('rtwdemo_configrpinterface');
cm = coder.mapping.api.get('rtwdemo_configrpinterface');
lut1_ports = get_param('rtwdemo_configrpinterface/Table1','PortHandles');
lut1_outPort = lut1_ports.Outport;
addSignal(cm,lut1_outPort);
Signal_1 = find(cm,'Signal');
setSignal(cm,Signal_1,'Export',true);
setSignal(cm,Signal_1,'CalibrationAccess','NoCalibration');
setSignal(cm,Signal_1,'CompuMethod','CM_Signal_1');
setSignal(cm,Signal_1,'DisplayIdentifier','Signal_display_name');
setSignal(cm,Signal_1,'Format','%4.2');
```

## Input Arguments

### `myCodeMappingObj` — Code mapping object

CodeMapping object

Code mapping object (model code mappings) returned by a call to function `coder.mapping.api.get`.

Example: `myCM`

### `portHandle` — Output port handle of signal source block

port handle | array of port handles

Signal to add to the code mappings, specified as a handle of an output port of the signal's source block. To specify multiple port handles, use an array.

Example: `portHandle`

Data Types: `port_handle` | array

### Name-Value Pair Arguments

Specify comma-separated pairs of `Name`, `Value` arguments. `Name` is the argument name and `Value` is the corresponding value. `Name` must appear inside quotes. You can specify several name and value



pair arguments as `Name1, Value1, ..., NameN, ValueN`. The order of the name and value pair arguments does not matter.

Example: 'StorageClass' 'ExportedGlobal'

### **StorageClass — Name of storage class**

Auto | Dictionary default | ExportedGlobal | ImportedExtern | ImportedExternPointer | Model default

Storage class to set for the specified signals. The name of a predefined storage class or storage class that is defined in the Embedded Coder Dictionary associated with the model. See “Configure Signal Data for C Code Generation”.

### **Identifier — Name of variable**

character vector | string scalar

Name for the variable that represents the signal data in the generated code.

Data Types: char | string

### **Export — Enable or disable generation of the signal to calibration file (a2l)**

true (default) | false

Enable this property to generate the signal to calibration file (a2l).

### **BitMask — Extract single bits from the signal value**

hexadecimal value

Mask value in hexadecimal format to extract single bits from the signal during calibration. This property is applicable only for integers.

Data Types: hexadecimal

### **CalibrationAccess — Enable or disable calibration of the signal**

NoCalibration (default) | Calibration

Select `Calibration` for the signal to enable the calibration. Select `NoCalibration` to view the value of the signal and disable the calibration.

### **CompuMethod — Name of conversion method**

character vector | string scalar

Name of the method for converting the ECU-internal value to a physical value for easy readability.

Data Types: char | string

### **DisplayIdentifier — Display name of the signal**

character vector | string scalar

Optional display name of the signal for the measurement purpose in the calibration tool, which is different than the signal name in the Simulink model.

Data Types: char | string

### **Format — Display format of the signal value**

%[length].[layout]

Special display format to be specified for measurement in the calibration tool. This format specification overrides the display format specified in `CompuMethod` of the signal.

## **Version History**

**Introduced in R2020b**

### **See Also**

`addSignal` | `coder.mapping.api.CodeMapping` | `coder.mapping.api.get` | `find` | `getDataDefault` | `getSignal` | `removeSignal` | `setDataDefault`

### **Topics**

“Configure Signal Data for C Code Generation”

“C Code Generation Configuration for Model Interface Elements”

# setState

Configure block states for code and calibration file (a2l) generation

## Syntax

```
setState(myCodeMappingObj,block,Name,Value)
```

## Description

setState(myCodeMappingObj,block,Name,Value) configures specified block states for code and calibration file (a2l) generation. Use this function to map specified block states to the storage class and storage class property settings that the code generator uses to produce C code. Or, set the calibration access for the for the states.

## Examples

### Configure Storage Class for Block State

In the model code mappings for model rtwdemo\_configrpinterface, set the storage class for the state X of Unit Delay block Delay to ExportedGlobal.

```
open_system('rtwdemo_configrpinterface');
cm = coder.mapping.api.get('rtwdemo_configrpinterface');
setState(cm,'rtwdemo_configrpinterface/Delay','StorageClass','ExportedGlobal');
```

### Configure Storage Class for Block States in Model to Model default

In the model code mappings for model rtwdemo\_configrpinterface, configure the storage class for block states throughout the model to Model default.

```
open_system('rtwdemo_configrpinterface');
cm = coder.mapping.api.get('rtwdemo_configrpinterface');
blockHandles = find(cm,'States');
setState(cm,blockHandles,'StorageClass','Model default');
```

### Configure Code Identifier for Block State

In the model code mappings for model rtwdemo\_configrpinterface, configure the code identifier for the state X of Unit Delay block Delay to dstate\_X.

```
open_system('rtwdemo_configrpinterface');
cm = coder.mapping.api.get('rtwdemo_configrpinterface');
blockHandles = find(cm,'States');
setState(cm,blockHandles,'StorageClass','Model default');
setState(cm,blockHandles,'Identifier','dstate_X');
```

### Configure Calibration Properties for State of Unit Delay Block

From the model code mappings for model `rtwdemo_configrpinterface`, set the calibration properties configured for state X of Unit Delay block `Delay`.

```
open_system('rtwdemo_configrpinterface');
cm = coder.mapping.api.get('rtwdemo_configrpinterface');
state = find(cm,'State');
setState(cm,state,'Export',true);
setState(cm,state,'CalibrationAccess','Calibration');
setState(cm,state,'CompuMethod','CM_state');
setState(cm,state,'DisplayIdentifier','state_X');
setState(cm,state,'Format','%4.2');
```

## Input Arguments

### **myCodeMappingObj** — Code mapping object

CodeMapping object

Code mapping object (model code mappings) returned by a call to function `coder.mapping.api.get`.

Example: `myCM`

### **block** — Path or handle of block

character vector | string scalar | block handle | cell array of character vectors | cell array of string scalars | cell array of block handles

Path or handle of the block containing the state to configure. To specify multiple block states, use a cell array.

Example: `blockHandle`

Data Types: `char` | `string` | `block_handle` | `cell`

### **Name-Value Pair Arguments**

Specify comma-separated pairs of `Name`, `Value` arguments. `Name` is the argument name and `Value` is the corresponding value. `Name` must appear inside quotes. You can specify several name and value pair arguments as `Name1, Value1, ..., NameN, ValueN`. The order of the name and value pair arguments does not matter.

Example: `'StorageClass' 'ExportedGlobal'`

### **StorageClass** — Name of storage class

`Auto` | `Dictionary default` | `ExportedGlobal` | `ImportedExtern` | `ImportedExternPointer` | `Model default`

Storage class to set for the specified block state. The name of a predefined storage class or storage class that is defined in the Embedded Coder Dictionary associated with the model. See “Configure Block States for C Code Generation”.

### **Identifier** — Name of variable

character vector | string scalar

Name for the variable that represents the block state in the generated code.

Data Types: `char` | `string`

**Export — Enable or disable generation of the block state to calibration file (a2l)**

`true` (default) | `false`

Enable this property to generate the block state to calibration file (a2l).

**BitMask — Extract single bits from the block state value**

hexadecimal value

Mask value in hexadecimal format to extract single bits from the block state during calibration. This property is applicable only for integers.

Data Types: `hexadecimal`

**CalibrationAccess — Enable or disable calibration of the block state**

`NoCalibration` (default) | `Calibration`

Select `Calibration` for the block state to enable the calibration. Select `NoCalibration` to view the value of the block state and disable the calibration.

**CompuMethod — Name of conversion method**

character vector | string scalar

Name of the method for converting the ECU-internal value to a physical value for easy readability.

Data Types: `char` | `string`

**DisplayIdentifier — Display name of the block state**

character vector | string scalar

Optional display name of the block state for the measurement purpose in the calibration tool, which is different than the block state name in the Simulink model.

Data Types: `char` | `string`

**Format — Display format of the block state value**

`%[length].[layout]`

Special display format to be specified for measurement in the calibration tool. This format specification overrules the display format specified in `CompuMethod` of the state.

## Version History

Introduced in R2020b

### See Also

`coder.mapping.api.CodeMapping` | `coder.mapping.api.get` | `find` | `getDataDefault` | `getState` | `setDataDefault`

### Topics

“Configure Block States for C Code Generation”

“C Code Generation Configuration for Model Interface Elements”

## coder.mapping.utils.create

Create code mappings object for configuring data and function interface for C and C++ code generation

### Syntax

```
myCodeMappingObj = coder.mapping.utils.create(model)
myCodeMappingObj = coder.mapping.utils.create(dictionary)
```

### Description

`myCodeMappingObj = coder.mapping.utils.create(model)` creates code mappings environment for the specified model and returns the mappings as object `myCodeMappingObj`. Code mappings associate model data elements and functions with configurations for C or C++ code generation. If code mappings exist for the specified model, the function returns those code mappings.

`myCodeMappingObj = coder.mapping.utils.create(dictionary)` creates C code mappings environment for the specified data dictionary and returns the mappings as object `myCodeMappingObj`. Code mappings associate data elements and functions with configurations for C or C++ code generation. If code mappings exist for the specified data dictionary, the function returns those code mappings.

### Examples

#### Create Code Mappings for Model

For model `myConfigModel`, create C code mappings by calling `coder.mapping.utils.create`. Then, get the code mappings with a call to `coder.mapping.api.get`.

```
myCodeMappingObj = coder.mapping.utils.create('myConfigModel');
myCodeMappingObj = coder.mapping.api.get('myConfigModel');
```

### Input Arguments

#### **model** — Name of model

handle | character vector | string scalar

Model file for which to create and return a code mappings object, specified as a handle or a character vector or string scalar representing the model name. The model must be loaded (for example, by using `load_system`) or open. Omit the `.slx` file extension.

Example: `'myConfigModel'`

Data Types: `char` | `string` | `model_handle`

#### **dictionary** — Name of data dictionary

character vector | string scalar

Data dictionary for which to return code mappings object, specified as a character vector or string scalar representing the dictionary name.

Example: 'exCodeDefs.sldd'

Data Types: char | string

## Output Arguments

### **myCodeMappingObj** — Code mapping object

CodeMapping object | CodeMappingCPP object | CoderDictionary object

The model or dictionary code mappings, returned as a CodeMapping object, a CodeMappingCPP object, or a CoderDictionary object.

| Output                            | Input Object                                      |
|-----------------------------------|---------------------------------------------------|
| coder.mapping.api.CodeMapping     | Simulink model configured for C code generation   |
| coder.mapping.api.CodeMappingCPP  | Simulink model configured for C++ code generation |
| coder.mapping.api.CoderDictionary | Simulink data dictionary                          |

## Version History

Introduced in R2020b

### See Also

coder.mapping.api.get | coder.mapping.api.CodeMapping |  
 coder.mapping.api.CoderDictionary | coder.mapping.api.CodeMappingCPP

### Topics

"C Code Generation Configuration for Model Interface Elements"  
 "Programmatically Configure C++ Interface" (Embedded Coder)

## coder.mapping.api.CoderDictionary

Query and set the code settings of dictionary defaults in an Embedded Coder dictionary within a Simulink data dictionary

### Description

A coder dictionary code mappings object and its related functions enable you to configure C code generation settings for dictionary defaults in an Embedded Coder dictionary within a Simulink data dictionary. For model data categories, code mappings associate data categories with configurations that consist of a storage class and storage class properties. Reduce the effort of preparing a model for code generation by specifying default configurations for categories of data elements across a model.

### Creation

#### Syntax

```
myCoderDictionaryObj = coder.mapping.api.get(dictionary)
myCoderDictionaryObj = coder.mapping.utils.create(dictionary)
```

#### Description

`myCoderDictionaryObj = coder.mapping.api.get(dictionary)` returns the active code mappings for the specified dictionary as object `myCoderDictionaryObj`. Code mappings associate data elements in the data dictionary with configurations for code generation.

If code mappings do not exist, Simulink returns an error. You can create a code mappings object with a call to `coder.mapping.utils.create`.

`myCoderDictionaryObj = coder.mapping.utils.create(dictionary)` creates a code mappings environment for the specified data dictionary and returns the mappings as object `myCoderDictionaryObj`. Code mappings associate data elements and functions with configurations for C or C++ code generation. If code mappings exist for the specified data dictionary, the function returns those code mappings.

#### Input Arguments

##### **dictionary** — Name of data dictionary

character vector | string scalar

Data dictionary for which to return code mappings object, specified as a character vector or string scalar representing the dictionary name.

Example: 'exCodeDefs.sldd'

Data Types: char | string



## Object Functions

`getDataDefault` Get default code settings for data category  
`getFunctionDefault` Get default function customization template or memory section for model functions category

## Examples

### Create Environment to Configure Code Mappings for Data Dictionary

For the data dictionary `exCodeDefs.sldd`, create the environment for configuring the data and functions for code generation. After calling this function, use calls to other functions listed under Object Functions to configure aspects of code generation for the interface elements.

```
coder.mapping.utils.create('exCodeDefs.sldd');
```

## Version History

Introduced in R2021a

### See Also

`coder.mapping.api.CodeMapping` | `coder.mapping.utils.create` |  
`coder.mapping.api.CodeMappingCPP`

### Topics

“C Code Generation Configuration for Model Interface Elements”  
“Programmatically Configure C++ Interface” (Embedded Coder)

## setDataDefault

Set default code settings for data category

### Syntax

```
setDataDefault(myCoderDictionaryObj, category, Name, Value)
```

### Description

`setDataDefault(myCoderDictionaryObj, category, Name, Value)` sets the default storage class and storage class property values in the code mappings for the specified category of model data.

### Examples

#### Configure default code settings for a data category in a data dictionary

Use the `coder.mapping.api.get` function to access the `CoderDictionary` object associated with the data dictionary.

```
cm = coder.mapping.api.get('codeDefinitions.sldd');
```

To see the storage class of root-level inports for the dictionary, use the `getDataDefault` function.

```
value = getDataDefault(cm, 'Inports', 'StorageClass')
```

```
value =
 'Default'
```

The dictionary uses the default storage class for inports.

To configure the storage class, use the `setDataDefault` function.

```
setDataDefault(cm, 'Inports', 'StorageClass', 'ExportedGlobal')
```

To verify that the storage class of inports is now set to `ExportedGlobal`, use the `getDataDefault` function.

```
value = getDataDefault(cm, 'Inports', 'StorageClass')
```

```
value =
 'ExportedGlobal'
```

### Input Arguments

**myCoderDictionaryObj** — Coder dictionary object

`CoderDictionary` object

Coder dictionary object returned by a call to function `coder.mapping.api.get`.

**category — Model data element category**

ExternalParameterObjects | GlobalDataStores | Inports | InternalData |  
ModelParameters | Outports | SharedLocalDataStores

Category of data elements to return a property value for.

Example: 'Inports'

**Name-Value Pair Arguments**

Specify comma-separated pairs of `Name`, `Value` arguments. `Name` is the argument name and `Value` is the corresponding value. `Name` must appear inside quotes. You can specify several name and value pair arguments as `Name1, Value1, ..., NameN, ValueN`. The order of the name and value pair arguments does not matter.

Example: 'StorageClass','ExportedGlobal'

**StorageClass — Name of storage class**

Auto | Dictionary default | ExportedGlobal | ImportedExtern | ImportedExternPointer  
| Model default

Storage class to set for the specified data element category. The name of a predefined storage class or storage class that is defined in the Embedded Coder Dictionary associated with the model. Values that you can specify vary depending on the category that you specify. See “Choose Storage Class for Controlling Data Representation in Generated Code”.

Example: 'StorageClass','ImportedExtern'

## Version History

**Introduced in R2021a**

**See Also**

coder.mapping.api.CoderDictionary | getDataDefault | setFunctionDefault |  
getFunctionDefault

## getDataDefault

Get default code settings for data category

### Syntax

```
value = getDataDefault(myCoderDictionaryObj, category, property)
```

### Description

`value = getDataDefault(myCoderDictionaryObj, category, property)` returns the value from the code mappings of the specified property for the specified data category.

### Examples

#### Configure default code settings for a data category in a data dictionary

Use the `coder.mapping.api.get` function to access the `CoderDictionary` object associated with the data dictionary.

```
cm = coder.mapping.api.get('codeDefinitions.sldd');
```

To see the storage class of root-level inports for the dictionary, use the `getDataDefault` function.

```
value = getDataDefault(cm, 'Inports', 'StorageClass')
```

```
value =
 'Default'
```

The dictionary uses the default storage class for inports.

To configure the storage class, use the `setDataDefault` function.

```
setDataDefault(cm, 'Inports', 'StorageClass', 'ExportedGlobal')
```

To verify that the storage class of inports is now set to `ExportedGlobal`, use the `getDataDefault` function.

```
value = getDataDefault(cm, 'Inports', 'StorageClass')
```

```
value =
 'ExportedGlobal'
```

### Input Arguments

**myCoderDictionaryObj** — Coder dictionary object

`CoderDictionary` object

Coder dictionary object returned by a call to function `coder.mapping.api.get`.

**category — Model data element category**

ExternalParameterObjects | GlobalDataStores | Inports | InternalData | ModelParameters | Outports | SharedLocalDataStores

Category of data elements to return a property value for.

Example: 'Inports'

**property — Code mapping property value to return**

StorageClass | Identifier

Code mapping property that you return a value for. Specify one of these property names.

| Information to Return                                                                                               | Property Name |
|---------------------------------------------------------------------------------------------------------------------|---------------|
| Name of storage class                                                                                               | StorageClass  |
| Name of variable for data element in the generated code                                                             | Identifier    |
| Character vector or string scalar that names a memory section for a model defined in the Embedded Coder Dictionary. | MemorySection |

Example: 'Identifier'

**Output Arguments**

**value — Code mapping property value of category**

character vector

The code mapping property value of the specified category, returned as a character vector.

**Version History**

Introduced in R2021a

**See Also**

coder.mapping.api.CoderDictionary | setDataDefault | setFunctionDefault | getFunctionDefault

## setFunctionDefault

Set default function customization template and memory section for model functions category

### Syntax

```
setFunctionDefault(myCoderDictionaryObj, category, Name, Value)
```

### Description

`setFunctionDefault(myCoderDictionaryObj, category, Name, Value)` sets the default function customization template and memory section for the specified category of model entry-point functions.

### Examples

#### Configure the default memory section for a data category

Use the `coder.mapping.api.get` function to access the `CoderDictionary` object associated with the data dictionary.

```
cm = coder.mapping.api.get('codeDefinitions.sldd');
```

To see the memory section for Execution functions in the dictionary, use the `getFunctionDefault` function.

```
value = getFunctionDefault(cm, 'Execution', 'MemorySection')
```

```
value =
 'None'
```

To configure the memory section for the category, use the `setFunctionDefault` function.

```
setFunctionDefault(cm, 'Execution', 'MemorySection', 'functionFastMem')
```

To verify that the memory section for the Execution category is now set to `functionFastMem`, use the `getFunctionDefault` function.

```
value = getFunctionDefault(cm, 'Execution', 'MemorySection')
```

```
value =
 'functionFastMem'
```

### Input Arguments

**myCoderDictionaryObj** — Coder dictionary object

`CoderDictionary` object

Coder dictionary object returned by a call to function `coder.mapping.api.get`.

**category — Model function category**

InitializeTerminate | Execution | SharedUtility

Category of model entry-point functions for which to set the function customization template and memory section.

Example: 'Execution'

**Name-Value Pair Arguments**

Specify comma-separated pairs of `Name`, `Value` arguments. `Name` is the argument name and `Value` is the corresponding value. `Name` must appear inside quotes. You can specify several name and value pair arguments as `Name1, Value1, ..., NameN, ValueN`. The order of the name and value pair arguments does not matter.

Example: 'FunctionCustomizationTemplate' 'exFastFunction'

**FunctionCustomizationTemplate — Name of function customization template**

character vector | string scalar

Name of a function customization template defined in the Embedded Coder Dictionary associated with the model. If you set the default function customization template for a category of functions to `Default`, you can specify a memory section for the category of functions.

Data Types: char | string

**MemorySection — Name of memory section**

None | MemConst | MemVolatile | MemConstVolatile | internalDataMem | functionFastMem | functionSlowMem

Name of a memory section that is defined in the Embedded Coder Dictionary associated with the model.

Data Types: char | string

**Version History****Introduced in R2021a****See Also**

coder.mapping.api.CoderDictionary | setDataDefault | getDataDefault | getFunctionDefault

## getFunctionDefault

Get default function customization template or memory section for model functions category

### Syntax

```
propertyValue = getFunctionDefault(myCoderDictionaryObj, category, property)
```

### Description

`propertyValue = getFunctionDefault(myCoderDictionaryObj, category, property)` returns the value of the specified property for the specified function category.

### Examples

#### Configure the default memory section for a data category

Use the `coder.mapping.api.get` function to access the `CoderDictionary` object associated with the data dictionary.

```
cm = coder.mapping.api.get('codeDefinitions.sldd');
```

To see the memory section for Execution functions in the dictionary, use the `getFunctionDefault` function.

```
value = getFunctionDefault(cm, 'Execution', 'MemorySection')
```

```
value =
 'None'
```

To configure the memory section for the category, use the `setFunctionDefault` function.

```
setFunctionDefault(cm, 'Execution', 'MemorySection', 'functionFastMem')
```

To verify that the memory section for the Execution category is now set to `functionFastMem`, use the `getFunctionDefault` function.

```
value = getFunctionDefault(cm, 'Execution', 'MemorySection')
```

```
value =
 'functionFastMem'
```

### Input Arguments

**myCoderDictionaryObj** — Coder dictionary object

`CoderDictionary` object

Coder dictionary object returned by a call to function `coder.mapping.api.get`.



**category — Model function category**`InitializeTerminate | Execution | SharedUtility`

Category of model entry-point functions for which to set the function customization template and memory section.

Example: 'Execution'

**property — Function customization template or memory section**`FunctionCustomizationTemplate | MemorySection`

FunctionCustomizationTemplate or MemorySection for which to return a value.

Example: 'FunctionCustomizationTemplate'

**Output Arguments****propertyValue — Name of function customization template or memory section**`character vector | string scalar`

Name of the function customization template or memory section.

Data Types: `char` | `string`

**Version History**

**Introduced in R2021a**

**See Also**

`coder.mapping.api.CoderDictionary` | `setDataDefault` | `getDataDefault` | `setFunctionDefault`

## **coder.report.close**

Close HTML code generation report

### **Syntax**

```
coder.report.close()
```

### **Description**

`coder.report.close()` closes the HTML code generation report.

### **Examples**

#### **Close code generation report for a model**

After opening a code generation report for `rtwdemo_counter`, close the report.

```
coder.report.close()
```

## **Version History**

**Introduced in R2012a**

### **See Also**

`coder.report.open` | `coder.report.generate`

### **Topics**

“Reports for Code Generation”

# coder.report.generate

Generate HTML code generation report

## Syntax

```
coder.report.generate(model)
coder.report.generate(subsystem)
coder.report.generate(model,Name,Value)
```

## Description

`coder.report.generate(model)` generates a code generation report for the `model`. The build folder for the model must be present in the current working folder.

`coder.report.generate(subsystem)` generates the code generation report for the `subsystem`. The build folder for the subsystem must be present in the current working folder.

`coder.report.generate(model,Name,Value)` generates the code generation report using the current model configuration and additional options specified by one or more `Name,Value` pair arguments. Possible values for the `Name,Value` arguments are parameters on the **Code Generation > Report** pane. Without modifying the model configuration, using the `Name,Value` arguments you can generate a report with a different report configuration.

## Examples

### Generate Code Generation Report for Model

Open the model `rtwdemo_counter`.

```
open rtwdemo_counter
```

Build the model. The model is configured to create and open a code generation report.

```
slbuild('rtwdemo_counter');
```

Close the code generation report.

```
coder.report.close;
```

Generate a code generation report.

```
coder.report.generate('rtwdemo_counter');
```

### Generate Code Generation Report for Subsystem

Open the model `rtwdemo_counter`.

```
open rtwdemo_counter
```

Build the subsystem. The model is configured to create and open a code generation report.

```
slbuild('rtwdemo_counter/Amplifier');
```

Close the code generation report.

```
coder.report.close;
```

Generate a code generation report for the subsystem.

```
coder.report.generate('rtwdemo_counter/Amplifier');
```

### **Generate Code Generation Report to Include Static Code Metrics Report**

Generate a code generation report to include a static code metrics report after the build process, without modifying the model.

Open the model `rtwdemo_hyperlinks`.

```
open rtwdemo_hyperlinks
```

Build the model. The model is configured to create and open a code generation report.

```
slbuild('rtwdemo_hyperlinks');
```

Close the code generation report.

```
coder.report.close;
```

Generate a code generation report that includes the static code metrics report.

```
coder.report.generate('rtwdemo_hyperlinks', ...
'GenerateCodeMetricsReport', 'on');
```

The code generation report opens. In the left navigation pane, click **Static Code Metrics Report** to view the report.

## **Input Arguments**

### **model** — Model name

character vector

Model name specified as a character vector

Example: 'rtwdemo\_counter'

Data Types: char

### **subsystem** — Subsystem name

character vector

Subsystem name specified as a character vector

Example: 'rtwdemo\_counter/Amplifier'

Data Types: char

## Name-Value Pair Arguments

Specify optional pairs of arguments as `Name1=Value1, . . . ,NameN=ValueN`, where `Name` is the argument name and `Value` is the corresponding value. Name-value arguments must appear after other arguments, but the order of the pairs does not matter.

*Before R2021a, use commas to separate each name and value, and enclose `Name` in quotes.*

Each `Name, Value` argument corresponds to a parameter on the Configuration Parameters **Code Generation > Report** pane. When the configuration parameter `GenerateReport` is on, the parameters are enabled. The `Name, Value` arguments are used only for generating the current report. The arguments will override, but not modify, the parameters in the model configuration. The following parameters require an Embedded Coder license.

Example: `'GenerateWebview','on','GenerateCodeMetricsReport','on'` includes a model Web view and static code metrics in the code generation report.

## Navigation

### IncludeHyperlinkInReport — Code-to-model hyperlinks

`'off' | 'on'`

Code-to-model hyperlinks, specified as `'on'` or `'off'`. Specify `'on'` to include code-to-model hyperlinks in the code generation report. The hyperlinks link code to the corresponding blocks, Stateflow<sup>®</sup> objects, and MATLAB<sup>®</sup> functions in the model diagram. For more information see Code-to-model (Embedded Coder).

Example: `'IncludeHyperlinkInReport','on'`

Data Types: char

### GenerateTraceInfo — Model-to-code highlighting

`'off' | 'on'`

Model-to-code highlighting, specified as `'on'` or `'off'`. Specify `'on'` to include model-to-code highlighting in the code generation report. For more information see Model-to-code (Embedded Coder).

Example: `'GenerateTraceInfo','on'`

Data Types: char

### GenerateWebview — Model Web view

`'off' | 'on'`

Model Web view, specified as `'on'` or `'off'`. Specify `'on'` to include the model Web view in the code generation report. For more information, see Generate model Web view (Embedded Coder).

Example: `'GenerateWebview','on'`

Data Types: char

## Traceability Report Contents

### GenerateTraceReport — Summary of eliminated and virtual blocks

`'off' | 'on'`

Summary of eliminated and virtual blocks, specified as 'on' or 'off'. Specify 'on' to include a summary of eliminated and virtual blocks in the code generation report. For more information, see [Eliminated / virtual blocks \(Embedded Coder\)](#).

Example: `'GenerateTraceReport','on'`

Data Types: char

### **GenerateTraceReportSl — Summary of Simulink blocks and the corresponding code location**

'off' | 'on'

Summary of the Simulink blocks and the corresponding code location, specified as 'on' or 'off'. Specify 'on' to include a summary of the Simulink blocks and the corresponding code location in the code generation report. For more information, see [Traceable Simulink blocks \(Embedded Coder\)](#).

Example: `'GenerateTraceReportSl','on'`

Data Types: char

### **GenerateTraceReportsSf — Summary of Stateflow objects and the corresponding code location**

'off' | 'on'

Summary of the Stateflow objects and the corresponding code location, specified as 'on' or 'off'. Specify 'on' to include a summary of Stateflow objects and the corresponding code location in the code generation report. For more information, see [Traceable Stateflow objects \(Embedded Coder\)](#).

Example: `'GenerateTraceReportSf','on'`

Data Types: char

### **GenerateTraceReportEmL — Summary of MATLAB functions and the corresponding code location**

'off' | 'on'

Summary of the MATLAB functions and the corresponding code location, specified as 'on' or 'off'. Specify 'on' to include a summary of the MATLAB objects and the corresponding code location in the code generation report. For more information, see [Traceable MATLAB functions \(Embedded Coder\)](#).

Example: `'GenerateTraceReportEmL','on'`

Data Types: char

## **Metrics**

### **GenerateCodeMetricsReport — Static code metrics**

'off' | 'on'

Static code metrics, specified as 'on' or 'off'. Specify 'on' to include static code metrics in the code generation report. For more information, see [Generate static code metrics \(Embedded Coder\)](#).

Example: `'GenerateCodeMetricsReport','on'`

Data Types: char

## **Version History**

**Introduced in R2012a**

## **See Also**

`coder.report.open` | `coder.report.close`

## **Topics**

“Reports for Code Generation”

“Generate Code Generation Report Programmatically” (Embedded Coder)

## **coder.report.open**

Open existing HTML code generation report

### **Syntax**

```
coder.report.open(model)
coder.report.open(subsystem)
```

### **Description**

`coder.report.open(model)` opens a code generation report for the `model`. The build folder for the model must be present in the current working folder.

`coder.report.open(subsystem)` opens a code generation report for the `subsystem`. The build folder for the subsystem must be present in the current working folder.

### **Examples**

#### **Open code generation report for a model**

After generating code for `rtwdemo_counter`, open a code generation report for the model.

```
coder.report.open('rtwdemo_counter')
```

#### **Open code generation report for a subsystem**

Open a code generation report for the subsystem 'Amplifier' in model 'rtwdemo\_counter'.

```
coder.report.open('rtwdemo_counter/Amplifier')
```

### **Input Arguments**

#### **model — Model name**

character vector

Model name specified as a character vector

Example: 'rtwdemo\_counter'

Data Types: char

#### **subsystem — Subsystem name**

character vector

Subsystem name specified as a character vector

Example: 'rtwdemo\_counter/Amplifier'

Data Types: char



## **Version History**

**Introduced in R2012a**

### **See Also**

`coder.report.close` | `coder.report.generate`

### **Topics**

“Reports for Code Generation”

“Generate Code Generation Report” (Embedded Coder)

## **coder.cdf.export**

Generate CDF (Calibration Data Format) file according to ASAM AE CDF standards

### **Syntax**

```
coder.cdf.export(modelName)
coder.cdf.export(modelName,Name=Value)
```

### **Description**

`coder.cdf.export(modelName)` generates a CDF file for `modelName`.

`coder.cdf.export(modelName,Name=Value)` specifies additional options for CDF file creation with one or more Name, Value pair arguments. For example, you can specify a location where to save the CDF file.

### **Examples**

#### **Generate CDF File for Model**

Generate a CDF file for the selected model and save it in the build folder of the model.

```
% Generate CDF file for model
coder.cdf.export('modelName')
```

#### **Generate CDF File and Save it with a Custom Name**

Generate a CDF file for the selected model and save it with the custom name specified.

```
% Export CDF file and save it as
coder.cdf.export('modelName',FileName='test_car')
```

#### **Generate CDF File at Specified Location**

Generate a CDF file for the selected model and save it in the specified folder.

```
% Export CDF file to specified path
coder.cdf.export('modelName',Folder='/home/temp/workspace/')
```

#### **Generate CDF File with Specified Schema Type**

Generate a CDF file of the specified schema type for the selected model.

```
% Export CDF file with dtd schema type
coder.cdf.export('modelName', SchemaType='DTD')
```

## Input Arguments

### **modelName** — name of the model

character vector | string scalar

Name of the model.

Example: 'MyModel', 'nav\_app'

### **Name-Value Pair Arguments**

Specify optional pairs of arguments as `Name1=Value1, ..., NameN=ValueN`, where `Name` is the argument name and `Value` is the corresponding value. Name-value arguments must appear after other arguments, but the order of the pairs does not matter.

*Before R2021a, use commas to separate each name and value, and enclose Name in quotes.*

Example: `Folder='/home/applications'` generate a CDF file for the model and saves it in a specified folder.

### **Folder** — Folder location for exported CDF file

character vector | string scalar

Full path to a folder in which to place an exported CDF file.

Example: `Folder='/home/temp/prjct/'`

### **FileName** — Custom name for the exported CDF file

character vector | string scalar

Name for the CDF file to save it as in the folder.

Example: `FileName='test_car'`

### **SchemaType** — Schema type for CDF file

DTD (default) | XSD

Schema type for the CDF file can be XSD (XML Schema Definition) or DTD (Document Type Definition).

Example: `SchemaType='DTD'`

## Version History

**Introduced in R2021a**

### **See Also**

`coder.asap2.export`

### **Topics**

“Generate ASAP2 and CDF Calibration Files”

## coder.asap2.export

Generate ASAP2 (A2L) file according to ASAM MCD-2 MC standards

### Syntax

```
coder.asap2.export(modelName)
coder.asap2.export(modelName,Name=Value)
```

### Description

`coder.asap2.export(modelName)` generates an ASAP2 (A2L) file for `modelName`. The ASAP2 (A2L) file generated for a top model contains information from the referenced models.

`coder.asap2.export(modelName,Name=Value)` specifies additional options for ASAP2 (A2L) creation with one or more "Name=Value" arguments. For example, you can specify a location where to save the A2L file. You can provide the symbol file of the model to replace ECU addresses in the A2L file.

### Examples

#### Generate ASAP2 File for Model

Generate an A2L file for the selected model and save it in the build folder of the model.

```
% Generate A2L file for model
coder.asap2.export('modelName')
```

#### Generate A2L File by Using Customizations

Generate an A2L file by modifying the name of ASAP2 file, location where to save it, version of A2L to be generated, and excluding comments.

```
% Export A2L file and save it as
coder.asap2.export('modelName',FileName='test_car')

% Export A2L file to specified path
coder.asap2.export('modelName',Folder='/home/temp/workspace/')

% Generate A2L file with version 1.71
coder.asap2.export('modelName',Version='1.71')

% Generate A2L file with comments excluded
coder.asap2.export('modelName',Comments=false)
```

### Generate ASAP2 File for Model by Using Symbol File

Generate an A2L file for the selected model that has ECU addresses based on the ELF symbol file associated with the executable.

```
% Generate A2L file for model
coder.asap2.export('modelName',MapFile='model.elf')
```

### Exclude A2ML and IF\_DATA Sections from Generated A2L File

Generate an A2L file for the selected model and exclude the A2ML and IF\_DATA sections.

```
% Generate A2L file with A2ML and IF_DATA excluded
coder.asap2.export('modelName',GenerateXCPIInfo=false)
```

### Generate ASAP2 File by Using Custom Model Class Instance Name

Specify the name of the model class instance. The objName is declared in the global namespace.

```
% Use custom specified name as object name in A2L file
coder.asap2.export('modelName',ModelClassName='objName')

% Specify the name of model class instance declared inside the namespace. Here instance customObj
% is declared in customNameSpace
coder.asap2.export('modelName',ModelClassName='customNamespace::customObj')
```

### Generate ASAP2 File by Using Customized ASAP2 Fields

Create a custom base object and specify the fields. Customize the contents of the A2L file by using a custom base object.

```
% Create custom base object and provide fields you want to modify
obj = coder.asap2.UserCustomizeBase;
obj.HeaderComment = 'Header comment';
obj.ModParComment = 'Mod Par comment';
obj.ModCommonComment = 'Mod Common comment';
obj.ASAP2FileName = 'File name';
obj.ByteOrder = 'BYTE_ORDER_MSB_LAST';

% Generate A2L file with custom base created
coder.asap2.export('modelName',CustomizationObject=obj);
```

### Generate ASAP2 File by Grouping Parameters and Measurements

Group the parameters and measurements into arrays, scalars, maps, and curves by using this command:

```
coder.asap2.export('modelName',CustomizeGroupsBy={'ARRAY','SCALAR','MAP','CURVE'});
```

### Export Record Layouts

Export the record layouts of the base data types to a file named RecordLayouts.a2l.

```
coder.asap2.export('modelName', IncludeAllRecordLayouts=true)
```

### Generate ASAP2 File by Excluding Structures

Exclude structure elements by using this command:

```
coder.asap2.export('modelName', SupportStructureElements=false);
```

### Generate ASAP2 File by Excluding 64-Bit Elements

Exclude 64-bit integers by using this command:

```
coder.asap2.export('modelName', Support64bitIntegers=false);
```

### Generate ASAP2 File by Specifying ECU Address Extension

Specify additional address information in the A2L file by using this command:

```
coder.asap2.export('modelName', EcuAddressExtension=4);
```

### Generate ASAP2 File by Excluding RTE Elements

Exclude AUTOSAR RTE elements in the A2L file for a classic AUTOSAR model by using this command:

```
coder.asap2.export('classicautosar-modelName', IncludeAutosarRteElements=false);
```

### Generate ASAP2 File Using the Saved Preferences

Generate the ASAP2 file using the settings updated by using this command:

```
coder.asap2.export('modelName', UseSavedSettings=false);
```

### Generate ASAP2 File by Excluding RTE Elements

Exclude AUTOSAR RTE elements in the A2L file for a classic AUTOSAR model by using this command:

```
coder.asap2.export('classicautosar-modelName', IncludeAutosarRteElements=false);
```

### Generate ASAP2 File by Updating Array Layout

Export ASAP2 file by modifying the array layout to view the array data in required format by using this command:

```
coder.asap2.export('modelName', ToggleArrayLayout=true);
```

## Input Arguments

### modelName — name of the model

character vector | string scalar

Name of the model.

Example: 'MyModel', 'nav\_app'

### Name-Value Pair Arguments

Specify optional pairs of arguments as `Name1=Value1, ..., NameN=ValueN`, where `Name` is the argument name and `Value` is the corresponding value. Name-value arguments must appear after other arguments, but the order of the pairs does not matter.

*Before R2021a, use commas to separate each name and value, and enclose Name in quotes.*

Example: `MapFile='model.elf'` generates an A2L file for the model containing debug mapping information from the `model.elf` file.

### Folder — Folder location to export A2L file

character vector | string scalar

Full path to a folder in which to place an exported A2L file.

Example: `Folder='/home/temp/prjct/'`

### FileName — Custom name for the exported A2L file

character vector | string scalar

Name for the exported A2L file.

Example: `FileName='test_car'`

### MapFile — Name of symbol file for model

ELF | PDB | DWARF | executable

Name of the model symbol file that contains symbols of generated code. For example, the addresses of variables used in generated code.

Example: `MapFile='model.elf'`

### Version — Version of A2L file

1.71 (default) | 1.31 | 1.61

A2L file format based on the ASAM MCD-2 MC standard defined by ASAM. There are multiple versions of the ASAM MCD-2 MC standard. Specify the version of A2L that you want.

Example: `Version='1.61'` or `Version='1.31'`

### Comments — Include comments in A2L file

true (default) | false

Generate the A2L file by including or excluding comments.

Example: `Comments=true`

**GenerateXCPIInfo — Include A2ML and IF\_DATA in A2L file**

true (default) | false

Generate the A2L file by including or excluding A2ML and IF\_DATA sections.

Example: `GenerateXCPIInfo=true`

**ModelClassName — Specify class instance and path names**

character vector | string scalar

Custom model instance name in an A2L file. This argument is applicable only for Adaptive AUTOSAR models.

Example: `ModelClassName='customObj'` or  
`ModelClassName='customNameSpace::customObj'`

**IndentFile — Follow indentation in A2L file**

false (default) | true

Generate an A2L file by following indentation.

Example: `IndentFile=true`

**CustomizationObject — Customize ASAP2 fields**

coder.asap2.UserCustomizeBase object (default)

Create a user base and customize the ASAP2 fields such as:

- `ASAP2FileName`
- `ByteOrder`
- `HeaderComment`
- `ModParComment`
- `ModCommonComment`

Example: `CustomizationObject=obj`

**CustomizeGroupsBy — Customize groups in ASAP2 file**

ARRAY | SCALAR | MAP | CUBOID | CURVE | CUBE\_4 | CUBE\_5

Group the parameters and signals based on their properties.

Example: `CustomizeGroupsBy={'ARRAY','MAP'}`

**IncludeAllRecordLayouts — Export record layouts of the base data types**

false (default) | true

Export record layouts of all the base data types to a file named `RecordLayouts.a2l` according to the version of the A2L file.

Example: `IncludeAllRecordLayouts=true`

**SupportStructureElements — Include or exclude the structure elements in ASAP2 file**

true (default) | false

Specify `false` to exclude elements that are part of the structure in the generated ASAP2 file.

Example: `SupportStructureElements=false`



**Support64bitIntegers — Include or exclude the 64-bit integers in ASAP2 file**

true (default) | false

Specify false to exclude 64-bit integers in the generated ASAP2 file.

Example: Support64bitIntegers=false

**EcuAddressExtension — Specify additional address information**

int

Specify a 32-bit integer value to specify additional address information in the ASAP2 file. By default, no additional address information is required.

Example: EcuAddressExtension=4

**CustomEcuDescriptions — Update the ECU descriptions**

ECU description object

Update the current ECU description in the ASAP2 file to custom values by creating and providing a description object.

Example: CustomEcuDescriptions=description\_object

**IncludeAutosarRteElements — Export RTE elements**

true (default) | false

Generate the A2L file by including or excluding the AUTOSAR RTE elements.

---

**Note** This option is applicable only for Classic AUTOSAR models.

---

Example: IncludeAutosarRteElements=true

**UseSavedSettings — Save and use the preferences**

false (default) | true

Save the preferences made and generate the ASAP2 file with the preferences updated such as including the comments, version of the ASAP2 file.

Example: UseSavedSettings=false

**IncludeDefaultEventList — Create default event**

true (default) | false

Specify true to include a default event list in the A2L file.

Example: IncludeDefaultEventList=true

**ToggleArrayLayout — Modify the array layout**

false (default) | true

Update the array layout to ROW\_DIR or COL\_DIR to view the array data in row wise or column wise.

Example: ToggleArrayLayout=true

## **Version History**

**Introduced in R2021a**

### **Applicable for SLRT Models**

The function is now applicable for Simulink Real-Time models. Additional name=value pairs are added to save the preferences of ASAP2 file generation, include the default event list, and toggle array layout.

For classic AUTOSAR models, use the function to include/exclude RTE elements.

### **Additional Name=Value pairs**

Additional name=value pairs are added to include/exclude structure elements, 64-bit integers, and add custom ECU descriptions to the ASAP2 file.

### **See Also**

`coder.cdf.export`

### **Topics**

“Generate ASAP2 and CDF Calibration Files”

“Customize Generated ASAP2 File”

# coder.asap2.AxisInfo

Set values for axis to describe lookup table

## Syntax

```
axis = coder.asap2.AxisInfo()
```

## Description

`axis = coder.asap2.AxisInfo()` creates an axis object. You can use the object to define axis for a lookup table element and export it to the ASAP2 file.

## Examples

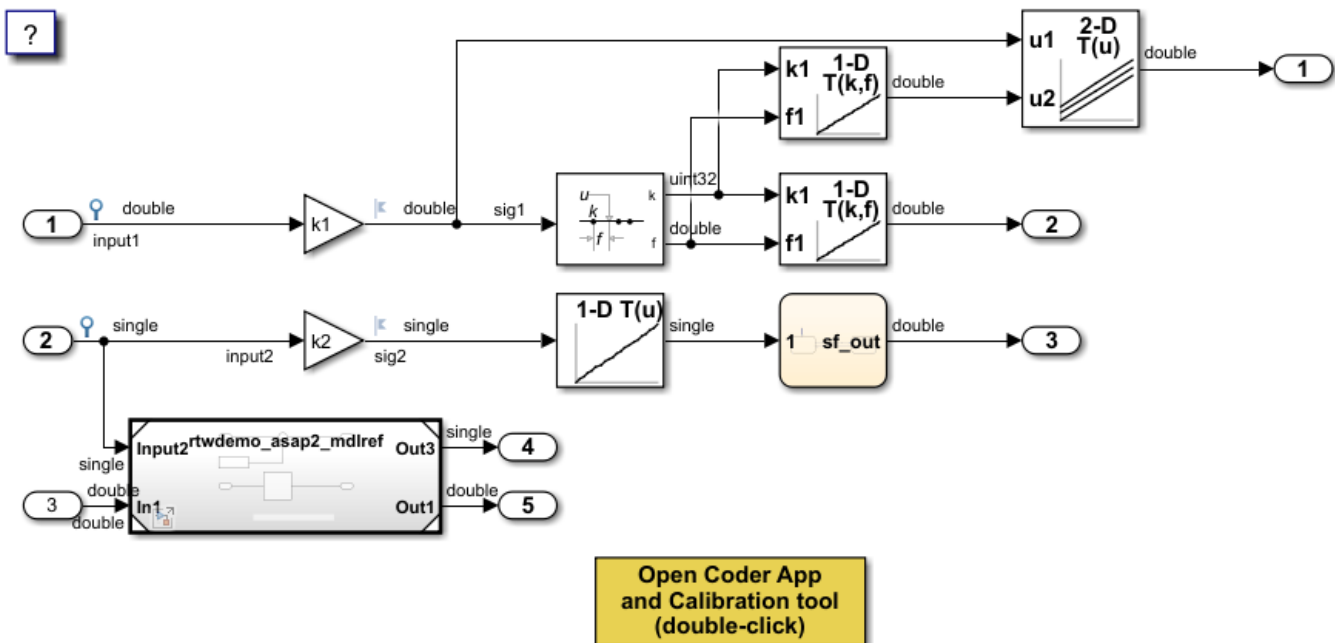
### Customize an ASAP2 File

This example shows how to add, update, filter, find, and remove ECU descriptions in an ASAP2 file.

### Open and build the example model

Open the example model `rtwdemo_asap2`

```
open_system("rtwdemo_asap2");
```



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Build the model.

```

rtwbuild("rtwdemo_asap2");

Starting serial model reference code generation build.
Successfully updated the model reference code generation target for: rtwdemo_asap2_mdref
Starting build procedure for: rtwdemo_asap2
Successful completion of build procedure for: rtwdemo_asap2

Build Summary

Code generation targets built:

Model Action Rebuild Reason
=====
rtwdemo_asap2_mdref Code generated and compiled. rtwdemo_asap2_mdref.c does not exist.

Top model targets built:

Model Action Rebuild Reason
=====
rtwdemo_asap2 Code generated and compiled. Code generation information file does not exist.

2 of 2 models built (0 models already up to date)
Build duration: 0h 0m 30.237s

```

Create the ECU description object for the model.

```
descObj=coder.asap2.getEcuDescriptions("rtwdemo_asap2");
```

Get the list of available compu methods in the description object using the command:

```

find(descObj,"CompuMethod")

ans = 1x10 string
 Columns 1 through 3
 "rtwdemo_asap2_CM..." "rtwdemo_asap2_CM..." "rtwdemo_asap2_CM..."
 Columns 4 through 6
 "rtwdemo_asap2_CM..." "rtwdemo_asap2_CM..." "rtwdemo_asap2_CM..."
 Columns 7 through 9
 "rtwdemo_asap2_CM..." "rtwdemo_asap2_CM..." "rtwdemo_asap2_md..."
 Column 10
 "rtwdemo_asap2_md..."

```

Filter the compu methods and get the list of compu methods with units as "rpm".

```

find(descObj,"CompuMethod",Units='rpm')

ans = 1x3 string
 "rtwdemo_asap2_CM..." "rtwdemo_asap2_CM..." "rtwdemo_asap2_md..."

```

## Create and Add a Custom Compu Method

To add a new compu method to the ASAP2 file, create a custom compu method using the commands:

```
CompuMethod_CM1 = coder.asap2.CompuMethod;
CompuMethod_CM1.Name = 'CompuMethod_1';
CompuMethod_CM1.ConversionType = 'LINEAR';
CompuMethod_CM1.Coefficients = [2 3];
CompuMethod_CM1.LongIdentifier = 'longIdentifierTest';
CompuMethod_CM1.Format = '%2.3';
CompuMethod_CM1.Units = 's';
```

Add the custom compu method to the ECU description object using the command:

```
add(descObj, CompuMethod_CM1);
```

Get the properties of the newly added compu method using the command:

```
get(descObj, "CompuMethod", "CompuMethod_1")
```

```
ans =
 CompuMethod with properties:
 Name: 'CompuMethod_1'
 LongIdentifier: 'longIdentifierTest'
 Format: '%2.3'
 Units: 's'
 Coefficients: [2 3]
 ConversionType: 'LINEAR'
 CompuVTabValues: [1x1 struct]
```

To modify any property of the compu method, use set function. Update the "LongIdentifier" field of the compu method using the command:

```
set(descObj, "CompuMethod", "CompuMethod_1", LongIdentifier="longIdentifierCM1")
```

Generate the ASAP2 file using the updated ECU description object and verify that the ASAP2 file contains the compu method with name "CompuMethod\_1".

```
coder.asap2.export("rtwdemo_asap2", CustomEcuDescriptions=descObj);
```

Following Characteristics or Measurements with unsupported data types are not exported in ASAP2

## Delete a Compu Method

Remove the newly added compu method from the description object using the command:

```
delete(descObj, "CompuMethod", "CompuMethod_1");
```

## Create and Add Custom Characteristic

To add a new characteristic to the ASAP2 file, create a custom characteristic using the commands:

```
Parameter_1 = coder.asap2.Characteristic;
Parameter_1.Name = 'Custom_parameter1';
Parameter_1.LongIdentifier = 'longIdentifierParam';
Parameter_1.UpperLimit = 255;
Parameter_1.LowerLimit = 0;
```

Add the custom characteristic to the ECU description object using the command:

```
add(descObj,Parameter_1);
```

Get the properties of the newly added characteristic using the command:

```
get(descObj,"Characteristic","Custom_parameter1")
```

```
ans =
```

```
Characteristic with properties:
```

```
 Name: 'Custom_parameter1'
 LongIdentifier: 'longIdentifierParam'
 Type: 'VALUE'
 EcuAddress: '0x0000'
 CompuMethodName: 'NO_COMPU_METHOD'
 LowerLimit: 0
 UpperLimit: 255
 EcuAddressComment: ''
 EcuAddressExtension: []
 CalibrationAccess: 'Calibration'
 DisplayIdentifier: ''
 Format: ''
 BitMask: []
 AxisInfo: []
 RecordLayout: ''
 Dimensions: []
 Export: 1
 SymbolLink: [1x1 struct]
```

To modify any property of the characteristic, use set function. Update the "UpperLimit" field of the characteristic using the command:

```
set(descObj,"Characteristic","Custom_parameter1",UpperLimit=128)
```

Generate the ASAP2 file using the updated ECU description object and verify that the ASAP2 file contains the characteristic with name "Custom\_parameter1".

```
coder.asap2.export("rtwdemo_asap2",CustomEcuDescriptions=descObj);
```

Following Characteristics or Measurements with unsupported data types are not exported in ASAP2

Remove the newly added characteristic from the description object using the command:

```
delete(descObj,"Characteristic","Custom_parameter1");
```

### **Create and Add Custom Measurement**

To add a new measurement to the ASAP2 file, create a custom measurement using the commands:

```
Signal_1 = coder.asap2.Measurement;
Signal_1.Name = 'Custom_signal1';
Signal_1.LongIdentifier = 'longIdentifierSignal';
Signal_1.UpperLimit = 255;
Signal_1.LowerLimit = 0;
```

Add the custom measurement to the ECU description object using the command:

```
add(descObj,Signal_1);
```

Get the properties of the newly added measurement using the command:

```
get(descObj,"Measurement","Custom_signal1")
```

```
ans =
```

```
Measurement with properties:
```

```

 Name: 'Custom_signal1'
 LongIdentifier: 'longIdentifierSignal'
 DataType: 'UBYTE'
 EcuAddress: '0x0000'
 CompuMethodName: ""
 LowerLimit: 0
 UpperLimit: 255
 Raster: [1x1 struct]
 EcuAddressComment: ""
 EcuAddressExtension: []
 CalibrationAccess: 'NoCalibration'
 DisplayIdentifier: ""
 Format: ""
 BitMask: []
 Dimensions: []
 Export: 1
 SymbolLink: [1x1 struct]

```

To modify any property of the measurement, use set function. Update the "CalibrationAccess" field of the measurement using the command:

```
set(descObj,"Measurement","Custom_signal1",CalibrationAccess='Calibration')
```

Generate the ASAP2 file using the updated ECU description object and verify that the ASAP2 file contains the measurement with name "Custom\_signal1".

```
coder.asap2.export("rtwdemo_asap2",CustomEcuDescriptions=descObj);
```

Following Characteristics or Measurements with unsupported data types are not exported in ASAP2

Remove the newly added measurement from the description object using the command:

```
delete(descObj,"Measurement","Custom_signal1");
```

### Create and Add a Lookup Table Parameter

To add a lookup table parameter, create a parameter using the commands:

```
LUT_Parameter = coder.asap2.Characteristic;
LUT_Parameter.Name = "custom_lookup_table";
LUT_Parameter.Type = "MAP";
```

Create and add axis information to the parameter.

```
axis_data = coder.asap2.AxisInfo;
axis_data(1).Name = 'BP3';
axis_data(2).Name = 'Bp4';
axis_data(1).CompuMethodName = 'rtwdemo_asap2_CM_double';
axis_data(2).CompuMethodName = 'rtwdemo_asap2_CM_double';
```

```
axis_data(1).MaxAxisPoints = '3';
axis_data(2).MaxAxisPoints = '3';
axis_data(1).AxisType = 'STD_AXIS';
axis_data(2).AxisType = 'STD_AXIS';
LUT_Parameter.AxisInfo = axis_data;
```

Add the lookup table parameter to the description object.

```
add(descObj, LUT_Parameter)
```

Generate the ASAP2 file using the updated ECU description object and verify that the ASAP2 file contains the lookup table parameter with name "custom\_lookup\_table".

```
coder.asap2.export("rtwdemo_asap2", CustomEcuDescriptions=descObj);
```

Following Characteristics or Measurements with unsupported data types are not exported in ASAP2

## Output Arguments

### axis — Axis object

coder.asap2.AxisInfo object

The axis object that can be used to add the axis description for a parameter in the ASAP2 file.

Example: Custom\_Axis = coder.asap2.AxisInfo()

## Tips

Table below shows the available fields in the axis object.

| Element         | Description                                                                      |
|-----------------|----------------------------------------------------------------------------------|
| Name            | Unique identifier in the ECU program                                             |
| LongIdentifier  | Description or comment                                                           |
| EcuAddress      | Address of the element in memory                                                 |
| RecordLayout    | Description of the various data structures                                       |
| AxisType        | Description of the axis                                                          |
| InputQuantity   | Name of the measurement to be used as input quantity for the corresponding axis  |
| CompuMethodName | Name of the conversion method                                                    |
| MaxAxisPoints   | Maximum number of axis points                                                    |
| LowerLimit      | Possible minimum value                                                           |
| UpperLimit      | Possible maximum value                                                           |
| AxisPointsRef   | Reference to the AXIS_PTS record for description of the axis points distribution |
| FixAxisType     | Type of the fix axis                                                             |
| Distance        | Distance attribute for FIX_AXIS_PAR and FIX_AXIS_PAR_DIST                        |



| Element             | Description                                                                                                       |
|---------------------|-------------------------------------------------------------------------------------------------------------------|
| Offset              | Offset attribute for FIX_AXIS_PAR, FIX_AXIS_PAR_DIST, and list of values for FIX_AXIS_PAR_LIST                    |
| Format              | Display format                                                                                                    |
| DisplayIdentifier   | Display name                                                                                                      |
| CalibrationAccess   | Access of the element for calibration                                                                             |
| EcuAddressComment   | Specify symbols for address replacement                                                                           |
| EcuAddressExtension | Additional address information to distinguish different address spaces of an ECU (multi-micro controller devices) |
| SymbolLink          | Reference to symbol name within a linker map file                                                                 |

## Version History

Introduced in R2022b

### See Also

`coder.asap2.Characteristic` | `coder.asap2.getEcuDescriptions` | `add`

### Topics

“Generate ASAP2 and CDF Calibration Files”

## coder.asap2.Characteristic

Create characteristic object

### Syntax

```
param = coder.asap2.Characteristic()
```

### Description

param = coder.asap2.Characteristic() creates a characteristic object. You can use the object to define a characteristic element and export it to the ASAP2 file.

### Examples

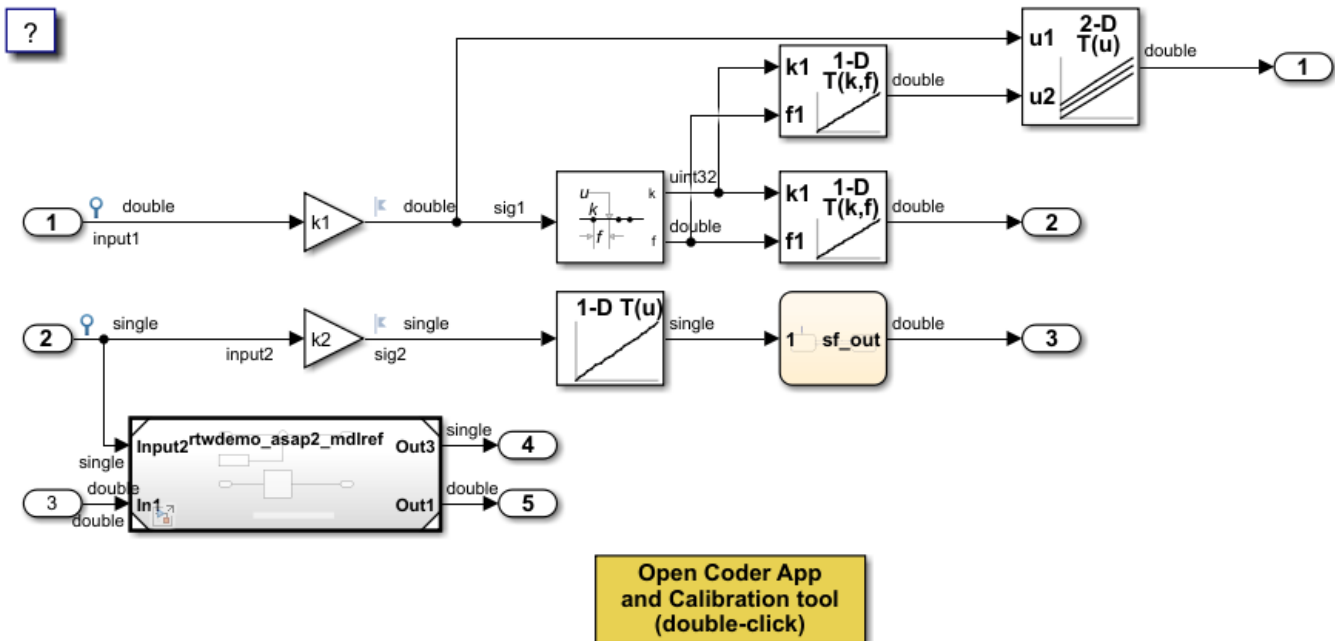
#### Customize an ASAP2 File

This example shows how to add, update, filter, find, and remove ECU descriptions in an ASAP2 file.

#### Open and build the example model

Open the example model `rtwdemo_asap2`

```
open_system("rtwdemo_asap2");
```



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Build the model.

```
rtwbuild("rtwdemo_asap2");

Starting serial model reference code generation build.
Successfully updated the model reference code generation target for: rtwdemo_asap2 mdlref
Starting build procedure for: rtwdemo_asap2
Successful completion of build procedure for: rtwdemo_asap2

Build Summary

Code generation targets built:

Model Action Rebuild Reason
=====
rtwdemo_asap2_mdlref Code generated and compiled. rtwdemo_asap2_mdlref.c does not exist.

Top model targets built:

Model Action Rebuild Reason
=====
rtwdemo_asap2 Code generated and compiled. Code generation information file does not exist.

2 of 2 models built (0 models already up to date)
Build duration: 0h 0m 30.237s
```

Create the ECU description object for the model.

```
descObj=coder.asap2.getEcuDescriptions("rtwdemo_asap2");
```

Get the list of available compu methods in the description object using the command:

```
find(descObj,"CompuMethod")

ans = 1x10 string
Columns 1 through 3
 "rtwdemo_asap2_CM..." "rtwdemo_asap2_CM..." "rtwdemo_asap2_CM..."
Columns 4 through 6
 "rtwdemo_asap2_CM..." "rtwdemo_asap2_CM..." "rtwdemo_asap2_CM..."
Columns 7 through 9
 "rtwdemo_asap2_CM..." "rtwdemo_asap2_CM..." "rtwdemo_asap2_md..."
Column 10
 "rtwdemo_asap2_md..."
```

Filter the compu methods and get the list of compu methods with units as "rpm".

```
find(descObj,"CompuMethod",Units='rpm')

ans = 1x3 string
 "rtwdemo_asap2_CM..." "rtwdemo_asap2_CM..." "rtwdemo_asap2_md..."
```

### Create and Add a Custom Compu Method

To add a new compu method to the ASAP2 file, create a custom compu method using the commands:

```
CompuMethod_CM1 = coder.asap2.CompuMethod;
CompuMethod_CM1.Name = 'CompuMethod_1';
CompuMethod_CM1.ConversionType = 'LINEAR';
CompuMethod_CM1.Coefficients = [2 3];
CompuMethod_CM1.LongIdentifier = 'longIdentifierTest';
CompuMethod_CM1.Format = '%2.3';
CompuMethod_CM1.Units = 's';
```

Add the custom compu method to the ECU description object using the command:

```
add(descObj, CompuMethod_CM1);
```

Get the properties of the newly added compu method using the command:

```
get(descObj, "CompuMethod", "CompuMethod_1")
```

```
ans =
 CompuMethod with properties:

 Name: 'CompuMethod_1'
 LongIdentifier: 'longIdentifierTest'
 Format: '%2.3'
 Units: 's'
 Coefficients: [2 3]
 ConversionType: 'LINEAR'
 CompuVTabValues: [1x1 struct]
```

To modify any property of the compu method, use set function. Update the "LongIdentifier" field of the compu method using the command:

```
set(descObj, "CompuMethod", "CompuMethod_1", LongIdentifier="longIdentifierCM1")
```

Generate the ASAP2 file using the updated ECU description object and verify that the ASAP2 file contains the compu method with name "CompuMethod\_1".

```
coder.asap2.export("rtwdemo_asap2", CustomEcuDescriptions=descObj);
```

Following Characteristics or Measurements with unsupported data types are not exported in ASAP2

### Delete a Compu Method

Remove the newly added compu method from the description object using the command:

```
delete(descObj, "CompuMethod", "CompuMethod_1");
```

### Create and Add Custom Characteristic

To add a new characteristic to the ASAP2 file, create a custom characteristic using the commands:

```
Parameter_1 = coder.asap2.Characteristic;
Parameter_1.Name = 'Custom_parameter1';
Parameter_1.LongIdentifier = 'longIdentifierParam';
Parameter_1.UpperLimit = 255;
Parameter_1.LowerLimit = 0;
```

Add the custom characteristic to the ECU description object using the command:

```
add(descObj,Parameter_1);
```

Get the properties of the newly added characteristic using the command:

```
get(descObj,"Characteristic","Custom_parameter1")
```

```
ans =
```

```
Characteristic with properties:
```

```

 Name: 'Custom_parameter1'
 LongIdentifier: 'longIdentifierParam'
 Type: 'VALUE'
 EcuAddress: '0x0000'
 CompuMethodName: 'NO_COMPU_METHOD'
 LowerLimit: 0
 UpperLimit: 255
 EcuAddressComment: ""
 EcuAddressExtension: []
 CalibrationAccess: 'Calibration'
 DisplayIdentifier: ""
 Format: ""
 BitMask: []
 AxisInfo: []
 RecordLayout: ""
 Dimensions: []
 Export: 1
 SymbolLink: [1x1 struct]
```

To modify any property of the characteristic, use set function. Update the "UpperLimit" field of the characteristic using the command:

```
set(descObj,"Characteristic","Custom_parameter1",UpperLimit=128)
```

Generate the ASAP2 file using the updated ECU description object and verify that the ASAP2 file contains the characteristic with name "Custom\_parameter1".

```
coder.asap2.export("rtwdemo_asap2",CustomEcuDescriptions=descObj);
```

Following Characteristics or Measurements with unsupported data types are not exported in ASAP2

Remove the newly added characteristic from the description object using the command:

```
delete(descObj,"Characteristic","Custom_parameter1");
```

### Create and Add Custom Measurement

To add a new measurement to the ASAP2 file, create a custom measurement using the commands:

```
Signal_1 = coder.asap2.Measurement;
Signal_1.Name = 'Custom_signal1';
Signal_1.LongIdentifier = 'longIdentifierSignal';
Signal_1.UpperLimit = 255;
Signal_1.LowerLimit = 0;
```

Add the custom measurement to the ECU description object using the command:

```
add(descObj,Signal_1);
```

Get the properties of the newly added measurement using the command:

```
get(descObj,"Measurement","Custom_signal1")
```

```
ans =
```

```
Measurement with properties:
```

```
 Name: 'Custom_signal1'
 LongIdentifier: 'longIdentifierSignal'
 DataType: 'UBYTE'
 EcuAddress: '0x0000'
 CompuMethodName: ""
 LowerLimit: 0
 UpperLimit: 255
 Raster: [1x1 struct]
 EcuAddressComment: ""
 EcuAddressExtension: []
 CalibrationAccess: 'NoCalibration'
 DisplayIdentifier: ""
 Format: ""
 BitMask: []
 Dimensions: []
 Export: 1
 SymbolLink: [1x1 struct]
```

To modify any property of the measurement, use set function. Update the "CalibrationAccess" field of the measurement using the command:

```
set(descObj,"Measurement","Custom_signal1",CalibrationAccess='Calibration')
```

Generate the ASAP2 file using the updated ECU description object and verify that the ASAP2 file contains the measurement with name "Custom\_signal1".

```
coder.asap2.export("rtwdemo_asap2",CustomEcuDescriptions=descObj);
```

Following Characteristics or Measurements with unsupported data types are not exported in ASAP2

Remove the newly added measurement from the description object using the command:

```
delete(descObj,"Measurement","Custom_signal1");
```

### **Create and Add a Lookup Table Parameter**

To add a lookup table parameter, create a parameter using the commands:

```
LUT_Parameter = coder.asap2.Characteristic;
LUT_Parameter.Name = "custom_lookup_table";
LUT_Parameter.Type = "MAP";
```

Create and add axis information to the parameter.

```
axis_data = coder.asap2.AxisInfo;
axis_data(1).Name = 'BP3';
axis_data(2).Name = 'Bp4';
axis_data(1).CompuMethodName = 'rtwdemo_asap2_CM_double';
axis_data(2).CompuMethodName = 'rtwdemo_asap2_CM_double';
```

```
axis_data(1).MaxAxisPoints = '3';
axis_data(2).MaxAxisPoints = '3';
axis_data(1).AxisType = 'STD_AXIS';
axis_data(2).AxisType = 'STD_AXIS';
LUT_Parameter.AxisInfo = axis_data;
```

Add the lookup table parameter to the description object.

```
add(descObj, LUT_Parameter)
```

Generate the ASAP2 file using the updated ECU description object and verify that the ASAP2 file contains the lookup table parameter with name "custom\_lookup\_table".

```
coders.asap2.export("rtwdemo_asap2", CustomEcuDescriptions=descObj);
```

Following Characteristics or Measurements with unsupported data types are not exported in ASAP2

## Output Arguments

### param – Characteristic object

coders.asap2.Characteristic object

The characteristic object that can be used to add the required information and use it in the ASAP2 file.

```
Example: Custom_Parameter = coders.asap2.Characteristic()
```

## Tips

Table below shows the available fields in the characteristic object.

| Element             | Description                                                               |
|---------------------|---------------------------------------------------------------------------|
| Name                | Unique identifier in the ECU program                                      |
| LongIdentifier      | Description or comment                                                    |
| Type                | Possible types such as CURVE, MAP, CUBOID, CUBE_4, CUBE_5, VALUE, VAL_BLK |
| EcuAddress          | Address of the element in memory                                          |
| CompuMethodName     | Name of the conversion method                                             |
| LowerLimit          | Minimum possible value                                                    |
| UpperLimit          | Maximum possible value                                                    |
| EcuAddressComment   | Specify symbols for address replacement                                   |
| EcuAddressExtension | Additional address information                                            |
| CalibrationAccess   | Access of the element for calibration                                     |
| DisplayIdentifier   | Display name                                                              |
| Format              | Display format                                                            |
| BitMask             | Specify to handle the single bits                                         |
| AxisInfo            | Specify the parameters for the axis descriptions                          |

| Element              | Description                                                                               |
|----------------------|-------------------------------------------------------------------------------------------|
| ExportArrayAsFixAxis | Specify 'true' to export array as a look up table of type FIX_AXIS                        |
| Transpose            | Set true to transpose the axis. It is applicable only for lookup tables                   |
| ComparisonQuantity   | References a valid MEASUREMENT in the ASAP2 file. It is applicable only for lookup tables |
| RecordLayout         | Description of the various data structures                                                |
| Dimensions           | Dimensions for an array data type                                                         |
| ForceShared          | Describe STD_AXIS as COM_AXIS                                                             |
| Export               | Export or do not export the element to A2L file                                           |
| SymbolLink           | Reference to symbol name within a linker map file                                         |

## Version History

Introduced in R2022b

### See Also

`coder.asap2.AxisInfo` | `coder.asap2.getEcuDescriptions` | `add`

### Topics

“Generate ASAP2 and CDF Calibration Files”



# coder.asap2.CompuMethod

Create compu method object

## Syntax

```
compu = coder.asap2.CompuMethod()
```

## Description

compu = coder.asap2.CompuMethod() creates a compu method object. You can use the object to define a compu method and export it to the ASAP2 file.

## Examples

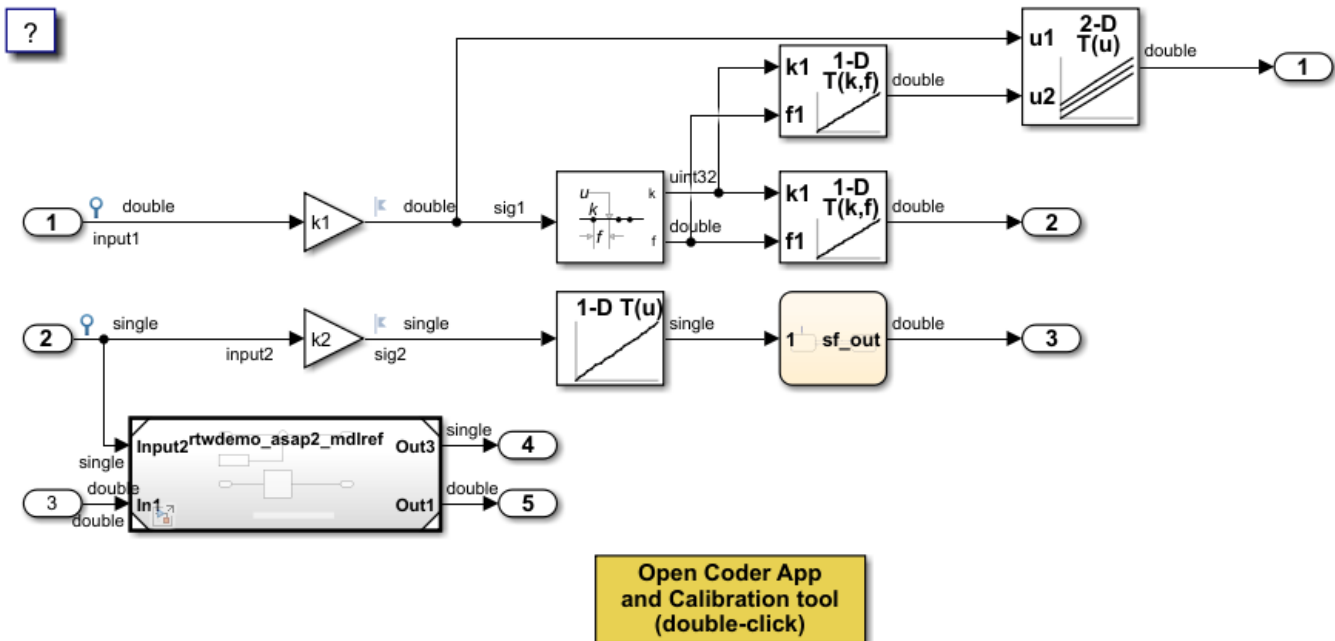
### Customize an ASAP2 File

This example shows how to add, update, filter, find, and remove ECU descriptions in an ASAP2 file.

### Open and build the example model

Open the example model rtwdemo\_asap2

```
open_system("rtwdemo_asap2");
```



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Build the model.

```

rtwbuild("rtwdemo_asap2");

Starting serial model reference code generation build.
Successfully updated the model reference code generation target for: rtwdemo_asap2_mdref
Starting build procedure for: rtwdemo_asap2
Successful completion of build procedure for: rtwdemo_asap2

Build Summary

Code generation targets built:

Model Action Rebuild Reason
=====
rtwdemo_asap2_mdref Code generated and compiled. rtwdemo_asap2_mdref.c does not exist.

Top model targets built:

Model Action Rebuild Reason
=====
rtwdemo_asap2 Code generated and compiled. Code generation information file does not exist.

2 of 2 models built (0 models already up to date)
Build duration: 0h 0m 30.237s

```

Create the ECU description object for the model.

```
descObj=coder.asap2.getEcuDescriptions("rtwdemo_asap2");
```

Get the list of available compu methods in the description object using the command:

```

find(descObj,"CompuMethod")

ans = 1x10 string
 Columns 1 through 3
 "rtwdemo_asap2_CM..." "rtwdemo_asap2_CM..." "rtwdemo_asap2_CM..."
 Columns 4 through 6
 "rtwdemo_asap2_CM..." "rtwdemo_asap2_CM..." "rtwdemo_asap2_CM..."
 Columns 7 through 9
 "rtwdemo_asap2_CM..." "rtwdemo_asap2_CM..." "rtwdemo_asap2_md..."
 Column 10
 "rtwdemo_asap2_md..."

```

Filter the compu methods and get the list of compu methods with units as "rpm".

```

find(descObj,"CompuMethod",Units='rpm')

ans = 1x3 string
 "rtwdemo_asap2_CM..." "rtwdemo_asap2_CM..." "rtwdemo_asap2_md..."

```

## Create and Add a Custom Compu Method

To add a new compu method to the ASAP2 file, create a custom compu method using the commands:

```
CompuMethod_CM1 = coder.asap2.CompuMethod;
CompuMethod_CM1.Name = 'CompuMethod_1';
CompuMethod_CM1.ConversionType = 'LINEAR';
CompuMethod_CM1.Coefficients = [2 3];
CompuMethod_CM1.LongIdentifier = 'longIdentifierTest';
CompuMethod_CM1.Format = '%2.3';
CompuMethod_CM1.Units = 's';
```

Add the custom compu method to the ECU description object using the command:

```
add(descObj, CompuMethod_CM1);
```

Get the properties of the newly added compu method using the command:

```
get(descObj, "CompuMethod", "CompuMethod_1")
```

```
ans =
 CompuMethod with properties:

 Name: 'CompuMethod_1'
 LongIdentifier: 'longIdentifierTest'
 Format: '%2.3'
 Units: 's'
 Coefficients: [2 3]
 ConversionType: 'LINEAR'
 CompuVTabValues: [1x1 struct]
```

To modify any property of the compu method, use set function. Update the "LongIdentifier" field of the compu method using the command:

```
set(descObj, "CompuMethod", "CompuMethod_1", LongIdentifier="longIdentifierCM1")
```

Generate the ASAP2 file using the updated ECU description object and verify that the ASAP2 file contains the compu method with name "CompuMethod\_1".

```
coder.asap2.export("rtwdemo_asap2", CustomEcuDescriptions=descObj);
```

Following Characteristics or Measurements with unsupported data types are not exported in ASAP2

## Delete a Compu Method

Remove the newly added compu method from the description object using the command:

```
delete(descObj, "CompuMethod", "CompuMethod_1");
```

## Create and Add Custom Characteristic

To add a new characteristic to the ASAP2 file, create a custom characteristic using the commands:

```
Parameter_1 = coder.asap2.Characteristic;
Parameter_1.Name = 'Custom_parameter1';
Parameter_1.LongIdentifier = 'longIdentifierParam';
Parameter_1.UpperLimit = 255;
Parameter_1.LowerLimit = 0;
```

Add the custom characteristic to the ECU description object using the command:

```
add(descObj,Parameter_1);
```

Get the properties of the newly added characteristic using the command:

```
get(descObj,"Characteristic","Custom_parameter1")
```

```
ans =
```

```
Characteristic with properties:
```

```
 Name: 'Custom_parameter1'
 LongIdentifier: 'longIdentifierParam'
 Type: 'VALUE'
 EcuAddress: '0x0000'
 CompuMethodName: 'NO_COMPU_METHOD'
 LowerLimit: 0
 UpperLimit: 255
 EcuAddressComment: ''
 EcuAddressExtension: []
 CalibrationAccess: 'Calibration'
 DisplayIdentifier: ''
 Format: ''
 BitMask: []
 AxisInfo: []
 RecordLayout: ''
 Dimensions: []
 Export: 1
 SymbolLink: [1x1 struct]
```

To modify any property of the characteristic, use set function. Update the "UpperLimit" field of the characteristic using the command:

```
set(descObj,"Characteristic","Custom_parameter1",UpperLimit=128)
```

Generate the ASAP2 file using the updated ECU description object and verify that the ASAP2 file contains the characteristic with name "Custom\_parameter1".

```
coder.asap2.export("rtwdemo_asap2",CustomEcuDescriptions=descObj);
```

Following Characteristics or Measurements with unsupported data types are not exported in ASAP2

Remove the newly added characteristic from the description object using the command:

```
delete(descObj,"Characteristic","Custom_parameter1");
```

### **Create and Add Custom Measurement**

To add a new measurement to the ASAP2 file, create a custom measurement using the commands:

```
Signal_1 = coder.asap2.Measurement;
Signal_1.Name = 'Custom_signal1';
Signal_1.LongIdentifier = 'longIdentifierSignal';
Signal_1.UpperLimit = 255;
Signal_1.LowerLimit = 0;
```

Add the custom measurement to the ECU description object using the command:

```
add(descObj,Signal_1);
```

Get the properties of the newly added measurement using the command:

```
get(descObj,"Measurement","Custom_signal1")
```

```
ans =
```

```
Measurement with properties:
```

```

 Name: 'Custom_signal1'
 LongIdentifier: 'longIdentifierSignal'
 DataType: 'UBYTE'
 EcuAddress: '0x0000'
 CompuMethodName: ""
 LowerLimit: 0
 UpperLimit: 255
 Raster: [1x1 struct]
 EcuAddressComment: ""
 EcuAddressExtension: []
 CalibrationAccess: 'NoCalibration'
 DisplayIdentifier: ""
 Format: ""
 BitMask: []
 Dimensions: []
 Export: 1
 SymbolLink: [1x1 struct]

```

To modify any property of the measurement, use set function. Update the "CalibrationAccess" field of the measurement using the command:

```
set(descObj,"Measurement","Custom_signal1",CalibrationAccess='Calibration')
```

Generate the ASAP2 file using the updated ECU description object and verify that the ASAP2 file contains the measurement with name "Custom\_signal1".

```
coder.asap2.export("rtwdemo_asap2",CustomEcuDescriptions=descObj);
```

Following Characteristics or Measurements with unsupported data types are not exported in ASAP2

Remove the newly added measurement from the description object using the command:

```
delete(descObj,"Measurement","Custom_signal1");
```

### Create and Add a Lookup Table Parameter

To add a lookup table parameter, create a parameter using the commands:

```

LUT_Parameter = coder.asap2.Characteristic;
LUT_Parameter.Name = "custom_lookup_table";
LUT_Parameter.Type = "MAP";

```

Create and add axis information to the parameter.

```

axis_data = coder.asap2.AxisInfo;
axis_data(1).Name = 'BP3';
axis_data(2).Name = 'Bp4';
axis_data(1).CompuMethodName = 'rtwdemo_asap2_CM_double';
axis_data(2).CompuMethodName = 'rtwdemo_asap2_CM_double';

```

```
axis_data(1).MaxAxisPoints = '3';
axis_data(2).MaxAxisPoints = '3';
axis_data(1).AxisType = 'STD_AXIS';
axis_data(2).AxisType = 'STD_AXIS';
LUT_Parameter.AxisInfo = axis_data;
```

Add the lookup table parameter to the description object.

```
add(descObj, LUT_Parameter)
```

Generate the ASAP2 file using the updated ECU description object and verify that the ASAP2 file contains the lookup table parameter with name "custom\_lookup\_table".

```
coder.asap2.export("rtwdemo_asap2", CustomEcuDescriptions=descObj);
```

Following Characteristics or Measurements with unsupported data types are not exported in ASAP2

## Output Arguments

### compu — compu method object

coder.asap2.CompuMethod object

The compu method object that can be used to add the required information and export it to the ASAP2 file.

Example: `Compu_CM1 = coder.asap2.CompuMethod()`

## Tips

Table below shows the available fields in the compu method object.

| Element         | Description                                                       |
|-----------------|-------------------------------------------------------------------|
| Name            | Unique identifier in the ECU program                              |
| LongIdentifier  | Description or comment                                            |
| Format          | Display format                                                    |
| Units           | Physical units                                                    |
| Coefficients    | Coefficients for the fractional rational function                 |
| ConversionType  | Conversion type for internal source value to physical value       |
| CompuVTabValues | Define the values for compu methd with ConversionType as TAB_VERB |

## Version History

Introduced in R2022b

## See Also

coder.asap2.AxisInfo | coder.asap2.getEcuDescriptions | add

**Topics**

“Generate ASAP2 and CDF Calibration Files”

## coder.asap2.Function

Create function object

### Syntax

```
userFunction = coder.asap2.Function()
```

### Description

`userFunction = coder.asap2.Function()` creates a function object. You can use the object to define new function description and export it to ASAP2 file.

### Examples

#### Create and Add Custom Function

This example shows how to add a custom function to the ASAP2 file.

#### Create ECU Description Object

Open a model, build, and create ECU description object.

```
open_system("rtwdemo_asap2")
rtwbuild("rtwdemo_asap2")

Starting serial model reference code generation build.
Successfully updated the model reference code generation target for: rtwdemo_asap2_mdref
Starting build procedure for: rtwdemo_asap2
Successful completion of build procedure for: rtwdemo_asap2

Build Summary

Code generation targets built:

Model Action Rebuild Reason
=====
rtwdemo_asap2_mdref Code generated and compiled. rtwdemo_asap2_mdref.c does not exist.

Top model targets built:

Model Action Rebuild Reason
=====
rtwdemo_asap2 Code generated and compiled. Code generation information file does not exist.

2 of 2 models built (0 models already up to date)
Build duration: 0h 0m 49.389s

descObj=coder.asap2.getEcuDescriptions("rtwdemo_asap2")

descObj =
 Data with no properties.
```



## Create Custom Function

Create a function object template and add the necessary fields.

```
userFunction = coder.asap2.Function
```

```
userFunction =
 Function with properties:
 Name: "undefined"
 FunctionVersion: [1x0 char]
 LongIdentifier: [1x0 char]
 Annotation: [1x0 char]
 InMeasurements: [1x0 string]
 OutMeasurements: [1x0 string]
 LocMeasurements: [1x0 string]
 DefCharacteristics: [1x0 string]
 RefCharacteristics: [1x0 string]
 SubFunctions: [1x0 string]
```

```
userFunction.Name = 'Custom_Function1'
```

```
userFunction =
 Function with properties:
 Name: 'Custom_Function1'
 FunctionVersion: [1x0 char]
 LongIdentifier: [1x0 char]
 Annotation: [1x0 char]
 InMeasurements: [1x0 string]
 OutMeasurements: [1x0 string]
 LocMeasurements: [1x0 string]
 DefCharacteristics: [1x0 string]
 RefCharacteristics: [1x0 string]
 SubFunctions: [1x0 string]
```

```
userFunction.LongIdentifier = 'Custom Function by user'
```

```
userFunction =
 Function with properties:
 Name: 'Custom_Function1'
 FunctionVersion: [1x0 char]
 LongIdentifier: 'Custom Function by user'
 Annotation: [1x0 char]
 InMeasurements: [1x0 string]
 OutMeasurements: [1x0 string]
 LocMeasurements: [1x0 string]
 DefCharacteristics: [1x0 string]
 RefCharacteristics: [1x0 string]
 SubFunctions: [1x0 string]
```

## Export the Function to ASAP2 File

Add the function to ECU description object and generate ASAP2 file using the description object.

```
add(descObj,userFunction)
coder.asap2.export("rtwdemo_asap2",CustomEcuDescriptions=descObj)
```

Following Characteristics or Measurements with unsupported data types are not exported in ASAP2

## Output Arguments

### userFunction – function object template

char vector | string scalar

The function object that can be used to define a function and export it to ASAP2 file.

Example: Custom\_Function = coder.asap2.Function()

## Tips

Table below shows the available fields in the Function object.

| Element            | Description                                                    |
|--------------------|----------------------------------------------------------------|
| Name               | Name of the function                                           |
| LongIdentifier     | Description or comment                                         |
| FunctionVersion    | Version of the function                                        |
| Annotation         | Set of notes represented as multi-line ASCII description texts |
| InMeasurements     | Array of input measurements                                    |
| OutMeasurements    | Array of output measurements                                   |
| LocMeasurements    | Array of local measurements                                    |
| DefCharacteristics | Array of defined characteristics                               |
| RefCharacteristics | Array of referenced characteristics                            |
| SubFunctions       | Array of sub functions                                         |

## Version History

Introduced in R2022b

### See Also

add | coder.asap2.getEcuDescriptions

### Topics

“Generate ASAP2 and CDF Calibration Files”

# coder.asap2.Measurement

Create measurement object

## Syntax

```
signal = coder.asap2.Measurement()
```

## Description

`signal = coder.asap2.Measurement()` creates a measurement object. You can use the object to define a signal and export it to ASAP2 file.

## Examples

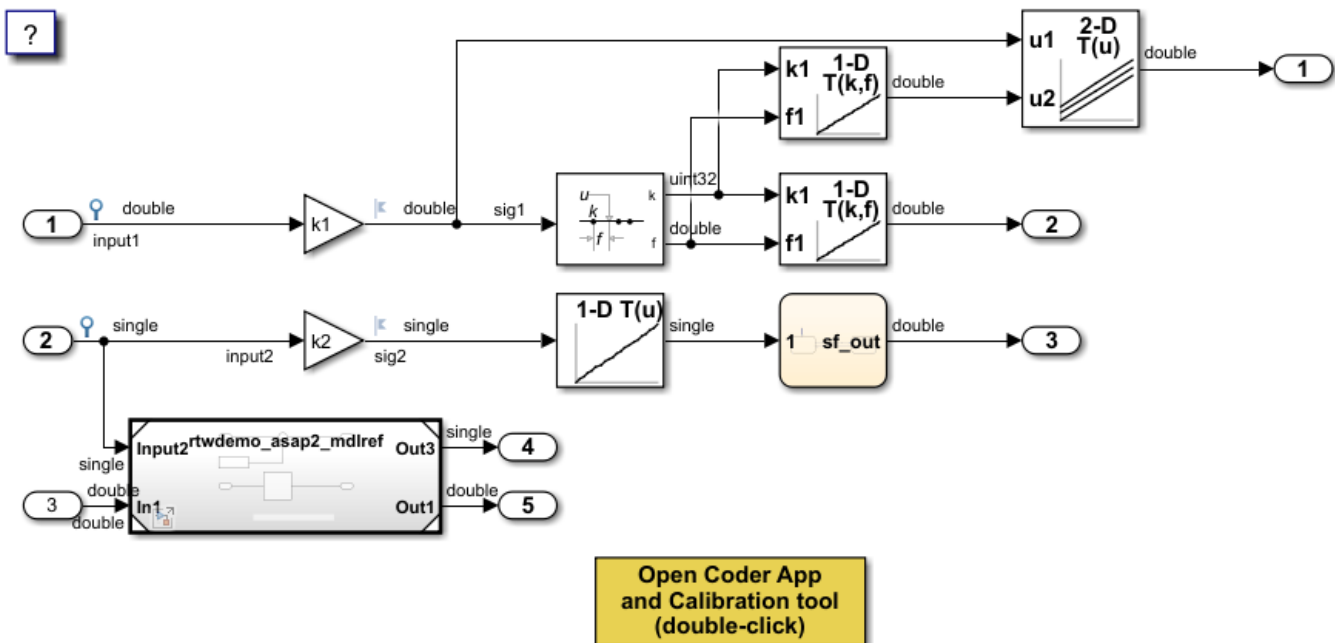
### Customize an ASAP2 File

This example shows how to add, update, filter, find, and remove ECU descriptions in an ASAP2 file.

### Open and build the example model

Open the example model `rtwdemo_asap2`

```
open_system("rtwdemo_asap2");
```



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Build the model.

```
rtwbuild("rtwdemo_asap2");

Starting serial model reference code generation build.
Successfully updated the model reference code generation target for: rtwdemo_asap2 mdlref
Starting build procedure for: rtwdemo_asap2
Successful completion of build procedure for: rtwdemo_asap2

Build Summary

Code generation targets built:

Model Action Rebuild Reason
=====
rtwdemo_asap2_mdlref Code generated and compiled. rtwdemo_asap2_mdlref.c does not exist.

Top model targets built:

Model Action Rebuild Reason
=====
rtwdemo_asap2 Code generated and compiled. Code generation information file does not exist.

2 of 2 models built (0 models already up to date)
Build duration: 0h 0m 30.237s
```

Create the ECU description object for the model.

```
descObj=coder.asap2.getEcuDescriptions("rtwdemo_asap2");
```

Get the list of available compu methods in the description object using the command:

```
find(descObj,"CompuMethod")

ans = 1x10 string
 Columns 1 through 3
 "rtwdemo_asap2_CM..." "rtwdemo_asap2_CM..." "rtwdemo_asap2_CM..."
 Columns 4 through 6
 "rtwdemo_asap2_CM..." "rtwdemo_asap2_CM..." "rtwdemo_asap2_CM..."
 Columns 7 through 9
 "rtwdemo_asap2_CM..." "rtwdemo_asap2_CM..." "rtwdemo_asap2_md..."
 Column 10
 "rtwdemo_asap2_md..."
```

Filter the compu methods and get the list of compu methods with units as "rpm".

```
find(descObj,"CompuMethod",Units='rpm')

ans = 1x3 string
 "rtwdemo_asap2_CM..." "rtwdemo_asap2_CM..." "rtwdemo_asap2_md..."
```

## Create and Add a Custom Compu Method

To add a new compu method to the ASAP2 file, create a custom compu method using the commands:

```
CompuMethod_CM1 = coder.asap2.CompuMethod;
CompuMethod_CM1.Name = 'CompuMethod_1';
CompuMethod_CM1.ConversionType = 'LINEAR';
CompuMethod_CM1.Coefficients = [2 3];
CompuMethod_CM1.LongIdentifier = 'longIdentifierTest';
CompuMethod_CM1.Format = '%2.3';
CompuMethod_CM1.Units = 's';
```

Add the custom compu method to the ECU description object using the command:

```
add(descObj, CompuMethod_CM1);
```

Get the properties of the newly added compu method using the command:

```
get(descObj, "CompuMethod", "CompuMethod_1")
```

```
ans =
 CompuMethod with properties:
 Name: 'CompuMethod_1'
 LongIdentifier: 'longIdentifierTest'
 Format: '%2.3'
 Units: 's'
 Coefficients: [2 3]
 ConversionType: 'LINEAR'
 CompuVTabValues: [1x1 struct]
```

To modify any property of the compu method, use set function. Update the "LongIdentifier" field of the compu method using the command:

```
set(descObj, "CompuMethod", "CompuMethod_1", LongIdentifier="longIdentifierCM1")
```

Generate the ASAP2 file using the updated ECU description object and verify that the ASAP2 file contains the compu method with name "CompuMethod\_1".

```
coder.asap2.export("rtwdemo_asap2", CustomEcuDescriptions=descObj);
```

Following Characteristics or Measurements with unsupported data types are not exported in ASAP2

## Delete a Compu Method

Remove the newly added compu method from the description object using the command:

```
delete(descObj, "CompuMethod", "CompuMethod_1");
```

## Create and Add Custom Characteristic

To add a new characteristic to the ASAP2 file, create a custom characteristic using the commands:

```
Parameter_1 = coder.asap2.Characteristic;
Parameter_1.Name = 'Custom_parameter1';
Parameter_1.LongIdentifier = 'longIdentifierParam';
Parameter_1.UpperLimit = 255;
Parameter_1.LowerLimit = 0;
```

Add the custom characteristic to the ECU description object using the command:

```
add(descObj,Parameter_1);
```

Get the properties of the newly added characteristic using the command:

```
get(descObj,"Characteristic","Custom_parameter1")
```

```
ans =
```

```
Characteristic with properties:
```

```
 Name: 'Custom_parameter1'
 LongIdentifier: 'longIdentifierParam'
 Type: 'VALUE'
 EcuAddress: '0x0000'
 CompuMethodName: 'NO_COMPU_METHOD'
 LowerLimit: 0
 UpperLimit: 255
 EcuAddressComment: ''
 EcuAddressExtension: []
 CalibrationAccess: 'Calibration'
 DisplayIdentifier: ''
 Format: ''
 BitMask: []
 AxisInfo: []
 RecordLayout: ''
 Dimensions: []
 Export: 1
 SymbolLink: [1x1 struct]
```

To modify any property of the characteristic, use set function. Update the "UpperLimit" field of the characteristic using the command:

```
set(descObj,"Characteristic","Custom_parameter1",UpperLimit=128)
```

Generate the ASAP2 file using the updated ECU description object and verify that the ASAP2 file contains the characteristic with name "Custom\_parameter1".

```
coder.asap2.export("rtwdemo_asap2",CustomEcuDescriptions=descObj);
```

Following Characteristics or Measurements with unsupported data types are not exported in ASAP2

Remove the newly added characteristic from the description object using the command:

```
delete(descObj,"Characteristic","Custom_parameter1");
```

### **Create and Add Custom Measurement**

To add a new measurement to the ASAP2 file, create a custom measurement using the commands:

```
Signal_1 = coder.asap2.Measurement;
Signal_1.Name = 'Custom_signal1';
Signal_1.LongIdentifier = 'longIdentifierSignal';
Signal_1.UpperLimit = 255;
Signal_1.LowerLimit = 0;
```

Add the custom measurement to the ECU description object using the command:

```
add(descObj,Signal_1);
```

Get the properties of the newly added measurement using the command:

```
get(descObj,"Measurement","Custom_signal1")
```

```
ans =
```

```
Measurement with properties:
```

```

 Name: 'Custom_signal1'
 LongIdentifier: 'longIdentifierSignal'
 DataType: 'UBYTE'
 EcuAddress: '0x0000'
 CompuMethodName: ""
 LowerLimit: 0
 UpperLimit: 255
 Raster: [1x1 struct]
 EcuAddressComment: ""
 EcuAddressExtension: []
 CalibrationAccess: 'NoCalibration'
 DisplayIdentifier: ""
 Format: ""
 BitMask: []
 Dimensions: []
 Export: 1
 SymbolLink: [1x1 struct]

```

To modify any property of the measurement, use set function. Update the "CalibrationAccess" field of the measurement using the command:

```
set(descObj,"Measurement","Custom_signal1",CalibrationAccess='Calibration')
```

Generate the ASAP2 file using the updated ECU description object and verify that the ASAP2 file contains the measurement with name "Custom\_signal1".

```
coder.asap2.export("rtwdemo_asap2",CustomEcuDescriptions=descObj);
```

Following Characteristics or Measurements with unsupported data types are not exported in ASAP2

Remove the newly added measurement from the description object using the command:

```
delete(descObj,"Measurement","Custom_signal1");
```

### Create and Add a Lookup Table Parameter

To add a lookup table parameter, create a parameter using the commands:

```

LUT_Parameter = coder.asap2.Characteristic;
LUT_Parameter.Name = "custom_lookup_table";
LUT_Parameter.Type = "MAP";

```

Create and add axis information to the parameter.

```

axis_data = coder.asap2.AxisInfo;
axis_data(1).Name = 'BP3';
axis_data(2).Name = 'Bp4';
axis_data(1).CompuMethodName = 'rtwdemo_asap2_CM_double';
axis_data(2).CompuMethodName = 'rtwdemo_asap2_CM_double';

```

```
axis_data(1).MaxAxisPoints = '3';
axis_data(2).MaxAxisPoints = '3';
axis_data(1).AxisType = 'STD_AXIS';
axis_data(2).AxisType = 'STD_AXIS';
LUT_Parameter.AxisInfo = axis_data;
```

Add the lookup table parameter to the description object.

```
add(descObj, LUT_Parameter)
```

Generate the ASAP2 file using the updated ECU description object and verify that the ASAP2 file contains the lookup table parameter with name "custom\_lookup\_table".

```
coder.asap2.export("rtwdemo_asap2", CustomEcuDescriptions=descObj);
```

Following Characteristics or Measurements with unsupported data types are not exported in ASAP2

## Output Arguments

### signal — Measurement object

coder.asap2.Measurement object

The measurement object that can be used to add the required information and export it to the ASAP2 file.

Example: Custom\_Signal = coder.asap2.Measurement()

## Tips

Table below shows the available fields in the measurement object.

| Element             | Description                            |
|---------------------|----------------------------------------|
| Name                | Unique identifier in the ECU program   |
| LongIdentifier      | Description or comment                 |
| DataType            | Data type of the measurement           |
| EcuAddress          | Address of the element in memory       |
| CompuMethodName     | Name of the conversion method          |
| LowerLimit          | Minimum possible value                 |
| UpperLimit          | Maximum possible value                 |
| Raster              | Refresh time of the signal             |
| EcuAddressComment   | Specify symbol for address replacement |
| EcuAddressExtension | Additional address information         |
| CalibrationAccess   | Access of the element for calibration  |
| DisplayIdentifier   | Display name                           |
| Format              | Display format                         |
| BitMask             | Specify to handle the single bits      |
| Dimensions          | Specify dimensions                     |



| Element    | Description                                       |
|------------|---------------------------------------------------|
| Export     | Export or do not export the element to A2L file   |
| SymbolLink | Reference to symbol name within a linker map file |

## Version History

Introduced in R2022b

### See Also

`coder.asap2.Measurement` | `coder.asap2.getEcuDescriptions` | `add`

### Topics

“Generate ASAP2 and CDF Calibration Files”

## coder.asap2.UserCustomizeBase

Customize project and module settings

### Syntax

```
Obj = coder.asap2.UserCustomizeBase
```

### Description

Obj = coder.asap2.UserCustomizeBase creates an object to define PROJECT, MODULE, MOD, MOD\_PAR, and MOD\_COMMON settings. Use the object to add the fields to ASAP2 file.

### Examples

#### Define Custom Settings to Project and Module

Open and build the model.

```
open_system("rtwdemo_asap2");
rtwbuild("rtwdemo_asap2");
```

Create a custom base object and define the fields.

```
Obj = coder.asap2.UserCustomizeBase;
Obj.ProjectName = 'Demo project name';
Obj.ProjectComment = 'Custom comment for the demo project';
Obj.ModuleName = 'Demo module name';
Obj.ModuleComment = 'Custom comment for the demo module';
Obj.HeaderComment = 'Custom comment';
```

Generate an ASAP2 file by passing the object using the command:

```
coder.asap2.export("rtwdemo_asap2",CustomizationObject=Obj);
```

### Output Arguments

#### Obj — Base object

coder.asap2.UserCustomizeBase object

The function creates an UserCustomizeBase object and it can be used to add the PROJECT, MODULE, MOD, MOD\_PAR, and MOD\_COMMON settings in the ASAP2 file.

### User Custom Base

Use the coder.asap2.UserCustomizeBase object to define the following fields:

| Field         |
|---------------|
| HeaderComment |

| <b>Field</b>                |
|-----------------------------|
| ModParComment               |
| ModCommonComment            |
| ASAP2FileName               |
| ByteOrder                   |
| ProjectName                 |
| ProjectComment              |
| ModuleName                  |
| ModuleComment               |
| AfterBeginHeaderComments    |
| BeforeEndHeaderComments     |
| AfterBeginProjectComments   |
| BeforeEndProjectComments    |
| AfterBeginModuleComments    |
| BeforeEndModuleComments     |
| AfterBeginModParComments    |
| BeforeEndModParComments     |
| AfterBeginModCommonComments |
| BeforeEndModCommonComments  |
| AddA2MLSection              |
| AddIfDataSection            |

## **Version History**

**Introduced in R2022b**

### **See Also**

coder.asap2.export

### **Topics**

“Generate ASAP2 and CDF Calibration Files”

# **coder.asap2.getEcuDescriptions**

ECU description object for model

## **Description**

An ECU description object and its functions allows you to add, delete, find, filter, update, and fetch ECU descriptions in an ASAP2 file. You can use the function to create the information object for a model.

## **Creation**

`descObj = coder.asap2.getEcuDescriptions(modelName)` creates an ECU description object with name `descObj` for the model `modelName`.

## **Properties**

### **Folder — Folder location to export A2L file**

character vector | string scalar

Full path to a folder in which to place an exported A2L file.

Example: `Folder='/home/temp/prjct/'`

### **FileName — Custom name for the exported A2L file**

character vector | string scalar

Name for the exported A2L file.

Example: `FileName='test_car'`

### **MapFile — Name of symbol file for model**

ELF | PDB | DWARF | executable

Name of the model symbol file that contains symbols of generated code. For example, the addresses of variables used in generated code.

Example: `MapFile='model.elf'`

### **Version — Version of A2L file**

1.71 (default) | 1.31 | 1.61

A2L file format based on the ASAM MCD-2 MC standard defined by ASAM. There are multiple versions of the ASAM MCD-2 MC standard. Specify the version of A2L that you want.

Example: `Version='1.61'` or `Version='1.31'`

### **Comments — Include comments in A2L file**

true (default) | false

Generate the A2L file by including or excluding comments.

Example: `Comments=true`

### **GenerateXCPIInfo — Include A2ML and IF\_DATA in A2L file**

`true` (default) | `false`

Generate the A2L file by including or excluding A2ML and IF\_DATA sections.

Example: `GenerateXCPIInfo=true`

### **ModelClassName — Specify class instance and path names**

character vector | string scalar

Custom model instance name in an A2L file. This argument is applicable only for Adaptive AUTOSAR models.

Example: `ModelClassName='customObj'` or  
`ModelClassName='customNameSpace::customObj'`

### **IndentFile — Follow indentation in A2L file**

`false` (default) | `true`

Generate an A2L file by following indentation.

Example: `IndentFile=true`

### **CustomizationObject — Customize ASAP2 fields**

`coder.asap2.UserCustomizeBase` object (default)

Create a user base and customize the ASAP2 fields such as:

- `ASAP2FileName`
- `ByteOrder`
- `HeaderComment`
- `ModParComment`
- `ModCommonComment`

Example: `CustomizationObject=obj`

### **CustomizeGroupsBy — Customize groups in ASAP2 file**

`ARRAY` | `SCALAR` | `MAP` | `CUBOID` | `CURVE` | `CUBE_4` | `CUBE_5`

Group the parameters and signals based on their properties.

Example: `CustomizeGroupsBy={'ARRAY', 'MAP'}`

### **IncludeAllRecordLayouts — Export record layouts of the base data types**

`false` (default) | `true`

Export record layouts of all the base data types to a file named `RecordLayouts.a2l` according to the version of the A2L file.

Example: `IncludeAllRecordLayouts=true`

### **SupportStructureElements — Include or exclude the structure elements in ASAP2 file**

`true` (default) | `false`

Specify `false` to exclude elements that are part of the structure in the generated ASAP2 file.

Example: `SupportStructureElements=false`

**Support64bitIntegers — Include or exclude the 64-bit integers in ASAP2 file**

true (default) | false

Specify false to exclude 64-bit integers in the generated ASAP2 file.

Example: `Support64bitIntegers=false`

**EcuAddressExtension — Specify additional address information**

int

Specify a 32-bit integer value to specify additional address information in the ASAP2 file. By default, no additional address information is required.

Example: `EcuAddressExtension=4`

**IncludeAutosarRteElements — Export RTE elements**

true (default) | false

Generate the A2L file by including or excluding the AUTOSAR RTE elements.

---

**Note** This option is applicable only for Classic AUTOSAR models.

---

Example: `IncludeAutosarRteElements=true`

**UseSavedSettings — Save and use the preferences**

false (default) | true

Save the preferences made and generate the ASAP2 file with the preferences updated such as including the comments, version of the ASAP2 file.

Example: `UseSavedSettings=false`

**IncludeDefaultEventList — Create default event**

true (default) | false

Specify true to include a default event list in the A2L file.

Example: `IncludeDefaultEventList=true`

**ToggleArrayLayout — Modify the array layout**

false (default) | true

Update the array layout to ROW\_DIR or COL\_DIR to view the array data in row wise or column wise.

Example: `ToggleArrayLayout=true`

**Object Functions**

|        |                                         |
|--------|-----------------------------------------|
| add    | Add element to ASAP2 file               |
| delete | Remove element from ASAP2 file          |
| find   | Filter and get ECU description names    |
| get    | Return ASAP2 properties of data element |
| set    | Set property for data element           |

## Examples

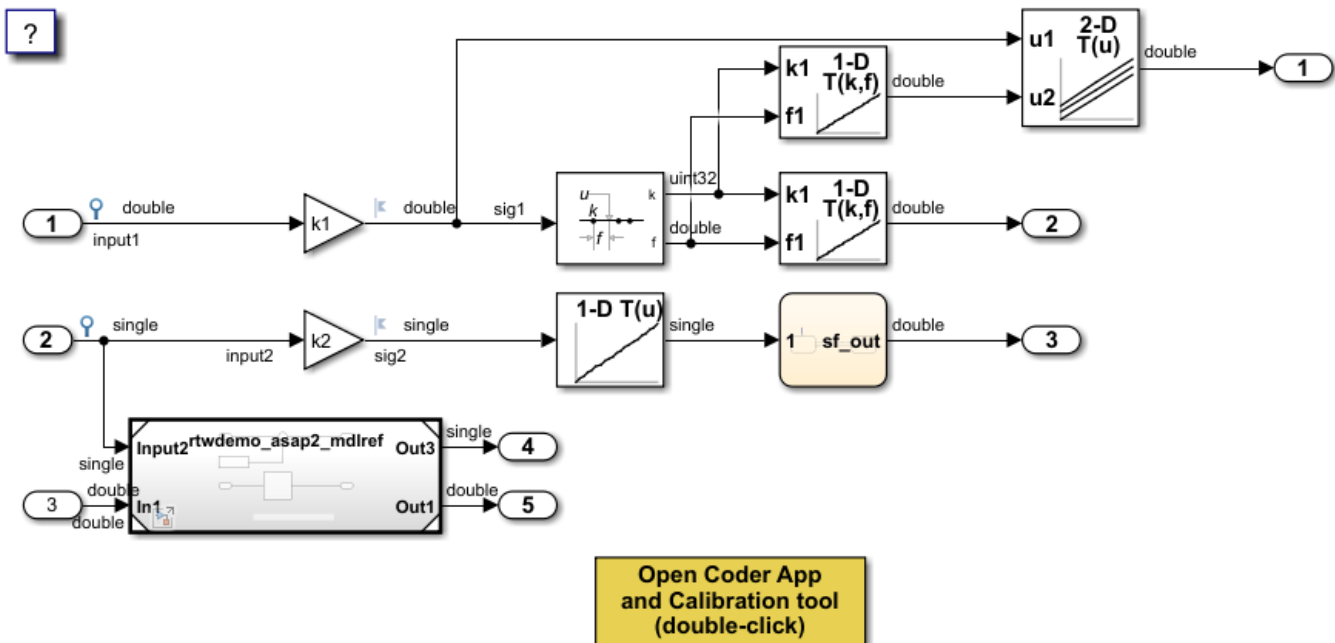
### Customize an ASAP2 File

This example shows how to add, update, filter, find, and remove ECU descriptions in an ASAP2 file.

#### Open and build the example model

Open the example model `rtwdemo_asap2`

```
open_system("rtwdemo_asap2");
```



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Build the model.

```
rtwbuild("rtwdemo_asap2");
```

```
Starting serial model reference code generation build.
Successfully updated the model reference code generation target for: rtwdemo_asap2_mdref
Starting build procedure for: rtwdemo_asap2
Successful completion of build procedure for: rtwdemo_asap2
```

Build Summary

Code generation targets built:

| Model               | Action                       | Rebuild Reason                        |
|---------------------|------------------------------|---------------------------------------|
| rtwdemo_asap2_mdref | Code generated and compiled. | rtwdemo_asap2_mdref.c does not exist. |

Top model targets built:

```

Model Action Rebuild Reason
=====
rtwdemo_asap2 Code generated and compiled. Code generation information file does not exist.

2 of 2 models built (0 models already up to date)
Build duration: 0h 0m 30.237s

```

Create the ECU description object for the model.

```
descObj=coder.asap2.getEcuDescriptions("rtwdemo_asap2");
```

Get the list of available compu methods in the description object using the command:

```
find(descObj, "CompuMethod")

ans = 1x10 string
 Columns 1 through 3
 "rtwdemo_asap2_CM..." "rtwdemo_asap2_CM..." "rtwdemo_asap2_CM..."
 Columns 4 through 6
 "rtwdemo_asap2_CM..." "rtwdemo_asap2_CM..." "rtwdemo_asap2_CM..."
 Columns 7 through 9
 "rtwdemo_asap2_CM..." "rtwdemo_asap2_CM..." "rtwdemo_asap2_md..."
 Column 10
 "rtwdemo_asap2_md..."
```

Filter the compu methods and get the list of compu methods with units as "rpm".

```
find(descObj, "CompuMethod", Units='rpm')

ans = 1x3 string
 "rtwdemo_asap2_CM..." "rtwdemo_asap2_CM..." "rtwdemo_asap2_md..."
```

### Create and Add a Custom Compu Method

To add a new compu method to the ASAP2 file, create a custom compu method using the commands:

```
CompuMethod_CM1 = coder.asap2.CompuMethod;
CompuMethod_CM1.Name = 'CompuMethod_1';
CompuMethod_CM1.ConversionType = 'LINEAR';
CompuMethod_CM1.Coefficients = [2 3];
CompuMethod_CM1.LongIdentifier = 'longIdentifierTest';
CompuMethod_CM1.Format = '%2.3';
CompuMethod_CM1.Units = 's';
```

Add the custom compu method to the ECU description object using the command:

```
add(descObj, CompuMethod_CM1);
```

Get the properties of the newly added compu method using the command:

```
get(descObj, "CompuMethod", "CompuMethod_1")
```



```
ans =
 CompuMethod with properties:
 Name: 'CompuMethod_1'
 LongIdentifier: 'longIdentifierTest'
 Format: '%2.3'
 Units: 's'
 Coefficients: [2 3]
 ConversionType: 'LINEAR'
 CompuVTabValues: [1x1 struct]
```

To modify any property of the compu method, use set function. Update the "LongIdentifier" field of the compu method using the command:

```
set(descObj, "CompuMethod", "CompuMethod_1", LongIdentifier="longIdentifierCM1")
```

Generate the ASAP2 file using the updated ECU description object and verify that the ASAP2 file contains the compu method with name "CompuMethod\_1".

```
coder.asap2.export("rtwdemo_asap2", CustomEcuDescriptions=descObj);
```

Following Characteristics or Measurements with unsupported data types are not exported in ASAP2

### Delete a Compu Method

Remove the newly added compu method from the description object using the command:

```
delete(descObj, "CompuMethod", "CompuMethod_1");
```

### Create and Add Custom Characteristic

To add a new characteristic to the ASAP2 file, create a custom characteristic using the commands:

```
Parameter_1 = coder.asap2.Characteristic;
Parameter_1.Name = 'Custom_parameter1';
Parameter_1.LongIdentifier = 'longIdentifierParam';
Parameter_1.UpperLimit = 255;
Parameter_1.LowerLimit = 0;
```

Add the custom characteristic to the ECU description object using the command:

```
add(descObj, Parameter_1);
```

Get the properties of the newly added characteristic using the command:

```
get(descObj, "Characteristic", "Custom_parameter1")
```

```
ans =
 Characteristic with properties:
 Name: 'Custom_parameter1'
 LongIdentifier: 'longIdentifierParam'
 Type: 'VALUE'
 EcuAddress: '0x0000'
 CompuMethodName: 'NO_COMPU_METHOD'
 LowerLimit: 0
 UpperLimit: 255
 EcuAddressComment: ""
```

```
EcuAddressExtension: []
CalibrationAccess: 'Calibration'
DisplayIdentifier: ""
 Format: ""
 BitMask: []
 AxisInfo: []
RecordLayout: ""
 Dimensions: []
 Export: 1
SymbolLink: [1x1 struct]
```

To modify any property of the characteristic, use set function. Update the "UpperLimit" field of the characteristic using the command:

```
set(descObj, "Characteristic", "Custom_parameter1", UpperLimit=128)
```

Generate the ASAP2 file using the updated ECU description object and verify that the ASAP2 file contains the characteristic with name "Custom\_parameter1".

```
coder.asap2.export("rtwdemo_asap2", CustomEcuDescriptions=descObj);
```

Following Characteristics or Measurements with unsupported data types are not exported in ASAP2

Remove the newly added characteristic from the description object using the command:

```
delete(descObj, "Characteristic", "Custom_parameter1");
```

### **Create and Add Custom Measurement**

To add a new measurement to the ASAP2 file, create a custom measurement using the commands:

```
Signal_1 = coder.asap2.Measurement;
Signal_1.Name = 'Custom_signal1';
Signal_1.LongIdentifier = 'longIdentifierSignal';
Signal_1.UpperLimit = 255;
Signal_1.LowerLimit = 0;
```

Add the custom measurement to the ECU description object using the command:

```
add(descObj, Signal_1);
```

Get the properties of the newly added measurement using the command:

```
get(descObj, "Measurement", "Custom_signal1")
```

```
ans =
 Measurement with properties:

 Name: 'Custom_signal1'
 LongIdentifier: 'longIdentifierSignal'
 DataType: 'UBYTE'
 EcuAddress: '0x0000'
 CompuMethodName: ""
 LowerLimit: 0
 UpperLimit: 255
 Raster: [1x1 struct]
 EcuAddressComment: ""
 EcuAddressExtension: []
```

```

CalibrationAccess: 'NoCalibration'
DisplayIdentifier: ""
 Format: ""
 BitMask: []
 Dimensions: []
 Export: 1
SymbolLink: [1x1 struct]

```

To modify any property of the measurement, use set function. Update the "CalibrationAccess" field of the measurement using the command:

```
set(descObj, "Measurement", "Custom_signal1", CalibrationAccess='Calibration')
```

Generate the ASAP2 file using the updated ECU description object and verify that the ASAP2 file contains the measurement with name "Custom\_signal1".

```
coder.asap2.export("rtwdemo_asap2", CustomEcuDescriptions=descObj);
```

Following Characteristics or Measurements with unsupported data types are not exported in ASAP2

Remove the newly added measurement from the description object using the command:

```
delete(descObj, "Measurement", "Custom_signal1");
```

### Create and Add a Lookup Table Parameter

To add a lookup table parameter, create a parameter using the commands:

```
LUT_Parameter = coder.asap2.Characteristic;
LUT_Parameter.Name = "custom_lookup_table";
LUT_Parameter.Type = "MAP";
```

Create and add axis information to the parameter.

```
axis_data = coder.asap2.AxisInfo;
axis_data(1).Name = 'BP3';
axis_data(2).Name = 'Bp4';
axis_data(1).CompuMethodName = 'rtwdemo_asap2_CM_double';
axis_data(2).CompuMethodName = 'rtwdemo_asap2_CM_double';
axis_data(1).MaxAxisPoints = '3';
axis_data(2).MaxAxisPoints = '3';
axis_data(1).AxisType = 'STD_AXIS';
axis_data(2).AxisType = 'STD_AXIS';
LUT_Parameter.AxisInfo = axis_data;
```

Add the lookup table parameter to the description object.

```
add(descObj, LUT_Parameter)
```

Generate the ASAP2 file using the updated ECU description object and verify that the ASAP2 file contains the lookup table parameter with name "custom\_lookup\_table".

```
coder.asap2.export("rtwdemo_asap2", CustomEcuDescriptions=descObj);
```

Following Characteristics or Measurements with unsupported data types are not exported in ASAP2 .

## **Version History**

**Introduced in R2022b**

### **See Also**

add | delete | find | get | set

# add

**Package:** coder.asap2

Add element to ASAP2 file

## Syntax

`add(descObj, object)`

## Description

`add(descObj, object)` adds the new custom ASAP2 element object to ECU description object `descObj` in order to generate an ASAP2 file with new element.

## Examples

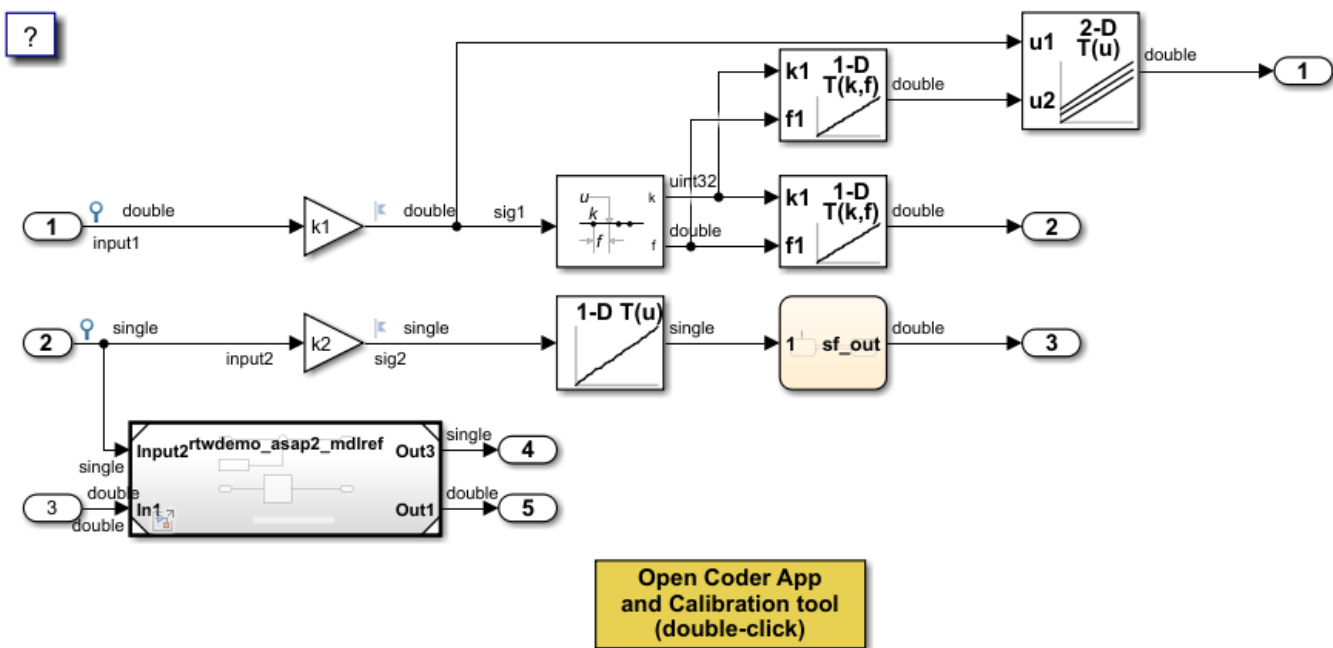
### Customize an ASAP2 File

This example shows how to add, update, filter, find, and remove ECU descriptions in an ASAP2 file.

### Open and build the example model

Open the example model `rtwdemo_asap2`

```
open_system("rtwdemo_asap2");
```



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Build the model.

```
rtwbuild("rtwdemo_asap2");
Starting serial model reference code generation build.
Successfully updated the model reference code generation target for: rtwdemo_asap2_mdref
Starting build procedure for: rtwdemo_asap2
Successful completion of build procedure for: rtwdemo_asap2
```

Build Summary

Code generation targets built:

| Model               | Action                       | Rebuild Reason                        |
|---------------------|------------------------------|---------------------------------------|
| rtwdemo_asap2_mdref | Code generated and compiled. | rtwdemo_asap2_mdref.c does not exist. |

Top model targets built:

| Model         | Action                       | Rebuild Reason                                   |
|---------------|------------------------------|--------------------------------------------------|
| rtwdemo_asap2 | Code generated and compiled. | Code generation information file does not exist. |

2 of 2 models built (0 models already up to date)  
Build duration: 0h 0m 30.237s

Create the ECU description object for the model.

```
descObj=coder.asap2.getEcuDescriptions("rtwdemo_asap2");
```

Get the list of available compu methods in the description object using the command:

```
find(descObj,"CompuMethod")
ans = 1x10 string
 Columns 1 through 3
 "rtwdemo_asap2_CM..." "rtwdemo_asap2_CM..." "rtwdemo_asap2_CM..."
 Columns 4 through 6
 "rtwdemo_asap2_CM..." "rtwdemo_asap2_CM..." "rtwdemo_asap2_CM..."
 Columns 7 through 9
 "rtwdemo_asap2_CM..." "rtwdemo_asap2_CM..." "rtwdemo_asap2_md..."
 Column 10
 "rtwdemo_asap2_md..."
```

Filter the compu methods and get the list of compu methods with units as "rpm".

```
find(descObj,"CompuMethod",Units='rpm')
ans = 1x3 string
 "rtwdemo_asap2_CM..." "rtwdemo_asap2_CM..." "rtwdemo_asap2_md..."
```

## Create and Add a Custom Compu Method

To add a new compu method to the ASAP2 file, create a custom compu method using the commands:

```
CompuMethod_CM1 = coder.asap2.CompuMethod;
CompuMethod_CM1.Name = 'CompuMethod_1';
CompuMethod_CM1.ConversionType = 'LINEAR';
CompuMethod_CM1.Coefficients = [2 3];
CompuMethod_CM1.LongIdentifier = 'longIdentifierTest';
CompuMethod_CM1.Format = '%2.3';
CompuMethod_CM1.Units = 's';
```

Add the custom compu method to the ECU description object using the command:

```
add(descObj, CompuMethod_CM1);
```

Get the properties of the newly added compu method using the command:

```
get(descObj, "CompuMethod", "CompuMethod_1")
```

```
ans =
 CompuMethod with properties:

 Name: 'CompuMethod_1'
 LongIdentifier: 'longIdentifierTest'
 Format: '%2.3'
 Units: 's'
 Coefficients: [2 3]
 ConversionType: 'LINEAR'
 CompuVTabValues: [1x1 struct]
```

To modify any property of the compu method, use set function. Update the "LongIdentifier" field of the compu method using the command:

```
set(descObj, "CompuMethod", "CompuMethod_1", LongIdentifier="longIdentifierCM1")
```

Generate the ASAP2 file using the updated ECU description object and verify that the ASAP2 file contains the compu method with name "CompuMethod\_1".

```
coder.asap2.export("rtwdemo_asap2", CustomEcuDescriptions=descObj);
```

Following Characteristics or Measurements with unsupported data types are not exported in ASAP2

## Delete a Compu Method

Remove the newly added compu method from the description object using the command:

```
delete(descObj, "CompuMethod", "CompuMethod_1");
```

## Create and Add Custom Characteristic

To add a new characteristic to the ASAP2 file, create a custom characteristic using the commands:

```
Parameter_1 = coder.asap2.Characteristic;
Parameter_1.Name = 'Custom_parameter1';
Parameter_1.LongIdentifier = 'longIdentifierParam';
Parameter_1.UpperLimit = 255;
Parameter_1.LowerLimit = 0;
```

Add the custom characteristic to the ECU description object using the command:

```
add(descObj,Parameter_1);
```

Get the properties of the newly added characteristic using the command:

```
get(descObj,"Characteristic","Custom_parameter1")
```

```
ans =
```

```
Characteristic with properties:
```

```
 Name: 'Custom_parameter1'
 LongIdentifier: 'longIdentifierParam'
 Type: 'VALUE'
 EcuAddress: '0x0000'
 CompuMethodName: 'NO_COMPU_METHOD'
 LowerLimit: 0
 UpperLimit: 255
 EcuAddressComment: ''
 EcuAddressExtension: []
 CalibrationAccess: 'Calibration'
 DisplayIdentifier: ''
 Format: ''
 BitMask: []
 AxisInfo: []
 RecordLayout: ''
 Dimensions: []
 Export: 1
 SymbolLink: [1x1 struct]
```

To modify any property of the characteristic, use set function. Update the "UpperLimit" field of the characteristic using the command:

```
set(descObj,"Characteristic","Custom_parameter1",UpperLimit=128)
```

Generate the ASAP2 file using the updated ECU description object and verify that the ASAP2 file contains the characteristic with name "Custom\_parameter1".

```
coder.asap2.export("rtwdemo_asap2",CustomEcuDescriptions=descObj);
```

Following Characteristics or Measurements with unsupported data types are not exported in ASAP2

Remove the newly added characteristic from the description object using the command:

```
delete(descObj,"Characteristic","Custom_parameter1");
```

### **Create and Add Custom Measurement**

To add a new measurement to the ASAP2 file, create a custom measurement using the commands:

```
Signal_1 = coder.asap2.Measurement;
Signal_1.Name = 'Custom_signal1';
Signal_1.LongIdentifier = 'longIdentifierSignal';
Signal_1.UpperLimit = 255;
Signal_1.LowerLimit = 0;
```

Add the custom measurement to the ECU description object using the command:



```
add(descObj,Signal_1);
```

Get the properties of the newly added measurement using the command:

```
get(descObj,"Measurement","Custom_signal1")
```

```
ans =
```

```
Measurement with properties:
```

```

 Name: 'Custom_signal1'
 LongIdentifier: 'longIdentifierSignal'
 DataType: 'UBYTE'
 EcuAddress: '0x0000'
 CompuMethodName: ""
 LowerLimit: 0
 UpperLimit: 255
 Raster: [1x1 struct]
 EcuAddressComment: ""
 EcuAddressExtension: []
 CalibrationAccess: 'NoCalibration'
 DisplayIdentifier: ""
 Format: ""
 BitMask: []
 Dimensions: []
 Export: 1
 SymbolLink: [1x1 struct]

```

To modify any property of the measurement, use set function. Update the "CalibrationAccess" field of the measurement using the command:

```
set(descObj,"Measurement","Custom_signal1",CalibrationAccess='Calibration')
```

Generate the ASAP2 file using the updated ECU description object and verify that the ASAP2 file contains the measurement with name "Custom\_signal1".

```
coder.asap2.export("rtwdemo_asap2",CustomEcuDescriptions=descObj);
```

Following Characteristics or Measurements with unsupported data types are not exported in ASAP2

Remove the newly added measurement from the description object using the command:

```
delete(descObj,"Measurement","Custom_signal1");
```

### Create and Add a Lookup Table Parameter

To add a lookup table parameter, create a parameter using the commands:

```

LUT_Parameter = coder.asap2.Characteristic;
LUT_Parameter.Name = "custom_lookup_table";
LUT_Parameter.Type = "MAP";

```

Create and add axis information to the parameter.

```

axis_data = coder.asap2.AxisInfo;
axis_data(1).Name = 'BP3';
axis_data(2).Name = 'Bp4';
axis_data(1).CompuMethodName = 'rtwdemo_asap2_CM_double';
axis_data(2).CompuMethodName = 'rtwdemo_asap2_CM_double';

```

```
axis_data(1).MaxAxisPoints = '3';
axis_data(2).MaxAxisPoints = '3';
axis_data(1).AxisType = 'STD_AXIS';
axis_data(2).AxisType = 'STD_AXIS';
LUT_Parameter.AxisInfo = axis_data;
```

Add the lookup table parameter to the description object.

```
add(descObj, LUT_Parameter)
```

Generate the ASAP2 file using the updated ECU description object and verify that the ASAP2 file contains the lookup table parameter with name "custom\_lookup\_table".

```
coder.asap2.export("rtwdemo_asap2", CustomEcuDescriptions=descObj);
```

Following Characteristics or Measurements with unsupported data types are not exported in ASAP2

## Input Arguments

### **descObj** — ECU description object

getEcuDescriptions object

Information object created by using the `coder.asap2.getEcuDescriptions` function containing the ASAP2 properties of a given model.

Example: `descObj = coder.asap2.getEcuDescriptions(<modelName>)`

### **object** — Custom ASAP2 element

`coder.asap2.AxisInfo` object | `coder.asap2.Characteristic` object | `coder.asap2.CompuMethod` object | `coder.asap2.Function` object | `coder.asap2.Measurement` object

Create an object representing ASAP2 element such as characteristic, measurement, axis-point, function, or compu method. Add the object to the existing information object and export it to the ASAP2 file.

```
Example: CompuMethod_CM1 = coder.asap2.CompuMethod;
add(descObj, CompuMethod_CM1); coder.asap2.export(<modelName>, CustomEcuDescriptions=descObj)
```

## Version History

Introduced in R2022b

### See Also

`get` | `set` | `find` | `delete` | `coder.asap2.getEcuDescriptions`

# delete

**Package:** coder.asap2

Remove element from ASAP2 file

## Syntax

```
delete(descObj, category, name)
```

## Description

`delete(descObj, category, name)` removes the ASAP2 element of the specified name, category from the descObj, and deletes the element from ASAP2 file.

## Examples

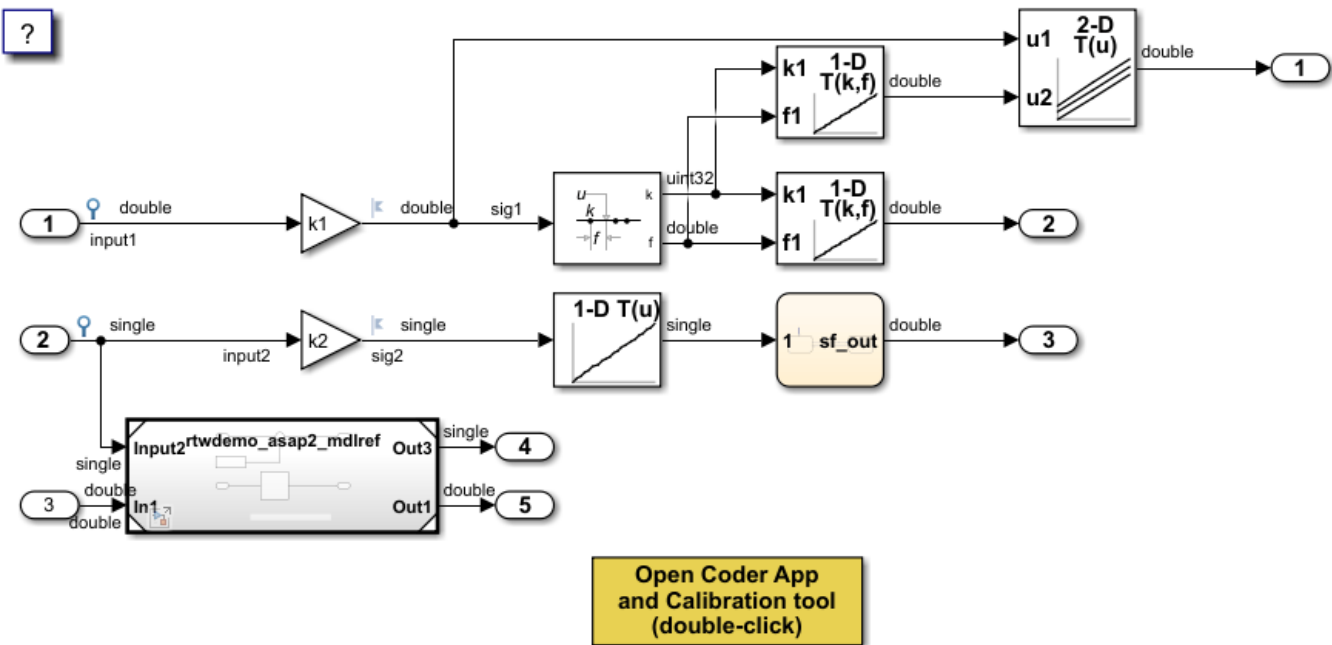
### Customize an ASAP2 File

This example shows how to add, update, filter, find, and remove ECU descriptions in an ASAP2 file.

### Open and build the example model

Open the example model `rtwdemo_asap2`

```
open_system("rtwdemo_asap2");
```



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Build the model.

```
rtwbuild("rtwdemo_asap2");

Starting serial model reference code generation build.
Successfully updated the model reference code generation target for: rtwdemo_asap2_mdref
Starting build procedure for: rtwdemo_asap2
Successful completion of build procedure for: rtwdemo_asap2
```

Build Summary

Code generation targets built:

| Model               | Action                       | Rebuild Reason                        |
|---------------------|------------------------------|---------------------------------------|
| rtwdemo_asap2_mdref | Code generated and compiled. | rtwdemo_asap2_mdref.c does not exist. |

Top model targets built:

| Model         | Action                       | Rebuild Reason                                   |
|---------------|------------------------------|--------------------------------------------------|
| rtwdemo_asap2 | Code generated and compiled. | Code generation information file does not exist. |

2 of 2 models built (0 models already up to date)  
Build duration: 0h 0m 30.237s

Create the ECU description object for the model.

```
descObj=coder.asap2.getEcuDescriptions("rtwdemo_asap2");
```

Get the list of available compu methods in the description object using the command:

```
find(descObj,"CompuMethod")

ans = 1x10 string
 Columns 1 through 3
 "rtwdemo_asap2_CM..." "rtwdemo_asap2_CM..." "rtwdemo_asap2_CM..."
 Columns 4 through 6
 "rtwdemo_asap2_CM..." "rtwdemo_asap2_CM..." "rtwdemo_asap2_CM..."
 Columns 7 through 9
 "rtwdemo_asap2_CM..." "rtwdemo_asap2_CM..." "rtwdemo_asap2_md..."
 Column 10
 "rtwdemo_asap2_md..."
```

Filter the compu methods and get the list of compu methods with units as "rpm".

```
find(descObj,"CompuMethod",Units='rpm')

ans = 1x3 string
 "rtwdemo_asap2_CM..." "rtwdemo_asap2_CM..." "rtwdemo_asap2_md..."
```

## Create and Add a Custom Compu Method

To add a new compu method to the ASAP2 file, create a custom compu method using the commands:

```
CompuMethod_CM1 = coder.asap2.CompuMethod;
CompuMethod_CM1.Name = 'CompuMethod_1';
CompuMethod_CM1.ConversionType = 'LINEAR';
CompuMethod_CM1.Coefficients = [2 3];
CompuMethod_CM1.LongIdentifier = 'longIdentifierTest';
CompuMethod_CM1.Format = '%2.3';
CompuMethod_CM1.Units = 's';
```

Add the custom compu method to the ECU description object using the command:

```
add(descObj, CompuMethod_CM1);
```

Get the properties of the newly added compu method using the command:

```
get(descObj, "CompuMethod", "CompuMethod_1")
```

```
ans =
 CompuMethod with properties:

 Name: 'CompuMethod_1'
 LongIdentifier: 'longIdentifierTest'
 Format: '%2.3'
 Units: 's'
 Coefficients: [2 3]
 ConversionType: 'LINEAR'
 CompuVTabValues: [1x1 struct]
```

To modify any property of the compu method, use set function. Update the "LongIdentifier" field of the compu method using the command:

```
set(descObj, "CompuMethod", "CompuMethod_1", LongIdentifier="longIdentifierCM1")
```

Generate the ASAP2 file using the updated ECU description object and verify that the ASAP2 file contains the compu method with name "CompuMethod\_1".

```
coder.asap2.export("rtwdemo_asap2", CustomEcuDescriptions=descObj);
```

Following Characteristics or Measurements with unsupported data types are not exported in ASAP2

## Delete a Compu Method

Remove the newly added compu method from the description object using the command:

```
delete(descObj, "CompuMethod", "CompuMethod_1");
```

## Create and Add Custom Characteristic

To add a new characteristic to the ASAP2 file, create a custom characteristic using the commands:

```
Parameter_1 = coder.asap2.Characteristic;
Parameter_1.Name = 'Custom_parameter1';
Parameter_1.LongIdentifier = 'longIdentifierParam';
Parameter_1.UpperLimit = 255;
Parameter_1.LowerLimit = 0;
```

Add the custom characteristic to the ECU description object using the command:

```
add(descObj,Parameter_1);
```

Get the properties of the newly added characteristic using the command:

```
get(descObj,"Characteristic","Custom_parameter1")
```

```
ans =
```

```
Characteristic with properties:
```

```
 Name: 'Custom_parameter1'
 LongIdentifier: 'longIdentifierParam'
 Type: 'VALUE'
 EcuAddress: '0x0000'
 CompuMethodName: 'NO_COMPU_METHOD'
 LowerLimit: 0
 UpperLimit: 255
 EcuAddressComment: ''
 EcuAddressExtension: []
 CalibrationAccess: 'Calibration'
 DisplayIdentifier: ''
 Format: ''
 BitMask: []
 AxisInfo: []
 RecordLayout: ''
 Dimensions: []
 Export: 1
 SymbolLink: [1x1 struct]
```

To modify any property of the characteristic, use set function. Update the "UpperLimit" field of the characteristic using the command:

```
set(descObj,"Characteristic","Custom_parameter1",UpperLimit=128)
```

Generate the ASAP2 file using the updated ECU description object and verify that the ASAP2 file contains the characteristic with name "Custom\_parameter1".

```
coder.asap2.export("rtwdemo_asap2",CustomEcuDescriptions=descObj);
```

Following Characteristics or Measurements with unsupported data types are not exported in ASAP2

Remove the newly added characteristic from the description object using the command:

```
delete(descObj,"Characteristic","Custom_parameter1");
```

### **Create and Add Custom Measurement**

To add a new measurement to the ASAP2 file, create a custom measurement using the commands:

```
Signal_1 = coder.asap2.Measurement;
Signal_1.Name = 'Custom_signal1';
Signal_1.LongIdentifier = 'longIdentifierSignal';
Signal_1.UpperLimit = 255;
Signal_1.LowerLimit = 0;
```

Add the custom measurement to the ECU description object using the command:

```
add(descObj,Signal_1);
```

Get the properties of the newly added measurement using the command:

```
get(descObj,"Measurement","Custom_signal1")
```

```
ans =
```

```
Measurement with properties:
```

```

 Name: 'Custom_signal1'
 LongIdentifier: 'longIdentifierSignal'
 DataType: 'UBYTE'
 EcuAddress: '0x0000'
 CompuMethodName: ""
 LowerLimit: 0
 UpperLimit: 255
 Raster: [1x1 struct]
 EcuAddressComment: ""
 EcuAddressExtension: []
 CalibrationAccess: 'NoCalibration'
 DisplayIdentifier: ""
 Format: ""
 BitMask: []
 Dimensions: []
 Export: 1
 SymbolLink: [1x1 struct]

```

To modify any property of the measurement, use set function. Update the "CalibrationAccess" field of the measurement using the command:

```
set(descObj,"Measurement","Custom_signal1",CalibrationAccess='Calibration')
```

Generate the ASAP2 file using the updated ECU description object and verify that the ASAP2 file contains the measurement with name "Custom\_signal1".

```
coder.asap2.export("rtwdemo_asap2",CustomEcuDescriptions=descObj);
```

Following Characteristics or Measurements with unsupported data types are not exported in ASAP2

Remove the newly added measurement from the description object using the command:

```
delete(descObj,"Measurement","Custom_signal1");
```

### Create and Add a Lookup Table Parameter

To add a lookup table parameter, create a parameter using the commands:

```
LUT_Parameter = coder.asap2.Characteristic;
LUT_Parameter.Name = "custom_lookup_table";
LUT_Parameter.Type = "MAP";
```

Create and add axis information to the parameter.

```
axis_data = coder.asap2.AxisInfo;
axis_data(1).Name = 'BP3';
axis_data(2).Name = 'Bp4';
axis_data(1).CompuMethodName = 'rtwdemo_asap2_CM_double';
axis_data(2).CompuMethodName = 'rtwdemo_asap2_CM_double';
```

```
axis_data(1).MaxAxisPoints = '3';
axis_data(2).MaxAxisPoints = '3';
axis_data(1).AxisType = 'STD_AXIS';
axis_data(2).AxisType = 'STD_AXIS';
LUT_Parameter.AxisInfo = axis_data;
```

Add the lookup table parameter to the description object.

```
add(descObj,LUT_Parameter)
```

Generate the ASAP2 file using the updated ECU description object and verify that the ASAP2 file contains the lookup table parameter with name "custom\_lookup\_table".

```
coder.asap2.export("rtwdemo_asap2",CustomEcuDescriptions=descObj);
```

Following Characteristics or Measurements with unsupported data types are not exported in ASAP2

## Input Arguments

### **descObj** — ECU description object

getEcuDescriptions object

Information object created by using the `coder.asap2.getEcuDescriptions` function containing the ASAP2 properties of a given model.

Example: `descObj = coder.asap2.getEcuDescriptions(<modelName>)`

### **category** — Category in ECU descriptions

AxisPoint | Characteristic | CompuMethod | Function | Measurement

Specify the category of the element to remove it from the ECU description.

Example: `Characteristic`

### **name** — Name from the category

char vector | string scalar

Specify the name available in the specified category to remove it from the ECU description and ASAP2 file.

Example: `Compu_Method1`

Example: `Parameter_p1`

## Version History

**Introduced in R2022b**

### See Also

`add` | `get` | `set` | `find` | `coder.asap2.getEcuDescriptions`



# find

**Package:** coder.asap2

Filter and get ECU description names

## Syntax

```
find(descObj, category)
find(descObj, category, property=value)
```

## Description

`find(descObj, category)` returns the available ASAP2 element names from the specified category.

`find(descObj, category, property=value)` filters and returns the available ASAP2 element names from the specified category with the specified property set to value.

## Examples

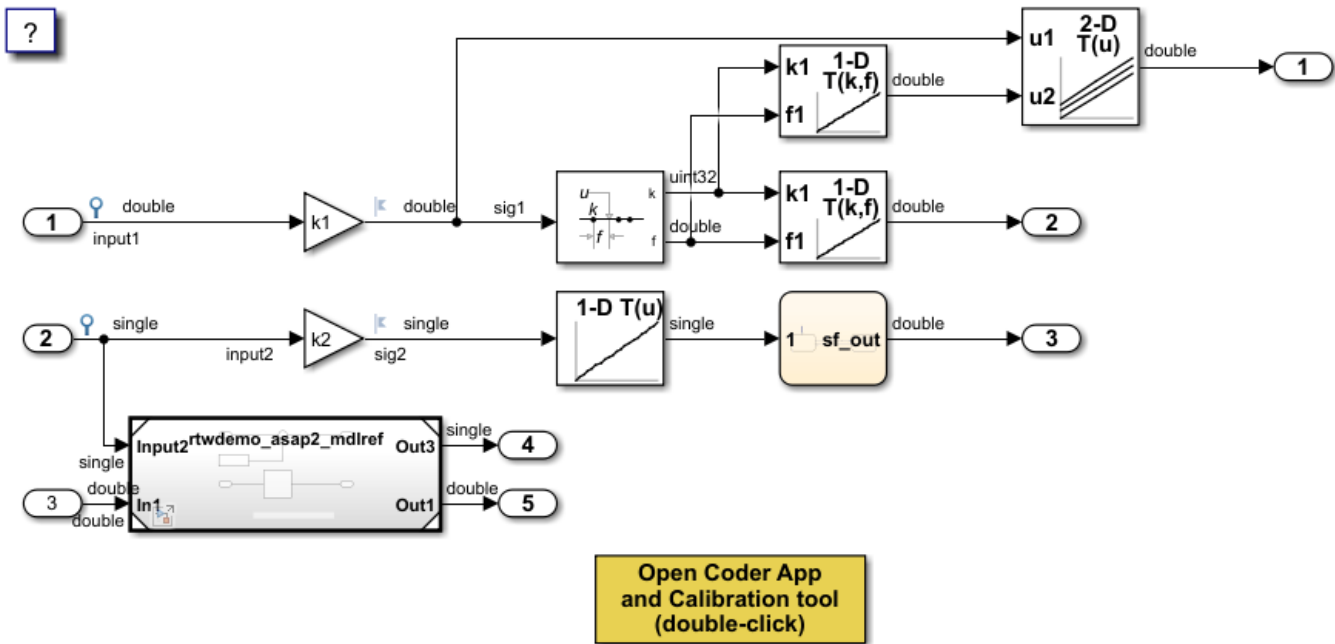
### Customize an ASAP2 File

This example shows how to add, update, filter, find, and remove ECU descriptions in an ASAP2 file.

### Open and build the example model

Open the example model `rtwdemo_asap2`

```
open_system("rtwdemo_asap2");
```



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Build the model.

```
rtwbuild("rtwdemo_asap2");
```

```
Starting serial model reference code generation build.
Successfully updated the model reference code generation target for: rtwdemo_asap2_mdref
Starting build procedure for: rtwdemo_asap2
Successful completion of build procedure for: rtwdemo_asap2
```

Build Summary

Code generation targets built:

| Model               | Action                       | Rebuild Reason                        |
|---------------------|------------------------------|---------------------------------------|
| rtwdemo_asap2_mdref | Code generated and compiled. | rtwdemo_asap2_mdref.c does not exist. |

Top model targets built:

| Model         | Action                       | Rebuild Reason                                   |
|---------------|------------------------------|--------------------------------------------------|
| rtwdemo_asap2 | Code generated and compiled. | Code generation information file does not exist. |

2 of 2 models built (0 models already up to date)  
Build duration: 0h 0m 30.237s

Create the ECU description object for the model.

```
descObj=coder.asap2.getEcuDescriptions("rtwdemo_asap2");
```

Get the list of available compu methods in the description object using the command:

```
find(descObj, "CompuMethod")
```

```
ans = 1x10 string
 Columns 1 through 3
 "rtwdemo_asap2_CM..." "rtwdemo_asap2_CM..." "rtwdemo_asap2_CM..."
 Columns 4 through 6
 "rtwdemo_asap2_CM..." "rtwdemo_asap2_CM..." "rtwdemo_asap2_CM..."
 Columns 7 through 9
 "rtwdemo_asap2_CM..." "rtwdemo_asap2_CM..." "rtwdemo_asap2_md..."
 Column 10
 "rtwdemo_asap2_md..."
```

Filter the compu methods and get the list of compu methods with units as "rpm".

```
find(descObj, "CompuMethod", Units='rpm')

ans = 1x3 string
 "rtwdemo_asap2_CM..." "rtwdemo_asap2_CM..." "rtwdemo_asap2_md..."
```

### Create and Add a Custom Compu Method

To add a new compu method to the ASAP2 file, create a custom compu method using the commands:

```
CompuMethod_CM1 = coder.asap2.CompuMethod;
CompuMethod_CM1.Name = 'CompuMethod_1';
CompuMethod_CM1.ConversionType = 'LINEAR';
CompuMethod_CM1.Coefficients = [2 3];
CompuMethod_CM1.LongIdentifier = 'longIdentifierTest';
CompuMethod_CM1.Format = '%2.3';
CompuMethod_CM1.Units = 's';
```

Add the custom compu method to the ECU description object using the command:

```
add(descObj, CompuMethod_CM1);
```

Get the properties of the newly added compu method using the command:

```
get(descObj, "CompuMethod", "CompuMethod_1")
```

```
ans =
 CompuMethod with properties:
 Name: 'CompuMethod_1'
 LongIdentifier: 'longIdentifierTest'
 Format: '%2.3'
 Units: 's'
 Coefficients: [2 3]
 ConversionType: 'LINEAR'
 CompuVTabValues: [1x1 struct]
```

To modify any property of the compu method, use set function. Update the "LongIdentifier" field of the compu method using the command:

```
set(descObj, "CompuMethod", "CompuMethod_1", LongIdentifier="longIdentifierCM1")
```

Generate the ASAP2 file using the updated ECU description object and verify that the ASAP2 file contains the compu method with name "CompuMethod\_1".

```
coder.asap2.export("rtwdemo_asap2", CustomEcuDescriptions=descObj);
```

Following Characteristics or Measurements with unsupported data types are not exported in ASAP2

### Delete a Compu Method

Remove the newly added compu method from the description object using the command:

```
delete(descObj, "CompuMethod", "CompuMethod_1");
```

### Create and Add Custom Characteristic

To add a new characteristic to the ASAP2 file, create a custom characteristic using the commands:

```
Parameter_1 = coder.asap2.Characteristic;
Parameter_1.Name = 'Custom_parameter1';
Parameter_1.LongIdentifier = 'longIdentifierParam';
Parameter_1.UpperLimit = 255;
Parameter_1.LowerLimit = 0;
```

Add the custom characteristic to the ECU description object using the command:

```
add(descObj, Parameter_1);
```

Get the properties of the newly added characteristic using the command:

```
get(descObj, "Characteristic", "Custom_parameter1")
```

```
ans =
 Characteristic with properties:

 Name: 'Custom_parameter1'
 LongIdentifier: 'longIdentifierParam'
 Type: 'VALUE'
 EcuAddress: '0x0000'
 CompuMethodName: 'NO_COMPU_METHOD'
 LowerLimit: 0
 UpperLimit: 255
 EcuAddressComment: ''
 EcuAddressExtension: []
 CalibrationAccess: 'Calibration'
 DisplayIdentifier: ''
 Format: ''
 BitMask: []
 AxisInfo: []
 RecordLayout: ''
 Dimensions: []
 Export: 1
 SymbolLink: [1x1 struct]
```

To modify any property of the characteristic, use set function. Update the "UpperLimit" field of the characteristic using the command:

```
set(descObj, "Characteristic", "Custom_parameter1", UpperLimit=128)
```

Generate the ASAP2 file using the updated ECU description object and verify that the ASAP2 file contains the characteristic with name "Custom\_parameter1".

```
coder.asap2.export("rtwdemo_asap2", CustomEcuDescriptions=descObj);
```

Following Characteristics or Measurements with unsupported data types are not exported in ASAP2

Remove the newly added characteristic from the description object using the command:

```
delete(descObj, "Characteristic", "Custom_parameter1");
```

### Create and Add Custom Measurement

To add a new measurement to the ASAP2 file, create a custom measurement using the commands:

```
Signal_1 = coder.asap2.Measurement;
Signal_1.Name = 'Custom_signal1';
Signal_1.LongIdentifier = 'longIdentifierSignal';
Signal_1.UpperLimit = 255;
Signal_1.LowerLimit = 0;
```

Add the custom measurement to the ECU description object using the command:

```
add(descObj, Signal_1);
```

Get the properties of the newly added measurement using the command:

```
get(descObj, "Measurement", "Custom_signal1")
```

```
ans =
 Measurement with properties:
 Name: 'Custom_signal1'
 LongIdentifier: 'longIdentifierSignal'
 DataType: 'UBYTE'
 EcuAddress: '0x0000'
 CompuMethodName: ''
 LowerLimit: 0
 UpperLimit: 255
 Raster: [1x1 struct]
 EcuAddressComment: ''
 EcuAddressExtension: []
 CalibrationAccess: 'NoCalibration'
 DisplayIdentifier: ''
 Format: ''
 BitMask: []
 Dimensions: []
 Export: 1
 SymbolLink: [1x1 struct]
```

To modify any property of the measurement, use set function. Update the "CalibrationAccess" field of the measurement using the command:

```
set(descObj, "Measurement", "Custom_signal1", CalibrationAccess='Calibration')
```

Generate the ASAP2 file using the updated ECU description object and verify that the ASAP2 file contains the measurement with name "Custom\_signal1".

```
coder.asap2.export("rtwdemo_asap2", CustomEcuDescriptions=descObj);
```

Following Characteristics or Measurements with unsupported data types are not exported in ASAP2 .

Remove the newly added measurement from the description object using the command:

```
delete(descObj, "Measurement", "Custom_signal1");
```

### Create and Add a Lookup Table Parameter

To add a lookup table parameter, create a parameter using the commands:

```
LUT_Parameter = coder.asap2.Characteristic;
LUT_Parameter.Name = "custom_lookup_table";
LUT_Parameter.Type = "MAP";
```

Create and add axis information to the parameter.

```
axis_data = coder.asap2.AxisInfo;
axis_data(1).Name = 'BP3';
axis_data(2).Name = 'Bp4';
axis_data(1).CompuMethodName = 'rtwdemo_asap2_CM_double';
axis_data(2).CompuMethodName = 'rtwdemo_asap2_CM_double';
axis_data(1).MaxAxisPoints = '3';
axis_data(2).MaxAxisPoints = '3';
axis_data(1).AxisType = 'STD_AXIS';
axis_data(2).AxisType = 'STD_AXIS';
LUT_Parameter.AxisInfo = axis_data;
```

Add the lookup table parameter to the description object.

```
add(descObj, LUT_Parameter)
```

Generate the ASAP2 file using the updated ECU description object and verify that the ASAP2 file contains the lookup table parameter with name "custom\_lookup\_table".

```
coder.asap2.export("rtwdemo_asap2", CustomEcuDescriptions=descObj);
```

Following Characteristics or Measurements with unsupported data types are not exported in ASAP2 .

## Input Arguments

### descObj — ECU description object

getEcuDescriptions object

Information object created by using the `coder.asap2.getEcuDescriptions` function containing the ASAP2 properties of a given model.

Example: `descObj = coder.asap2.getEcuDescriptions(<modelName>)`

### category — Category in ECU descriptions

AxisPoint | Characteristic | CompuMethod | Function | Measurement | RecordLayout

Specify the category available in the information object to fetch the available ECU description names.

Example: `Characteristic`

Example: `RecordLayout`

**property – Property to filter the ECU description names**

`char` | `string`

Specify a property and value to filter the list of available ECU description names in the category.

Example: `Units = 'rpm'`

## **Version History**

**Introduced in R2022b**

### **See Also**

`add` | `get` | `set` | `delete` | `coder.asap2.getEcuDescriptions`

# get

**Package:** coder.asap2

Return ASAP2 properties of data element

## Syntax

`get(descObj, category, name)`

## Description

`get(descObj, category, name)` returns the ASAP2 properties of the name for a given category.

## Examples

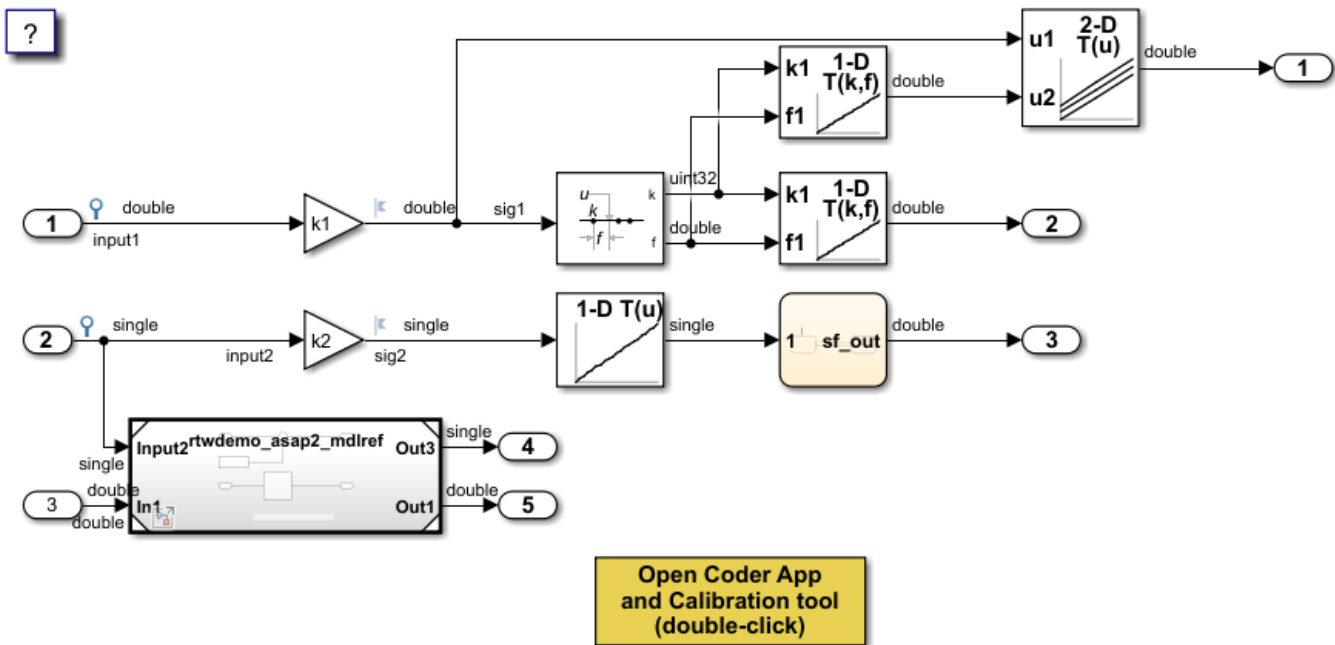
### Customize an ASAP2 File

This example shows how to add, update, filter, find, and remove ECU descriptions in an ASAP2 file.

### Open and build the example model

Open the example model `rtwdemo_asap2`

```
open_system("rtwdemo_asap2");
```



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Build the model.

```
rtwbuild("rtwdemo_asap2");
Starting serial model reference code generation build.
Successfully updated the model reference code generation target for: rtwdemo_asap2_mdref
Starting build procedure for: rtwdemo_asap2
Successful completion of build procedure for: rtwdemo_asap2
```

Build Summary

Code generation targets built:

| Model               | Action                       | Rebuild Reason                        |
|---------------------|------------------------------|---------------------------------------|
| rtwdemo_asap2_mdref | Code generated and compiled. | rtwdemo_asap2_mdref.c does not exist. |

Top model targets built:

| Model         | Action                       | Rebuild Reason                                   |
|---------------|------------------------------|--------------------------------------------------|
| rtwdemo_asap2 | Code generated and compiled. | Code generation information file does not exist. |

2 of 2 models built (0 models already up to date)  
Build duration: 0h 0m 30.237s

Create the ECU description object for the model.

```
descObj=coder.asap2.getEcuDescriptions("rtwdemo_asap2");
```

Get the list of available compu methods in the description object using the command:

```
find(descObj,"CompuMethod")
```

```
ans = 1x10 string
 Columns 1 through 3
 "rtwdemo_asap2_CM..." "rtwdemo_asap2_CM..." "rtwdemo_asap2_CM..."
 Columns 4 through 6
 "rtwdemo_asap2_CM..." "rtwdemo_asap2_CM..." "rtwdemo_asap2_CM..."
 Columns 7 through 9
 "rtwdemo_asap2_CM..." "rtwdemo_asap2_CM..." "rtwdemo_asap2_md..."
 Column 10
 "rtwdemo_asap2_md..."
```

Filter the compu methods and get the list of compu methods with units as "rpm".

```
find(descObj,"CompuMethod",Units='rpm')
```

```
ans = 1x3 string
 "rtwdemo_asap2_CM..." "rtwdemo_asap2_CM..." "rtwdemo_asap2_md..."
```

### Create and Add a Custom Compu Method

To add a new compu method to the ASAP2 file, create a custom compu method using the commands:

```
CompuMethod_CM1 = coder.asap2.CompuMethod;
CompuMethod_CM1.Name = 'CompuMethod_1';
CompuMethod_CM1.ConversionType = 'LINEAR';
CompuMethod_CM1.Coefficients = [2 3];
CompuMethod_CM1.LongIdentifier = 'longIdentifierTest';
CompuMethod_CM1.Format = '%2.3';
CompuMethod_CM1.Units = 's';
```

Add the custom compu method to the ECU description object using the command:

```
add(descObj, CompuMethod_CM1);
```

Get the properties of the newly added compu method using the command:

```
get(descObj, "CompuMethod", "CompuMethod_1")
```

```
ans =
 CompuMethod with properties:

 Name: 'CompuMethod_1'
 LongIdentifier: 'longIdentifierTest'
 Format: '%2.3'
 Units: 's'
 Coefficients: [2 3]
 ConversionType: 'LINEAR'
 CompuVTabValues: [1x1 struct]
```

To modify any property of the compu method, use set function. Update the "LongIdentifier" field of the compu method using the command:

```
set(descObj, "CompuMethod", "CompuMethod_1", LongIdentifier="longIdentifierCM1")
```

Generate the ASAP2 file using the updated ECU description object and verify that the ASAP2 file contains the compu method with name "CompuMethod\_1".

```
coder.asap2.export("rtwdemo_asap2", CustomEcuDescriptions=descObj);
```

Following Characteristics or Measurements with unsupported data types are not exported in ASAP2

### Delete a Compu Method

Remove the newly added compu method from the description object using the command:

```
delete(descObj, "CompuMethod", "CompuMethod_1");
```

### Create and Add Custom Characteristic

To add a new characteristic to the ASAP2 file, create a custom characteristic using the commands:

```
Parameter_1 = coder.asap2.Characteristic;
Parameter_1.Name = 'Custom_parameter1';
Parameter_1.LongIdentifier = 'longIdentifierParam';
Parameter_1.UpperLimit = 255;
Parameter_1.LowerLimit = 0;
```

Add the custom characteristic to the ECU description object using the command:

```
add(descObj,Parameter_1);
```

Get the properties of the newly added characteristic using the command:

```
get(descObj,"Characteristic","Custom_parameter1")
```

```
ans =
```

```
Characteristic with properties:
```

```

 Name: 'Custom_parameter1'
 LongIdentifier: 'longIdentifierParam'
 Type: 'VALUE'
 EcuAddress: '0x0000'
 CompuMethodName: 'NO_COMPU_METHOD'
 LowerLimit: 0
 UpperLimit: 255
 EcuAddressComment: ""
 EcuAddressExtension: []
 CalibrationAccess: 'Calibration'
 DisplayIdentifier: ""
 Format: ""
 BitMask: []
 AxisInfo: []
 RecordLayout: ""
 Dimensions: []
 Export: 1
 SymbolLink: [1x1 struct]
```

To modify any property of the characteristic, use set function. Update the "UpperLimit" field of the characteristic using the command:

```
set(descObj,"Characteristic","Custom_parameter1",UpperLimit=128)
```

Generate the ASAP2 file using the updated ECU description object and verify that the ASAP2 file contains the characteristic with name "Custom\_parameter1".

```
coder.asap2.export("rtwdemo_asap2",CustomEcuDescriptions=descObj);
```

Following Characteristics or Measurements with unsupported data types are not exported in ASAP2

Remove the newly added characteristic from the description object using the command:

```
delete(descObj,"Characteristic","Custom_parameter1");
```

### Create and Add Custom Measurement

To add a new measurement to the ASAP2 file, create a custom measurement using the commands:

```
Signal_1 = coder.asap2.Measurement;
Signal_1.Name = 'Custom_signal1';
Signal_1.LongIdentifier = 'longIdentifierSignal';
Signal_1.UpperLimit = 255;
Signal_1.LowerLimit = 0;
```

Add the custom measurement to the ECU description object using the command:

```
add(descObj,Signal_1);
```

Get the properties of the newly added measurement using the command:

```
get(descObj,"Measurement","Custom_signal1")
```

```
ans =
```

```
Measurement with properties:
```

```
 Name: 'Custom_signal1'
 LongIdentifier: 'longIdentifierSignal'
 DataType: 'UBYTE'
 EcuAddress: '0x0000'
 CompuMethodName: ""
 LowerLimit: 0
 UpperLimit: 255
 Raster: [1x1 struct]
 EcuAddressComment: ""
 EcuAddressExtension: []
 CalibrationAccess: 'NoCalibration'
 DisplayIdentifier: ""
 Format: ""
 BitMask: []
 Dimensions: []
 Export: 1
 SymbolLink: [1x1 struct]
```

To modify any property of the measurement, use set function. Update the "CalibrationAccess" field of the measurement using the command:

```
set(descObj,"Measurement","Custom_signal1",CalibrationAccess='Calibration')
```

Generate the ASAP2 file using the updated ECU description object and verify that the ASAP2 file contains the measurement with name "Custom\_signal1".

```
coder.asap2.export("rtwdemo_asap2",CustomEcuDescriptions=descObj);
```

Following Characteristics or Measurements with unsupported data types are not exported in ASAP2

Remove the newly added measurement from the description object using the command:

```
delete(descObj,"Measurement","Custom_signal1");
```

### **Create and Add a Lookup Table Parameter**

To add a lookup table parameter, create a parameter using the commands:

```
LUT_Parameter = coder.asap2.Characteristic;
LUT_Parameter.Name = "custom_lookup_table";
LUT_Parameter.Type = "MAP";
```

Create and add axis information to the parameter.

```
axis_data = coder.asap2.AxisInfo;
axis_data(1).Name = 'BP3';
axis_data(2).Name = 'Bp4';
axis_data(1).CompuMethodName = 'rtwdemo_asap2_CM_double';
axis_data(2).CompuMethodName = 'rtwdemo_asap2_CM_double';
```

```
axis_data(1).MaxAxisPoints = '3';
axis_data(2).MaxAxisPoints = '3';
axis_data(1).AxisType = 'STD_AXIS';
axis_data(2).AxisType = 'STD_AXIS';
LUT_Parameter.AxisInfo = axis_data;
```

Add the lookup table parameter to the description object.

```
add(descObj,LUT_Parameter)
```

Generate the ASAP2 file using the updated ECU description object and verify that the ASAP2 file contains the lookup table parameter with name "custom\_lookup\_table".

```
coder.asap2.export("rtwdemo_asap2",CustomEcuDescriptions=descObj);
```

Following Characteristics or Measurements with unsupported data types are not exported in ASAP2

## Input Arguments

### **descObj** — ECU description object

getEcuDescriptions object

Information object created by using the `coder.asap2.getEcuDescriptions` function containing the ASAP2 properties of a given model.

Example: `descObj = coder.asap2.getEcuDescriptions(<modelName>)`

### **category** — Category in ASAP2 element properties

AxisPoint | Characteristic | CompuMethod | Function | Measurement

Specify the category available in the information object to get the ASAP2 element.

Example: `Characteristic`

### **name** — Name from the category

char vector | string scalar

Specify the name available in the specified category to fetch the ASAP2 element.

Example: `CompuMethod1`

Example: `Parameter_p1`

## Version History

**Introduced in R2022b**

## See Also

`add` | `set` | `find` | `delete` | `coder.asap2.getEcuDescriptions`

# set

**Package:** coder.asap2

Set property for data element

## Syntax

```
set(descObj,category,name,Property = value)
```

## Description

set(descObj,category,name,Property = value) sets the value for the property Property, of the name in the category present in ECU description.

## Examples

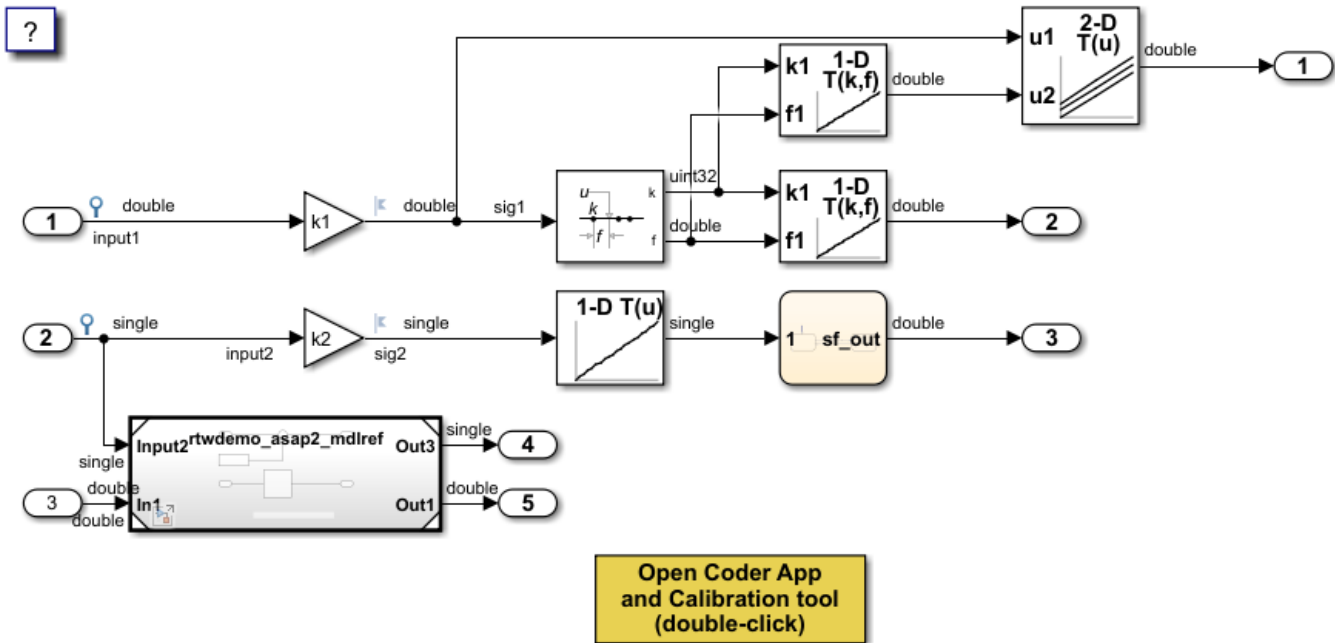
### Customize an ASAP2 File

This example shows how to add, update, filter, find, and remove ECU descriptions in an ASAP2 file.

### Open and build the example model

Open the example model rtwdemo\_asap2

```
open_system("rtwdemo_asap2");
```



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Build the model.

```
rtwbuild("rtwdemo_asap2");
Starting serial model reference code generation build.
Successfully updated the model reference code generation target for: rtwdemo_asap2_mdref
Starting build procedure for: rtwdemo_asap2
Successful completion of build procedure for: rtwdemo_asap2
```

Build Summary

Code generation targets built:

| Model               | Action                       | Rebuild Reason                        |
|---------------------|------------------------------|---------------------------------------|
| rtwdemo_asap2_mdref | Code generated and compiled. | rtwdemo_asap2_mdref.c does not exist. |

Top model targets built:

| Model         | Action                       | Rebuild Reason                                   |
|---------------|------------------------------|--------------------------------------------------|
| rtwdemo_asap2 | Code generated and compiled. | Code generation information file does not exist. |

2 of 2 models built (0 models already up to date)  
Build duration: 0h 0m 30.237s

Create the ECU description object for the model.

```
descObj=coder.asap2.getEcuDescriptions("rtwdemo_asap2");
```

Get the list of available compu methods in the description object using the command:

```
find(descObj,"CompuMethod")
ans = 1x10 string
 Columns 1 through 3
 "rtwdemo_asap2_CM..." "rtwdemo_asap2_CM..." "rtwdemo_asap2_CM..."
 Columns 4 through 6
 "rtwdemo_asap2_CM..." "rtwdemo_asap2_CM..." "rtwdemo_asap2_CM..."
 Columns 7 through 9
 "rtwdemo_asap2_CM..." "rtwdemo_asap2_CM..." "rtwdemo_asap2_md..."
 Column 10
 "rtwdemo_asap2_md..."
```

Filter the compu methods and get the list of compu methods with units as "rpm".

```
find(descObj,"CompuMethod",Units='rpm')
ans = 1x3 string
 "rtwdemo_asap2_CM..." "rtwdemo_asap2_CM..." "rtwdemo_asap2_md..."
```

### Create and Add a Custom Compu Method

To add a new compu method to the ASAP2 file, create a custom compu method using the commands:

```
CompuMethod_CM1 = coder.asap2.CompuMethod;
CompuMethod_CM1.Name = 'CompuMethod_1';
CompuMethod_CM1.ConversionType = 'LINEAR';
CompuMethod_CM1.Coefficients = [2 3];
CompuMethod_CM1.LongIdentifier = 'longIdentifierTest';
CompuMethod_CM1.Format = '%2.3';
CompuMethod_CM1.Units = 's';
```

Add the custom compu method to the ECU description object using the command:

```
add(descObj, CompuMethod_CM1);
```

Get the properties of the newly added compu method using the command:

```
get(descObj, "CompuMethod", "CompuMethod_1")
```

```
ans =
 CompuMethod with properties:

 Name: 'CompuMethod_1'
 LongIdentifier: 'longIdentifierTest'
 Format: '%2.3'
 Units: 's'
 Coefficients: [2 3]
 ConversionType: 'LINEAR'
 CompuVTabValues: [1x1 struct]
```

To modify any property of the compu method, use set function. Update the "LongIdentifier" field of the compu method using the command:

```
set(descObj, "CompuMethod", "CompuMethod_1", LongIdentifier="longIdentifierCM1")
```

Generate the ASAP2 file using the updated ECU description object and verify that the ASAP2 file contains the compu method with name "CompuMethod\_1".

```
coder.asap2.export("rtwdemo_asap2", CustomEcuDescriptions=descObj);
```

Following Characteristics or Measurements with unsupported data types are not exported in ASAP2

### Delete a Compu Method

Remove the newly added compu method from the description object using the command:

```
delete(descObj, "CompuMethod", "CompuMethod_1");
```

### Create and Add Custom Characteristic

To add a new characteristic to the ASAP2 file, create a custom characteristic using the commands:

```
Parameter_1 = coder.asap2.Characteristic;
Parameter_1.Name = 'Custom_parameter1';
Parameter_1.LongIdentifier = 'longIdentifierParam';
Parameter_1.UpperLimit = 255;
Parameter_1.LowerLimit = 0;
```



Add the custom characteristic to the ECU description object using the command:

```
add(descObj,Parameter_1);
```

Get the properties of the newly added characteristic using the command:

```
get(descObj,"Characteristic","Custom_parameter1")
```

```
ans =
```

```
Characteristic with properties:
```

```

 Name: 'Custom_parameter1'
 LongIdentifier: 'longIdentifierParam'
 Type: 'VALUE'
 EcuAddress: '0x0000'
 CompuMethodName: 'NO_COMPU_METHOD'
 LowerLimit: 0
 UpperLimit: 255
 EcuAddressComment: ""
 EcuAddressExtension: []
 CalibrationAccess: 'Calibration'
 DisplayIdentifier: ""
 Format: ""
 BitMask: []
 AxisInfo: []
 RecordLayout: ""
 Dimensions: []
 Export: 1
 SymbolLink: [1x1 struct]
```

To modify any property of the characteristic, use set function. Update the "UpperLimit" field of the characteristic using the command:

```
set(descObj,"Characteristic","Custom_parameter1",UpperLimit=128)
```

Generate the ASAP2 file using the updated ECU description object and verify that the ASAP2 file contains the characteristic with name "Custom\_parameter1".

```
coder.asap2.export("rtwdemo_asap2",CustomEcuDescriptions=descObj);
```

Following Characteristics or Measurements with unsupported data types are not exported in ASAP2

Remove the newly added characteristic from the description object using the command:

```
delete(descObj,"Characteristic","Custom_parameter1");
```

### Create and Add Custom Measurement

To add a new measurement to the ASAP2 file, create a custom measurement using the commands:

```
Signal_1 = coder.asap2.Measurement;
Signal_1.Name = 'Custom_signal1';
Signal_1.LongIdentifier = 'longIdentifierSignal';
Signal_1.UpperLimit = 255;
Signal_1.LowerLimit = 0;
```

Add the custom measurement to the ECU description object using the command:

```
add(descObj,Signal_1);
```

Get the properties of the newly added measurement using the command:

```
get(descObj,"Measurement","Custom_signal1")
```

```
ans =
```

```
Measurement with properties:
```

```

 Name: 'Custom_signal1'
 LongIdentifier: 'longIdentifierSignal'
 DataType: 'UBYTE'
 EcuAddress: '0x0000'
 CompuMethodName: ""
 LowerLimit: 0
 UpperLimit: 255
 Raster: [1x1 struct]
 EcuAddressComment: ""
 EcuAddressExtension: []
 CalibrationAccess: 'NoCalibration'
 DisplayIdentifier: ""
 Format: ""
 BitMask: []
 Dimensions: []
 Export: 1
 SymbolLink: [1x1 struct]

```

To modify any property of the measurement, use set function. Update the "CalibrationAccess" field of the measurement using the command:

```
set(descObj,"Measurement","Custom_signal1",CalibrationAccess='Calibration')
```

Generate the ASAP2 file using the updated ECU description object and verify that the ASAP2 file contains the measurement with name "Custom\_signal1".

```
coder.asap2.export("rtwdemo_asap2",CustomEcuDescriptions=descObj);
```

Following Characteristics or Measurements with unsupported data types are not exported in ASAP2

Remove the newly added measurement from the description object using the command:

```
delete(descObj,"Measurement","Custom_signal1");
```

### Create and Add a Lookup Table Parameter

To add a lookup table parameter, create a parameter using the commands:

```
LUT_Parameter = coder.asap2.Characteristic;
LUT_Parameter.Name = "custom_lookup_table";
LUT_Parameter.Type = "MAP";
```

Create and add axis information to the parameter.

```
axis_data = coder.asap2.AxisInfo;
axis_data(1).Name = 'BP3';
axis_data(2).Name = 'Bp4';
axis_data(1).CompuMethodName = 'rtwdemo_asap2_CM_double';
axis_data(2).CompuMethodName = 'rtwdemo_asap2_CM_double';
```

```
axis_data(1).MaxAxisPoints = '3';
axis_data(2).MaxAxisPoints = '3';
axis_data(1).AxisType = 'STD_AXIS';
axis_data(2).AxisType = 'STD_AXIS';
LUT_Parameter.AxisInfo = axis_data;
```

Add the lookup table parameter to the description object.

```
add(descObj,LUT_Parameter)
```

Generate the ASAP2 file using the updated ECU description object and verify that the ASAP2 file contains the lookup table parameter with name "custom\_lookup\_table".

```
coder.asap2.export("rtwdemo_asap2",CustomEcuDescriptions=descObj);
```

Following Characteristics or Measurements with unsupported data types are not exported in ASAP2

## Input Arguments

### **descObj** — ECU description object

getEcuDescriptions object

Information object created by using the `coder.asap2.getEcuDescriptions` function containing the ASAP2 properties of a given model.

Example: `descObj = coder.asap2.getEcuDescriptions(<modelName>)`

### **category** — Category in ECU descriptions

AxisPoint | Characteristic | CompuMethod | Function | Measurement

Specify the category available in the information object to set the ASAP2 element.

Example: `Characteristic`

### **name** — Name from the category

char vector | string scalar

Specify the name available in the specified category to set value to a property of the ASAP2 element.

Example: `CompuMethod1`

Example: `Parameter_p1`

### **Property** — Name of the property

char vector | string scalar

Specify a value for the property in the available names from the specified category of the ASAP2 elements.

Example: `descObj.set("CompuMethod","CompuMethod_CM1",Units='custom_units')`

Example: `descObj.set("Characteristic","Parameter_P1",DisplayIdentifier='ParamGain')`

## Version History

**Introduced in R2022b**

**See Also**

add | get | find | delete | coder.asap2.getEcuDescriptions

# extmodeBackgroundRun

Perform external mode background activity

## Syntax

```
errorCode = extmodeBackgroundRun();
```

## Description

`errorCode = extmodeBackgroundRun()`; performs external mode background activity, for example, retrieving packets from the network, running the packets protocol layer, and sending packets to the development computer.

Do not invoke the function in a thread with real-time constraints.

Use this function with other external mode functions to enable communication between Simulink and the target application during an external mode simulation.

## Examples

### Set Up External Mode Communication

For a pseudo-code example that shows how you can provide external mode communication by using the function with related functions, see “External Mode Abstraction Layer”.

## Output Arguments

### **errorCode** — Error detection

`extmodeErrorCode_T` enumeration

Error code, returned as an `extmodeErrorCode_T` enumeration with one of these values:

- `EXTMODE_SUCCESS` (0) -- No error detected.
- `EXTMODE_BUSY` (-6) -- Resource busy detected, try later
- `EXTMODE_INV_MSG_FORMAT` (-7) -- Invalid message format detected by external mode communication protocol.
- `EXTMODE_INV_SIZE` (-8) -- Invalid size detected by the external mode communication protocol.
- `EXTMODE_NOT_INITIALIZED` (-9) -- External mode not initialized yet.
- `EXTMODE_NO_MEMORY` (-10) -- No memory available on the target hardware.
- `EXTMODE_ERROR` (-12) -- External mode generic error detected.
- `EXTMODE_PKT_CHECKSUM_ERROR` (-13) -- Checksum inconsistency detected by external mode communication protocol.
- `EXTMODE_PKT_RX_TIMEOUT_ERROR` (-14) -- Timeout error detected during the reception of a packet.
- `EXTMODE_PKT_TX_TIMEOUT_ERROR` (-15) -- Timeout error detected during the transmission of a packet.

## **Version History**

**Introduced in R2018a**

### **See Also**

[extmodeEvent](#) | [extmodeGetFinalSimulationTime](#) | [extmodeInit](#) | [extmodeParseArgs](#) | [extmodeReset](#) | [extmodeSetFinalSimulationTime](#) | [extmodeSimulationComplete](#) | [extmodeStopRequested](#) | [extmodeWaitForHostRequest](#)

### **Topics**

["External Mode Simulation by Using XCP Communication"](#)

["Customize XCP Server Software"](#)

# extmodeEvent

External mode event trigger

## Syntax

```
errorCode = extmodeEvent(eventId, simulationTime)
```

## Description

`errorCode = extmodeEvent(eventId, simulationTime)` informs the external mode abstraction layer of the occurrence of an event.

`eventId` is the sample time ID of the model, for example, 0 for base rate, 1 for first subrate, and so on.

The function:

- Samples all signals associated with a given sample time.
- Stores signal values in a new packet buffer.
- Passes the packet buffer to the underlying transport layer for subsequent transmission to the development computer.

Use this function with other external mode functions to enable communication between Simulink and the target application during an external mode simulation.

For correct sampling of signal values, run the function immediately after `model_step()` for the corresponding sample time ID. You can invoke the function with different sample time IDs in separate threads because the function is thread-safe.

The `extmodeBackgroundRun` function performs the transmission of signal values to the development computer.

## Examples

### Set Up External Mode Communication

For a pseudo-code example that shows how you can provide external mode communication by using the function with related functions, see “External Mode Abstraction Layer”.

## Input Arguments

### eventId — Event ID

`uint16_T`

Sample time ID of the model, which is 0 for base rate, 1 for first subrate, 2 for second subrate, and so on.

### simulationTime — Simulation time

`real_T`

Time when event occurs.

## Output Arguments

### **errorCode** — Error detection

`extmodeErrorCode_T` enumeration

Error code, returned as an `extmodeErrorCode_T` enumeration with one of these values:

- `EXTMODE_SUCCESS` (0) -- No error detected.
- `EXTMODE_INV_ARG` (-1) -- Arguments invalid.
- `EXTMODE_NOT_INITIALIZED` (-9) -- External mode not initialized yet.
- `EXTMODE_NO_MEMORY` (-10) -- No memory available on the target hardware.

## Version History

Introduced in R2018a

### See Also

`extmodeBackgroundRun` | `extmodeGetFinalSimulationTime` | `extmodeInit` |  
`extmodeParseArgs` | `extmodeReset` | `extmodeSetFinalSimulationTime` |  
`extmodeSimulationComplete` | `extmodeStopRequested` | `extmodeWaitForHostRequest`

### Topics

“External Mode Simulation by Using XCP Communication”

“Customize XCP Server Software”



## extmodeGetFinalSimulationTime

Get final simulation time for external mode platform abstraction layer

### Syntax

```
errorCode = extmodeGetFinalSimulationTime(finalTime);
```

### Description

`errorCode = extmodeGetFinalSimulationTime(finalTime);` gets the model's final simulation time for the external mode platform abstraction layer. The function is a complementary function for `extmodeSetFinalSimulationTime`.

### Output Arguments

#### **finalTime** – Final simulation time

`real_T` pointer

Final simulation time of model.

#### **errorCode** – Error detection

`extmodeErrorCode_T` enumeration

Error code, returned as an `extmodeErrorCode_T` enumeration with one of these values:

- `EXTMODE_SUCCESS` (0) -- No error detected.
- `EXTMODE_INV_ARG` (-1) -- Arguments invalid.
- `EXTMODE_NOT_INITIALIZED` (-9) -- External mode not initialized yet.

## Version History

**Introduced in R2018a**

### See Also

`extmodeBackgroundRun` | `extmodeEvent` | `extmodeInit` | `extmodeParseArgs` | `extmodeReset` | `extmodeSetFinalSimulationTime` | `extmodeSimulationComplete` | `extmodeStopRequested` | `extmodeWaitForHostRequest`

### Topics

“External Mode Simulation by Using XCP Communication”  
 “Customize XCP Server Software”

## extmodeInit

Initialize external mode target connectivity

### Syntax

```
errorCode = extmodeInit(extmodeInfo, finalTime);
```

### Description

`errorCode = extmodeInit(extmodeInfo, finalTime);` initializes the external mode target connectivity, including the underlying communication stack.

Use this function with other external mode functions to enable communication between Simulink and the target application during an external mode simulation.

### Examples

#### Set Up External Mode Communication

For a pseudo-code example that shows how you can provide external mode communication by using the function with related functions, see “External Mode Abstraction Layer”.

### Input Arguments

#### **extmodeInfo** — External mode information structure

RTWExtModeInfo structure

Model structure that contains information for the external mode simulation. RTWExtModeInfo is defined in `matlabroot/simulink/include/rtw_extmode.h`.

#### **finalTime** — Final simulation time

real\_T pointer

If the model’s final simulation time in the external mode abstraction layer is initialized, then `finalTime` is an output and the pointer location is updated with the initialized value. You might initialize the final simulation time through the `'-tf'` option detected by `extmodeParseArgs()` or `extmodeSetFinalSimulationTime()`

If the model’s final simulation time in the external mode abstraction layer is not initialized, then `finalTime` is an input and the model’s final simulation time in external mode is updated accordingly.

### Output Arguments

#### **errorCode** — Error detection

extmodeErrorCode\_T enumeration

Error code, returned as an `extmodeErrorCode_T` enumeration with one of these values:

- EXTMODE\_SUCCESS (0) -- No error detected.
- EXTMODE\_INV\_ARG (-1) -- Arguments invalid.
- EXTMODE\_ERROR (-12) -- External mode generic error detected.

## Version History

Introduced in R2018a

### See Also

[extmodeBackgroundRun](#) | [extmodeEvent](#) | [extmodeGetFinalSimulationTime](#) | [extmodeParseArgs](#) | [extmodeReset](#) | [extmodeSetFinalSimulationTime](#) | [extmodeSimulationComplete](#) | [extmodeStopRequested](#) | [extmodeWaitForHostRequest](#)

### Topics

[“External Mode Simulation by Using XCP Communication”](#)  
[“Customize XCP Server Software”](#)

## extmodeParseArgs

Extract values of configuration parameters supported by external mode abstraction layer

### Syntax

```
errorCode = extmodeParseArgs(argCount, argValues);
```

### Description

`errorCode = extmodeParseArgs(argCount, argValues);` extracts the values of the configuration parameters that are supported by the external mode abstraction layer. The function parses the array of strings passed as input arguments. The array of strings is from the command-line arguments of the executable file running on the target hardware.

The external mode abstraction layer interprets only two options and passes the other arguments to `rtIOStreamOpen` for the initialization of the communication driver.

Use this function with other external mode functions to enable communication between Simulink and the target application during an external mode simulation.

If your target hardware does not support the parsing of command-line arguments, define the preprocessor macro `EXTMODE_DISABLE_ARGS_PROCESSING`. See information about parsing command-line arguments in “Other Platform Abstraction Layer Functionality”.

### Examples

#### Set Up External Mode Communication

For a pseudo-code example that shows how you can provide external mode communication by using the function with related functions, see “External Mode Abstraction Layer”.

### Input Arguments

#### **argCount** — Number of arguments

`int_T` scalar

Number of elements in `argValues` array.

#### **argValues** — Command-line arguments

array of null-terminated strings

Command-line arguments of the executable file running on the target hardware. The external mode abstraction layer interprets only these options:

- `'-w'` - Enables the `extmodeWaitForStartRequest()` function, which waits for a model start request from Simulink in external mode. If you do not specify this option, the `extmodeWaitForStartRequest()` function has no effect.
- `'-tf finalSimulationTime'` - `finalSimulationTime` overrides the Simulink configuration parameter, `StopTime`.

If the command contains more options, they are passed to `rtIOStreamOpen` as configuration parameters for the communication driver.

## Output Arguments

### **errorCode** – Error detection

`extmodeErrorCode_T` enumeration

Error code, returned as an `extmodeErrorCode_T` enumeration with one of these values:

- `EXTMODE_SUCCESS` (0) -- No error detected.
- `EXTMODE_INV_ARG` (-1) -- Arguments invalid.

## Version History

**Introduced in R2018a**

### **See Also**

`extmodeBackgroundRun` | `extmodeEvent` | `extmodeGetFinalSimulationTime` | `extmodeInit` | `extmodeReset` | `extmodeSetFinalSimulationTime` | `extmodeSimulationComplete` | `extmodeStopRequested` | `extmodeWaitForHostRequest`

### **Topics**

“External Mode Simulation by Using XCP Communication”  
“Customize XCP Server Software”

## extmodeReset

Reset external mode target connectivity

### Syntax

```
errorCode = extmodeReset();
```

### Description

`errorCode = extmodeReset();` restores the external mode abstraction layer, including the communication stack, to the initial, default state.

Use this function with other external mode functions to enable communication between Simulink and the target application during an external mode simulation.

### Examples

#### Set Up External Mode Communication

For a pseudo-code example that shows how you can provide external mode communication by using the function with related functions, see “External Mode Abstraction Layer”.

### Output Arguments

#### **errorCode** — Error detection

`extmodeErrorCode_T` enumeration

Error code, returned as an `extmodeErrorCode_T` enumeration with one of these values:

- `EXTMODE_SUCCESS` (0) -- No error detected.
- `EXTMODE_ERROR` (-12) -- External mode generic error detected.

## Version History

Introduced in R2018a

### See Also

`extmodeBackgroundRun` | `extmodeEvent` | `extmodeGetFinalSimulationTime` | `extmodeInit` | `extmodeParseArgs` | `extmodeSetFinalSimulationTime` | `extmodeSimulationComplete` | `extmodeStopRequested` | `extmodeWaitForHostRequest`

### Topics

“External Mode Simulation by Using XCP Communication”  
“Customize XCP Server Software”

# extmodeSetFinalSimulationTime

Set final simulation time in external mode platform abstraction layer

## Syntax

```
errorCode = extmodeSetFinalSimulationTime(finalTime);
```

## Description

`errorCode = extmodeSetFinalSimulationTime(finalTime);` sets the final simulation time of the model in the external mode platform abstraction layer.

In the main function of your external mode target application, before `extmodeInit`, you can call `extmodeSetFinalSimulationTime` to set the final simulation time if:

- You do not want to use `extmodeParseArgs`.
- Your target hardware does not support parsing of command-line arguments but you want to override `StopTime` from the target application.

`extmodeGetFinalSimulationTime` and `extmodeSetFinalSimulationTime` are complementary functions.

## Input Arguments

**finalTime** — Final simulation time

`real_T`

Final simulation time of model.

## Output Arguments

**errorCode** — Error detection

`extmodeErrorCode_T` enumeration

Error code, returned as an `extmodeErrorCode_T` enumeration with one of these values:

- `EXTMODE_SUCCESS` (0) -- No error detected.
- `EXTMODE_INV_ARG` (-1) -- Arguments invalid.

## Version History

Introduced in R2018a

## See Also

`extmodeBackgroundRun` | `extmodeEvent` | `extmodeGetFinalSimulationTime` | `extmodeInit` | `extmodeParseArgs` | `extmodeReset` | `extmodeSimulationComplete` | `extmodeStopRequested` | `extmodeWaitForHostRequest`

**Topics**

“External Mode Simulation by Using XCP Communication”  
“Customize XCP Server Software”



# extmodeSimulationComplete

Check that external mode simulation is complete

## Syntax

```
simComplete = extmodeSimulationComplete();
```

## Description

`simComplete = extmodeSimulationComplete();` during an external mode simulation, checks whether the model simulation time has reached the final simulation time specified by the command-line `'-tf'` option or the Simulink configuration parameter, `StopTime`.

Use this function with other external mode functions to enable communication between Simulink and the target application during an external mode simulation.

## Examples

### Set Up External Mode Communication

For a pseudo-code example that shows how you can provide external mode communication by using the function with related functions, see “External Mode Abstraction Layer”.

## Output Arguments

### `simComplete` — Simulation complete

true | false

true if model simulation time has reached the specified final simulation time. Otherwise, returns false.

## Version History

Introduced in R2018a

## See Also

`extmodeBackgroundRun` | `extmodeEvent` | `extmodeGetFinalSimulationTime` | `extmodeInit` | `extmodeParseArgs` | `extmodeReset` | `extmodeSetFinalSimulationTime` | `extmodeStopRequested` | `extmodeWaitForHostRequest`

## Topics

“External Mode Simulation by Using XCP Communication”  
“Customize XCP Server Software”

## extmodeStopRequested

Check whether request to stop external mode simulation is received from model

### Syntax

```
stopRequest = extmodeStopRequested();
```

### Description

`stopRequest = extmodeStopRequested()`; checks whether a request to stop the external mode simulation is received from the Simulink model on the development computer.

Use this function with other external mode functions to enable communication between Simulink and the target application during an external mode simulation.

### Examples

#### Set Up External Mode Communication

For a pseudo-code example that shows how you can provide external mode communication by using the function with related functions, see “External Mode Abstraction Layer”.

### Output Arguments

#### **stopRequest** — Stop request

true | false

true if request to stop external mode simulation is received. Otherwise, returns false.

### Version History

**Introduced in R2018a**

### See Also

`extmodeBackgroundRun` | `extmodeEvent` | `extmodeGetFinalSimulationTime` | `extmodeInit` | `extmodeParseArgs` | `extmodeReset` | `extmodeSetFinalSimulationTime` | `extmodeSimulationComplete` | `extmodeWaitForHostRequest`

### Topics

“External Mode Simulation by Using XCP Communication”

“Customize XCP Server Software”

# extmodeWaitForHostRequest

Wait for request from development computer to start or stop external mode simulation

## Syntax

```
errorCode = extmodeWaitForHostRequest(timeoutInMicroseconds);
```

## Description

`errorCode = extmodeWaitForHostRequest(timeoutInMicroseconds);` waits for a start or stop request from the development computer and times out when the timeout value is reached.

Use this function with other external mode functions to enable communication between Simulink and the target application during an external mode simulation. Use the function during initialization because the function is a blocking function.

## Examples

### Set Up External Mode Communication

For a pseudo-code example that shows how you can provide external mode communication by using the function with related functions, see “External Mode Abstraction Layer”.

## Input Arguments

### `timeoutInMicroseconds` — Timeout

`uint32_T`

Specifies the timeout value. If the value is set to `EXTMODE_WAIT_FOREVER`, the function waits indefinitely. If `'-w'` is not extracted by `extmodeParseArgs()`, the function has no effect.

## Output Arguments

### `errorCode` — Error detection

`extmodeErrorCode_T` enumeration

Error code, returned as an `extmodeErrorCode_T` enumeration with one of these values:

- `EXTMODE_SUCCESS` (0) -- No error detected.
- `EXTMODE_INV_ARG` (-1) -- Arguments invalid.
- `EXTMODE_TIMEOUT_ERROR` (-100) -- External mode timeout error detected.

## Version History

Introduced in R2018a

### **See Also**

[extmodeBackgroundRun](#) | [extmodeEvent](#) | [extmodeGetFinalSimulationTime](#) | [extmodeInit](#) | [extmodeParseArgs](#) | [extmodeReset](#) | [extmodeSetFinalSimulationTime](#) | [extmodeSimulationComplete](#) | [extmodeStopRequested](#)

### **Topics**

[“External Mode Simulation by Using XCP Communication”](#)  
[“Customize XCP Server Software”](#)

# findBuildArg

**Package:** RTW

Find a specific build argument in build information

## Syntax

```
[identifier,value] = findBuildArg(buildinfo,buildArgName)
```

## Description

[identifier,value] = findBuildArg(buildinfo,buildArgName) searches for a build argument from the build information.

If the build argument is present in the build information, the function returns the name and value.

## Examples

### Find Build Argument in Build Information

Find a build argument and its value stored in build information myBuildInfo. Then, view the argument identifier and value.

```
load buildInfo.mat
myBuildInfo = buildInfo;
myBuildArgExtmodeStaticAlloc = 'EXTMODE_STATIC_ALLOC';
[buildArgId buildArgValue] = findBuildArg(buildInfo, ...
 myBuildArgExtmodeStaticAlloc);
```

```
>> buildArgId
```

```
buildArgId =
```

```
 'EXTMODE_STATIC_ALLOC'
```

```
>> buildArgValue
```

```
buildArgValue =
```

```
 '0'
```

## Input Arguments

**buildinfo** — Name of build information object returned by RTW.BuildInfo object

**buildArgName** — Name of build argument to find in build information  
character vector | string scalar

To get the build argument identifiers from the build information, use the `getBuildArgs` function.

## Output Arguments

**identifier** — Name of the build argument

character vector | string scalar

**value** — Value of the build argument

character vector | string scalar

## Version History

Introduced in R2014a

### See Also

`getBuildArgs`

### Topics

“Customize Post-Code-Generation Build Processing”

# findIncludeFiles

**Package:** RTW

Find and add include (header) files to build information

## Syntax

```
findIncludeFiles(buildinfo,extPatterns,Name,Value)
```

## Description

`findIncludeFiles(buildinfo,extPatterns,Name,Value)` searches for and adds include files to the build information.

Use the `findIncludeFiles` function to:

- Search for include files in source and include paths from the build information.
- Apply the optional *extPatterns* argument to specify file name extension patterns for search.
- Add the found files with their full paths to the build information.
- Delete duplicate include file entries from the build information.

To ensure that `findIncludeFiles` finds header files, add their paths to `buildInfo` by using the `addIncludePaths` function.

## Examples

### Find and Add Include Files to Build Information

Find include files with file name extension `.h` that are in the build information, `myBuildInfo`. Add the full paths for these files to the build information. View the include files from the build information.

```
myBuildInfo = RTW.BuildInfo;
addSourcePaths(myBuildInfo,{fullfile(pwd,...
 'mycustomheaders')},'myheaders');
findIncludeFiles(myBuildInfo);
headerfiles = getIncludeFiles(myBuildInfo,true,false);
```

```
>> headerfiles
```

```
headerfiles =
```

```
 'W:\work\mycustomheaders\myheader.h'
```

## Input Arguments

**buildinfo** — Name of build information object returned by `RTW.BuildInfo` object

Object provides information for compiling and linking generated code.

**extPatterns — Patterns of file name extensions that specify files for the search**

'\*.h' (default) | cell array of character vectors | string array

To specify files for the search, the character vectors or strings in the *extPatterns* argument:

- Must start with an asterisk immediately followed by a period (\*.)
- Can include a combination of alphanumeric and underscore (\_) characters

Example: '\*.h' '\*.hpp' '\*.x\*'

**Name-Value Pair Arguments**

Specify optional pairs of arguments as *Name1=Value1, ..., NameN=ValueN*, where *Name* is the argument name and *Value* is the corresponding value. Name-value arguments must appear after other arguments, but the order of the pairs does not matter.

*Before R2021a, use commas to separate each name and value, and enclose Name in quotes.*

Example: `minimalHeaders=false,ignoreParseError=true`

**minimalHeaders — Specifies whether to include only the minimal header files**

true (default) | false

If true, include only the minimal header files required to build the code.

If false, include header files found on the include path.

Example: `minimalHeaders=false`

**ignoreParseError — Response to parse errors**

false (default) | true

If false, terminate on parse errors.

If true, do not terminate on parse errors.

Example: `ignoreParseError=true`

## Version History

**Introduced in R2006b**

**See Also**

`addIncludeFiles` | `getIncludeFiles` | `packNGo`

**Topics**

“Customize Post-Code-Generation Build Processing”



# getBuildArgs

**Package:** RTW

Get build arguments from build information

## Syntax

```
[identifiers,values] = getBuildArgs(buildinfo,includeGroupIDs,
excludeGroupIDs)
```

## Description

[*identifiers*,*values*] = `getBuildArgs`(*buildinfo*,*includeGroupIDs*,  
*excludeGroupIDs*) returns build argument identifiers and values from build information.

The function requires the *buildinfo*, *identifiers*, and *values* arguments. You can use optional *includeGroupIDs* and *excludeGroupIDs* arguments. These optional arguments let you include or exclude groups selectively from the build arguments returned by the function.

If you choose to specify *excludeGroupIDs* and omit *includeGroupIDs*, specify a null character vector ( ' ') for *includeGroupIDs*.

## Examples

### Get Build Arguments from Build Information

After you build a project, the build information is available in the `buildInfo.mat` file. Retrieve the build arguments from the build information object.

```
load buildInfo.mat
[buildArgIds,buildArgValues] = getBuildArgs(buildInfo);
```

To get the value of a single build argument from the build information, you can use the `findBuildArg` function.

To view the build argument identifiers, enter:

```
buildArgIds
```

To view the build argument values, enter:

```
buildArgValues
```

## Input Arguments

**buildinfo** — Name of build information object returned by `RTW.BuildInfo` object

**includeGroupIDs** — Group identifiers of build arguments to include in the return from the function

cell array of character vectors | string

To use the *includeGroupIDs* argument, view available build argument identifier groups by using `myGroups = getGroups(buildInfo)`.

Example: ''

**excludeGroupIDs** — Group identifiers of build arguments to exclude from the return from the function

cell array of character vectors | string

To use the *excludeGroupIDs* argument, view available build argument identifier groups by using `myGroups = getGroups(buildInfo)`.

Example: ''

## Output Arguments

**identifiers** — Names of the build arguments

cell array of character vectors

**values** — Values of the build arguments

cell array of character vectors

## Version History

Introduced in R2014a

### See Also

`findBuildArg`

### Topics

“Customize Post-Code-Generation Build Processing”

# getCodeDescriptor

Create `coder.codedescriptor.CodeDescriptor` object for model

## Syntax

```
getCodeDescriptor(model)
getCodeDescriptor(folder)
```

## Description

`getCodeDescriptor(model)` creates a `coder.codedescriptor.CodeDescriptor` object for the specified model.

`getCodeDescriptor(folder)` creates a `coder.codedescriptor.CodeDescriptor` object for the specified build folder.

## Examples

### Create a Code Descriptor Object Using Model Name

Create a `coder.codedescriptor.CodeDescriptor` object by using model name:

```
codeDescObj = coder.getCodeDescriptor('rtwdemo_comments')
```

### Create a Code Descriptor Object Using Build Folder

Create a `coder.codedescriptor.CodeDescriptor` object by using build folder:

```
codeDescObj = coder.getCodeDescriptor('C:\Users\Desktop\work\rtwdemo_comments_ert_rtw')
```

## Input Arguments

### **model** — Name of the model

string

Model object or name for which to obtain the `coder.codedescriptor.CodeDescriptor` object. You can get the `coder.codedescriptor.CodeDescriptor` object only for the top model if the model has referenced models.

Example: `rtwdemo_comments`

Data Types: `string`

### **folder** — Build folder of the model

string

Build folder of the model for which to obtain the `coder.codedescriptor.CodeDescriptor` object. You can get the `coder.codedescriptor.CodeDescriptor` object only for the top model if the model has referenced models.

Example: `C:\Users\Desktop\Work\rtwdemo_comments_ert_rtw`

Data Types: `string`

## **Version History**

**Introduced in R2018a**

### **See Also**

`coder.codedescriptor.CodeDescriptor`

### **Topics**

“Get Code Description of Generated Code”

# getCompileFlags

**Package:** RTW

Get compiler options from build information

## Syntax

```
options = getCompileFlags(buildinfo,includeGroups,excludeGroups)
```

## Description

`options = getCompileFlags(buildinfo,includeGroups,excludeGroups)` returns compiler options from the build information.

The function requires the *buildinfo* argument. You can use optional *includeGroups* and *excludeGroups* arguments. These optional arguments let you include or exclude groups selectively from the compiler options returned by the function.

If you choose to specify *excludeGroups* and omit *includeGroups*, specify a null character vector ( `' '`) for *includeGroups*.

## Examples

### Get Compiler Options from Build Information

Get the compiler options stored in the build information `myBuildInfo`.

```
myBuildInfo = RTW.BuildInfo;
addCompileFlags(myBuildInfo,{'-Zi -Wall' '-03'}, ...
 'OPTS');
compflags = getCompileFlags(myBuildInfo);
```

```
>> compflags
```

```
compflags =
```

```
 '-Zi -Wall' '-03'
```

### Get Compiler Options with Include Group Argument

Get the compiler options stored with the group name `Debug` in the build information `myBuildInfo`.

```
myBuildInfo = RTW.BuildInfo;
addCompileFlags(myBuildInfo,{'-Zi -Wall' '-03'}, ...
 {'Debug' 'MemOpt'});
compflags = getCompileFlags(myBuildInfo,'Debug');
```

```
>> compflags
```

```
compflags =
 '-Zi -Wall'
```

### Get Compiler Options with Exclude Group Argument

Get the compiler options stored in the build information `myBuildInfo`, except those options with the group name `Debug`.

```
myBuildInfo = RTW.BuildInfo;
addCompileFlags(myBuildInfo,{'-Zi -Wall' '-O3'}, ...
 {'Debug' 'MemOpt'});
compflags = getCompileFlags(myBuildInfo, '', 'Debug');
```

```
>> compflags

compflags =
 '-O3'
```

## Input Arguments

**buildinfo** — Name of the build information object returned by `RTW.BuildInfo`  
object

**includeGroups** — Group names of compiler options to include in the return from the function

cell array of character vectors | string

To use the *includeGroups* argument, view available groups by using `myGroups = getGroups(buildInfo)`.

Example: ''

**excludeGroups** — Group names of compiler options to exclude from the return from the function

cell array of character vectors | string

To use the *excludeGroups* argument, view available groups by using `myGroups = getGroups(buildInfo)`.

Example: ''

## Output Arguments

**options** — Compiler options from the build information

cell array of character vectors

## Version History

Introduced in R2006a

## **See Also**

`addCompileFlags` | `getDefines` | `getLinkFlags`

## **Topics**

“Customize Post-Code-Generation Build Processing”

## getDefines

**Package:** RTW

Get preprocessor macro definitions from build information

### Syntax

```
[macrodefs,identifiers,values] = getDefines(buildinfo,includeGroups,
excludeGroups)
```

### Description

[macrodefs,identifiers,values] = getDefines(buildinfo,includeGroups,excludeGroups) returns preprocessor macro definitions from the build information.

The function requires the *buildinfo*, *macrodefs*, *identifiers*, and *values* arguments. You can use optional *includeGroups* and *excludeGroups* arguments. These optional arguments let you include or exclude groups selectively from the preprocessor macro definitions returned by the function.

If you choose to specify *excludeGroups* and omit *includeGroups*, specify a null character vector (') for *includeGroups*.

### Examples

#### Get Macro Definitions from Build Information

Get the preprocessor macro definitions stored in the build information `myBuildInfo`.

```
myBuildInfo = RTW.BuildInfo;
addDefines(myBuildInfo, ...
 {'PROTO=first' '-DDEBUG' 'test' '-dPRODUCTION'}, 'OPTS');
[defs,names,values] = getDefines(myBuildInfo);
```

```
>> defs
```

```
defs =
```

```
 '-DPROTO=first' '-DDEBUG' '-Dtest' '-DPRODUCTION'
```

```
>> names
```

```
names =
```

```
 'PROTO'
 'DEBUG'
 'test'
 'PRODUCTION'
```



```
>> values
```

```
values =
 'first'
 ''
 ''
 ''
```

### Get Macro Definitions with Include Group Argument

Get the preprocessor macro definitions stored with the group name `Debug` in the build information `myBuildInfo`.

```
myBuildInfo = RTW.BuildInfo;
addDefines(myBuildInfo, ...
 {'PROTO=first' '-DDEBUG' 'test' '-dPRODUCTION'}, ...
 {'Debug' 'Debug' 'Debug' 'Release'});
[defs,names,values] = getDefines(myBuildInfo,'Debug');
```

```
>> defs
```

```
defs =
 '-DPROTO=first' '-DDEBUG' '-Dtest'
```

### Get Macro Definitions with Exclude Group Argument

Get the preprocessor macro definitions stored in the build information `myBuildInfo`, except those definitions with the group name `Debug`.

```
myBuildInfo = RTW.BuildInfo;
addDefines(myBuildInfo, ...
 {'PROTO=first' '-DDEBUG' 'test' '-dPRODUCTION'}, ...
 {'Debug' 'Debug' 'Debug' 'Release'});
[defs,names,values] = getDefines(myBuildInfo,'','Debug');
```

```
>> defs
```

```
defs =
 '-DPRODUCTION'
```

## Input Arguments

**buildinfo** — Name of the build information object returned by `RTW.BuildInfo`  
object

**includeGroups** — Group names of macro definitions to include in the return from the function

cell array of character vectors | string

To use the *includeGroups* argument, view available groups by using `myGroups = getGroups(buildInfo)`.

Example: ''

### **excludeGroups — Group names of macro definitions to exclude from the return from the function**

cell array of character vectors | string

To use the *excludeGroups* argument, view available groups by using `myGroups = getGroups(buildInfo)`.

Example: ''

## **Output Arguments**

### **macrodefs — Macro definitions from the build information**

cell array of character vectors

The *macrodefs* provide the complete macro definitions with a -D prefix. When the function returns a definition:

- If the -D was not specified when the definition was added to the build information, prepends a -D to the definition.
- Changes a lowercase -d to -D.

### **identifiers — Names of the macros from the build information**

cell array of character vectors

### **values — Values assigned to the macros from the build information**

cell array of character vectors

The *values* provide anything specified to the right of the first equal sign in the macro definition. The default is an empty character vector ('').

## **Version History**

**Introduced in R2006a**

### **See Also**

`addDefines` | `getCompileFlags` | `getLinkFlags`

### **Topics**

“Customize Post-Code-Generation Build Processing”

# getFullFileList

**Package:** RTW

Get list of files from build information

## Syntax

```
[fPathNames, names] = getFullFileList(buildinfo, fcase)
```

## Description

[fPathNames, names] = `getFullFileList(buildinfo, fcase)` returns the fully qualified paths and names of files, or files of a selected type (source, include, or nonbuild), from the build information.

The function requires the *buildinfo*, *fPathNames*, and *names* arguments. You can use the optional *fcase* argument. This optional argument lets you include or exclude file cases selectively from file list returned by the function.

To ensure that header files are added to the file list (for example, header files in the `_sharedutils` on page 15-11 folder), run `findIncludeFiles` before `getFullFileList`.

The `packNGo` function calls `getFullFileList` to return a list of files in the build information before processing files for packaging.

The makefile for the build resolves file locations based on source paths and rules. The build process does not require you to resolve the path of every file in the build information. The `getFullFileList` function returns the path for each file:

- If a path was explicitly associated with the file when it was added.
- If you called `updateFilePathsAndExtensions` to resolve file paths and extensions before calling `getFullFileList`.

## Examples

### Get Full List of Files

After building a project and loading the generated `buildInfo.mat` file, you can list the files stored in the build information object, `buildInfo`. This example returns information for the current project and its submodels.

From the code generation folder that contains the `buildInfo.mat` file, run:

```
bi = load('buildInfo.mat');
findIncludeFiles(bi.buildInfo);
[fPathNames, names] = getFullFileList(bi.buildInfo);
```

### Get List of Source Files

If you use an *fcase* option, you limit the listing to the files stored in the build information object for the current project. This example returns information for the current project only (not for submodels).

```
[fPathNames,names] = getFullFileList(bi.buildInfo,'source');
```

### Input Arguments

**buildinfo** — Name of the build information object returned by `RTW.BuildInfo`  
object

**fcase** — File case to return from the build information

' ' (default) | 'source' | 'include' | 'nonbuild'

The *fcase* argument selects whether the function returns the full list for files in the build information or returns selected cases of files. If you omit the argument or specify a null character vector ( ' '), the function returns the files from the build information.

| Specify    | Function Action                                    |
|------------|----------------------------------------------------|
| 'source'   | Returns source files from the build information.   |
| 'include'  | Returns include files from the build information.  |
| 'nonbuild' | Returns nonbuild files from the build information. |

Example: 'source'

### Output Arguments

**fPathNames** — Fully qualified file paths from the build information

cell array of character vectors

**names** — File names from the build information

cell array of character vectors

## Version History

Introduced in R2008a

### See Also

`findIncludeFiles`

### Topics

“Customize Post-Code-Generation Build Processing”

# getIncludeFiles

**Package:** RTW

Get include files from build information

## Syntax

```
files = getIncludeFiles(buildinfo,concatenatePaths,replaceMatlabroot,
includeGroups,excludeGroups)
```

## Description

`files = getIncludeFiles(buildinfo,concatenatePaths,replaceMatlabroot,includeGroups,excludeGroups)` returns the names of include files from the build information.

The function requires the *buildinfo*, *concatenatePaths*, and *replaceMatlabroot* arguments. You can use optional *includeGroups* and *excludeGroups* arguments. These optional arguments let you include or exclude groups selectively from the include files returned by the function.

If you choose to specify *excludeGroups* and omit *includeGroups*, specify a null character vector (' ') for *includeGroups*.

The makefile for the build resolves file locations based on source paths and rules. The build process does not require you to resolve the path of every file in the build information. If you specify `true` for the *concatenatePaths* argument, the `getIncludeFiles` function returns the path for each file:

- If a path was explicitly associated with the file when it was added.
- If you called `updateFilePathsAndExtensions` to resolve file paths and extensions before calling `getIncludeFiles`.

## Examples

### Get Include Paths and Files from Build Information

Get the include paths and file names from the build information, `myBuildInfo`.

```
myBuildInfo = RTW.BuildInfo;
addIncludeFiles(myBuildInfo,{'etc.h' 'etc_private.h' ...
 'mytypes.h'},{'/etc/proj/etclib' '/etcproj/etc/etc_build' ...
 '/common/lib'},{'etc' 'etc' 'shared'});
incfiles=getIncludeFiles(myBuildInfo,true,false);
```

```
>> incfiles
```

```
incfiles =
```

```
 [1x22 char] [1x36 char] [1x21 char]
```

### Get Include Paths and Files with Include Group Argument

Get the names of include files in group `etc` from the build information, `myBuildInfo`.

```
myBuildInfo = RTW.BuildInfo;
addIncludeFiles(myBuildInfo,{'etc.h' 'etc_private.h' ...
 'mytypes.h'},{'/etc/proj/etclib' '/etcproj/etc/etc_build' ...
 '/common/lib'},{'etc' 'etc' 'shared'});
incfiles = getIncludeFiles(myBuildInfo,false,false, ...
 'etc');
```

```
>> incfiles
```

```
incfiles =
 'etc.h' 'etc_private.h'
```

### Input Arguments

**buildinfo** — Name of the build information object returned by `RTW.BuildInfo` object

**concatenatePaths** — Choice of whether to concatenate paths and file names in return  
false | true

| Specify | Function Action                                                      |
|---------|----------------------------------------------------------------------|
| true    | Concatenates and returns each file name with its corresponding path. |
| false   | Returns only file names.                                             |

Example: true

**replaceMatlabroot** — Choice of whether to replace the `$(MATLAB_ROOT)` token with absolute paths in return  
false | true

Use the `replaceMatlabroot` argument to control whether the function includes the MATLAB root definition in the output it returns.

| Specify | Function Action                                                                                             |
|---------|-------------------------------------------------------------------------------------------------------------|
| true    | Replaces the token <code>\$(MATLAB_ROOT)</code> with the absolute path for your MATLAB installation folder. |
| false   | Does not replace the token <code>\$(MATLAB_ROOT)</code> .                                                   |

Example: true

**includeGroups** — Group names of include paths and files to include in the return from the function

cell array of character vectors | string

To use the `includeGroups` argument, view available groups by using `myGroups = getGroups(buildInfo)`.

Example: ''

**excludeGroups — Group names of include paths and files to exclude from the return from the function**

cell array of character vectors | string

To use the *excludeGroups* argument, view available groups by using `myGroups = getGroups(buildInfo)`.

Example: ''

**Output Arguments****files — Names of include files from the build information**

cell array of character vectors

The names of include files that you add with the `addIncludeFiles` function. If you call the `packNGo` function, the names include files that `packNGo` found and added while packaging code.

**Version History**

Introduced in R2006a

**See Also**

`addIncludeFiles` | `findIncludeFiles` | `getIncludePaths` | `getSourceFiles` | `getSourcePaths` | `updateFilePathsAndExtensions`

**Topics**

“Customize Post-Code-Generation Build Processing”

## getIncludePaths

**Package:** RTW

Get include paths from build information

### Syntax

```
paths = getIncludePaths(buildinfo,replaceMatlabroot,includeGroups,
excludeGroups)
```

### Description

`paths = getIncludePaths(buildinfo,replaceMatlabroot,includeGroups,excludeGroups)` returns the names of include file paths from the build information.

The function requires the *buildinfo* and *replaceMatlabroot* arguments. You can use optional *includeGroups* and *excludeGroups* arguments. These optional arguments let you include or exclude groups selectively from the include paths returned by the function.

If you choose to specify *excludeGroups* and omit *includeGroups*, specify a null character vector ( ' ') for *includeGroups*.

### Examples

#### Get Include Paths from Build Information

Get the include paths from the build information, `myBuildInfo`.

```
myBuildInfo = RTW.BuildInfo;
addIncludePaths(myBuildInfo,{'/etc/proj/etclib' ...
 '/etcproj/etc/etc_build' '/common/lib'}, ...
 {'etc' 'etc' 'shared'});
incpaths = getIncludePaths(myBuildInfo,false);
```

```
>> incpaths
```

```
incpaths =
```

```
 '\etc\proj\etclib' [1x22 char] '\common\lib'
```

#### Get Include Paths with Include Group Argument

Get the paths in group shared from the build information, `myBuildInfo`.

```
myBuildInfo = RTW.BuildInfo;
addIncludePaths(myBuildInfo,{'/etc/proj/etclib' ...
 '/etcproj/etc/etc_build' '/common/lib'}, ...
```



```

 {'etc' 'etc' 'shared'});
incpaths = getIncludePaths(myBuildInfo, false, 'shared');

>> incpaths

incpaths =

 '\common\lib'

```

## Input Arguments

**buildinfo** — Name of the build information object returned by `RTW.BuildInfo` object

**replaceMatlabroot** — Choice of whether to replace the `$(MATLAB_ROOT)` token with absolute paths in return from the function  
false | true

Use the *replaceMatlabroot* argument to control whether the function includes the MATLAB root definition in the output that it returns.

| Specify | Function Action                                                                                             |
|---------|-------------------------------------------------------------------------------------------------------------|
| true    | Replaces the token <code>\$(MATLAB_ROOT)</code> with the absolute path for your MATLAB installation folder. |
| false   | Does not replace the token <code>\$(MATLAB_ROOT)</code> .                                                   |

Example: true

**includeGroups** — Group names of include paths to include in the return from the function  
cell array of character vectors | string

To use the *includeGroups* argument, view available groups by using `myGroups = getGroups(buildInfo)`.

Example: ''

**excludeGroups** — Group names of include paths to exclude from the return from the function

cell array of character vectors | string

To use the *excludeGroups* argument, view available groups by using `myGroups = getGroups(buildInfo)`.

Example: ''

## Output Arguments

**paths** — Paths of include files from the build information  
cell array of character vectors

## Version History

Introduced in R2006a

**See Also**

[addIncludePaths](#) | [getIncludeFiles](#) | [getSourceFiles](#) | [getSourcePaths](#)

**Topics**

[“Customize Post-Code-Generation Build Processing”](#)

# getLinkFlags

**Package:** RTW

Get link options from build information

## Syntax

```
options = getLinkFlags(buildinfo,includeGroups,excludeGroups)
```

## Description

`options = getLinkFlags(buildinfo,includeGroups,excludeGroups)` returns linker options from the build information.

The function requires the *buildinfo* argument. You can use optional *includeGroups* and *excludeGroups* arguments. These optional arguments let you include or exclude groups selectively from the compiler options returned by the function.

If you choose to specify *excludeGroups* and omit *includeGroups*, specify a null character vector ( ' ') for *includeGroups*.

## Examples

### Get Linker Options from Build Information

Get the linker options from the build information, `myBuildInfo`.

```
myBuildInfo = RTW.BuildInfo;
addLinkFlags(myBuildInfo,{'-MD -Gy' '-T'},'OPTS');
linkflags = getLinkFlags(myBuildInfo);
```

```
>> linkflags
```

```
linkflags =
```

```
 '-MD -Gy' '-T'
```

### Get Linker Options with Include Group Argument

Get the linker options with the group name `Debug` from the build information, `myBuildInfo`.

```
myBuildInfo = RTW.BuildInfo;
addLinkFlags(myBuildInfo,{'-MD -Gy' '-T'}, ...
 {'Debug' 'MemOpt'});
linkflags = getLinkFlags(myBuildInfo,{'Debug'});
```

```
>> linkflags
```

```
linkflags =
 '-MD -Gy'
```

### Get Linker Options with Exclude Group Argument

Get the linker options from the build information `myBuildInfo`, except those options with the group name `Debug`.

```
myBuildInfo = RTW.BuildInfo;
addLinkFlags(myBuildInfo,{'-MD -Gy' '-T'}, ...
 {'Debug' 'MemOpt'});
linkflags = getLinkFlags(myBuildInfo, '', {'Debug'});
```

```
>> linkflags

linkflags =
 '-T'
```

## Input Arguments

**buildinfo** — Name of the build information object returned by `RTW.BuildInfo`  
object

**includeGroups** — Group names of linker options to include in the return from the function  
cell array of character vectors | string

To use the *includeGroups* argument, view available groups by using `myGroups = getGroups(buildInfo)`.

Example: ''

**excludeGroups** — Group names of linker options to exclude from the return from the function

cell array of character vectors | string

To use the *excludeGroups* argument, view available groups by using `myGroups = getGroups(buildInfo)`.

Example: ''

## Output Arguments

**options** — Linker options from the build information  
cell array of character vectors

## Version History

Introduced in R2006a

## **See Also**

[addLinkFlags](#) | [getCompileFlags](#) | [getDefines](#)

## **Topics**

[“Customize Post-Code-Generation Build Processing”](#)

## getNonBuildFiles

**Package:** RTW

Get nonbuild-related files from build information

### Syntax

```
files = getNonBuildFiles(buildinfo, concatenatePaths, replaceMatlabroot,
includeGroups, excludeGroups)
```

### Description

`files = getNonBuildFiles(buildinfo, concatenatePaths, replaceMatlabroot, includeGroups, excludeGroups)` returns the names of non-build files from the build information, such as DLL files required for a final executable or a README file.

The function requires the *buildinfo*, *concatenatePaths*, and *replaceMatlabroot* arguments. You can use optional *includeGroups* and *excludeGroups* arguments. These optional arguments let you include or exclude groups selectively from the non-build files returned by the function.

If you choose to specify *excludeGroups* and omit *includeGroups*, specify a null character vector ( ' ') for *includeGroups*.

The makefile for the build resolves file locations based on source paths and rules. The build process does not require you to resolve the path of every file in the build information. If you specify `true` for the *concatenatePaths* argument, the `getNonBuildFiles` function returns the path for each file:

- If a path was explicitly associated with the file when it was added.
- If you called `updateFilePathsAndExtensions` to resolve file paths and extensions before calling `getIncludeFiles`.

### Examples

#### Get Nonbuild Files from Build Information

Get the nonbuild file names stored in the build information, `myBuildInfo`.

```
myBuildInfo = RTW.BuildInfo;
addNonBuildFiles(myBuildInfo, {'readme.txt' 'myutility1.dll' ...
 'myutility2.dll'});
nonbuildfiles = getNonBuildFiles(myBuildInfo, false, false);
```

```
>> nonbuildfiles
```

```
nonbuildfiles =
```

```
'readme.txt' 'myutility1.dll' 'myutility2.dll'
```

## Input Arguments

**buildinfo** — Name of the build information object returned by `RTW.BuildInfo` object

**concatenatePaths** — Choice of whether to concatenate paths and file names in return from function

false | true

| Specify | Function Action                                                      |
|---------|----------------------------------------------------------------------|
| true    | Concatenates and returns each file name with its corresponding path. |
| false   | Returns only file names.                                             |

Example: true

**replaceMatlabroot** — Choice of whether to replace the `$(MATLAB_ROOT)` token with absolute paths in return from function

false | true

Use the `replaceMatlabroot` argument to control whether the function includes the MATLAB root definition in the output that it returns.

| Specify | Function Action                                                                                             |
|---------|-------------------------------------------------------------------------------------------------------------|
| true    | Replaces the token <code>\$(MATLAB_ROOT)</code> with the absolute path for your MATLAB installation folder. |
| false   | Does not replace the token <code>\$(MATLAB_ROOT)</code> .                                                   |

Example: true

**includeGroups** — Group names of non-build files to include in the return from the function

cell array of character vectors | string

To use the `includeGroups` argument, view available groups by using `myGroups = getGroups(buildInfo)`.

Example: ''

**excludeGroups** — Group names of non-build files to exclude from the return from the function

cell array of character vectors | string

To use the `excludeGroups` argument, view available groups by using `myGroups = getGroups(buildInfo)`.

Example: ''

## Output Arguments

**files** — Names of non-build files from the build information

cell array of character vectors

## **Version History**

**Introduced in R2008a**

### **See Also**

`addNonBuildFiles`

### **Topics**

“Customize Post-Code-Generation Build Processing”



# getSourceFiles

**Package:** RTW

Get source files from build information

## Syntax

```
srcfiles = getSourceFiles(buildinfo, concatenatePaths, replaceMatlabroot,
includeGroups, excludeGroups)
```

## Description

`srcfiles = getSourceFiles(buildinfo, concatenatePaths, replaceMatlabroot, includeGroups, excludeGroups)` returns the names of source files from the build information.

The function requires the *buildinfo*, *concatenatePaths*, and *replaceMatlabroot* arguments. You can use optional *includeGroups* and *excludeGroups* arguments. These optional arguments let you include or exclude groups selectively from the source files returned by the function.

If you choose to specify *excludeGroups* and omit *includeGroups*, specify a null character vector ( ' ') for *includeGroups*.

The makefile for the build resolves file locations based on source paths and rules. The build process does not require you to resolve the path of every file in the build information. If you specify `true` for the *concatenatePaths* argument, the `getSourceFiles` function returns the path for each file:

- If a path was explicitly associated with the file when it was added.
- If you called `updateFilePathsAndExtensions` to resolve file paths and extensions before calling `getSourceFiles`.

## Examples

### Get Source Files from Build Information

Get the source paths and file names from the build information, `myBuildInfo`.

```
myBuildInfo = RTW.BuildInfo;
addSourceFiles(myBuildInfo, ...
 {'test1.c' 'test2.c' 'driver.c'}, '', ...
 {'Tests' 'Tests' 'Drivers'});
srcfiles = getSourceFiles(myBuildInfo, false, false);
```

```
>> srcfiles
```

```
srcfiles =
```

```
 'test1.c' 'test2.c' 'driver.c'
```

### Get Source Files with Include Group Argument

Get the names of source files in group `tests` from the build information, `myBuildInfo`.

```
myBuildInfo = RTW.BuildInfo;
addSourceFiles(myBuildInfo,{'test1.c' 'test2.c'...
 'driver.c'}, {'/proj/test1' '/proj/test2'...
 '/drivers/src'}, {'tests', 'tests', 'drivers'});
incfiles = getSourceFiles(myBuildInfo,false,false,...
 'tests');
```

```
>> incfiles
```

```
incfiles =
```

```
 'test1.c' 'test2.c'
```

### Input Arguments

**buildinfo** — Name of the build information object returned by `RTW.BuildInfo` object

**concatenatePaths** — Choice of whether to concatenate paths and file names in return  
false | true

| Specify | Function Action                                                      |
|---------|----------------------------------------------------------------------|
| true    | Concatenates and returns each file name with its corresponding path. |
| false   | Returns only file names.                                             |

Example: true

**replaceMatlabroot** — Choice of whether to replace the `$(MATLAB_ROOT)` token with absolute paths in return  
false | true

Use the `replaceMatlabroot` argument to control whether the function includes the MATLAB root definition in the output it returns.

| Specify | Function Action                                                                                             |
|---------|-------------------------------------------------------------------------------------------------------------|
| true    | Replaces the token <code>\$(MATLAB_ROOT)</code> with the absolute path for your MATLAB installation folder. |
| false   | Does not replace the token <code>\$(MATLAB_ROOT)</code> .                                                   |

Example: true

**includeGroups** — Group names of source files to include in the return from the function  
cell array of character vectors | string

To use the `includeGroups` argument, view available groups by using `myGroups = getGroups(buildInfo)`.

Example: ''

**excludeGroups — Group names of source files to exclude from the return from the function**

cell array of character vectors | string

To use the *excludeGroups* argument, view available groups by using `myGroups = getGroups(buildInfo)`.

Example: ''

**Output Arguments****srcfiles — Names of source files from the build information**

cell array of character vectors

The names of source files that you add with the `addIncludeFiles` function. If you call the `packNGo` function, the names include files that `packNGo` found and added while packaging code.

**Version History****Introduced in R2006a****See Also**`addSourceFiles` | `getIncludeFiles` | `getIncludePaths` | `getSourcePaths` | `updateFilePathsAndExtensions`**Topics**

“Customize Post-Code-Generation Build Processing”

## getSourcePaths

**Package:** RTW

Get source paths from build information

### Syntax

```
srcpaths = getSourcePaths(buildinfo,replaceMatlabroot,includeGroups,
excludeGroups)
```

### Description

`srcpaths = getSourcePaths(buildinfo,replaceMatlabroot,includeGroups,excludeGroups)` returns the names of source file paths from the build information. The function returns only the file paths that were added to the build information by using `addSourcePaths`. The build process uses build information source paths to locate source files that were specified without an explicit path.

The function requires the *buildinfo* and *replaceMatlabroot* arguments. You can use optional *includeGroups* and *excludeGroups* arguments. These optional arguments let you include or exclude groups selectively from the source paths returned by the function.

If you choose to specify *excludeGroups* and omit *includeGroups*, specify a null character vector ( `' '` ) for *includeGroups*.

### Examples

#### Get Source Paths from Build Information

Get the source paths from the build information, `myBuildInfo`.

```
myBuildInfo = RTW.BuildInfo;
addSourcePaths(myBuildInfo,{'/proj/test1' ...
 '/proj/test2' '/drivers/src'}, {'tests' 'tests' ...
 'drivers'});
srcpaths = getSourcePaths(myBuildInfo,false);
```

```
>> srcpaths
```

```
srcpaths =
```

```
 '\proj\test1' '\proj\test2' '\drivers\src'
```

#### Get Source Paths with Include Group Argument

Get the paths in group `tests` from the build information, `myBuildInfo`.

```

myBuildInfo = RTW.BuildInfo;
addSourcePaths(myBuildInfo,{'/proj/test1' ...
 '/proj/test2' '/drivers/src'}, {'tests' 'tests' ...
 'drivers'});
srcpaths = getSourcePaths(myBuildInfo,true,'tests');

```

```

>> srcpaths

srcpaths =

 '\proj\test1' '\proj\test2'

```

### Get Source Paths from Build Information

Get a source path from the build information, `myBuildInfo`. First, get the path without replacing `$(MATLAB_ROOT)` with an absolute path. Then, get it with replacement. Here, the MATLAB root folder is `\\myserver\myworkspace\matlab`.

```

myBuildInfo = RTW.BuildInfo;
addSourcePaths(myBuildInfo, fullfile(matlabroot, ...
 'rtw', 'c', 'src'));
srcpaths = getSourcePaths(myBuildInfo,false);

```

```

>> srcpaths{:}

ans =

$(MATLAB_ROOT)\rtw\c\src

>> srcpaths = getSourcePaths(myBuildInfo,true);
>> srcpaths{:}

ans =

\\myserver\myworkspace\matlab\rtw\c\src

```

## Input Arguments

**buildinfo** — Name of the build information object returned by `RTW.BuildInfo` object

`RTW.BuildInfo` object that contains information for compiling and linking generated code.

**replaceMatlabroot** — Choice of whether to replace the `$(MATLAB_ROOT)` token with absolute paths in return

false | true

Use the `replaceMatlabroot` argument to control whether the function includes the MATLAB root definition in the output it returns.

| Specify | Function Action                                                                                |
|---------|------------------------------------------------------------------------------------------------|
| true    | Replaces the token \$(MATLAB_ROOT) with the absolute path for your MATLAB installation folder. |
| false   | Does not replace the token \$(MATLAB_ROOT).                                                    |

Example: true

### **includeGroups** — Group names of source paths to include in the return from the function

cell array of character vectors | string

To use the *includeGroups* argument, view available groups with `myGroups = getGroups(buildInfo)`.

Example: ''

### **excludeGroups** — Group names of source paths to exclude from the return from the function

cell array of character vectors | string

To use the *excludeGroups* argument, view available groups with `myGroups = getGroups(buildInfo)`.

Example: ''

## **Output Arguments**

### **srcpaths** — Source file paths

cell array of character vectors

Paths of source files from the build information.

## **Version History**

Introduced in R2006a

## **See Also**

`addSourcePaths` | `getIncludeFiles` | `getIncludePaths` | `getSourceFiles`

## **Topics**

“Customize Post-Code-Generation Build Processing”

# model\_initialize

Generated C/C++ entry-point function that contains initialization code for a Simulink model

## Syntax

```
void model_initialize(void)
```

## Description

`void model_initialize(void)` is a generated C or C++ entry-point function called one time to execute the initialization code for a Simulink model. This function is not intended to reset the real-time model data structure (rtM) for a model.

The generated calling interface of the initialize entry-point function for a model differs depending on the **Language** and **Code interface packaging** parameters. For more information, see “Code interface packaging” on page 12-15.

To preview and customize the name of a generated C initialize entry-point function an Embedded Coder license is required. To preview the function, open the Code Mappings editor and click the **Functions** tab. To customize the function name, in the **Function Name** column click and edit the spreadsheet directly. To customize the function using a template, in the **Function Customization Template** column select a template to apply to the function. For more information, see “Configure Names for Individual C Entry-Point Functions” (Embedded Coder), and “Configure Default Code Generation for Functions” (Embedded Coder).

To view the generated initialize entry-point function, open the **Code** view or Code Generation Report and examine the source code for your model. For more information see, “Analyze Generated Data Code Interface” (Embedded Coder).

## Examples

### Generate An Initialize Entry-Point Function

This example shows the basic workflow for how to configure, customize, generate, and examine an initialize entry-point function. This specific example generates a nonreusable C initialization function for the model `rtwdemo_irt_base`.

- 1 Open a model. For this example, use `rtwdemo_irt_base`.
- 2 Select a coder. In the Apps gallery, click **Simulink Coder** or **Embedded Coder**.
- 3 Configure the parameters. In the Configuration Parameters dialog box, set the **Language** and **Code interface packaging** parameters. In this example, the parameters are set for you.
- 4 (Embedded Coder only) Customize the function. Using Embedded Coder, you can customize the name of the initialize entry-point function.
  - Open the Code Mappings editor.
  - Click the **Functions** tab.

- Edit the spreadsheet directly. In the **Function Name** column, enter a name for the function.
- 5 Generate code.
  - 6 Examine the generated code. In the **Code** view, verify that the generated initialize function appears with the expected name and parameters.

## Input Arguments

### **void — Default initialize function parameter**

void (default)

The initialize entry-point C or C++ function provides an interface to start application code. By default, the generated function provides a `void-void` interface that does not have arguments.

Example: void

## Output Arguments

### **void — Initialize function return value**

void (default)

The initialize entry-point C or C++ function provides an interface to start application code. By default, the generated function provides a `void-void` interface that does not have a return value.

Example: void

## Version History

**Introduced before R2006a**

### **See Also**

`model_step` | `model_terminate` | `model_reset`

### **Topics**

- “Configure Generated C Function Interface for Model Entry-Point Functions”
- “Configure Names for Individual C Entry-Point Functions” (Embedded Coder)
- “Configure Default Code Generation for Functions” (Embedded Coder)
- “Analyze Generated Data Code Interface” (Embedded Coder)
- “Generate Code That Responds to Initialize, Reset, and Terminate Events”



# model\_reset

Generated C/C++ entry-point function that contains reset code for a Simulink model

## Syntax

```
void model_reset(void)
```

## Description

`void model_reset(void)` is a generated C or C++ entry-point function that executes reset code for a Simulink model. If a model includes a Reset Function block, reset code is generated. To reset conditions or state, call the function from the application code.

The generated calling interface of the reset entry-point function for a model differs depending on the **Language** and **Code interface packaging** parameters. For more information, see “Code interface packaging” on page 12-15.

To preview and customize the name of the generated reset entry-point function an Embedded Coder license is required. To preview the reset entry-point function, open the Code Mappings editor and click the **Functions** tab. To customize the function name, in the **Function Name** column click and edit the spreadsheet directly. To customize the function name and arguments, in the **Function Preview** column click the function hyperlink and configure the reset function from the opened dialogue box. To customize a function using a template, in the **Function Customization Template** column select a template to apply to the function. For more information, see “Configure Name and Arguments for Individual Step Functions” (Embedded Coder), “Interactively Configure C++ Interface” (Embedded Coder), and “Configure Default Code Generation for Functions” (Embedded Coder).

To view the generated reset entry-point function, open the **Code** view or Code Generation Report and view the source code for your model. For more information see, “Analyze Generated Data Code Interface” (Embedded Coder).

## Examples

### Generate A Reset Entry-Point Function

This example shows the basic workflow for how to configure, customize, generate, and examine a reset entry-point function. This specific example generates a nonreusable C reset function for the model `rtwdemo_irt_base`.

- 1 Open a model. For this example, use `rtwdemo_irt_base`.
- 2 Select a coder. In the Apps gallery, click **Simulink Coder** or **Embedded Coder**.
- 3 Configure the parameters. In the Configuration Parameters dialog box, set the **Language**, and **Code interface packaging** parameters. In this example, the parameters are set for you.
- 4 (Embedded Coder only) Customize the function. Using Embedded Coder, you can customize the name of the reset entry-point function.

- Open the Code Mappings editor.
  - Click the **Functions** tab.
  - Edit the spreadsheet directly. In the **Function Name** column, enter a name for the function.
- 5 Generate code.
  - 6 Examine the generated code. In the **Code** view, verify that the generated reset function appears with the expected name and parameters.

## Input Arguments

### **void — Default reset function parameter**

void (default)

The reset entry-point C or C++ function provides an interface to the model reset code. By default, the generated function provides a `void-void` interface that does not have arguments.

## Output Arguments

### **void — Reset function return value**

void

The reset entry-point C or C++ function provides an interface to model reset code. By default, the generated function provides a `void-void` interface that does not have a return value.

## Version History

**Introduced before R2006a**

### **See Also**

`model_initialize` | `model_step` | `model_terminate`

### **Topics**

“Configure Generated C Function Interface for Model Entry-Point Functions”

“Configure Name and Arguments for Individual Step Functions” (Embedded Coder)

“Interactively Configure C++ Interface” (Embedded Coder)

“Configure Default Code Generation for Functions” (Embedded Coder)

“Analyze Generated Data Code Interface” (Embedded Coder)

“Generate Code That Responds to Initialize, Reset, and Terminate Events”

## model\_step

Generated C/C++ entry-point function that contains execution code for each step in a Simulink model

### Syntax

```
void model_step(void)
void model_step_N(void)
```

### Description

`void model_step(void)` is an execution function that contains the output and update code for the blocks in a Simulink model.

`void model_step_N(void)` is an execution function with a task identifier that contains the output and update code for the blocks in a Simulink model.

The step entry-point function computes the current values of the blocks. If logging is enabled, the step function updates logging variables. By design, the step function is called at the interrupt level from `rt_OneStep` (invoked as a timer ISR). The `rt_OneStep` function calls the `model_step` function to execute processing for one clock period of the model. For a more information, see “`rt_OneStep` and Scheduling Considerations” (Embedded Coder).

If the model has a finite stop time, the step function signals the end of execution when the current time equals the stop time. Otherwise, if one or more of these conditions are true, the step function does not check the current time against the stop time and the program runs indefinitely:

- The model stop time is set to `inf`.
- Logging is disabled.
- Parameter **Terminate function required** is not selected.

The generated calling interface of the step entry-point function for a model differs depending on these parameters:

- 1 To generate a step entry-point function, select the **Single output/update function** parameter. If you clear this parameter, `model_output` and `model_update` entry-point functions are generated in place of the step function.
- 2 To generate a single step function with configurable arguments, clear the **Treat each discrete rate as a separate task** parameter. To generate separate step functions based on timing requirements, select this parameter. For more information, see *Treat each discrete rate as a separate task*.
  - Parameter Value: `Off` (single rate or multirate single-tasking model)  
Function Prototype: `void model_step(void);`
  - Parameter Value: `On` (multirate multi-tasking model)  
Function Prototype: `void model_step_N (void);` (N is a task identifier)
- 3 To change the generated calling interface, set the **Language** and **Code interface packaging** parameters. For more information, see “Code interface packaging” on page 12-15.

To preview and customize the name and arguments of the generated C or C++ step entry-point function an Embedded Coder license is required. To preview a step entry-point function, open the Code Mappings editor and click the **Functions** tab. To customize the function name, in the **Function Name** column click and edit the spreadsheet directly. To customize the function name and arguments, in the **Function Preview** column click the function hyperlink and configure the step function from the opened dialog box. To customize a function using a template, in the **Function Customization Template** column select a template to apply to the function. For more information, see “Configure Name and Arguments for Individual Step Functions” (Embedded Coder), “Interactively Configure C++ Interface” (Embedded Coder), and “Configure Default Code Generation for Functions” (Embedded Coder).

To view the generated step entry-point function, open the **Code** view or Code Generation Report and view the source code for your model. For more information see, “Analyze Generated Data Code Interface” (Embedded Coder).

## Examples

### Generate A Step Entry-Point Function

This example shows the basic workflow for how to configure, customize, generate, and examine a step entry-point function. This specific example generates a nonreusable C termination function for the model `rtwdemo_irt_base`.

- 1 Open a model. For this example, use the `rtwdemo_irt_base` model.
- 2 Select a coder. In the Apps gallery, click **Simulink Coder** or **Embedded Coder**.
- 3 Configure the parameters. In the Configuration Parameters dialog box, set the **Single output/update function, Treat each discrete rate as a separate task, Language,** and **Code interface packaging** parameters. In this example, the parameters are set for you.
- 4 (Embedded Coder only) Customize the function. Using Embedded Coder, you can customize the name and arguments of the step entry-point function.
  - Open the Code Mappings editor.
  - Click on the **Functions** tab.
  - Customize the name and arguments. In the **Function Preview** column, click the function hyperlink to open the **Configure C Step Function Interface** dialog box. Configure the name and arguments.
- 5 Generate code.
- 6 Examine the generated code. In the **Code** view, verify the generated termination function appears with the expected name and parameters.

## Input Arguments

### **void** — Default step function parameter

`void` (default)

The step entry-point C or C++ function provides an interface to the model execution code. By default, the generated function provides a `void-void` interface that does not have arguments. To configure the input arguments for a C step function, use the **Code Mappings Editor - C**. To configure the input arguments for a C++ step function, use the **Code Mappings - C++ Editor**.

## Output Arguments

### **void — Step function return value**

void

The step entry-point C or C++ function provides an interface to the model execution code. By default, the generated function provides a `void-void` interface that does not have arguments. To configure the output arguments for a C step function, use the **Code Mappings Editor - C**. To configure the output arguments for a C++ step function, use the **Code Mappings - C++ Editor**.

## Version History

**Introduced before R2006a**

### **See Also**

`model_initialize` | `model_terminate` | `model_reset`

### **Topics**

- “Configure Generated C Function Interface for Model Entry-Point Functions”
- “Configure Name and Arguments for Individual Step Functions” (Embedded Coder)
- “Interactively Configure C++ Interface” (Embedded Coder)
- “Configure Default Code Generation for Functions” (Embedded Coder)
- “Analyze Generated Data Code Interface” (Embedded Coder)
- “Generate Code That Responds to Initialize, Reset, and Terminate Events”

## model\_terminate

Generated C/C++ entry-point function that contains termination code for a Simulink model

### Syntax

```
void model_terminate(void)
```

### Description

`void model_terminate(void)` is a generated C or C++ entry-point function called one time to execute termination code for a Simulink model.

The generated calling interface of the termination entry-point function for a model differs depending on the **Language** and **Code interface packaging** parameters. For more information, see “Code interface packaging” on page 12-15. With Embedded Coder, you can choose whether to generate a termination function for a model by using the **Terminate function required** parameter. If your application runs indefinitely, clear this parameter. For more information, see “Terminate function required” (Embedded Coder).

To preview and customize the name of a generated C terminate entry-point function an Embedded Coder license is required. To preview the terminate entry-point function, open the Code Mappings editor and click the **Functions** tab. To customize the function name, in the **Function Name** column click and edit the spreadsheet directly. To customize the function using a template, in the **Function Customization Template** column select a template to apply to the function. For more information, see “Configure Names for Individual C Entry-Point Functions” (Embedded Coder), and “Configure Default Code Generation for Functions” (Embedded Coder).

To view the generated terminate entry-point function, open the **Code** view or Code Generation Report and examine the source code for your model. For more information see, “Analyze Generated Data Code Interface” (Embedded Coder).

### Examples

#### Generate A Terminate Entry-Point Function

This example shows the basic workflow for how to configure, customize, generate, and examine the terminate entry-point function. This specific example generates a nonreusable C terminate function for the model `rtwdemo_irt_base`.

- 1 Open a model. For this example, use `rtwdemo_irt_base`.
- 2 Select a coder. In the Apps gallery, click **Simulink Coder** or **Embedded Coder**.
- 3 Configure the parameters. In the Configuration Parameters dialog box, select **Terminate function required** and set the **Language** and **Code interface packaging** parameters. In this example, the parameters are set for you.
- 4 (Embedded Coder only) Customize the function. Using Embedded Coder, you can customize the name of the terminate entry-point function.

- Open the Code Mappings editor.
  - Click the **Functions** tab.
  - Edit the spreadsheet directly. In the **Function Name** column, enter a name for the function.
- 5 Generate code.
  - 6 Examine the generated code. In the **Code** view, verify that the generated terminate function appears with the expected name and parameters.

## Input Arguments

### **void — Default terminate function parameter**

void (default)

The terminate entry-point C or C++ function provides an interface to terminate application code. By default, the generated function provides a `void-void` interface that does not have arguments.

Example: void

## Output Arguments

### **void — Terminate function return value**

void (default)

The terminate entry-point C or C++ function provides an interface to terminate application code. By default, the generated function provides a `void-void` interface that does not have a return value.

Example: void

## Version History

**Introduced before R2006a**

### **See Also**

`model_initialize` | `model_step` | `model_reset`

### **Topics**

“Configure Generated C Function Interface for Model Entry-Point Functions”

“Configure Names for Individual C Entry-Point Functions” (Embedded Coder)

“Configure Default Code Generation for Functions” (Embedded Coder)

“Analyze Generated Data Code Interface” (Embedded Coder)

“Generate Code That Responds to Initialize, Reset, and Terminate Events”

## packNGo

Package generated code in ZIP file for relocation

### Syntax

```
packNGo(buildInfo,Name,Value)
```

### Description

`packNGo(buildInfo,Name,Value)` packages the code files in a compressed ZIP file so that you can relocate, unpack, and rebuild them in another development environment. The list of name-value pairs is optional.

The ZIP file can include these types of files:

- Source files (for example, `.c`, `.cu`, and `.cpp` files)
- Header files (for example, `.h`, `.cuh`, and `.hpp` files)
- MAT-file that contains the build information object (`.mat` file)
- Nonbuild-related files (for example, `.dll` files and `.txt` informational files) required for a final executable
- Build-generated binary files (for example, executable `.exe` file or dynamic link library `.dll`).

The code generator includes the build-generated binary files (if present) in the ZIP file. The **ignoreFileMissing** property does not apply to build-generated binary files.

- CMake configuration files (`CMakeLists.txt`) that you use to generate makefiles or projects for a compiler environment.

Use this function to relocate files. You can then recompile the files for a specific target environment or rebuild them in a development environment in which MATLAB is not installed. By default, the function packages the files as a flat folder structure in a ZIP file within the code generation folder. You can customize the output by specifying name-value pairs. After relocating the ZIP file, use a standard ZIP utility to unpack the compressed file.

The `packNGo` function can potentially modify the build information passed in the first `packNGo` argument. As part of code packaging, `packNGo` can find additional files from source and include paths recorded in the build information. When these files are found, `packNGo` adds them to the build information.

To ensure that `packNGo` finds header files, add their paths to `buildInfo` by using the `addIncludePaths` function.

---

**Note** When generating standalone code by using the `codegen` command, you can use the `-package` option to both generate code and package the code in a ZIP file in a single step.

---

### Examples



## Run packNGo from Command Window

After the build process is complete, you can run packNGo from the Command Window. Use packNGo for ZIP file packaging of generated code in the file portzingbit.zip. Maintain the relative file hierarchy.

- 1 Change folders to the code generation folder. For example, using MATLAB Coder, codegen/dll/zingbit or for Simulink code generation, zingbit\_grt\_rtw.
- 2 Load the buildInfo object that describes the build.
- 3 Run packNGo with property settings for packType and fileName.

```
cd codegen/dll/zingbit;
load buildInfo.mat
packNGo(buildInfo, 'packType', 'hierarchical', ...
 'fileName', 'portzingbit');
```

## Configure packNGo in the Simulink Editor

If you configure ZIP file packaging from the code generation pane, the code generator uses packNGo to output a ZIP file during the build process.

- 1 Select **Code Generation > Package code and artifacts**. Optionally, provide a **Zip file name**. To apply the changes, click **OK**.
- 2 Build the model. At the end of the build process, the code generator outputs the ZIP file. The folder structure in the ZIP file is hierarchical.

## Configure packNGo for Simulink from the Command Line

You can configure ZIP file packaging by using the set\_param function. During the build process, the code generator uses packNGo to create a ZIP file.

To configure ZIP file packaging for the model zingbit, run this command:

```
set_param('zingbit', 'PackageGeneratedCodeAndArtifacts', 'on');
```

The packNGo function creates the file zingbit.zip.

To specify another name for the ZIP file, for example, portzingbit.zip, run these commands:

```
set_param('zingbit', 'PackageGeneratedCodeAndArtifacts', 'on');
set_param('zingbit', 'PackageName', 'portzingbit.zip')
```

## Input Arguments

### buildInfo — Object that provides build information

buildInfo object | path to buildInfo.mat

During the build process, the code generator places buildInfo.mat in the code generation folder. This MAT-file contains the buildInfo object. The object provides information that packNGo uses to produce the ZIP file.

You can specify the argument as a `buildInfo` object:

```
load buildInfo.mat
packNGo(buildInfo,'packType', 'hierarchical', ...
 'fileName','portzingbit');
```

Or, you can specify the argument as the path to the `buildInfo.mat` file:

```
buildInfoFile = fullfile(pathToBuildFolder, 'buildInfo.mat');
packNGo(buildInfoFile,'packType', 'hierarchical', ...
 'fileName','portzingbit');
```

Or, you can specify the argument as the path to the folder that contains `buildInfo.mat`:

```
packNGo(pathToBuildFolder,'packType', 'hierarchical', ...
 'fileName','portzingbit');
```

### Name-Value Pair Arguments

Specify optional pairs of arguments as `Name1=Value1, ..., NameN=ValueN`, where `Name` is the argument name and `Value` is the corresponding value. Name-value arguments must appear after other arguments, but the order of the pairs does not matter.

*Before R2021a, use commas to separate each name and value, and enclose Name in quotes.*

Example: `'packType','flat','nestedZipFiles',true`

### **packType** — Specify structure type of ZIP file

`'flat'` (default) | `'hierarchical'`

If `'flat'`, package the generated code files in a ZIP file as a single, flat folder. The function does *not* package:

- Child `buildInfo.mat` files.
- `CMakeLists.txt` files.

If `'hierarchical'`, package the generated code files hierarchically in a primary ZIP file. The hierarchy contains top model, referenced model, and shared utility folders. The function also packages:

- The corresponding `buildInfo.mat` files for the folders.
- `CMakeLists.txt` files in the build folder.

Example: `'packType','flat'`

### **nestedZipFiles** — Determines whether the paths for files in the secondary ZIP files are relative to the root folder of the primary ZIP file

`true` (default) | `false`

If `true`, create a primary ZIP file that contains three secondary ZIP files:

- `mlrFiles.zip` — Files in your `matlabroot` folder tree
- `sDirFiles.zip` — Files in and under your code generation folder
- `otherFiles.zip` — Required files not in the `matlabroot` or `start` folder trees

If `false`, create a primary ZIP file that contains folders, for example, your code generation folder and `matlabroot`.

Example: `'nestedZipFiles',true`

**fileName — Specifies a file name for the primary ZIP file**

`'modelOrFunctionName.zip'` (default) | `'myName'`

If you do not specify the `'fileName'`-value pair, the function packages the files in a ZIP file named `modelOrFunctionName.zip` and places the ZIP file in the code generation folder.

If you specify `'fileName'` with the value, `'myName'`, the function creates `myName.zip` in the code generation folder.

To specify another location for the primary ZIP file, provide the absolute path to the location, `fullPath/myName.zip`

Example: `'fileName','/home/user/myModel.zip'`

**minimalHeaders — Selects whether to include only the minimal header files**

`true` (default) | `false`

If `true`, include only the minimal header files required to build the code in the ZIP file.

If `false`, include header files found on the include path in the ZIP file.

Example: `'minimalHeaders',true`

**includeReport — Selects whether to include the html folder for your code generation report**

`false` (default) | `true`

If `false`, do not include the html folder in the ZIP file.

If `true`, include the html folder in the ZIP file.

Example: `'includeReport',false`

**ignoreParseError — Instruct packNGo not to terminate on parse errors**

`false` (default) | `true`

If `false`, terminate on parse errors.

If `true`, do not terminate on parse errors.

Example: `'ignoreParseError',false`

**ignoreFileMissing — Instruct packNGo not to terminate if files are missing**

`false` (default) | `true`

If `false`, terminate on missing file errors.

If `true`, do not terminate on missing files errors.

Example: `'ignoreFileMissing',false`

## Limitations

- The function operates on source files only, such as \*.c, \*.cpp, .cu, and \*.h files. The function does not support compile flags, defines, or makefiles.
- The function does not package source files for reusable library subsystems.
- Unnecessary files might be included. The function might find additional files from source paths and include paths recorded in the build information, even if those files are not used.

## Version History

**Introduced in R2006b**

### See Also

codebuild

### Topics

“Customize Post-Code-Generation Build Processing”

“Relocate or Share Generated Code”

“Compile Code in Another Development Environment”

# removeSourceFiles

Remove source files from build information object

## Syntax

```
removeSourceFiles(buildInfo,filenames,groups)
```

## Description

`removeSourceFiles(buildInfo,filenames,groups)` removes source file names from build information that is stored in an `RTW.BuildInfo` object.

## Examples

### Remove Source File Names from Build Information

Suppose you add a list of source files to an `RTW.BuildInfo` object, `myBuildInfo`.

```
myBuildInfo = RTW.BuildInfo;
addSourceFiles(myBuildInfo, ...
 {'test1.c' 'test2.c' 'driver1.c' 'driver2.c'}, ...
 '/proj/src', ...
 {'Tests' 'Tests' 'Drivers' 'Drivers'});
```

To remove `test1.c` from the object, run:

```
removeSourceFiles(myBuildInfo, 'test1.c');
```

To remove `test2.c` and `driver1.c`, run:

```
removeSourceFiles(myBuildInfo, {'test2.c' 'driver1.c'});
```

To remove the names of files that belong to the `'Drivers'` group, run:

```
removeSourceFiles(myBuildInfo, '', 'Drivers');
```

## Input Arguments

### **buildInfo** — Build information object

object

`RTW.BuildInfo` object that contains information for compiling and linking generated code.

Example: `myBuildInfo`

### **filenames** — Source files to remove

character vector | array of character vectors | string

Specify source files that you want to remove from the build information object.

Example: `'test1.c'`

**groups — File groups to remove**

character vector | array of character vectors | string

Specify groups of source files that you want to remove from the build information object.

Example: {'Tests' 'Drivers'}

## **Version History**

**Introduced in R2021b**

### **See Also**

`addSourceFiles`

### **Topics**

“Customize Post-Code-Generation Build Processing”

# rtiostreamtest

Test custom `rtiostream` interface implementation

## Syntax

```
rtiostreamtest(connection, parameterOne, parameterTwo, verbosityFlag)
rtiostreamtest('tcp', host, port)
rtiostreamtest('serial', port, baud)
```

## Description

`rtiostreamtest(connection, parameterOne, parameterTwo, verbosityFlag)` runs a test suite to verify your custom `rtiostream` interface implementation.

`rtiostreamtest('tcp', host, port)`, via TCP/IP communication, connects MATLAB to the target hardware using the specified host and port.

`rtiostreamtest('serial', port, baud)`, via serial communication, connects MATLAB to the target hardware using the specified port and baud value.

During initialization, the function uses basic `rtiostream` I/O. The function determines:

- Byte ordering of data on the target hardware.
- Granularity of memory address.
- Size of data types.
- Whether `rtIOStreamRecv` blocks, that is, when there is no data whether `rtIOStreamRecv` waits for data or returns immediately with `size received == 0`.
- The size (`BUFFER_SIZE`) of its internal buffer for receiving or transmitting data through `rtiostream`. The default is 128 bytes.

In Test 1 (fixed size data exchange), the function:

- Checks data can be sent and received correctly in different chunk sizes. The chunk sizes for your development computer and target hardware are *symmetric*.
- Sends data as a known sequence that it can validate.
- Performs “host-to-target” tests. Your development computer sends data and your target hardware receives data in successive chunks of 1, 4, and 128 bytes.
- Performs “target-to-host” tests. Your target hardware sends data and your development computer receives data in successive chunks of 1, 4, and 128 bytes.

In Test 2 (varying size data exchange), the function:

- Checks that data can be sent and received correctly in different chunk sizes. The chunk sizes for your development computer and target hardware are *asymmetric*.
- Sends data as a known sequence that it can validate.
- Performs “host-to-target” tests:

- Your development computer sends data in chunks of 128 bytes and your target hardware receives data in chunks of 64 bytes.
- Your development computer sends data in chunks of 64 bytes and your target hardware receives data in chunks of 128 bytes.
- Performs “target-to-host” tests:
  - Your target hardware sends data in chunks of 64 bytes and your development computer receives data in chunks of 128 bytes.
  - Your target hardware sends data in chunks of 128 bytes and your development computer receives data in chunks of 64 bytes.

In Test 3 (receive buffer detection), the function determines the data that it can store in between calls to `rtIOStreamRecv` on the target hardware. The function uses an iterative process:

- 1 The development computer transmits a data sequence while the target hardware sleeps. `rtIOStreamRecv` is not called while the target hardware sleeps.
- 2 When the target hardware wakes up, it calls `rtIOStreamRecv` to receive data from the internal buffer of the driver.
- 3 The function determines whether the internal buffer overflowed by checking for errors and checking the received data values.
- 4 If there are no overflow errors and the transmitted data is received correctly, the function starts another iteration, performing step 1 with a larger data sequence.

The function reports the size of the last known good buffer.

## Examples

### Verify Behavior of Custom `rtiostream` Interface Implementation

The test suite consists of two parts. One part of the test suite is an application that runs on the target hardware. The other part runs in MATLAB.

- 1 To create the target application, compile and link these files:
  - `rtiostreamtest.c`
  - `rtiostreamtest.h`
  - `rtiostream.h`
  - The `rtiostream` implementation under investigation, for example, `rtiostream_tcpip.c`.
  - `main.c`

`rtiostreamtest.c`, `rtiostreamtest.h`, and `main.c` are located in `matlabroot/toolbox/coder/rtiostream/src/rtiostreamtest`.

- 2 Download and run the application on your target hardware.
- 3 To run the MATLAB part of the test suite, invoke the `rtiostreamtest` function. For example:

```
rtiostreamtest('tcp', 'myProcessor', '2345')
```

The function produces an output like this:

```
Test suite for rtiostream ###
Initializing connection with target...
```



```

Hardware characteristics discovered
Size of char : 8 bit
Size of short : 16 bit
Size of int : 32 bit
Size of long : 32 bit
Size of float : 32 bit
Size of double : 64 bit
Size of pointer: 64 bit
Byte ordering : Little Endian

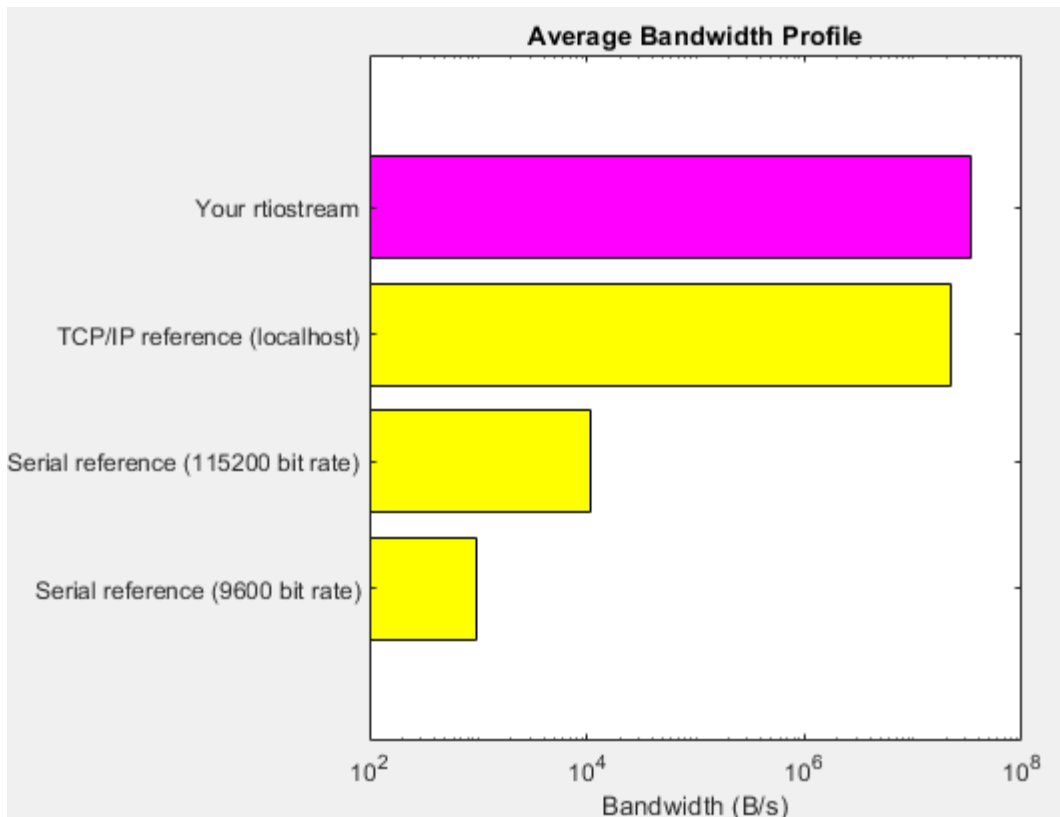
rtiostream characteristics discovered
Round trip time : 0.25098 ms
rtIOStreamRecv behavior : non-blocking

Test results
Test 1 (fixed size data exchange): PASS
Test 2 (varying size data exchange): PASS

Test suite for rtiostream finished successfully

```

The function also generates the average bandwidth profile.



## Input Arguments

**connection** — Transport protocol

'tcp' | 'serial'

Specify transport protocol for communication channel:

- 'tcp' -- TCP/IP
- 'serial' -- RS-232 serial

**parameterOne — Host name or COM port**

character vector | string scalar

If connection is 'tcp', specify name of target processor. For example, if your development computer is the target processor, you can specify 'localhost'.

If connection is 'serial', specify serial port ID, for example, 'COM1' for COM1, 'COM2' for COM2, and so on.

**parameterTwo — Port number or baud value**

integer

If connection is 'tcp', specify port number of TCP/IP server, an integer value between 256 and 65535.

If connection is 'serial', specify baud value, for example, 9600.

**verbosityFlag — Verbosity**

'' (default) | 'verbose'

If you specify 'verbose', the function displays messages that contain progress information. You can use the messages to debug runtime failures.

## Version History

Introduced in R2013a

## See Also

### Topics

“Customize XCP Server Software”

# rsimgetrtp

Global model parameter structure

## Syntax

```
parameter_structure= rsimgetrtp('model')
```

## Description

`parameter_structure= rsimgetrtp('model')` forces a block update diagram action for `model`, a model for which you are running rapid simulations, and returns the global parameter structure for that model. The function includes tunable parameter information in the parameter structure.

## Examples

### Return Global Parameter Structure

Return global parameter structure for model `rtwdemo_rsimtf` to `param_struct`.

```
rtwdemo_rsimtf
param_struct = rsimgetrtp('rtwdemo_rsimtf')

param_struct =

 modelChecksum: [1.7165e+009 3.0726e+009 2.6061e+009
2.3064e+009]
 parameters: [1x1 struct]
```

## Input Arguments

**model** — Model for which you are running rapid simulations

character vector | array of character vectors | string

## Output Arguments

**parameter\_structure** — Global parameter structure that includes tunable parameter information

parameter structure

The model parameter structure contains these fields:

| Field                      | Description                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                |
|----------------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| <code>modelChecksum</code> | A four-element vector that encodes the structure. The code generator uses the <i>checksum</i> to check whether the structure has changed since the RSim executable was generated. If you delete or add a block, and then generate a new version of the structure, the new <i>checksum</i> does not match the original <i>checksum</i> . The RSim executable detects this incompatibility in model parameter structures and exits to avoid returning incorrect simulation results. If the structure changes, regenerate code for the model. |
| <code>parameters</code>    | A structure that defines model global parameters.                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          |

The `parameters` substructure includes these fields:

| Field                        | Description                                                       |
|------------------------------|-------------------------------------------------------------------|
| <code>dataTypeName</code>    | Name of the parameter data type, for example, <code>double</code> |
| <code>dataTypeID</code>      | An internal data type identifier                                  |
| <code>complex</code>         | Value 1 if parameter values are complex and 0 if real             |
| <code>dtTransIdx</code>      | Internal use only                                                 |
| <code>values</code>          | Vector of parameter values                                        |
| <code>structParamInfo</code> | Information about structure and bus parameters in the model       |

The `structParamInfo` substructure contains these fields:

| Field                   | Description                                                                |
|-------------------------|----------------------------------------------------------------------------|
| <code>Identifier</code> | Name of the parameter                                                      |
| <code>ModelParam</code> | Value 1 if parameter is a model parameter and 0 if it is a block parameter |
| <code>BlockPath</code>  | Block path for a block parameter and empty for model parameters            |
| <code>CAPIIdx</code>    | Internal use only.                                                         |

Do not modify fields in `structParamInfo`.

The function also includes an array of substructures, `map`, which represents tunable parameter information with these fields:

| Field                      | Description                            |
|----------------------------|----------------------------------------|
| <code>Identifier</code>    | Parameter name                         |
| <code>ValueIndicies</code> | Vector of indices to parameter values  |
| <code>Dimensions</code>    | Vector indicating parameter dimensions |

## Version History

Introduced in R2006a

### See Also

`rsimsetrtpparam`

**Topics**

“Create a MAT-File That Includes a Model Parameter Structure”

“Update Diagram and Run Simulation”

Default parameter behavior

“Block Authoring and Simulation Integration”

“Tune Parameters”

## rsimsetrtpparam

Set parameters of rtP model parameter structure

### Syntax

```
rtP = rsimsetrtpparam(rtP,idx)
rtP = rsimsetrtpparam(rtP,'paramName',paramValue)
rtP = rsimsetrtpparam(rtP,idx,'paramName',paramValue)
```

### Description

`rtP = rsimsetrtpparam(rtP,idx)` expands the `rtP` structure to have `idx` sets of parameters. The `rsimsetrtpparam` utility defines the values of an existing `rtP` parameter structure. The `rtP` structure matches the format of the structure returned by `rsimgetrtp('model')`.

`rtP = rsimsetrtpparam(rtP,'paramName',paramValue)` takes an `rtP` structure that contains tunable parameter information and sets the values associated with `'paramName'` to be `paramValue`. You can specify multiple name-value pairs.

`rtP = rsimsetrtpparam(rtP,idx,'paramName',paramValue)` takes an `rtP` structure that contains tunable parameter information and sets the values associated with `'paramName'` to be `paramValue` in the `nth` `idx` parameter set. You can specify multiple name-value pairs. If the `rtP` structure does not have `idx` parameter sets, the first set is copied and appended until there are `idx` parameter sets. Subsequently, the `nth` `idx` set is changed.

### Examples

#### Expand Parameter Sets

Expand the number of parameter sets in the `rtp` structure to 10.

```
rtp = rsimsetrtpparam(rtp,10);
```

#### Add Parameter Sets

Add three parameter sets to the parameter structure `rtp`.

```
rtp = rsimsetrtpparam(rtp,idx,'X1',iX1,'X2',iX2,'Num',iNum);
```

### Input Arguments

**rtP** — Parameter structure that contains sets of parameter names and respective values  
parameter structure

**idx** — Index used to indicate the number of parameter sets in `rtP` structure  
index of parameter sets

**paramValue** — Value of rtP parameter paramName

value of paramName

**paramName** — Name of parameter set to add to rtP structure

name of parameter set

## Output Arguments

**rtP** — Expanded rtP parameter structure that contains the number of additional parameter sets indicated by **idx** and defined by the **rsimsetrtpparam** function call

expanded rtP parameter structure

## Version History

Introduced in R2009b

## See Also

[rsimgetrtP](#)

## Topics

[“Create a MAT-File That Includes a Model Parameter Structure”](#)

[“Update Diagram and Run Simulation”](#)

[Default parameter behavior](#)

[“Block Authoring and Simulation Integration”](#)

[“Tune Parameters”](#)

## rtw\_precompile\_libs

Build model libraries without building model

### Syntax

```
rtw_precompile_libs(model,build_spec)
```

### Description

`rtw_precompile_libs(model,build_spec)` builds libraries within *model*, according to the *build\_spec* field values, and places the libraries in a precompiled folder. Use the function to precompile new or updated S-function libraries (MEX-files), which can reduce the overall build time for the model.

Model builds that use the template makefile approach support the function. Model builds that use the toolchain approach do not support the function.

### Examples

#### Precompile Libraries for Model

Build the libraries in *my\_model* without building *my\_model*.

```
% Specify the library suffix
if isunix
 suffix = '_std.a';
elseif ismac
 suffix = '_std.a';
else
 suffix = '_vcx64.lib';
end
open_system(my_model);
set_param(my_model, 'TargetLibSuffix',suffix);

% Set the precompiled library folder
set_param(my_model, 'TargetPreCompLibLocation',fullfile(pwd,'lib'));

% Define a build specification that specifies
% the location of the files to compile.
my_build_spec = [];
my_build_spec.rtwmakecfgDirs = {fullfile(pwd,'src')};

% Build the libraries in 'my_model'
rtw_precompile_libs(my_model,my_build_spec);
```

### Input Arguments

**model** — Model object or name for which to build libraries

*object* | 'modelName'



Name of the model containing the libraries that you want to build.

### **build\_spec — Structure with field values that provides the build specification**

struct

Structure with fields that define a build specification. Fields except `rtwmakecfgDirs` are optional.

#### **Field Values in build\_spec**

Specify the structure field values of the `build_spec`.

Example: `build_spec.rtwmakecfgDirs = {fullfile(pwd, 'src')}`;

#### **rtwmakecfgDirs — Fully qualified paths to the folders containing rtwmakecfg files for libraries to precompile**

array of paths

Uses the `Name` and `Location` elements of `makeInfo.library`, as returned by the `rtwmakecfg` function, to specify name and location of precompiled libraries. If you use the `TargetPreCompLibLocation` parameter to specify the library folder, it overrides the `makeInfo.library.Location` setting.

The specified model must contain S-function blocks that use precompiled libraries, which the `rtwmakecfg` files specify. The makefile that the build approach generates contains the library rules only if the conversion requires the libraries.

Example: `build_spec.rtwmakecfgDirs = {fullfile(pwd, 'src')}`;

#### **libSuffix — Suffix, including the file type extension, to append to the name of each library (for example, `_std.a` or `_vcx64.lib`)**

character vector

The suffix must include a period (.). Set the suffix by using either this field or the `TargetLibSuffix` parameter. If you specify a suffix with both mechanisms, the `TargetLibSuffix` setting overrides the setting of this field.

Example: `build_spec.libSuffix = '_vcx64.lib'`;

#### **intOnlyBuild — Selects library optimization**

'false' (default) | 'true'

When set to `true`, indicates that the function optimizes the libraries so that they compile from integer code only. Applies to ERT-based targets only.

Example: `build_spec.intOnlyBuild = 'false'`;

#### **makeOpts — Specifies an option for rtwMake**

character vector

Specifies an option to include in the `rtwMake` command line.

Example: `build_spec.makeOpts = ''`;

#### **addLibs — Specifies libraries to build**

cell array of structures

This cell array of structures specifies the libraries to build that an `rtwmakecfg` function does not specify. Define each structure with two fields that are character arrays:

- `libName` — Name of the library without a suffix
- `libLoc` — Location for the precompiled library

With the template makefile build approach, you can specify other libraries and how to build them. Use this field if you must precompile libraries.

Example: `build_spec.addLibs = 'libs_list';`

## **Version History**

**Introduced in R2009b**

### **See Also**

#### **Topics**

“Precompile S-Function Libraries”

“Approaches for Building Code Generated from Simulink Models”

“Use `rtwmakecfg.m` API to Customize Generated Makefiles”

# rtwbuild

(Not recommended) Build generated code from a model

---

**Note** rtwbuild is not recommended. Use slbuild instead.

---

## Syntax

```
rtwbuild(model)
rtwbuild(model,Name,Value)

rtwbuild(subsystem)

rtwbuild(subsystem,'Mode','ExportFunctionCalls')
blockHandle = rtwbuild(subsystem,'Mode','ExportFunctionCalls')
```

## Description

rtwbuild(model) generates code from model based on current model configuration parameter settings. If model is not already loaded into the MATLAB environment, rtwbuild loads it before generating code.

If you clear the **Generate code only** model configuration parameter, the function generates code and builds an executable image.

To reduce code generation time, when rebuilding a model, rtwbuild provides incremental model build. The code generator rebuilds a model or submodels only when they have changed since the most recent model build. To force a top-model build, see the 'ForceTopModelBuild' argument.

rtwbuild(model,Name,Value) uses additional options specified by one or more Name,Value pair arguments.

rtwbuild(subsystem) generates code from subsystem based on current model configuration parameter settings. Before initiating the build, open (or load) the parent model.

If you clear the **Generate code only** model configuration parameter, the function generates code and builds an executable image.

rtwbuild(subsystem,'Mode','ExportFunctionCalls') generates code from subsystem that includes function calls that you can export to external application code if you have Embedded Coder.

blockHandle = rtwbuild(subsystem,'Mode','ExportFunctionCalls') returns the handle to a SIL block created for code generated from the specified subsystem if the **Create block** configuration parameter is set to SIL and if you have Embedded Coder. You can then use the SIL block for numerical equivalence testing.

## Examples

### Generate Code and Build Executable Image for Model

Generate C code for model `rtwdemo_rtwintr`.

```
rtwbuild('rtwdemo_rtwintr')
```

For the GRT system target file, the code generator produces the following code files and places them in folders `rtwdemo_rtwintr_grt_rtw` and `slprj/grt/_sharedutils`.

| Model Files                            | Shared Files                        | Interface Files        |
|----------------------------------------|-------------------------------------|------------------------|
| <code>rtwdemo_rtwintr.c</code>         | <code>rtGetInf.c</code>             | <code>rtmodel.h</code> |
| <code>rtwdemo_rtwintr.h</code>         | <code>rtGetInf.h</code>             |                        |
| <code>rtwdemo_rtwintr_private.h</code> | <code>rtGetNaN.c</code>             |                        |
| <code>rtwdemo_rtwintrtypes.h</code>    | <code>rtGetNaN.h</code>             |                        |
|                                        | <code>rt_nonfinite.c</code>         |                        |
|                                        | <code>rt_nonfinite.h</code>         |                        |
|                                        | <code>rtwtypes.h</code>             |                        |
|                                        | <code>multiword_types.h</code>      |                        |
|                                        | <code>builtin_typeid_types.h</code> |                        |

If the following model configuration parameters settings apply, the code generator produces additional results.

| Parameter Setting                                                                 | Results                                                                                                                                                                                   |
|-----------------------------------------------------------------------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| <b>Code Generation &gt; Generate code only</b> is cleared                         | Executable image <code>rtwdemo_rtwintr.exe</code>                                                                                                                                         |
| <b>Code Generation &gt; Report &gt; Create code generation report</b> is selected | Report that provides information and links to generated code files, subsystem and code interface reports, entry-point functions, inports, outports, interface parameters, and data stores |

### Force Top Model Build

Generate code and build an executable image for `TopModelCode`, which refers to model `ReferenceModelCode`, regardless of model checksums and parameter settings.

```
openExample('simulinkcoder/FilePackagingModelsCodeAndDataExample', 'supportingFile', 'TopModelCode');
rtwbuild('TopModelCode', ...
 'ForceTopModelBuild', true)
```

### Generate Code and Build Executable Image for Subsystem

Generate C code for subsystem `Amplifier` in model `rtwdemo_rtwintr`.

```
rtwbuild('rtwdemo_rtwinintro/Amplifier')
```

For the GRT target, the code generator produces the following code files and places them in folders Amplifier\_grt\_rtw and slprj/grt/\_sharedutils.

| Model Files         | Shared Files           | Interface Files |
|---------------------|------------------------|-----------------|
| Amplifier.c         | rtGetInf.c             | rtmodel.h       |
| Amplifier.h         | rtGetInf.h             |                 |
| Amplifier_private.h | rtGetNaN.c             |                 |
| Amplifier_types.h   | rtGetNaN.h             |                 |
|                     | rt_nonfinite.c         |                 |
|                     | rt_nonfinite.h         |                 |
|                     | rtwtypes.h             |                 |
|                     | multiword_types.h      |                 |
|                     | builtin_typeid_types.h |                 |

If you apply the parameter settings listed in the table, the code generator produces the results listed.

| Parameter Setting                                                                 | Results                                                                                                                                                                                   |
|-----------------------------------------------------------------------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| <b>Code Generation &gt; Generate code only</b> is cleared                         | Executable image Amplifier.exe                                                                                                                                                            |
| <b>Code Generation &gt; Report &gt; Create code generation report</b> is selected | Report that provides information and links to generated code files, subsystem and code interface reports, entry-point functions, inports, outports, interface parameters, and data stores |

### Build Subsystem for Exporting Code to External Application

To export the image to external application code, build an executable image from a function-call subsystem.

```
rtwdemo_exporting_functions
rtwbuild('rtwdemo_exporting_functions/rtwdemo_subsystem','Mode','ExportFunctionCalls')
```

The executable image rtwdemo\_subsystem.exe appears in your working folder.

### Create SIL Block for Verification

From a function-call subsystem, create a SIL block that you can use to test the code generated from a model.

Open subsystem rtwdemo\_subsystem in model rtwdemo\_exporting\_functions and set the **Create block** model configuration parameter to SIL.

Create the SIL block.

```
mysilblockhandle = rtwbuild('rtwdemo_exporting_functions/rtwdemo_subsystem',...
'Mode','ExportFunctionCalls')
```

The code generator produces a SIL block for the generated subsystem code. You can add the block to an environment or test harness model that supplies test vectors or stimulus input. You can then run simulations that perform SIL tests and verify that the generated code in the SIL block produces the same result as the original subsystem.

### Name Exported Initialization Function

Name the initialization function generated when building an executable image from a function-call subsystem.

```
rtwdemo_exporting_functions
rtwbuild('rtwdemo_exporting_functions/rtwdemo_subsystem',...
'Mode','ExportFunctionCalls','ExportFunctionInitializeFunctionName','subsysinit')
```

The initialization function name `subsysinit` appears in `rtwdemo_subsystem_ert_rtw/ert_main.c`.

### Display Status Information in Build Status Window

Display build information in the Build Status window while generating code and running a parallel build of model `rtwdemo_mdltreftop_witherr`.

```
rtwbuild('rtwdemo_mdltreftop_witherr', ...
'OpenBuildStatusAutomatically',true)
```

## Input Arguments

### **model** — Model object or name for which to generate code or build an executable image

*object* | 'modelName'

Model for which to generate code or build an executable image, specified as an object or a character vector representing the model name.

Example: 'rtwdemo\_exporting\_functions'

### **subsystem** — Subsystem name for which to generate code or build executable image

'subsystemName'

Subsystem for which to generate code or build an executable image, specified as a character vector representing the subsystem name or the full block path.

Example: 'rtwdemo\_exporting\_functions/rtwdemo\_subsystem'

### Name-Value Pair Arguments

Specify optional pairs of arguments as `Name1=Value1, ..., NameN=ValueN`, where `Name` is the argument name and `Value` is the corresponding value. Name-value arguments must appear after other arguments, but the order of the pairs does not matter.

*Before R2021a, use commas to separate each name and value, and enclose Name in quotes.*

Example: `rtwbuild('TopModelCode','ForceTopModelBuild',true)`

### ForceTopModelBuild — Force regeneration of top model code

false (default) | true

Force regeneration of top model code, specified as true or false.

| Action                                                                                                                    | Specify |
|---------------------------------------------------------------------------------------------------------------------------|---------|
| Force the code generator to regenerate code for the top model of a system that includes referenced models                 | true    |
| Specify that the code generator determine whether to regenerate top model code based on model and model parameter changes | false   |

Consider forcing regeneration of code for a top model if you change items associated with external or custom code, such as code for a custom target. For example, set `ForceTopModelBuild` to true if you change:

- TLC code
- S-function source code, including `rtwmakecfg.m` files
- Integrated custom code

Alternatively, you can force regeneration of top model code by deleting folders in the “Code generation folder”, such as `slprj` or the generated model code folder.

### generateCodeOnly — Generate code only

false | true

If you do not specify a value, the **Generate code only** (`GenCodeOnly`) option on the **Code Generation** pane controls build process behavior.

If you specify a value, the argument overrides the **Generate code only** (`GenCodeOnly`) option on the **Code Generation** pane.

| Action                                   | Specify |
|------------------------------------------|---------|
| Generate code only.                      | true    |
| Generate code and build executable file. | false   |

### Mode — Export function calls (for subsystem builds only)

'ExportFunctionCalls' | 'Normal'

- 'ExportFunctionCalls' -- If you have Embedded Coder, generates code from subsystem that includes function calls that you can export to external application code.
- 'Normal' -- Does not export function calls.

### ExportFunctionInitializeFunctionName — Function name

character vector

Name the exported initialization function for specified subsystem.

Example:

```
rtwbuild(subsystem,'Mode','ExportFunctionCalls','ExportFunctionInitializeFunctionName',fcname)
```

**OpenBuildStatusAutomatically — Display build information in the Build Status window**

false (default) | true

Display build information in the Build Status window, specified as `true` or `false`. For more information about using the Build Status window, see “Monitor Parallel Building of Referenced Models”.

The Build Status window supports parallel builds of referenced model hierarchies. Do not use the Build Status window for serial builds.

| Action                                               | Specify |
|------------------------------------------------------|---------|
| Display build information in the Build Status window | true    |
| No action                                            | false   |

**ObfuscateCode — Generate obfuscated C code**

false (default) | true

Specify whether to generate obfuscated C code, specified as `true` or `false`.

| Action                                                                                                                          | Specify |
|---------------------------------------------------------------------------------------------------------------------------------|---------|
| Generate obfuscated C code that you can share with third parties with reduced likelihood of compromising intellectual property. | true    |
| No action.                                                                                                                      | false   |

**IncludeModelReferenceSimulationTargets — Option to build model reference simulation targets**

false (default) | true

Option to build model reference simulation targets, specified as the comma-separated pair consisting of 'IncludeModelReferenceSimulationTargets' and `true` or `false`.

Data Types: `logical`

**Output Arguments****blockHandle — Handle to SIL block created for generated subsystem code**

handle

Handle to SIL block created for generated subsystem code. Returned only if both of the following conditions apply:

- You are licensed to use Embedded Coder software.
- **Create block** model configuration parameter is set to SIL.

**Tips**

You can initiate code generation and the build process by:

- Pressing **Ctrl+B**.
- Selecting **Code > C/C++ Code > Build Model**.



- Invoking the `slbuild` command from the MATLAB command line.

## Version History

### Introduced in R2009a

#### **rtwbuild does not generate model reference simulation targets by default**

*Behavior changed in R2020b*

Starting in R2020b, the `rtwbuild` function does not generate model reference simulation targets by default. Excluding the model reference simulation targets allows for faster code generation for model hierarchies.

You can continue to generate both the simulation and code generation targets with the `rtwbuild` function by using the `IncludeModelReferenceSimulationTargets` argument.

## Extended Capabilities

### Automatic Parallel Support

Accelerate code by automatically running computation in parallel using Parallel Computing Toolbox™.

To build referenced models in parallel, in the top model, select the configuration parameter check box **Enable parallel model reference builds**. For more information, see “Reduce Build Time for Referenced Models by Using Parallel Builds”.

In Parallel Computing Toolbox™ commands, for example, a `parfor` or `spmd` loop, do not invoke `rtwbuild`, `rtwrebuild`, or `slbuild` commands that build models that are configured for parallel builds.

## See Also

`codebuild` | `rtwrebuild` | `slbuild` | `coder.buildstatus.open` | `coder.buildstatus.close`

### Topics

“Build and Run a Program”

“Approaches for Building Code Generated from Simulink Models”

“Control Regeneration of Top Model Code”

“Generate Component Source Code for Export to External Code Base” (Embedded Coder)

“Software-in-the-Loop Simulation” (Embedded Coder)

## RTW.BuildInfo

Provide information for compiling and linking generated code

### Description

An `RTW.BuildInfo` object contains information for compiling and linking generated code.

### Creation

#### Syntax

```
buildInformation = RTW.BuildInfo
```

#### Description

`buildInformation = RTW.BuildInfo` returns a build information object. You can use the object to specify information for compiling and linking generated code. For example:

- Compiler options
- Preprocessor identifier definitions
- Linker options
- Source files and paths
- Include files and paths
- Precompiled external libraries

### Properties

#### **ComponentName** — Component name

character vector | string

Name of generated code component.

### Object Functions

|                               |                                                         |
|-------------------------------|---------------------------------------------------------|
| <code>addCompileFlags</code>  | Add compiler options to build information               |
| <code>addDefines</code>       | Add preprocessor macro definitions to build information |
| <code>addIncludeFiles</code>  | Add include files to build information                  |
| <code>addIncludePaths</code>  | Add include paths to build information                  |
| <code>addLinkFlags</code>     | Add link options to build information                   |
| <code>addLinkObjects</code>   | Add link objects to build information                   |
| <code>addNonBuildFiles</code> | Add nonbuild-related files to build information         |
| <code>addSourceFiles</code>   | Add source files to build information                   |
| <code>addSourcePaths</code>   | Add source paths to build information                   |
| <code>addTMFTokens</code>     | Add template makefile (TMF) tokens to build information |
| <code>findBuildArg</code>     | Find a specific build argument in build information     |

|                                           |                                                                                                    |
|-------------------------------------------|----------------------------------------------------------------------------------------------------|
| <code>findIncludeFiles</code>             | Find and add include (header) files to build information                                           |
| <code>getBuildArgs</code>                 | Get build arguments from build information                                                         |
| <code>getCompileFlags</code>              | Get compiler options from build information                                                        |
| <code>getDefines</code>                   | Get preprocessor macro definitions from build information                                          |
| <code>getFullFileList</code>              | Get list of files from build information                                                           |
| <code>getIncludeFiles</code>              | Get include files from build information                                                           |
| <code>getIncludePaths</code>              | Get include paths from build information                                                           |
| <code>getLinkFlags</code>                 | Get link options from build information                                                            |
| <code>getNonBuildFiles</code>             | Get nonbuild-related files from build information                                                  |
| <code>getSourceFiles</code>               | Get source files from build information                                                            |
| <code>getSourcePaths</code>               | Get source paths from build information                                                            |
| <code>removeSourceFiles</code>            | Remove source files from build information object                                                  |
| <code>setTargetProvidesMain</code>        | Disable inclusion of code generator provided (generated or static) main.c source file during build |
| <code>updateFilePathsAndExtensions</code> | Update files in build information with missing paths and file extensions                           |
| <code>updateFileSeparator</code>          | Update file separator character for file lists in build information                                |

## Examples

### Retrieve Build Information Object

When you build generated code, the build process stores an `RTW.BuildInfo` object in the `buildInfo.mat` file. To retrieve the object, from the code generation folder that contains the `buildInfo.mat` file, run:

```
bi=load('buildInfo.mat');
bi.buildInfo
```

ans =

BuildInfo with properties:

```

 ComponentName: 'slexAircraftExample'
 Viewer: []
 Tokens: [27x1 RTW.BuildInfoKeyValuePair]
 BuildArgs: [13x1 RTW.BuildInfoKeyValuePair]
 MakeVars: []
 MakeArgs: ''
TargetPreCompLibLoc: ''
 TargetLibSuffix: ''
 ModelRefs: []
 SysLib: [1x1 RTW.BuildInfoModules]
 Maps: [1x1 struct]
 LinkObj: []
 Options: [1x1 RTW.BuildInfoOptions]
 Inc: [1x1 RTW.BuildInfoModules]
 Src: [1x1 RTW.BuildInfoModules]
 Other: [1x1 RTW.BuildInfoModules]
 Path: []
 Settings: [1x1 RTW.BuildInfoSettings]
 DisplayLabel: 'Build Info'
 Group: ''
```

The object contains build information.

### **Configure RTW.BuildInfo to Specify Code for Compilation**

This example shows how to create an RTW.BuildInfo object and register source files.

Create an RTW.BuildInfo object.

```
buildInfo = RTW.BuildInfo;
```

Register source files.

```
buildInfo.ComponentName = 'foo1';
addSourceFiles(buildInfo, 'foo1.c');
```

Specify the build method and create a static library.

```
tmf = fullfile(tmffolder, 'ert_vcx64.tmf');
buildResult1 = codebuild(pwd, buildInfo, tmf)
```

## **Version History**

**Introduced in R2006a**

### **See Also**

#### **Topics**

“Customize Post-Code-Generation Build Processing”

# RTW.getBuildDir

Get build folder information from model build information

## Syntax

```
RTW.getBuildDir(model)
folderStruct = RTW.getBuildDir(model)
```

## Description

RTW.getBuildDir(model) displays build folder information for model.

If the model is closed, the function opens and then closes the model, leaving it in its original state. If the model is large and closed, the RTW.getBuildDir function can take longer to execute.

folderStruct = RTW.getBuildDir(model) returns a structure containing build folder information.

You can use this function in automated scripts to determine the build folder in which the generated code for a model is placed.

This function can return build folder information for protected models.

## Examples

### Display Build Folder Information

Display build folder information for the model 'sldemo\_fuelsys'.

```
openExample('sldemo_fuelsys');
RTW.getBuildDir('sldemo_fuelsys')
```

ans =

```
BuildDirectory: 'C:\work\modelref\sldemo_fuelsys_ert_rtw'
CacheFolder: 'C:\work\modelref'
CodeGenFolder: 'C:\work\modelref'
RelativeBuildDir: 'sldemo_fuelsys_ert_rtw'
BuildDirSuffix: '_ert_rtw'
ModelRefRelativeRootSimDir: 'slprj\sim'
ModelRefRelativeRootTgtDir: 'slprj\ert'
ModelRefRelativeBuildDir: 'slprj\ert\sldemo_fuelsys'
ModelRefRelativeSimDir: 'slprj\sim\sldemo_fuelsys'
ModelRefRelativeHdlDir: 'slprj\hdl\sldemo_fuelsys'
ModelRefDirSuffix: ''
SharedUtilsSimDir: 'slprj\sim_sharedutils'
SharedUtilsTgtDir: 'slprj\ert_sharedutils'
```

### Get Build Folder Information

Return a structure `my_folderStruct` that contains build folder information for the model 'MyModel'.

```
>> my_folderStruct = RTW.getBuildDir('MyModel')
```

```
my_folderStruct =

 BuildDirectory: 'H:\MyModel_ert_rtw'
 CacheFolder: 'H:\'
 CodeGenFolder: 'H:\'
 RelativeBuildDir: 'MyModel_ert_rtw'
 BuildDirSuffix: '_ert_rtw'
 ModelRefRelativeRootSimDir: 'slprj\sim'
 ModelRefRelativeRootTgtDir: 'slprj\ert'
 ModelRefRelativeBuildDir: 'slprj\ert\MyModel'
 ModelRefRelativeSimDir: 'slprj\sim\MyModel'
 ModelRefRelativeHdlDir: 'slprj\hdl\MyModel'
 ModelRefDirSuffix: ''
 SharedUtilsSimDir: 'slprj\sim_sharedutils'
 SharedUtilsTgtDir: 'slprj\ert_sharedutils'
```

### Input Arguments

**model** — Model object or name for which to get the build folders

*object* | 'modelName'

Model for which to get the build folder, specified as an object or a character vector representing the model name.

Example: 'sldemo\_fuelsys'

### Output Arguments

**folderStruct** — Structure with field values that provide build folder information

struct

Structure with fields that provides build folder information.

Example: folderstruct = RTW.getBuildDir('MyModel')

**BuildDirectory** — Character vector specifying fully qualified path to build folder for model

character vector

**CacheFolder** — Character vector specifying root folder in which to place model build artifacts used for simulation

character vector

**CodeGenFolder** — Character vector specifying root folder in which to place code generation files

character vector

**RelativeBuildDir** — Character vector specifying build folder relative to the current working folder (pwd)

character vector

**BuildDirSuffix** — Character vector specifying suffix appended to model name to create build folder

character vector

**ModelRefRelativeRootSimDir** — Character vector specifying the relative root folder for the model reference target simulation folder

character vector

**ModelRefRelativeRootTgtDir** — Character vector specifying the relative root folder for the model reference target build folder

character vector

**ModelRefRelativeBuildDir** — Character vector specifying model reference target build folder relative to current working folder (pwd)

character vector

**ModelRefRelativeSimDir** — Character vector specifying model reference target simulation folder relative to current working folder (pwd)

character vector

**ModelRefRelativeHdlDir** — Character vector specifying model reference target HDL folder relative to current working folder (pwd)

character vector

**ModelRefDirSuffix** — Character vector specifying suffix appended to system target file name to create model reference build folder

character vector

**SharedUtilsSimDir** — Character vector specifying the shared utility folder for simulation

character vector

**SharedUtilsTgtDir** — Character vector specifying the shared utility folder for code generation

character vector

## Version History

Introduced in R2008b

### See Also

slbuild

### Topics

“Working Folder”

“Manage Build Process Folders”

## rtwrebuild

Rebuild generated code from model

### Syntax

```
rtwrebuild()
```

```
rtwrebuild(model)
```

```
rtwrebuild(path)
```

### Description

`rtwrebuild()` assumes that the current working folder is the build folder of the model (not the model location) and calls `codebuild`. If the current working folder is not the build folder, the function exits with an error.

`rtwrebuild` calls `codebuild` to recompile files you modified since that build. Operation of this function depends on the current working folder, not the current loaded model. If your model includes referenced models, `codebuild` recompiles code for all models in the hierarchy.

In Parallel Computing Toolbox commands, for example, a `parfor` or `spm` loop, do not invoke `rtwbuild`, `rtwrebuild`, or `slbuild` commands that build models that are configured for parallel builds. For information about parallel builds of referenced models, see “Reduce Build Time for Referenced Models by Using Parallel Builds”.

`rtwrebuild(model)` assumes that the current working folder is one level above the build folder and calls `codebuild`. If the current working folder (`pwd`) is not one level above the build folder, the function exits with an error.

`rtwrebuild(path)` finds the build folder indicated with the *path* argument. The *path* argument syntax lets the function operate without regard to the relationship between the current working folder and the build folder of the model.

### Examples

#### Rebuild Code from Build Folder

Call `codebuild` and recompile code when the current working folder is the build folder. For example,

- If the model name is `mymodel`
- And, if the model build was initiated in the `C:\work` folder
- And, if the system target is `GRT`

```
rtwrebuild()
```



## Rebuild Code from Parent Folder of Build Folder

When the current working folder is one level above the build folder, call `codebuild` to recompile code.

```
rtwrebuild('mymodel')
```

## Rebuild Code from a Folder

Recompile code from a current folder by specifying a path to the model build folder, `C:\work\mymodel_grt_rtw`.

```
rtwrebuild(fullfile('C:', 'work', 'mymodel_grt_rtw'))
```

## Input Arguments

**model** — Model object or name for which to regenerate code or rebuild an executable image  
*object* | 'modelName'

Model for which to regenerate code or rebuild an executable image, specified as an object or a character vector representing the model name.

Example: 'rtwdemo\_exporting\_functions'

**path** — Model path object or fully qualified path to the build folder for the model for which to regenerate code or rebuild an executable image

*object* | *modelPath*

Example: `fullfile('C:', 'work', 'mymodel_grt_rtw')`

## Version History

Introduced in R2009a

## See Also

`codebuild` | `rtwbuild` | `slbuild`

## Topics

"Rebuild a Model"

## rtwreport

(To be removed) Create generated code report for model with Simulink Report Generator

---

**Note** `rtwreport` will be removed in a future release. Use `coder.report.generate` instead. For more information, see “Compatibility Considerations”.

---

### Syntax

```
rtwreport(model)
rtwreport(model, folder)
```

### Description

`rtwreport(model)` creates a report of code generation information for a model. Before creating the report, the function loads the model and generates code. The code generator names the report `codegen.html`. It places the file in your current folder. The report includes:

- Snapshots of the model, including subsystems.
- Block execution order list.
- Code generation summary with a list of generated code files, configuration settings, a subsystem map, and a traceability report.
- Full listings of generated code that reside in the build folder.

`rtwreport(model, folder)` specifies the build folder, `model_target_rtw`. The build folder (`folder`) and `slprj` folder must reside in the “Code generation folder”. If the software cannot find the folder, an error occurs and code is not generated.

### Examples

#### Create Report Specifying Build Folder

Create a report for model `rtwdemo_secondOrderSystem` using build folder, `rtwdemo_secondOrderSystem_grt_rtw`:

```
rtwreport('rtwdemo_secondOrderSystem', ...
 'rtwdemo_secondOrderSystem_grt_rtw');
```

### Input Arguments

#### **model** — Model name

character vector

Model name for which the report is generated, specified as a character vector.

Example: `'rtwdemo_secondOrderSystem'`

Data Types: `char`

**folder — Build folder name**

character vector

Build folder name, specified as a character vector. When you have multiple build folders, include a folder name. For example, if you have multiple builds using different targets, such as GRT and ERT.

Example: 'rtwdemo\_secondOrderSystem\_grt\_rtw'

Data Types: char

## Version History

**Introduced in R2007a****rtwreport function will be removed**

*Warns starting in R2021a*

The function `rtwreport` will be removed in a future release. Use `coder.report.generate` instead.

To update your code, change instances of the function name `rtwreport` to `coder.report.generate`. You do not need to change the input arguments.

Unlike the `rtwreport` function, the `coder.report.generate` function provides additional input options that you can use to configure the generated report. However, the `coder.report.generate` function does not include snapshots of the model or the block execution order list.

## See Also

`coder.report.generate`

### Topics

["Document Generated Code with Simulink Report Generator"](#)

[Import Generated Code \(Simulink Report Generator\)](#)

["Working with Report Explorer" \(MATLAB Report Generator\)](#)

[Code Generation Summary \(Simulink Report Generator\)](#)

## rtwtrace

Trace a block to generated code in code generation report

### Syntax

```
rtwtrace('blockpath')
rtwtrace('Simulink_identifier')
rtwtrace('blockpath', 'hdl')
rtwtrace('blockpath', 'plc')
```

### Description

`rtwtrace('blockpath')` opens a code generation report that displays contents of the source code file and highlights the line of code corresponding to the specified block.

Before calling `rtwtrace`, make sure that:

- You select an ERT-based model and enable model to code navigation.

In the Configuration Parameters dialog box, select the **Model-to-code** (Embedded Coder) parameter.

- You generate code for the model by using the code generator.
- Your build folder is under the current working folder. Otherwise, `rtwtrace` might produce an error.

`rtwtrace('Simulink_identifier')` opens a code generation report that displays contents of the source code file and highlights the line of code corresponding to the block identified by the Simulink identifier (SID). SID is a unique designation for each block or element in the model.

`rtwtrace('blockpath', 'hdl')` opens a code generation report in HDL Coder™ that displays contents of the source code file and highlights the line of code corresponding to the specified block.

`rtwtrace('blockpath', 'plc')` opens a code generation report in Simulink PLC Coder™ that displays contents of the source code file and highlights the line of code corresponding to the specified block.

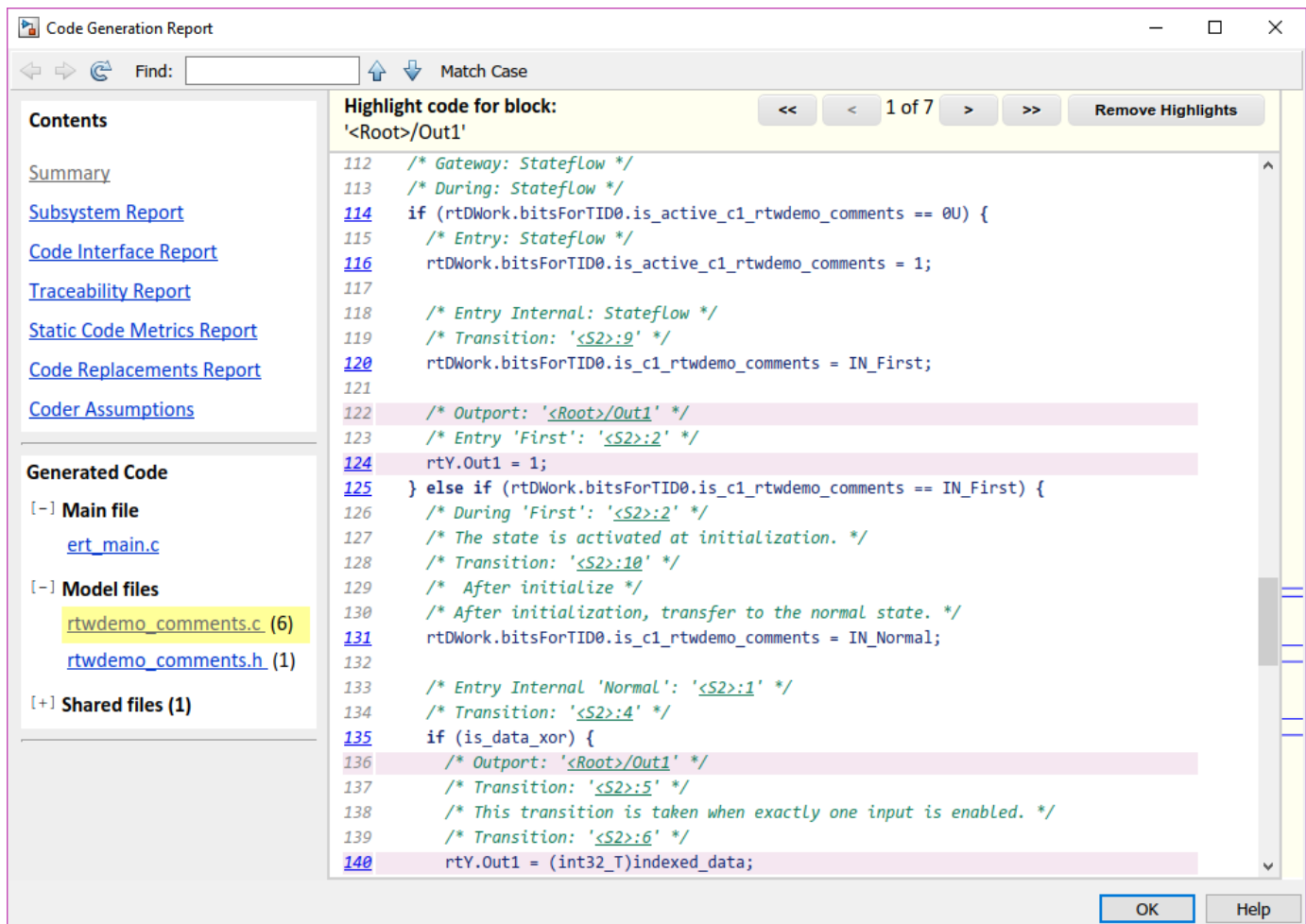
### Examples

#### Display Generated Code for a Block

Display the generated code for block `Out1` in the model `rtwdemo_comments` in code generation report:

```
% Using block path
rtwtrace('rtwdemo_comments/Out1')

% Using Simulink identifier
rtwtrace('rtwdemo_comments:33')
```



## Input Arguments

### **blockpath** — block path

character vector (default)

**blockpath** is a character vector enclosed in quotes specifying the full Simulink block path, for example, '*model\_name/block\_name*'.

Example: '*rtwdemo\_comments/Out1*'

Data Types: char

### **Simulink\_identifier** — Simulink identifier

character vector (default)

**Simulink\_identifier** is a character vector enclosed in quotes specifying the Simulink identifier, for example, '*model\_name:number*'.

For more information, see `Simulink.ID.getSID`.

Example: '*rtwdemo\_comments:33*'

Data Types: char

**hdl — HDL Coder**

character vector

hdl is a character vector enclosed in quotes specifying that the code report is from HDL Coder.

Example: 'Out1'

Data Types: char

**plc — PLC Coder**

character vector

plc is a character vector enclosed in quotes specifying that the code report is from Simulink PLC Coder.

Example: 'Out1'

Data Types: char

**Alternatives**

To trace from a block in the model diagram, right-click a block and select **C/C++ Code > Navigate to C/C++ Code**.

**Version History****Introduced in R2009b****See Also****Topics**

“Verify Generated Code by Using Code Tracing” (Embedded Coder)

“Model-to-Code Traceability” (Embedded Coder)

Model-to-code (Embedded Coder)

# setTargetProvidesMain

Disable inclusion of code generator provided (generated or static) `main.c` source file during build

## Syntax

```
setTargetProvidesMain(buildInfo,providesMain)
```

## Description

`setTargetProvidesMain(buildInfo,providesMain)` disables the code generator from including a sample `main.c` source file.

To replace the sample `main.c` file from the code generator with a custom `main.c` file, call the `setTargetProvidesMain` function during the 'after\_tlc' case in the `ert_make_rtw_hook.m` or `grt_make_rtw_hook.m` file.

## Examples

### Workflow for setTargetProvidesMain

To apply the `setTargetProvidesMain` function:

Add `buildInfo` to the arguments in the function call.

```
function ert_make_rtw_hook(hookMethod,Name,rtwroot, ...
 templateMakefile,buildOpts,buildArgs,buildInfo)
```

Add the `setTargetProvidesMain` function to the 'after\_tlc' stage.

```
case 'after_tlc'
% Called just after to invoking TLC Compiler (actual code generation.)
% Valid arguments at this stage are hookMethod, Name, and
% buildArgs, buildInfo
%
 setTargetProvidesMain(buildInfo,true);
```

Use the **Configuration Parameters > Code Generation > Custom Code > Source Files** field to add your custom `main.c` to the project. When you indicate that the target provides `main.c`, the project requires this file to build without errors.

## Input Arguments

**buildInfo** — Name of build information object returned by `RTW.BuildInfo` object

**providesmain** — Logical value that specifies whether the code generator includes the target provided `main.c` file  
false (default) | true

The *providesmain* argument specifies whether the code generator includes a (generated or static) `main.c` source file.

- `false` — The code generator includes a sample `main.obj` object file.
- `true` — The target provides the `main.c` source file.

## **Version History**

**Introduced in R2009a**

### **See Also**

`addSourceFiles` | `addSourcePaths`

### **Topics**

“Customize Build Process with `STF_make_rtw_hook` File”



# Simulink.fileGenControl

Specify root folders for files generated by diagram updates and model builds

## Syntax

```
cfg = Simulink.fileGenControl('getConfig')
Simulink.fileGenControl(Action,Name,Value)
```

## Description

`cfg = Simulink.fileGenControl('getConfig')` returns a handle to an instance of the `Simulink.FileGenConfig` object, which contains the current values of these file generation control parameters:

- **CacheFolder** - Specifies the root folder for model build artifacts that are used for simulation, including Simulink® cache files.
- **CodeGenFolder** - Specifies the root folder for code generation files.
- **CodeGenFolderStructure** - Controls the folder structure within the code generation folder.

To get or set the parameter values, use the `Simulink.FileGenConfig` object.

These Simulink preferences determine the initial parameter values for the MATLAB session:

- **Simulation cache folder** - CacheFolder
- **Code generation folder** - CodeGenFolder
- **Code generation folder structure** - CodeGenFolderStructure

`Simulink.fileGenControl(Action,Name,Value)` performs an action that uses the file generation control parameters of the current MATLAB session. Specify additional options with one or more `name,value` pair arguments.

## Examples

### Get File Generation Control Parameter Values

To obtain the file generation control parameter values for the current MATLAB session, use `getConfig`.

```
cfg = Simulink.fileGenControl('getConfig');
myCacheFolder = cfg.CacheFolder;
myCodeGenFolder = cfg.CodeGenFolder;
myCodeGenFolderStructure = cfg.CodeGenFolderStructure;
```

### Set File Generation Control Parameters by Using Simulink.FileGenConfig Object

To set the file generation control parameter values for the current MATLAB session, use the `setConfig` action. First, set values in an instance of the `Simulink.FileGenConfig` object. Then,

pass the object instance. This example assumes that your system has `aNonDefaultCacheFolder` and `aNonDefaultCodeGenFolder` folders.

```
% Get the current configuration
cfg = Simulink.fileGenControl('getConfig');

% Change the parameters to non-default locations
% for the cache and code generation folders
cfg.CacheFolder = fullfile('C:', 'aNonDefaultCacheFolder');
cfg.CodeGenFolder = fullfile('C:', 'aNonDefaultCodeGenFolder');
cfg.CodeGenFolderStructure = 'TargetEnvironmentSubfolder';

Simulink.fileGenControl('setConfig', 'config', cfg);
```

### Set File Generation Control Parameters Directly

You can set file generation control parameter values for the current MATLAB session without creating an instance of the `Simulink.FileGenConfig` object. This example assumes that your system has `aNonDefaultCacheFolder` and `aNonDefaultCodeGenFolder` folders.

```
myCacheFolder = fullfile('C:', 'aNonDefaultCacheFolder');
myCodeGenFolder = fullfile('C:', 'aNonDefaultCodeGenFolder');

Simulink.fileGenControl('set', 'CacheFolder', myCacheFolder, ...
 'CodeGenFolder', myCodeGenFolder, ...
 'CodeGenFolderStructure', ...
 Simulink.filegen.CodeGenFolderStructure.TargetEnvironmentSubfolder);
```

If you do not want to generate code for different target environments in separate folders, for `'CodeGenFolderStructure'`, specify the value `Simulink.filegen.CodeGenFolderStructure.ModelSpecific`.

### Reset File Generation Control Parameters

You can reset the file generation control parameters to values from Simulink preferences.

```
Simulink.fileGenControl('reset');
```

### Create Simulation Cache and Code Generation Folders

To create file generation folders, use the `set` action with the `'createDir'` option. You can keep previous file generation folders on the MATLAB path through the `'keepPreviousPath'` option.

```
%
myCacheFolder = fullfile('C:', 'aNonDefaultCacheFolder');
myCodeGenFolder = fullfile('C:', 'aNonDefaultCodeGenFolder');

Simulink.fileGenControl('set', ...
 'CacheFolder', myCacheFolder, ...
 'CodeGenFolder', myCodeGenFolder, ...
 'createDir', true, ...
 'keepPreviousPath', true);
```

```
'keepPreviousPath',true, ...
'createDir',true);
```

## Input Arguments

### Action — Specify action

'reset' | 'set' | 'setConfig'

Specify an action that uses the file generation control parameters of the current MATLAB session:

- 'reset' - Reset file generation control parameters to values from Simulink preferences.
- 'set' - Set file generation control parameters for the current MATLAB session by directly passing values.
- 'setConfig' - Set file generation control parameters for the current MATLAB session by using an instance of a `Simulink.FileGenConfig` object.

### Name-Value Pair Arguments

Specify optional pairs of arguments as `Name1=Value1, ..., NameN=ValueN`, where `Name` is the argument name and `Value` is the corresponding value. Name-value arguments must appear after other arguments, but the order of the pairs does not matter.

*Before R2021a, use commas to separate each name and value, and enclose Name in quotes.*

Example: `Simulink.fileGenControl(Action, Name, Value);`

### config — Specify instance of Simulink.FileGenConfig

object handle

Specify the `Simulink.FileGenConfig` object instance containing file generation control parameters that you want to set.

Option for `setConfig`.

Example: `Simulink.fileGenControl('setConfig', 'config', cfg);`

### CacheFolder — Specify simulation cache folder

character vector

Specify a simulation cache folder path value for the `CacheFolder` parameter.

Option for `set`.

Example: `Simulink.fileGenControl('set', 'CacheFolder', myCacheFolder);`

### CodeGenFolder — Specify code generation folder

character vector

Specify a code generation folder path value for the `CodeGenFolder` parameter. You can specify an absolute path or a path relative to build folders. For example:

- 'C:\Work\mymodelsimcache' and '/mywork/mymodelgencode' specify absolute paths.
- 'mymodelsimcache' is a path relative to the current working folder (pwd). The software converts a relative path to a fully qualified path at the time the `CacheFolder` or `CodeGenFolder`

parameter is set. For example, if `pwd` is  `'/mywork'`, the result is  `'/mywork/mymodelsimcache'`.

- `'../test/mymodelgencode'` is a path relative to `pwd`. If `pwd` is  `'/mywork'`, the result is  `'/test/mymodelgencode'`.

Option for `set`.

Example: `Simulink.fileGenControl('set', 'CodeGenFolder', myCodeGenFolder);`

### **CodeGenFolderStructure — Specify generated code folder structure**

`Simulink.filegen.CodeGenFolderStructure.ModelSpecific` (default) |  
`Simulink.filegen.CodeGenFolderStructure.TargetEnvironmentSubfolder`

Specify the layout of subfolders within the generated code folder:

- `Simulink.filegen.CodeGenFolderStructure.ModelSpecific` (default) - Place generated code in subfolders within a model-specific folder.
- `Simulink.filegen.CodeGenFolderStructure.TargetEnvironmentSubfolder` - If models are configured for different target environments, place generated code for each model in a separate subfolder. The name of the subfolder corresponds to the target environment.

Option for `set`.

Example: `Simulink.fileGenControl('set', 'CacheFolder', myCacheFolder, ...  
'CodeGenFolder', myCodeGenFolder, ... 'CodeGenFolderStructure', ...  
Simulink.filegen.CodeGenFolderStructure.TargetEnvironmentSubfolder);`

### **keepPreviousPath — Keep previous folder paths on MATLAB path**

`false` (default) | `true`

Specify whether to keep the previous values of `CacheFolder` and `CodeGenFolder` on the MATLAB path:

- `true` - Keep previous folder path values on MATLAB path.
- `false` (default) - Remove previous folder path values from MATLAB path.

Option for `reset`, `set`, or `setConfig`.

Example: `Simulink.fileGenControl('reset', 'keepPreviousPath', true);`

### **createDir — Create folders for file generation**

`false` (default) | `true`

Specify whether to create folders for file generation if the folders do not exist:

- `true` - Create folders for file generation.
- `false` (default) - Do not create folders for file generation.

Option for `set` or `setConfig`.

Example: `Simulink.fileGenControl('set', 'CacheFolder', myCacheFolder,  
'CodeGenFolder', myCodeGenFolder, 'keepPreviousPath', true,  
'createDir', true);`

## Avoid Naming Conflicts

Using `Simulink.fileGenControl` to set `CacheFolder` and `CodeGenFolder` adds the specified folders to your MATLAB search path. This function has the same potential for introducing a naming conflict as using `addpath` to add folders to the search path. For example, a naming conflict occurs if the folder that you specify for `CacheFolder` or `CodeGenFolder` contains a model file with the same name as an open model. For more information, see “What Is the MATLAB Search Path?” and “Files and Folders that MATLAB Accesses”.

To use a nondefault location for the simulation cache folder or code generation folder:

- 1 Delete any potentially conflicting artifacts that exist in:
  - The current working folder, `pwd`.
  - The nondefault simulation cache and code generation folders that you intend to use.
- 2 Specify the nondefault locations for the simulation cache and code generation folders by using `Simulink.fileGenControl` or Simulink preferences.

## Output Arguments

### **cfg** — Current values of file generation control parameters

object handle

Instance of a `Simulink.FileGenConfig` object, which contains the current values of file generation control parameters.

## Version History

Introduced in R2010b

## See Also

“Simulation cache folder” | “Code generation folder” | “Code generation folder structure”

## Topics

“Manage Build Process Folders”

“Share Simulink Cache Files for Faster Simulation”

## Simulink.ModelReference.modifyProtectedModel

Modify existing protected model

### Syntax

```
Simulink.ModelReference.modifyProtectedModel(model)
Simulink.ModelReference.modifyProtectedModel(model,Name,Value)

[harnessHandle] = Simulink.ModelReference.modifyProtectedModel(model,'
Harness',true)
[~,neededVars] = Simulink.ModelReference.modifyProtectedModel(model)
```

### Description

`Simulink.ModelReference.modifyProtectedModel(model)` modifies options for an existing protected model created from the specified model. If `Name,Value` pair arguments are not specified, the modified protected model is updated with default values and supports only simulation.

`Simulink.ModelReference.modifyProtectedModel(model,Name,Value)` uses additional options specified by one or more `Name,Value` pair arguments. These options are the same options that are provided by the `Simulink.ModelReference.protect` function. However, these options have additional options to change encryption passwords for read-only view, simulation, and code generation. When you add functionality to the protected model or change encryption passwords, the unprotected model must be available. The software searches for the model on the MATLAB path. If the model is not found, the software reports an error.

`[harnessHandle] = Simulink.ModelReference.modifyProtectedModel(model,'Harness',true)` creates a harness model for the protected model. It returns the handle of the harnessed model in `harnessHandle`.

`[~,neededVars] = Simulink.ModelReference.modifyProtectedModel(model)` returns a cell array that includes the names of base workspace variables used by the protected model.

### Examples

#### Update Protected Model with Default Values

Create a modifiable protected model with support for code generation, then reset it to default values.

Add the password for when a protected model is modified. If you skip this step, you are prompted to set a password when a modifiable protected model is created.

```
openExample('sldemo_mdhref_counter');
Simulink.ModelReference.ProtectedModel.setPasswordForModify(...
'sldemo_mdhref_counter','password');
```

Create a modifiable protected model with support for code generation and Web view.

```
Simulink.ModelReference.protect('sldemo_mdhref_counter','Mode',...
'CodeGeneration','Modifiable',true,'Report',true);
```

Provide the password to modify the protected model.

```
Simulink.ModelReference.ProtectedModel.setPasswordForModify(...
'sldemo_mdhref_counter', 'password');
```

Modify the model to use default values.

```
Simulink.ModelReference.modifyProtectedModel(...
'sldemo_mdhref_counter');
```

The resulting protected model is updated with default values and supports only simulation.

### Remove Functionality from Protected Model

Create a modifiable protected model with support for code generation and Web view, then modify it to remove the Web view support.

Add the password for when a protected model is modified. If you skip this step, you are prompted to set a password when a modifiable protected model is created.

```
openExample('sldemo_mdhref_counter');
Simulink.ModelReference.ProtectedModel.setPasswordForModify(...
'sldemo_mdhref_counter', 'password');
```

Create a modifiable protected model with support for code generation and Web view.

```
Simulink.ModelReference.protect('sldemo_mdhref_counter', 'Mode', ...
'CodeGeneration', 'Webview', true, 'Modifiable', true, 'Report', true);
```

Provide the password to modify the protected model.

```
Simulink.ModelReference.ProtectedModel.setPasswordForModify(...
'sldemo_mdhref_counter', 'password');
```

Remove support for Web view from the protected model that you created.

```
Simulink.ModelReference.modifyProtectedModel(...
'sldemo_mdhref_counter', 'Mode', 'CodeGeneration', 'Report', true);
```

### Change Encryption Password for Code Generation

Change an encryption password for a modifiable protected model.

Add the password for when a protected model is modified. If you skip this step, you are prompted to set a password when a modifiable protected model is created.

```
openExample('sldemo_mdhref_counter');
Simulink.ModelReference.ProtectedModel.setPasswordForModify(...
'sldemo_mdhref_counter', 'password');
```

Add the password that the protected model user must provide to generate code.

```
Simulink.ModelReference.ProtectedModel.setPasswordForSimulation(...
'sldemo_mdhref_counter', 'cgpassword');
```

Create a modifiable protected model with a report and support for code generation with encryption.

```
Simulink.ModelReference.protect('sldemo_mdref_counter', 'Mode', ...
'CodeGeneration', 'Encrypt', true, 'Modifiable', true, 'Report', true);
```

Provide the password to modify the protected model.

```
Simulink.ModelReference.ProtectedModel.setPasswordForModify(...
'sldemo_mdref_counter', 'password');
```

Change the encryption password for simulation.

```
Simulink.ModelReference.modifyProtectedModel(...
'sldemo_mdref_counter', 'Mode', 'CodeGeneration', 'Encrypt', true, ...
'Report', true, 'ChangeSimulationPassword', ...
{'cgpassword', 'new_password'});
```

### Add Harness Model for Protected Model

Add a harness model for an existing protected model.

Add the password for when a protected model is modified. If you skip this step, you are prompted to set a password when a modifiable protected model is created.

```
openExample('sldemo_mdref_counter');
Simulink.ModelReference.ProtectedModel.setPasswordForModify(...
'sldemo_mdref_counter', 'password');
```

Create a modifiable protected model with a report and support for code generation with encryption.

```
Simulink.ModelReference.protect('sldemo_mdref_counter', 'Mode', ...
'CodeGeneration', 'Modifiable', true, 'Report', true);
```

Provide the password to modify the protected model.

```
Simulink.ModelReference.ProtectedModel.setPasswordForModify(...
'sldemo_mdref_counter', 'password');
```

Add a harness model for the protected model.

```
[harnessHandle] = Simulink.ModelReference.modifyProtectedModel(...
'sldemo_mdref_counter', 'Mode', 'CodeGeneration', 'Report', true, ...
'Harness', true);
```

## Input Arguments

### **model** — Model name

string or character vector (default)

Model name, specified as a string or character vector. It contains the name of a model or the path name of a Model block that references the protected model.



## Name-Value Pair Arguments

Specify optional pairs of arguments as `Name1=Value1, . . . ,NameN=ValueN`, where `Name` is the argument name and `Value` is the corresponding value. Name-value arguments must appear after other arguments, but the order of the pairs does not matter.

*Before R2021a, use commas to separate each name and value, and enclose Name in quotes.*

Example: `'Mode','CodeGeneration','OutputFormat','Binaries','ObfuscateCode',true` specifies that obfuscated code be generated for the protected model. It also specifies that only binary files and headers in the generated code be visible to users of the protected model.

## General

### Path — Folder for protected model

current working folder (default) | string or character vector

Folder for protected model, specified as a string or character vector.

Example: `'Path','C:\Work'`

### Report — Option to generate a report

false (default) | true

Option to generate a report, specified as a Boolean value.

To view the report, right-click the protected-model badge icon and select **Display Report**. Or, call the `Simulink.ProtectedModel.open` function with the `report` option.

The report is generated in HTML format. It includes information on the environment, functionality, license requirements, and interface for the protected model.

Example: `'Report',true`

### hdl — Option to generate HDL code

false (default) | true

Option to generate HDL code, specified as a Boolean value.

This option requires HDL Coder license. When you enable this option, make sure that you specify the **Mode**. You can set this option to `true` in conjunction with the **Mode** set to `CodeGeneration` to enable both C code and HDL code generation support for the protected model.

If you want to enable only simulation and HDL code generation support, but not C code generation, set **Mode** to `HDLCodeGeneration`. You do not have to set the **hdl** option to `true`.

Example: `'hdl',true`

### Harness — Option to create a harness model

false (default) | true

Option to create a harness model, specified as a Boolean value.

Example: `'Harness',true`

### CustomPostProcessingHook — Option to add postprocessing function for protected model files

function handle

Option to add a postprocessing function for protected model files, specified as a function handle. The function accepts a `Simulink.ModelReference.ProtectedModel.HookInfo` object as an input variable. This object provides information on the source code files and other files generated during protected model creation. The object also provides information on exported symbols that you must not modify. Prior to packaging the protected model, the postprocessing function is called.

For a protected model with a top model interface, the `Simulink.ModelReference.ProtectedModel.HookInfo` object cannot provide information on exported symbols.

Example: `'CustomPostProcessingHook',@(protectedMdlInf)myHook(protectedMdlInf)`

### Functionality

#### Mode — Model protection mode

`'Normal'` (default) | `'Accelerator'` | `'CodeGeneration'` | `'HDLCodeGeneration'` | `'ViewOnly'`

Model protection mode. Specify one of the following values:

- `'Normal'`: If the top model is running in `'Normal'` mode, the protected model runs as a child of the top model.
- `'Accelerator'`: The top model can run in `'Normal'`, `'Accelerator'`, or `'Rapid Accelerator'` mode.
- `'CodeGeneration'`: The top model can run in `'Normal'`, `'Accelerator'`, or `'Rapid Accelerator'` mode and support code generation.
- `'HDLCodeGeneration'`: The top model can run in `'Normal'`, `'Accelerator'`, or `'Rapid Accelerator'` mode and support HDL code generation.
- `'ViewOnly'`: Turns off Simulate and Generate code functionality modes. Turns on the read-only view mode.

Example: `'Mode','Accelerator'`

#### OutputFormat — Protected code visibility

`'CompiledBinaries'` (default) | `'MinimalCode'` | `'AllReferencedHeaders'`

---

**Note** This argument affects the output only when you specify `Mode` as `'Accelerator'` or `'CodeGeneration'`. When you specify `Mode` as `'Normal'`, only a MEX-file is part of the output package.

---

Protected code visibility. This argument determines what part of the code generated for a protected model is visible to users. Specify one of the following values:

- `'CompiledBinaries'`: Only binary files and headers are visible.
- `'MinimalCode'`: Includes only the minimal header files required to build the code with the chosen build settings. Code in the build folder is visible. Users can inspect the code in the protected model report and recompile it for their purposes.
- `'AllReferencedHeaders'`: Includes header files found on the include path. Code in the build folder is visible. Header files referenced by the code are also visible.

Example: `'OutputFormat','AllReferencedHeaders'`

**ObfuscateCode — Option to obfuscate generated code**

true (default) | false

Option to obfuscate generated code, specified as a Boolean value. Applicable only when code generation is enabled for the protected model. Obfuscation is not supported for HDL code generation.

Example: 'ObfuscateCode', true

**Webview — Option to include a Web view**

false (default) | true

Option to include a read-only view of protected model, specified as a Boolean value.

To open the Web view of a protected model, use one of the following methods:

- Right-click the protected-model badge icon and select **Show Web view**.
- Use the `Simulink.ProtectedModel.open` function. For example, to display the Web view for protected model `sldemo_mdhref_counter`, you can call:

```
Simulink.ProtectedModel.open('sldemo_mdhref_counter', 'webview');
```

- Double-click the `.slxp` protected model file in the Current Folder browser.
- In the Block Parameter dialog box for the protected model, click **Open Model**.

Example: 'Webview', true

**Encryption****ChangeSimulationPassword — Option to change the encryption password for simulation**

cell array of two character vectors

Option to change the encryption password for simulation, specified as a cell array of two character vectors. The first vector is the old password, the second vector is the new password.

Example: 'ChangeSimulationPassword', {'old\_password', 'new\_password'}

**ChangeViewPassword — Option to change the encryption password for read-only view**

cell array of two character vectors

Option to change the encryption password for read-only view, specified as a cell array of two character vectors. The first vector is the old password, the second vector is the new password.

Example: 'ChangeViewPassword', {'old\_password', 'new\_password'}

**ChangeCodeGenerationPassword — Option to change the encryption password for code generation**

cell array of two character vectors

Option to change the encryption password for code generation, specified as a cell array of two character vectors. The first vector is the old password, the second vector is the new password.

Example: 'ChangeCodeGenerationPassword', {'old\_password', 'new\_password'}

**Encrypt — Option to encrypt protected model**

false (default) | true

Option to encrypt a protected model, specified as a Boolean value. Applicable when you have specified a password during protection, or by using the following methods:

- Password for read-only view of model:  
`Simulink.ModelReference.ProtectedModel.setPasswordForView`
- Password for simulation:  
`Simulink.ModelReference.ProtectedModel.setPasswordForSimulation`
- Password for code generation:  
`Simulink.ModelReference.ProtectedModel.setPasswordForCodeGeneration`
- Password for HDL code generation:  
`Simulink.ModelReference.ProtectedModel.setPasswordForHDLCodeGeneration`

Example: `'Encrypt', true`

## Output Arguments

### **harnessHandle** — Handle of the harness model

double

Handle of the harness model, returned as a double or 0, depending on the value of `Harness`.

If `Harness` is `true`, the value is the handle of the harness model; otherwise, the value is 0.

### **neededVars** — Names of base workspace variables

cell array

Names of base workspace variables used by the protected model, returned as a cell array.

The cell array can also include variables that the protected model does not use.

## Version History

**Introduced in R2014b**

### See Also

`Simulink.ModelReference.protect` |

`Simulink.ModelReference.ProtectedModel.setPasswordForModify`

# Simulink.ModelReference.protect

Obscure referenced model contents to hide intellectual property

## Syntax

```
Simulink.ModelReference.protect(model)
Simulink.ModelReference.protect(model,Name,Value)

[harnessHandle] = Simulink.ModelReference.protect(model,'Harness',true)
[~,neededVars] = Simulink.ModelReference.protect(model)
```

## Description

`Simulink.ModelReference.protect(model)` creates a protected model from the specified model. It places the protected model in the current working folder. The protected model has the same name as the source model. It has the extension `.slxp`.

`Simulink.ModelReference.protect(model,Name,Value)` uses additional options specified by one or more name-value pair arguments.

`[harnessHandle] = Simulink.ModelReference.protect(model,'Harness',true)` creates a harness model for the protected model. It returns the handle of the harnessed model in `harnessHandle`.

`[~,neededVars] = Simulink.ModelReference.protect(model)` returns a cell array that includes the names of base workspace variables used by the protected model.

## Examples

### Protect Referenced Model

Protect a referenced model and place the protected model in the current working folder.

```
openExample('sldemo_mdhref_bus');
model= 'sldemo_mdhref_counter_bus'
```

```
Simulink.ModelReference.protect(model);
```

A protected model named `sldemo_mdhref_counter_bus.slxp` is created. The protected model file is placed in the current working folder.

### Place Protected Model in Specified Folder

Protect a referenced model and place the protected model in a specified folder.

```
openExample('sldemo_mdhref_bus');
model= 'sldemo_mdhref_counter_bus'
```

```
Simulink.ModelReference.protect(model,'Path','C:\Work');
```

A protected model named `sldemo_mdhref_counter_bus.slxp` is created. The protected model file is placed in `C:\Work`.

### Generate Code for Protected Model

Protect a referenced model, generate code for it in normal mode, and obfuscate the code.

```
openExample('sldemo_mdhref_bus');
model= 'sldemo_mdhref_counter_bus'

Simulink.ModelReference.protect(model, 'Path', 'C:\Work', 'Mode', 'CodeGeneration', ...
'ObfuscateCode', true);
```

A protected model named `sldemo_mdhref_counter_bus.slxp` is created. The protected model file is placed in the `C:\Work` folder. The protected model runs as a child of the parent model. The code generated for the protected model is obfuscated by the software.

### Generate HDL Code for Protected Model

Protect a referenced model, and generate HDL code for it in normal mode.

```
openExample('hdlcoder/ParentModelWithModelReferenceExample')
parent_model= 'hdlcoder_protected_model_parent_harness';
reference_model_to_protect = 'hdlcoder_referenced_model_gain';

Simulink.ModelReference.protect(reference_model_to_protect, ...
'Mode', 'HDLCodeGeneration')
```

A protected model named `hdlcoder_referenced_model_gain.slxp` is created. The protected model file is placed in the same folder as the parent model and the referenced model. The protected model runs as a child of the parent model.

Set the **hdl** option to `true` with **Mode** set to `CodeGeneration` to enable both C code generation and HDL code generation support for a protected model that you create.

```
openExample('hdlcoder/ParentModelWithModelReferenceExample')
parent_model= 'hdlcoder_protected_model_parent_harness';
reference_model_to_protect = 'hdlcoder_referenced_model_gain';

Simulink.ModelReference.protect(reference_model_to_protect, ...
'Mode', 'CodeGeneration', 'hdl', true)
```

### Control Code Visibility for Protected Model

Control code visibility by allowing users to view only binary files and headers in the code generated for a protected model.

```
openExample('sldemo_mdhref_bus');
model= 'sldemo_mdhref_counter_bus'

Simulink.ModelReference.protect(model, 'Mode', 'CodeGeneration', 'OutputFormat', ...
'CompiledBinaries');
```

A protected model named `sldemo_mdhref_counter_bus.slxp` is created. The protected model file is placed in the current working folder. Users can view only binary files and headers in the code generated for the protected model.

### Create Harness Model for Protected Model

Create a harness model for a protected model and generate an HTML report.

```
openExample('sldemo_mdhref_bus');
modelPath= 'sldemo_mdhref_bus/CounterA'

[harnessHandle] = Simulink.ModelReference.protect(modelPath, 'Path', 'C:\Work', ...
'Harness', true, 'Report', true);
```

A protected model named `sldemo_mdhref_counter_bus.slxp` is created, along with an untitled harness model. The protected model file is placed in the `C:\Work` folder. The folder also contains an HTML report. The handle of the harness model is returned in `harnessHandle`.

### Determine Variables Required by Protected Model

To simulate a model that references a protected model, you might need to define variables in the base workspace or data dictionaries. For example, the `sldemo_mdhref_counter_bus` model needs the variables that specify the buses at the root input and output ports of the model. When you ship a protected model, you must include definitions of the required variables or the model is unusable.

---

**Tip** To automatically package required variable definitions with the protected model in a project, set `Project` to `true`.

---

Generate the protected model and determine the required variables.

```
openExample('sldemo_mdhref_bus');
model= 'sldemo_mdhref_counter_bus'

[~, neededVars] = Simulink.ModelReference.protect(model)
```

The second output, `neededVars`, determines the variables you must send to the recipient. The value of `neededVars` is a cell array that contains the names of the variables required by the protected model. However, the cell array might also contain the names of variables that the model does not need.

Before you share the protected model, edit `neededVars` to delete the names of any variables that the model does not need. Save the required variables in a data dictionary.

## Input Arguments

### **model** — Model name

character vector | string scalar

Model name, specified as a character vector or string scalar. It contains the name of a model or the path name of a Model block that references the model to be protected.

Data Types: char | string

### **Name-Value Pair Arguments**

Specify optional pairs of arguments as `Name1=Value1, ..., NameN=ValueN`, where `Name` is the argument name and `Value` is the corresponding value. Name-value arguments must appear after other arguments, but the order of the pairs does not matter.

*Before R2021a, use commas to separate each name and value, and enclose Name in quotes.*

Example: `'Mode', 'CodeGeneration', 'OutputFormat', 'Binaries', 'ObfuscateCode', true` specifies that obfuscated code be generated for the protected model. It also specifies that only binary files and headers in the generated code be visible to users of the protected model.

### **File Options**

#### **Project — Option to collect dependencies in project**

false (default) | true

Option to collect dependencies in project, specified as `true` or `false`.

The protected model, its dependencies, and its harness model are saved in a project archive (`.mlproj`). The project archive provides a way to share a project in a single file. You must open the project archive to create the interactive project.

---

**Note** Before sharing the project, check whether the project contains the necessary supporting files. If supporting files are missing, simulating or generating code for the related harness model can help identify them. Add the missing dependencies to the project and update the harness model as needed.

---

Example: `'Project', true`

Data Types: logical

#### **ProjectName — Custom project name**

character vector | string scalar

Custom project name, specified as a character vector or string scalar.

If you do not specify a custom project name, the default name for the project is the protected model name followed by `_protected`.

Example: `'ProjectName', 'myname'`

### **Dependencies**

To enable `ProjectName`, set `Project` to `true`.

Data Types: char | string

#### **Harness — Option to create harness model**

false (default) | true

Option to create harness model, specified as a Boolean value.

When you create a harness model for a protected model that relies on base workspace definitions, Simulink creates a MAT-file that contains the base workspace definitions.



The harness model must have access to supporting files, such as a MAT-file with base workspace definitions or a data dictionary.

Example: 'Harness', true

Data Types: logical

### Path — Folder for protected model

current working folder (default) | character vector | string scalar

Folder for protected model, specified as a character vector or string scalar.

Example: 'Path', 'C:\Work'

Data Types: char | string

### Functionality Options

#### Report — Option to generate report

false (default) | true

Option to generate report, specified as a Boolean value.

To view the report, right-click the protected-model badge icon and select **Display Report**. Or, call the `Simulink.ProtectedModel.open` function with the report option.

The report is generated in HTML format. It includes information on the environment, functionality, and interface for the protected model.

Example: 'Report', true

Data Types: logical

#### Webview — Option to include read-only Web view of protected model

false (default) | true

Option to include read-only Web view of protected model, specified as a Boolean value.

To open the Web view of a protected model, use one of the following methods:

- Right-click the protected-model badge icon and select **Show Web view**.
- Use the `Simulink.ProtectedModel.open` function. For example, to display the Web view for protected model `sldemo_mdhref_counter`, call:

```
Simulink.ProtectedModel.open('sldemo_mdhref_counter', 'webview');
```

- Double-click the `.slxp` protected model file in the Current Folder browser.
- In the Block Parameter dialog box for the protected model, click **Open Model**.

Example: 'Webview', true

Data Types: logical

#### Mode — Model protection mode

'Normal' (default) | 'Accelerator' | 'CodeGeneration' | 'HDLCodeGeneration' | 'ViewOnly'

Model protection mode, specified as one of the following values:

- `'Normal'`: If the top model is running in `'Normal'` mode, the protected model runs as a child of the top model.
- `'Accelerator'`: The top model can run in `'Normal'`, `'Accelerator'`, or `'Rapid Accelerator'` mode.
- `'CodeGeneration'`: The top model can run in `'Normal'`, `'Accelerator'`, or `'Rapid Accelerator'` mode and support code generation.
- `'HDLCodeGeneration'`: The top model can run in `'Normal'`, `'Accelerator'`, or `'Rapid Accelerator'` mode and support HDL code generation. Requires HDL Coder license.
- `'ViewOnly'`: This value turns off Simulate and Generate code functionality modes and turns on the read-only view mode.

Example: `'Mode', 'Accelerator'`

### **CodeInterface** — Interface through which generated code is accessed by Model block

`'Model reference'` (default) | `'Top model'`

Interface through which generated code is accessed by a Model block, specified as one of the following values:

- `'Model reference'`: Code access through the model reference code interface, which allows use of the protected model within a model reference hierarchy. Users of the protected model can generate code from a parent model that contains the protected model. In addition, users can run Model block SIL/PIL simulations with the protected model.
- `'Top model'`: Code access through the standalone interface. Users of the protected model can run Model block SIL/PIL simulations with the protected model.

Example: `'CodeInterface', 'Top model'`

### **Dependencies**

The system target file (`SystemTargetFile`) must be set to an ERT-based system target file, for example, `ert.tlc`). Requires Embedded Coder license.

### **hdl** — Option to generate HDL code

`false` (default) | `true`

Option to generate HDL code, specified as a Boolean value.

This option requires an HDL Coder license. When you enable this option, make sure that you specify the **Mode**. You can set this option to `true` in conjunction with the **Mode** set to `CodeGeneration` to enable both C code and HDL code generation support for the protected model.

If you want to enable only simulation and HDL code generation support, but not C code generation, set **Mode** to `HDLCodeGeneration`. You do not have to set the **hdl** option to `true`.

Example: `'hdl', true`

Data Types: `logical`

### **TunableParameters** — Tunable parameters for simulation

`'None'` or `{}` (default) | `'All'` | string array | cell array of character vectors

Tunable parameters for simulation, specified as `'None'`, `{}`, `'All'`, a string array, or a cell array of character vectors.

Recipients of the protected model can tune the specified parameters during simulation.

Parameters that are not tunable are not listed as needed variables unless:

- They are used by the model interface.
- They specify part of a data type, such as a bus object, enumerated type, or value type.
- They are used by data store memory.

When you protect a model that references one or more protected models, you must specify the tunable parameters of each referenced protected model as tunable for the model you are protecting.

Example: `'TunableParameters',{ 'param1', 'param2' }`

Example: `TunableParameters=["param1", "param2"]`

Data Types: `char | string | cell`

### **Callbacks — Option to specify callbacks for protected model**

`cell array`

Option to specify callbacks for protected model, specified as a cell array of `Simulink.ProtectedModel.Callback` objects.

Example: `'Callbacks',{ pmcallback_sim, pmcallback_cg }`

Data Types: `cell`

### **Protection Options**

#### **ObfuscateCode — Option to obfuscate generated code**

`true (default) | false`

Option to obfuscate generated code, specified as a Boolean value. Applicable only when code generation during protection is enabled. Obfuscation is not supported for HDL code generation.

Example: `'ObfuscateCode', true`

Data Types: `logical`

#### **OutputFormat — Protected code visibility**

`'CompiledBinaries' (default) | 'MinimalCode' | 'AllReferencedHeaders'`

Protected code visibility, specified as one of the following values:

- `'CompiledBinaries'`: Only binary files and headers are visible.
- `'MinimalCode'`: Includes only the minimal header files required to build the code with the chosen build settings. All code in the build folder is visible. Users can inspect the code in the protected model report and recompile it for their purposes.
- `'AllReferencedHeaders'`: Includes header files found on the include path. All code in the build folder is visible. All headers referenced by the code are also visible.

This argument determines what part of the code generated for a protected model is visible to users.

Example: `'OutputFormat', 'AllReferencedHeaders'`

### Dependencies

This argument affects the output only when you specify Mode as 'Accelerator' or 'CodeGeneration'. When you specify Mode as 'Normal', only a MEX-file is part of the output package.

### Encrypt — Option to encrypt protected model

false (default) | true

Option to encrypt protected model, specified as a Boolean value. Applicable when you have specified a password during protection, or by using the following methods:

- Password for read-only view of model:  
`Simulink.ModelReference.ProtectedModel.setPasswordForView`
- Password for simulation:  
`Simulink.ModelReference.ProtectedModel.setPasswordForSimulation`
- Password for code generation:  
`Simulink.ModelReference.ProtectedModel.setPasswordForCodeGeneration`
- Password for HDL code generation:  
`Simulink.ModelReference.ProtectedModel.setPasswordForHDLCodeGeneration`

Example: 'Encrypt', true

Data Types: logical

### Sign — Option to sign protected model with digital certificate

character vector | string scalar

Option to sign protected model with digital certificate, specified as a character vector or string scalar that specifies the digital certificate. If the certificate file is password-protected, use the `Simulink.ModelReference.ProtectedModel.setPasswordForCertificate` function to provide the password before you use the certificate.

Example: 'Sign', 'my\_certificate.pfx'

Data Types: char | string

### Modifiable — Option to create modifiable protected model

false (default) | true

Option to create modifiable protected model, specified as a Boolean value. To use this option:

- Add a password for modification by using the `Simulink.ModelReference.ProtectedModel.setPasswordForModify` function. If a password has not been added at the time that you create the modifiable protected model, you are prompted to create one.
- Modify the options of your protected model by first providing the modification password using the `Simulink.ModelReference.ProtectedModel.setPasswordForModify` function. Then, use the `Simulink.ModelReference.modifyProtectedModel` function to make your option changes.

Example: 'Modifiable', true

Data Types: logical

### **CustomPostProcessingHook — Option to add postprocessing function for protected model files**

function handle

Option to add a postprocessing function for protected model files, specified as a function handle.

The function accepts a `Simulink.ModelReference.ProtectedModel.HookInfo` object as an input variable. This object provides information on the source code files and other files generated during protected model creation. It also provides information on exported symbols that you must not modify. Prior to packaging the protected model, the postprocessing function is called.

For a protected model with a top model interface, the `Simulink.ModelReference.ProtectedModel.HookInfo` object cannot provide information on exported symbols.

Example: `'CustomPostProcessingHook',@(protectedMdlInf)myHook(protectedMdlInf)`

## **Output Arguments**

### **harnessHandle — Handle of harness model**

double

Handle of harness model, returned as a double. When model protection does not create a harness model or packages the harness model in a project archive, the returned value is `0`.

To create a harness model that is open after model protection, set `Harness` to `true` and `Project` to `false` (default).

### **neededVars — Names of base workspace variables**

cell array

Names of base workspace variables that the protected model uses, returned as a cell array.

The cell array can also include variables that the protected model does not use.

## **Alternatives**

“Protect Models to Conceal Contents”

## **Version History**

**Introduced in R2012b**

### **Tunable parameters for simulation are specified by the TunableParameters argument**

*Behavior changed in R2022a*

Starting in R2022a, you must specify the parameters of the protected model that you want to be tunable during simulation by using the `TunableParameters` name-value argument. By default, no parameters are tunable during simulation.

Previously, a parameter was tunable when its code generation storage class was set to a value other than `Auto`. By default, the storage class for an individual data element is `Auto`.

**See Also**

`Simulink.ModelReference.modifyProtectedModel` |  
`Simulink.ModelReference.ProtectedModel.setPasswordForModify` |  
`Simulink.ModelReference.ProtectedModel.setPasswordForCodeGeneration` |  
`Simulink.ModelReference.ProtectedModel.setPasswordForHDLCodeGeneration` |  
`Simulink.ModelReference.ProtectedModel.setPasswordForSimulation` |  
`Simulink.ModelReference.ProtectedModel.setPasswordForView` |  
`Simulink.ModelReference.ProtectedModel.clearPasswords` |  
`Simulink.ModelReference.ProtectedModel.clearPasswordsForModel` |  
`Simulink.ProtectedModel.getTunableParameters`

**Topics**

[“Protect Models to Conceal Contents”](#)  
[“Explore Protected Model Capabilities”](#)  
[“Test Protected Models”](#)  
[“Package and Share Protected Models”](#)  
[“Specify Custom Obfuscators for Protected Models”](#)  
[“Configure and Run SIL Simulation” \(Embedded Coder\)](#)  
[“Code Interfaces for SIL and PIL” \(Embedded Coder\)](#)  
[“Define Callbacks for Protected Models”](#)  
[“Reference Protected Models from Third Parties”](#)

# Simulink.ModelReference.ProtectedModel.clearPasswords

Clear cached passwords for protected models

## Syntax

```
Simulink.ModelReference.ProtectedModel.clearPasswords()
```

## Description

`Simulink.ModelReference.ProtectedModel.clearPasswords()` clears protected model passwords that have been cached during the current MATLAB session. If this function is not called, cached passwords are cleared at the end of a MATLAB session.

## Examples

### Clear cached passwords for protected models

After using protected models, clear passwords cached for the models during the MATLAB session.

```
Simulink.ModelReference.ProtectedModel.clearPasswords()
```

## Version History

**Introduced in R2014b**

## See Also

`Simulink.ModelReference.ProtectedModel.clearPasswordsForModel`

## Topics

“Protect Models to Conceal Contents”

## Simulink.ModelReference.ProtectedModel.clearPasswordsForModel

Clear cached passwords for a protected model

### Syntax

```
Simulink.ModelReference.ProtectedModel.clearPasswordsForModel(model)
```

### Description

`Simulink.ModelReference.ProtectedModel.clearPasswordsForModel(model)` clears protected model passwords for `model` that have been cached during the current MATLAB session. If this function is not called, cached passwords are cleared at the end of a MATLAB session.

### Examples

#### Clear cached passwords for a protected model

After using a protected model, clear passwords cached for the model during the MATLAB session.

```
Simulink.ModelReference.ProtectedModel.clearPasswordsForModel(model)
```

### Input Arguments

#### **model** — Protected model name

string or character vector

Model name specified as a string or character vector

Example: 'rtwdemo\_counter'

Data Types: char

### Version History

**Introduced in R2014b**

### See Also

`Simulink.ModelReference.ProtectedModel.clearPasswords`

### Topics

"Protect Models to Conceal Contents"



# Simulink.ProtectedModel.getTunableParameters

Get list of tunable parameters for protected model

## Syntax

```
parameters = Simulink.ProtectedModel.getTunableParameters(model)
```

## Description

`parameters = Simulink.ProtectedModel.getTunableParameters(model)` returns the tunable parameters for the protected model specified by `model`.

## Examples

### Get Tunable Parameters for Protected Model

Suppose you want to protect a model named `myModel` and you want the recipient of the protected model to be able to tune parameter values during simulation. You can use the `Simulink.ModelReference.protect` function to protect the model with all tunable parameters available to the protected model recipient.

```
Simulink.ModelReference.protect("myModel",TunableParameters="All")
```

The `Simulink.ProtectedModel.getTunableParameters` function returns the tunable parameters of the protected model.

```
Simulink.ProtectedModel.getTunableParameters("myModel")
```

```
ans =
 1x2 string array
 "K" "K2"
```

## Input Arguments

### **model** — Protected model to query

string scalar | character vector

Protected model to query, specified as a string scalar or character vector.

Data Types: `char` | `string`

## Output Arguments

### **parameters** — Tunable parameters in specified protected model

string array

Tunable parameters in specified protected model, returned as a string array.

## **Version History**

**Introduced in R2022a**

### **See Also**

`Simulink.ModelReference.protect`

### **Topics**

“Protect Models to Conceal Contents”

“Test Protected Models”

“Package and Share Protected Models”

“Best Practices for Creating Protected Models”

# Simulink.ModelReference.ProtectedModel.HookInfo

Files and exported symbols generated by creation of protected model

## Description

Information about files and symbols generated when creating a protected model. You can use this information for postprocessing of the generated files prior to packaging. To access the properties of this class, create a postprocessing function that accepts a `Simulink.ModelReference.ProtectedModel.HookInfo` object as input. When you protect your model, use the 'CustomPostProcessingHook' option of the `Simulink.ModelReference.protect` function to specify the postprocessing function. Prior to packaging the protected model, the postprocessing function is called with the `Simulink.ModelReference.ProtectedModel.HookInfo` from the protected model as input.

## Properties

### ExportedSymbols — Exported Symbols

cell array of character vectors

A list of exported symbols generated by a protected model that you must not modify, returned as a cell array of character vectors.

For a protected model with a top model interface, the `HookInfo` object cannot provide information on exported symbols.

### NonSourceFiles — Nonsource code files

cell array of character vectors

A list of nonsource files generated by protected model creation, returned as a cell array of character vectors. Nonsource files include MAT, RSP, and PRJ files.

### SourceFiles — Source code files

cell array of character vectors

A list of source code files generated by protected model creation, returned as a cell array of character vectors. Source files include C, H, CPP, and HPP files.

## Examples

### Use Protected Model Information in Postprocessing Function

- 1 On the MATLAB path, create a postprocessing function `pm_postprocessing.m` that contains this code:

```
function pm_postprocessing(hookInfoObject)
```

```
s1 = 'Exported Symbols: ';
symbols = hookInfoObject.ExportedSymbols;
s2 = 'Source Files: ';
srcfiles = hookInfoObject.SourceFiles;
s3 = 'Non-Source Files: ';
nonsrcfiles = hookInfoObject.NonSourceFiles;
disp([s1 symbols])
disp([s2 srcfiles])
disp([s3 nonsrcfiles])
```

This function displays a list of the exported symbols, source code files, and nonsource files generated by the model protection process.

- 2** Protect the model `sldemo_mdhref_counter` and specify the postprocessing function that you created. Before packaging the generated files, the model protection process calls the postprocessing function and inputs the `Simulink.ModelReference.ProtectedModel.HookInfo` object that was generated for the protected model.

```
Simulink.ModelReference.protect('sldemo_mdhref_counter',...
'Mode', 'CodeGeneration',...
'CustomPostProcessingHook',...
@(protectedMdlInf)pm_postprocessing(protectedMdlInf))
```

## Version History

Introduced in R2014a

### See Also

`Simulink.ModelReference.protect`

### Topics

“Specify Custom Obfuscators for Protected Models”

# Simulink.ModelReference.ProtectedModel.setPasswordForCertificate

Provide password for digital certificate

## Syntax

```
Simulink.ModelReference.ProtectedModel.setPasswordForCertificate(
certificateFile,password)
```

## Description

`Simulink.ModelReference.ProtectedModel.setPasswordForCertificate(certificateFile,password)` provides the required password to access the certificate file to digitally sign a protected model.

## Examples

### Sign a Protected Model by Using Password Protected Certificate

Protect a model, and then digitally sign it by using a password protected certificate.

Open and protect the model that you want to sign. For this example, protect the model `sldemo_mdhref_counter`.

```
openExample('sldemo_mdhref_counter');
Simulink.ModelReference.protect('sldemo_mdhref_counter');
```

Locate the certificate file that you want to use to sign the protected model. Enter the password for the certificate.

```
Simulink.ModelReference.ProtectedModel.setPasswordForCertificate('certificate_file.pfx','password');
```

Sign the protected model by using the certificate file.

```
Simulink.ProtectedModel.sign('sldemo_mdhref_counter.slxp','certificate_file.pfx');
```

## Input Arguments

### certificateFile — Certificate file to use for signing

character vector | string scalar

Certificate file to use for signing the protected model, specified as a character vector or string scalar. The certificate must be a PKCS #12 file with the extension `.pfx` or `.p12`.

Example: `'my_cert.pfx'`

Example: `'InstitutionCertificate.p12'`

### password — Password for certificate file

string or character vector

Password, specified as a string or character vector. If the certificate is encrypted for code generation, the password is required.

## **Version History**

**Introduced in R2020a**

### **See Also**

`Simulink.ProtectedModel.sign`

### **Topics**

“Sign a Protected Model”

# Simulink.ModelReference.ProtectedModel.setPasswordForCodeGeneration

Add or provide encryption password for code generation from protected model

## Syntax

```
Simulink.ModelReference.ProtectedModel.setPasswordForCodeGeneration(model,
password)
```

## Description

`Simulink.ModelReference.ProtectedModel.setPasswordForCodeGeneration(model, password)` adds an encryption password for code generation if you create a protected model. If you use a protected model, the function provides the required password to generate code from the model.

## Examples

### Create a Protected Model with Encryption

Create a protected model with encryption for code generation.

```
Simulink.ModelReference.ProtectedModel.setPasswordForCodeGeneration(...
'sldemo_mdhref_counter', 'password');
Simulink.ModelReference.protect('sldemo_mdhref_counter', ...
'Mode', 'CodeGeneration', 'Encrypt', true, 'Report', true);
```

A protected model named `sldemo_mdhref_counter.slxp` is created that requires an encryption password for code generation.

### Generate Code from an Encrypted Protected Model

Use a protected model with encryption for code generation.

Provide the encryption password required for code generation from the protected model.

```
Simulink.ModelReference.ProtectedModel.setPasswordForCodeGeneration(...
'sldemo_mdhref_counter', 'password');
```

After you have provided the encryption password, you can generate code from the protected model.

## Input Arguments

### **model** — Model name

string or character vector

Model name, specified as a string or character vector. It contains the name of a model or the path name of a Model block that references the protected model.

**password — Password for protected model code generation**

string or character vector

Password, specified as a string or character vector. If the protected model is encrypted for code generation, the password is required.

## Version History

**Introduced in R2014b**

### See Also

`Simulink.ModelReference.protect` |  
`Simulink.ModelReference.ProtectedModel.setPasswordForSimulation` |  
`Simulink.ModelReference.ProtectedModel.setPasswordForView` |  
`Simulink.ModelReference.ProtectedModel.setPasswordForHDLCodeGeneration`



# Simulink.ModelReference.ProtectedModel.setPasswordForModify

Add or provide password for modifying protected model

## Syntax

```
Simulink.ModelReference.ProtectedModel.setPasswordForModify(model,password)
```

## Description

`Simulink.ModelReference.ProtectedModel.setPasswordForModify(model,password)` adds a password for a modifiable protected model. After the password has been created, the function provides the password for modifying the protected model.

## Examples

### Add Functionality to Protected Model

Create a modifiable protected model with support for code generation, then modify it to add Web view support.

Add the password for when a protected model is modified. If you skip this step, you are prompted to set a password when a modifiable protected model is created.

```
openExample('sldemo_mdhref_counter');
Simulink.ModelReference.ProtectedModel.setPasswordForModify(...
'sldemo_mdhref_counter','password');
```

Create a modifiable protected model with support for code generation and Web view.

```
Simulink.ModelReference.protect('sldemo_mdhref_counter','Mode',...
'CodeGeneration','Modifiable',true,'Report',true);
```

Provide the password to modify the protected model.

```
Simulink.ModelReference.ProtectedModel.setPasswordForModify(...
'sldemo_mdhref_counter','password');
```

Add support for Web view to the protected model that you created.

```
Simulink.ModelReference.modifyProtectedModel(...
'sldemo_mdhref_counter','Mode','CodeGeneration','Webview',true,...
'Report',true);
```

## Input Arguments

**model** — Model name

string or character vector

Model name, specified as a string or character vector. It contains the name of a model or the path name of a Model block that references the protected model to be modified.

**password — Password to modify protected model**

string or character vector

Password, specified as a string or character vector. The password is required for modification of the protected model.

## **Version History**

**Introduced in R2014b**

### **See Also**

`Simulink.ModelReference.protect` | `Simulink.ModelReference.modifyProtectedModel`

# Simulink.ModelReference.ProtectedModel.setPasswordForSimulation

Add or provide encryption password for simulation of protected model

## Syntax

```
Simulink.ModelReference.ProtectedModel.setPasswordForSimulation(model,
password)
```

## Description

`Simulink.ModelReference.ProtectedModel.setPasswordForSimulation(model, password)` adds an encryption password for simulation if you create a protected model. If you use a protected model, the function provides the required password to simulate the model.

## Examples

### Create a Protected Model with Encryption

Create a protected model with encryption for simulation.

```
openExample('sldemo_mdhref_counter');
Simulink.ModelReference.ProtectedModel.setPasswordForSimulation(...
'sldemo_mdhref_counter', 'password');
Simulink.ModelReference.protect('sldemo_mdhref_counter', ...
'Encrypt', true, 'Report', true);
```

A protected model named `sldemo_mdhref_counter.slxp` is created that requires an encryption password for simulation.

### Simulate an Encrypted Protected Model

Use a protected model with encryption for simulation.

Provide the encryption password required for simulation of the protected model.

```
openExample('sldemo_mdhref_counter');
Simulink.ModelReference.ProtectedModel.setPasswordForSimulation(...
'sldemo_mdhref_counter', 'password');
```

After you have provided the encryption password, you can simulate the protected model.

## Input Arguments

**model** — Model name

string or character vector

Model name, specified as a string or character vector. It contains the name of a model or the path name of a Model block that references the protected model.

**password — Password for protected model simulation**

string or character vector

Password, specified as a string or character vector. If the protected model is encrypted for simulation, the password is required.

## **Version History**

**Introduced in R2014b**

### **See Also**

`Simulink.ModelReference.protect` |  
`Simulink.ModelReference.ProtectedModel.setPasswordForCodeGeneration` |  
`Simulink.ModelReference.ProtectedModel.setPasswordForHDLCodeGeneration` |  
`Simulink.ModelReference.ProtectedModel.setPasswordForView`

# Simulink.ModelReference.ProtectedModel.setPasswordForView

Add or provide encryption password for read-only view of protected model

## Syntax

```
Simulink.ModelReference.ProtectedModel.setPasswordForView(model,password)
```

## Description

`Simulink.ModelReference.ProtectedModel.setPasswordForView(model,password)` adds an encryption password for read-only view if you create a protected model. If you use a protected model, the function provides the required password for a read-only view of the model.

## Examples

### Create a Protected Model with Encryption

Create a protected model with encryption for read-only view.

```
openExample('sldemo_mdhref_counter');
Simulink.ModelReference.ProtectedModel.setPasswordForView(...
'sldemo_mdhref_counter','password');
Simulink.ModelReference.protect('sldemo_mdhref_counter',...
'Webview',true,'Encrypt',true,'Report',true);
```

A protected model named `sldemo_mdhref_counter.slxp` is created that requires an encryption password for read-only view.

### View an Encrypted Protected Model

Use a protected model with encryption for read-only view.

Provide the encryption password required for the read-only view of the protected model.

```
openExample('sldemo_mdhref_counter');
Simulink.ModelReference.ProtectedModel.setPasswordForView(...
'sldemo_mdhref_counter','password');
```

After you have provided the encryption password, you have access to the read-only view of the protected model.

## Input Arguments

**model** — Model name

string or character vector

Model name, specified as a string or character vector. It contains the name of a model or the path name of a Model block that references the protected model.

**password — Password for read-only view of protected model**

string or character vector

Password, specified as a string or character vector. If the protected model is encrypted for read-only view, the password is required.

## **Version History**

**Introduced in R2014b**

### **See Also**

`Simulink.ModelReference.protect` |  
`Simulink.ModelReference.ProtectedModel.setPasswordForCodeGeneration` |  
`Simulink.ModelReference.ProtectedModel.setPasswordForHDLCodeGeneration` |  
`Simulink.ModelReference.ProtectedModel.setPasswordForSimulation`

# Simulink.ProtectedModel.addTarget

Add code generation support for current target to protected model

## Syntax

```
Simulink.ProtectedModel.addTarget(model)
```

## Description

`Simulink.ProtectedModel.addTarget(model)` adds code generation support for the current `model` target to a protected model of the same name. Each target that the protected model supports is identified by the root of the **Code Generation > System Target file** (`SystemTargetFile`) parameter. For example, if the **System Target file** is `ert.tlc`, the target identifier is `ert`.

To add the current target:

- The model and the protected model of the same name must be on the MATLAB path.
- The protected model must have the `Modifiable` option enabled and have a password for modification.
- The target must be unique in the protected model.

If you add a target to a protected model that did not previously support code generation, the software switches the protected model `Mode` to `CodeGeneration` and `ObfuscateCode` to `true`.

## Examples

### Add a Target to a Protected Model

Add the currently configured model target to the protected model.

Load the model and save a local copy.

```
openExample('sldemo_mdhref_counter');
save_system('sldemo_mdhref_counter','mdhref_counter.slx');
```

Add a required password for modifying a protected model. If you do not add a password, you are prompted to set a password when you create a modifiable, protected model.

```
Simulink.ModelReference.ProtectedModel.setPasswordForModify(...
'mdhref_counter','password');
```

Create a modifiable, protected model with support for code generation.

```
Simulink.ModelReference.protect('mdhref_counter','Mode',...
'CodeGeneration','Modifiable',true,'Report',true);
```

Get a list of targets that the protected model supports.

```
st = Simulink.ProtectedModel.getSupportedTargets('mdhref_counter')
```

Configure the unprotected model to support a new target.

```
set_param('mdlref_counter', 'SystemTargetFile', 'ert.tlc');
save_system('mdlref_counter');
```

Add support to the protected model for the new target. You are prompted for the modification password.

```
Simulink.ProtectedModel.addTarget('mdlref_counter');
```

Verify that support for the new target has been added to the protected model.

```
st = Simulink.ProtectedModel.getSupportedTargets('mdlref_counter')
```

## Input Arguments

### **model** — Model name

string or character vector

Model name, specified as a string or character vector. It contains the name of a model or the path name of a Model block that references the protected model.

## Version History

**Introduced in R2015a**

### See Also

`Simulink.ModelReference.protect` | `Simulink.ProtectedModel.removeTarget` |  
`Simulink.ProtectedModel.getSupportedTargets` |  
`Simulink.ProtectedModel.getCurrentTarget` |  
`Simulink.ProtectedModel.setCurrentTarget` | `Simulink.ProtectedModel.getConfigSet`

### Topics

“Create Protected Models with Multiple Targets”



# Simulink.ProtectedModel.Callback

Callback code that executes in response to protected model events

## Description

For a specific protected model functionality, the `Simulink.ProtectedModel.Callback` object specifies code to execute in response to an event. The callback code can be a character vector of MATLAB commands or a MATLAB script.

When you create a protected model, to specify callbacks, call the `Simulink.ModelReference.protect` on page 3-369 function with the `'Callbacks'` option. The value of this option is a cell array of `Simulink.ProtectedModel.Callback` objects.

## Creation

### Syntax

```
Simulink.ProtectedModel.Callback(Event,AppliesTo,CallbackText)
Simulink.ProtectedModel.Callback(Event,AppliesTo,callbackFile)
```

### Description

`Simulink.ProtectedModel.Callback(Event,AppliesTo,CallbackText)` creates a callback object for a specific protected model functionality and event. The `CallbackText` specifies MATLAB commands to execute for the callback.

`Simulink.ProtectedModel.Callback(Event,AppliesTo,callbackFile)` creates a callback object for a specific protected model functionality and event. The `CallbackFileName` specifies a MATLAB script to execute for the callback. The script must be on the MATLAB path.

## Properties

### AppliesTo — Protected model functionality

'AUTO' (default) | 'CODEGEN' | 'SIM' | 'VIEW'

Protected model functionality that the event applies to, specified as one of these values:

- 'CODEGEN': Code generation.
- 'SIM': Simulation.
- 'VIEW': Read-only web view.
- 'AUTO': If the event is 'PreAccess', the callback executes for each functionality. If the event is 'Build', the callback executes for only 'CODEGEN' functionality.

Example: 'SIM'

### CallbackFileName — Callback script to execute

character vector | string scalar

MATLAB script to execute in response to an event, specified as a character vector or string scalar. The script must be on the MATLAB path.

Example: 'pmCallback.m'

### CallbackText — Callback code to execute

character vector | string scalar

MATLAB commands to execute in response to an event, specified as a character vector or string scalar.

Example: 'A = [15 150];disp(A)'

### Event — Event that triggers callback

'PreAccess' | 'Build'

Event that triggers the callback, specified as one of these options:

- 'PreAccess': Callback code is executed before simulation, build, or read-only viewing.
- 'Build': Callback code is executed before build. Valid for only 'CODEGEN' functionality.

Example: 'PreAccess'

### OverrideBuild — Option to override protected model build

false (default) | true

Option to override the protected model build process, specified as a Boolean value. The override option applies only to a callback object that you define for a 'Build' event for the 'CODEGEN' functionality. You set this option by using the `setOverrideBuild` method.

## Object Functions

`setOverrideBuild` Override protected model build

## Examples

### Create Protected Model by Using a Callback

- 1 Create the callback object.

```
pmCallback = Simulink.ProtectedModel.Callback('PreAccess', ...
 'SIM', 'disp(''Hello world!'')')
```

- 2 Protect the model `sldemo_mdhref_counter` and specify the callback object.

```
Simulink.ModelReference.protect('sldemo_mdhref_counter', ...
 'Callbacks', {pmCallback})
```

- 3 Simulate the model `sldemo_mdhref_basic`, which references the protected model that you created.

```
sim('sldemo_mdhref_basic')
```

For each instance of the protected model reference in the top model, the output is displayed.

```
Hello world!
Hello world!
Hello world!
```

### Create Protected Model That Uses a Callback Script

- 1 On the MATLAB path, create a callback script `pm_callback.m` that contains this code:

```
disp('Hello world!')
```

- 2 Create a callback object that uses the script for the callback code. Protect the model `sldemo_mdref_counter` and specify the callback object.

```
pmCallback = Simulink.ProtectedModel.Callback('Build',...
'CODEGEN','pm_callback.m')
Simulink.ModelReference.protect('sldemo_mdref_counter',...
'Mode','CodeGeneration','Callbacks',{pmCallback})
```

The callback script executes during the code generation phase of the model protection process.

- 3 Generate code for the model `sldemo_mdref_basic`, which references the protected model that you created.

```
slbuild('sldemo_mdref_basic')
```

During the code generation phase for the referenced protected model, code in `pm_callback.m` executes.

## Version History

Introduced in R2016a

### See Also

`Simulink.ModelReference.protect` | `Simulink.ProtectedModel.getCallbackInfo`

### Topics

“Define Callbacks for Protected Models”

“Protect Models to Conceal Contents”

“Code Generation Requirements and Limitations”

## setOverrideBuild

**Package:** Simulink.ProtectedModel

Override protected model build

### Syntax

```
setOverrideBuild(callback, override)
```

### Description

`setOverrideBuild(callback, override)` specifies whether a `Simulink.ProtectedModel.Callback` object can override the build process. This method is valid only for callbacks that execute in response to a 'Build' event for 'CODEGEN' functionality.

### Examples

#### Create Code Generation Callback to Override Build Process

- 1 Create a callback object that uses a character vector of MATLAB commands for the callback code. Define the callback for a 'Build' event for the 'CODEGEN' functionality.

```
pmCallback = Simulink.ProtectedModel.Callback('Build',...
'CODEGEN','disp('Hello world!')')
```

- 2 Specify that the callback override the build process.

```
setOverrideBuild(pmCallback, true);
```

- 3 Protect the model `sldemo_mdref_counter` and specify the callback that you created.

```
Simulink.ModelReference.protect('sldemo_mdref_counter',...
'Mode', 'CodeGeneration','Callbacks',{pmCallback})
```

- 4 Build the model `sldemo_mdref_basic`, which references the protected model `sldemo_mdref_counter`. When the top model begins to build the protected model, the callback that you created overrides the build process.

```
slbuild('sldemo_mdref_basic')
```

### Input Arguments

#### **callback** — Protected model callback

`Simulink.ProtectedModel.Callback` object

Protected model callback that you want to override the protected model build process, specified as a `Simulink.ProtectedModel.Callback`. The callback object must be defined for a 'Build' event for 'CODEGEN' functionality.

#### **override** — Option to override protected model build process

false (default) | true

Option to override the protected model build process, specified as a Boolean value. This option applies to only a callback object defined for a 'Build' event for the 'CODEGEN' functionality.

Example: `pmcallback.setOverrideBuild(true)`

## Version History

Introduced in R2016a

## See Also

`Simulink.ModelReference.protect` | `Simulink.ProtectedModel.Callback`

## Topics

“Define Callbacks for Protected Models”

“Protect Models to Conceal Contents”

“Code Generation Requirements and Limitations”

# Simulink.ProtectedModel.CallbackInfo

Protected model information for use in callbacks

## Description

A `Simulink.ProtectedModel.CallbackInfo` object contains information about a protected model that you can use in the code executed for a callback.

## Creation

### Syntax

```
Simulink.ProtectedModel.getCallbackInfo(ModelName,Event,Functionality)
```

### Description

`Simulink.ProtectedModel.getCallbackInfo(ModelName,Event,Functionality)` creates a `Simulink.ProtectedModel.CallbackInfo` object for the callback that applies to the protected model for the event and functionality that you specify.

## Properties

### CodeInterface — Code interface generated by protected model

'Top model' | 'Model reference'

Code interface that the protected model generates, specified as 'Top model' or 'Model reference'.

### Event — Event that triggered callback

'PreAccess' | 'Build'

Event that triggered the callback, specified as one of these values:

- 'PreAccess': Callback code executed before simulation, build, or read-only viewing.
- 'Build': Callback code executed before build. This option is valid only for the 'CODEGEN' functionality.

### Functionality — Protected model functionality

'AUTO' (default) | 'CODEGEN' | 'SIM' | 'VIEW'

Protected model functionality that the event applies to, specified as one of these values:

- 'CODEGEN': Code generation.
- 'SIM': Simulation.
- 'VIEW': Read-only web view.
- 'AUTO': If the event is 'PreAccess', the callback executes for each functionality. If the event is 'Build', the callback executes for only 'CODEGEN' functionality.

**ModelName — Protected model name**

character vector | string scalar

Protected model name, specified as a character vector or string scalar.

Example: 'myProtectedModel.slxp'

**SubModels — Models and submodels in the protected model container**

cell array of character vectors

Names of all models and submodels in the protected model container, specified as a cell array of character vectors.

**Target — Current target**

character vector

Current target identifier for the protected model, specified as a character vector. This property is available for only code generation callbacks.

Example: 'ert'

**Object Functions**

getBuildInfoForModel Build information object for specified model

**Examples****Use Protected Model Information in Simulation Callback**

- 1 On the MATLAB path, create a callback script `pm_callback.m` that contains this code:

```
s1 = 'Simulating protected model: ';
cbinfoobj = Simulink.ProtectedModel.getCallbackInfo(...
'sldemo_mdhref_counter','PreAccess','SIM');
disp([s1 cbinfoobj.ModelName])
```

The script uses the `Simulink.ProtectedModel.CallbackInfo` object to display the name of the protected model.

- 2 Create a callback object that uses the script for the callback code. Protect the model `sldemo_mdhref_counter` and specify the callback object.

```
pmCallback = Simulink.ProtectedModel.Callback('PreAccess'...
,'SIM', 'pm_callback.m')
Simulink.ModelReference.protect('sldemo_mdhref_counter',...
'Callbacks',{pmCallback})
```

- 3 Simulate the protected model. When each instance of the protected model reference in the top model is simulated, the output from the callback is listed.

```
sim('sldemo_mdhref_basic')

Simulating protected model: sldemo_mdhref_counter
Simulating protected model: sldemo_mdhref_counter
Simulating protected model: sldemo_mdhref_counter
```

## **Version History**

**Introduced in R2016a**

### **See Also**

`Simulink.ModelReference.protect` | `Simulink.ProtectedModel.getCallbackInfo`

### **Topics**

“Define Callbacks for Protected Models”

“Protect Models to Conceal Contents”

“Code Generation Requirements and Limitations”



# Simulink.ProtectedModel.getCallbackInfo

Get Simulink.ProtectedModel.CallbackInfo object for use by callbacks

## Syntax

```
cbinfoobj = Simulink.ProtectedModel.getCallbackInfo(modelName,event,
functionality)
```

## Description

cbinfoobj = Simulink.ProtectedModel.getCallbackInfo(modelName,event,functionality) returns a Simulink.ProtectedModel.CallbackInfo object that provides information for protected model callbacks. The object contains information about the protected model, including:

- Model name.
- List of models and submodels in the protected model container.
- Callback event.
- Callback functionality.
- Code interface.
- Current target. This information is available only for code generation callbacks.

## Examples

### Use Protected Model Information in Code Generation Callback

On the MATLAB path, create a callback script, pm\_callback.m, containing:

```
s1 = 'Code interface is: ';
cbinfoobj = Simulink.ProtectedModel.getCallbackInfo(...
'sldemo_mdref_counter','Build','CODEGEN');
disp([s1 cbinfoobj.CodeInterface]);
```

When you create a protected model with a simulation callback, use the script.

```
pmCallback = Simulink.ProtectedModel.Callback('Build',...
'CODEGEN','pm_callback.m')
Simulink.ModelReference.protect('sldemo_mdref_counter',...
'Mode','CodeGeneration','Callbacks',{pmCallback})
```

Build the protected model. Before the start of the protected model build process, the code interface is displayed.

```
slbuild('sldemo_mdref_basic')
```

## Input Arguments

**modelName** — Protected model name  
string or character vector

Protected model name, specified as a string or character vector.

**event – Event that triggered callback**

'PreAccess' | 'Build'

Callback trigger event. Value is one of the following:

- 'PreAccess': Callback code executed before simulation, build, or read-only viewing.
- 'Build': Callback code executed before build. Valid only for 'CODEGEN' functionality.

**functionality – Protected model functionality**

'CODEGEN' | 'SIM' | 'VIEW' | 'AUTO'

Protected model functionality that the event applies to. Value is one of the following:

- 'CODEGEN': Code generation.
- 'SIM': Simulation.
- 'VIEW': Read-only Web view.
- 'AUTO': If the event is 'PreAccess', the callback executes for each functionality. If the event is 'Build', the callback executes only for 'CODEGEN' functionality.

If the value of `functionality` is blank, the default behavior is 'AUTO'.

## Output Arguments

**cbinfoobj – Callback information object**

`Simulink.ProtectedModel.CallbackInfo`

Callback information, specified as a `Simulink.ProtectedModel.CallbackInfo` object.

## Version History

**Introduced in R2016a**

### See Also

`Simulink.ModelReference.protect` | `Simulink.ProtectedModel.CallbackInfo`

### Topics

“Define Callbacks for Protected Models”

“Protect Models to Conceal Contents”

“Code Generation Requirements and Limitations”

# getBuildInfoForModel

**Package:** Simulink.ProtectedModel

Build information object for specified model

## Syntax

```
bldobj = getBuildInfoForModel(callbackInfo, model)
```

## Description

`bldobj = getBuildInfoForModel(callbackInfo, model)` returns the `RTW.BuildInfo` object that specifies the build toolchain and arguments for the model. The `model` name must be in the list of model names in the `SubModels` property of the `Simulink.ProtectedModel.CallbackInfo` object. You can call this method for only code generation callbacks in response to a 'Build' event.

## Examples

### Get Build Information from a Code Generation Callback

- 1 On the MATLAB path, create a callback script, `pm_callback.m`, that contains this code:

```
cbinfoobj = Simulink.ProtectedModel.getCallbackInfo(...
 'sldemo_mdldref_counter', 'Build', 'CODEGEN');
bldinfo = cbinfoobj.getBuildInfoForModel(cbinfoobj.ModelName);
buildargs = getBuildArgs(bldinfo)
```

- 2 Create a callback object that uses the script.

```
pmCallback = Simulink.ProtectedModel.Callback('Build',...
 'CODEGEN', 'pm_callback.m')
Simulink.ModelReference.protect('sldemo_mdldref_counter',...
 'Mode', 'CodeGeneration', 'Callbacks', {pmCallback})
```

- 3 Build the protected model. Before the start of the protected model build, the build arguments are displayed.

```
slbuild('sldemo_mdldref_basic')
```

## Input Arguments

### `callbackInfo` — Callback information object

`Simulink.ProtectedModel.CallbackInfo` object

Callback information object, specified as a `Simulink.ProtectedModel.CallbackInfo` object. The callback object must be defined for a 'Build' event for the 'CODEGEN' functionality.

### `model` — Model name

string or character vector

Model name, specified as a string or character vector. The `model` name must be in the list of model names in the `SubModels` property of the `Simulink.ProtectedModel.CallbackInfo` object.

## Output Arguments

### **blldobj** — Build toolchain and arguments

RTW.BuildInfo object

Build toolchain and arguments, returned as a RTW.BuildInfo object.

## Version History

Introduced in R2016a

### See Also

`Simulink.ModelReference.protect` | `Simulink.ProtectedModel.CallbackInfo`

### Topics

“Define Callbacks for Protected Models”

“Protect Models to Conceal Contents”

“Code Generation Requirements and Limitations”

# Simulink.ProtectedModel.getConfigSet

Get configuration set for current protected model target or for specified target

## Syntax

```
configSet = Simulink.ProtectedModel.getConfigSet(protectedModel)
configSet = Simulink.ProtectedModel.getConfigSet(protectedModel,targetID)
```

## Description

`configSet = Simulink.ProtectedModel.getConfigSet(protectedModel)` returns the configuration set object for the current, protected model target.

`configSet = Simulink.ProtectedModel.getConfigSet(protectedModel,targetID)` returns the configuration set object for a specified target that the protected model supports.

## Examples

### Get Configuration Set for Current Target

Get the configuration set for the currently configured, protected model target.

Load the model and save a local copy.

```
openExample('sldemo_mdref_counter');
save_system('sldemo_mdref_counter','mdref_counter.slx');
```

Add a required password for modifying a protected model. If you do not add a password, you are prompted to set a password when you create a modifiable, protected model.

```
Simulink.ModelReference.ProtectedModel.setPasswordForModify(...
'mdref_counter','password');
```

Create a modifiable, protected model with support for code generation.

```
Simulink.ModelReference.protect('mdref_counter','Mode',...
'CodeGeneration','Modifiable',true,'Report',true);
```

Get the configuration set for the currently configured target.

```
cs = Simulink.ProtectedModel.getConfigSet('mdref_counter')
```

### Get Configuration Set for Specified Target

Get the configuration set for a specified target that the protected model supports.

Load the model and save a local copy.

```
openExample('sldemo_mdref_counter');
save_system('sldemo_mdref_counter','mdref_counter.slx');
```

Add a required password for modifying a protected model. If you do not add a password, you are prompted to set a password when you create a modifiable, protected model.

```
Simulink.ModelReference.ProtectedModel.setPasswordForModify(...
'mdlref_counter', 'password');
```

Create a modifiable, protected model with support for code generation.

```
Simulink.ModelReference.protect('mdlref_counter', 'Mode', ...
'CodeGeneration', 'Modifiable', true, 'Report', true);
```

Configure the unprotected model to support a new target.

```
set_param('mdlref_counter', 'SystemTargetFile', 'ert.tlc');
save_system('mdlref_counter');
```

Add support to the protected model for the new target. You are prompted for the modification password.

```
Simulink.ProtectedModel.addTarget('mdlref_counter');
```

Verify that support for the new target has been added to the protected model.

```
st = Simulink.ProtectedModel.getSupportedTargets('mdlref_counter')
```

Get the configuration set for the added target.

```
cs = Simulink.ProtectedModel.getConfigSet('mdlref_counter', 'ert')
```

## Input Arguments

### **protectedModel** — Model name

string or character vector

Protected model name, specified as a string or character vector.

### **targetID** — Target identifier

string or character vector

Identifier for selected target, specified as a string or character vector. The target identifier is the root of the **Code Generation > System Target file** (SystemTargetFile) parameter. For example, if the **System Target file** is `ert.tlc`, the target identifier is `ert`.

## Output Arguments

### **configSet** — Configuration object

Simulink.ConfigSet

Configuration set, specified as a Simulink.ConfigSet object

## Version History

Introduced in R2015a

**See Also**

Simulink.ModelReference.protect | Simulink.ProtectedModel.addTarget |  
Simulink.ProtectedModel.removeTarget |  
Simulink.ProtectedModel.getSupportedTargets |  
Simulink.ProtectedModel.getCurrentTarget |  
Simulink.ProtectedModel.setCurrentTarget

**Topics**

“Create Protected Models with Multiple Targets”  
“Reference Protected Models from Third Parties”

## Simulink.ProtectedModel.getCurrentTarget

Get current protected model target

### Syntax

```
currentTarget = Simulink.ProtectedModel.getCurrentTarget(protectedModel)
```

### Description

`currentTarget = Simulink.ProtectedModel.getCurrentTarget(protectedModel)` returns the target identifier for the target that is currently configured for the protected model. At the start of a MATLAB session, the default current target is the last target added to the protected model. Otherwise, the current target is the last target that you used. You can change the current target using the `Simulink.ProtectedModel.setCurrentTarget` function.

When building the model, the software changes the target to match the parent if the currently selected target does not match the target of the parent model.

### Examples

#### Get Currently Configured Target for Protected Model

Add a target to a protected model, and then get the currently configured target for the protected model.

Load the model and save a local copy.

```
openExample('sldemo_mdhref_counter');
save_system('sldemo_mdhref_counter','mdhref_counter.slx');
```

Add a required password for modifying a protected model. If you do not add a password, you are prompted to set a password when you create a modifiable, protected model.

```
Simulink.ModelReference.ProtectedModel.setPasswordForModify(...
'mdhref_counter','password');
```

Create a modifiable, protected model with support for code generation.

```
Simulink.ModelReference.protect('mdhref_counter','Mode',...
'CodeGeneration','Modifiable',true,'Report',true);
```

Configure the unprotected model to support a new target.

```
set_param('mdhref_counter','SystemTargetFile','ert.tlc');
save_system('mdhref_counter');
```

Add support to the protected model for the new target. You are prompted for the modification password.

```
Simulink.ProtectedModel.addTarget('mdhref_counter');
```



Verify that support for the new target has been added to the protected model.

```
st = Simulink.ProtectedModel.getSupportedTargets('mdlref_counter')
```

Get the currently configured target for the protected model.

```
ct = Simulink.ProtectedModel.getCurrentTarget('mdlref_counter')
```

## Input Arguments

### **protectedModel** — Model name

string or character vector

Protected model name, specified as a string or character vector.

## Output Arguments

### **currentTarget** — Current target

character vector

Current target for protected model, specified as a character vector.

## Version History

Introduced in R2015a

## See Also

`Simulink.ModelReference.protect` | `Simulink.ProtectedModel.addTarget` |  
`Simulink.ProtectedModel.removeTarget` |  
`Simulink.ProtectedModel.getSupportedTargets` |  
`Simulink.ProtectedModel.setCurrentTarget` | `Simulink.ProtectedModel.getConfigSet`

## Topics

“Create Protected Models with Multiple Targets”  
“Reference Protected Models from Third Parties”

## Simulink.ProtectedModel.getSupportedTargets

Get list of targets that protected model supports

### Syntax

```
supportedTargets = Simulink.ProtectedModel.getSupportedTargets(
protectedModel)
```

### Description

`supportedTargets = Simulink.ProtectedModel.getSupportedTargets(protectedModel)` returns a list of target identifiers for the code generation targets supported by the specified protected model. The target identifier `sim` represents simulation support.

### Examples

#### Get List of Supported Targets for a Protected Model

Add a target to a protected model, and then get a list of supported targets to verify the addition of the new target.

Load the model and save a local copy.

```
openExample('sldemo_mdref_counter');
save_system('sldemo_mdref_counter','mdref_counter.slx');
```

Add a required password for modifying a protected model. If you do not add a password, you are prompted to set a password when you create a modifiable, protected model.

```
Simulink.ModelReference.ProtectedModel.setPasswordForModify(...
'mdref_counter','password');
```

Create a modifiable, protected model with support for code generation.

```
Simulink.ModelReference.protect('mdref_counter','Mode',...
'CodeGeneration','Modifiable',true,'Report',true);
```

Configure the unprotected model to support a new target.

```
set_param('mdref_counter','SystemTargetFile','ert.tlc');
save_system('mdref_counter');
```

Add support to the protected model for the new target. You are prompted for the modification password.

```
Simulink.ProtectedModel.addTarget('mdref_counter');
```

Verify that support for the new target has been added to the protected model.

```
st = Simulink.ProtectedModel.getSupportedTargets('mdlref_counter')
```

## Input Arguments

### **protectedModel** — Model name

string or character vector

Protected model name, specified as a string or character vector.

## Output Arguments

### **supportedTargets** — List of target identifiers

cell array of character vectors

List of target identifiers for the targets that the protected model supports, specified as a cell array of character vectors.

## Version History

**Introduced in R2015a**

## See Also

Simulink.ModelReference.protect | Simulink.ProtectedModel.addTarget |  
Simulink.ProtectedModel.removeTarget | Simulink.ProtectedModel.getCurrentTarget  
| Simulink.ProtectedModel.setCurrentTarget |  
Simulink.ProtectedModel.getConfigSet

## Topics

“Create Protected Models with Multiple Targets”

“Reference Protected Models from Third Parties”

## Simulink.ProtectedModel.open

Open protected model

### Syntax

```
Simulink.ProtectedModel.open(model)
Simulink.ProtectedModel.open(model,type)
```

### Description

`Simulink.ProtectedModel.open(model)` opens a protected model. If you do not specify how to view the protected model, the software first tries to open the Web view. If the Web view is not enabled for the protected model, the software then tries to open the report. If you did not create a report, the software reports an error.

`Simulink.ProtectedModel.open(model,type)` opens a protected model using the specified viewing method. If you specify 'webview', the software opens the Web view for the protected model. If you specify 'report', the software opens the protected model report. If the method that you specify is not enabled, the software reports an error. The protected model is not opened.

### Examples

#### Open a Protected Model

Open a protected model without a specified method.

Load the model and save a local copy.

```
openExample('sldemo_mdhref_counter');
save_system('sldemo_mdhref_counter','mdhref_counter.slx');
```

Create a protected model enabling support for code generation and reporting.

```
Simulink.ModelReference.protect('mdhref_counter','Mode',...
'CodeGeneration','Report',true);
```

Open the protected model without specifying how to view it.

```
Simulink.ProtectedModel.open('mdhref_counter')
```

The protected model does not have Web view enabled, so the protected model report is opened.

#### Open a Protected Model Web View

Open a protected model, specifying the Web view.

Load the model and save a local copy.

```
openExample('sldemo_mdhref_counter');
save_system('sldemo_mdhref_counter','mdhref_counter.slx');
```

Create a protected model with support for code generation, Web view, and reporting.

```
Simulink.ModelReference.protect('mdhref_counter','Mode',...
'CodeGeneration','Webview',true,'Report',true);
```

Open the protected model and specify that you want to see the Web view.

```
Simulink.ProtectedModel.open('mdhref_counter','webview')
```

The protected model Web view is opened.

## Input Arguments

### **model** — Model name

string or character vector

Protected model name, specified as a string or character vector.

### **type** — Open method

'webview' | 'report'

Method for viewing the protected model. If you specify 'webview', the software opens the Web view for the protected model. If you specify 'report', the software opens the protected model report.

## Version History

Introduced in R2015a

## See Also

Simulink.ModelReference.protect

## Simulink.ProtectedModel.removeTarget

Remove support for specified target from protected model

### Syntax

```
Simulink.ProtectedModel.removeTarget(protectedModel,targetID)
```

### Description

`Simulink.ProtectedModel.removeTarget(protectedModel,targetID)` removes code generation support for the specified target from a protected model. You must provide the modification password to make this update. Removing a target does not require access to the unprotected model.

---

**Note** You cannot remove the `sim` target. If you do not want the protected model to support simulation, use the `Simulink.ModelReference.modifyProtectedModel` function to change the protected model mode to `ViewOnly`.

---

### Examples

#### Remove Target Support from a Protected Model

Remove a supported target from a protected model.

Load the model and save a local copy.

```
openExample('sldemo_mdhref_counter');
save_system('sldemo_mdhref_counter','mdhref_counter.slx');
```

Add a required password for modifying a protected model. If you do not add a password, you are prompted to set a password when you create a modifiable, protected model.

```
Simulink.ModelReference.ProtectedModel.setPasswordForModify(...
'mdhref_counter','password');
```

Create a modifiable, protected model with support for code generation.

```
Simulink.ModelReference.protect('mdhref_counter','Mode',...
'CodeGeneration','Modifiable',true,'Report',true);
```

Configure the unprotected model to support a new target.

```
set_param('mdhref_counter','SystemTargetFile','ert.tlc');
save_system('mdhref_counter');
```

Add support to the protected model for the new target. You are prompted for the modification password.

```
Simulink.ProtectedModel.addTarget('mdhref_counter');
```

Verify that support for the new target has been added to the protected model.

```
st = Simulink.ProtectedModel.getSupportedTargets('mdlref_counter')
```

Remove support for the ert target from the protected model. You are prompted for the modification password.

```
Simulink.ProtectedModel.removeTarget('mdlref_counter','ert');
```

Verify that support for the ert target has been removed from the protected model.

```
st = Simulink.ProtectedModel.getSupportedTargets('mdlref_counter')
```

## Input Arguments

### **protectedModel** — Model name

string or character vector

Protected model name, specified as a string or character vector.

### **targetID** — Target to be removed

string or character vector

Identifier for target to be removed, specified as a string or character vector.

## Version History

**Introduced in R2015a**

### See Also

[Simulink.ModelReference.protect](#) | [Simulink.ModelReference.modifyProtectedModel](#) | [Simulink.ProtectedModel.addTarget](#) | [Simulink.ProtectedModel.getSupportedTargets](#) | [Simulink.ProtectedModel.getCurrentTarget](#) | [Simulink.ProtectedModel.setCurrentTarget](#) | [Simulink.ProtectedModel.getConfigSet](#)

### Topics

“Create Protected Models with Multiple Targets”

## Simulink.ProtectedModel.setCurrentTarget

Configure protected model to use specified target

### Syntax

```
Simulink.ProtectedModel.setCurrentTarget(protectedModel, targetID)
```

### Description

`Simulink.ProtectedModel.setCurrentTarget(protectedModel, targetID)` configures the protected model to use the target that the target identifier specifies.

---

**Note** If you include the protected model in a model reference hierarchy, the software tries to change the current target to match the target of the parent model. If the software cannot match the target of the parent, it reports an error.

---

### Examples

#### Set Current Target for Protected Model

After you get a list of supported targets, set the current target for a protected model.

Load the model and save a local copy.

```
openExample('sldemo_mdhref_counter');
save_system('sldemo_mdhref_counter','mdhref_counter.slx');
```

Add a required password for modifying a protected model. If you do not add a password, you are prompted to set a password when you create a modifiable, protected model.

```
Simulink.ModelReference.ProtectedModel.setPasswordForModify(...
'mdhref_counter','password');
```

Create a modifiable, protected model with support for code generation.

```
Simulink.ModelReference.protect('mdhref_counter','Mode',...
'CodeGeneration','Modifiable',true,'Report',true);
```

Get a list of targets that the protected model supports.

```
st = Simulink.ProtectedModel.getSupportedTargets('mdhref_counter')
```

Configure the unprotected model to support a new target.

```
set_param('mdhref_counter','SystemTargetFile','ert.tlc');
save_system('mdhref_counter');
```

Add support to the protected model for the new target. You are prompted for the modification password.



```
Simulink.ProtectedModel.addTarget('mdlref_counter');
```

Verify that support for the new target has been added to the protected model.

```
st = Simulink.ProtectedModel.getSupportedTargets('mdlref_counter')
```

Configure the protected model to use the new target.

```
Simulink.ProtectedModel.setCurrentTarget('mdlref_counter','ert');
```

Verify that the current target is the new target.

```
ct = Simulink.ProtectedModel.getCurrentTarget('mdlref_counter')
```

## Input Arguments

### **protectedModel** — Model name

string or character vector

Protected model name, specified as a string or character vector.

### **targetID** — Target identifier

string or character vector

Identifier for selected target, specified as a string or character vector.

## Version History

**Introduced in R2015a**

## See Also

[Simulink.ModelReference.protect](#) | [Simulink.ProtectedModel.addTarget](#) |  
[Simulink.ProtectedModel.removeTarget](#) |  
[Simulink.ProtectedModel.getSupportedTargets](#) |  
[Simulink.ProtectedModel.getCurrentTarget](#) | [Simulink.ProtectedModel.getConfigSet](#)

## Topics

“Create Protected Models with Multiple Targets”

“Reference Protected Models from Third Parties”

## Simulink.ProtectedModel.sign

Attach digital signature to protected model

### Syntax

```
Simulink.ProtectedModel.sign(protectedModel,certificateFile)
```

### Description

`Simulink.ProtectedModel.sign(protectedModel,certificateFile)` attaches a digital signature with the certificate `certificateFile` to the protected model `protectedModel`.

### Examples

#### Sign a Protected Model

Protect a model, and then digitally sign it with a certificate.

Open and protect the model that you want to sign. For this example, protect the model `sldemo_mdhref_counter`.

```
openExample('sldemo_mdhref_counter');
Simulink.ModelReference.protect('sldemo_mdhref_counter');
```

Locate the certificate file that you want to use to sign the protected model. Sign the model by using the certificate file.

```
Simulink.ProtectedModel.sign('sldemo_mdhref_counter.slxp','certificate_file.pfx');
```

In the dialog box, enter the password for the certificate file.

### Input Arguments

#### **protectedModel** — Name of protected model

character vector | string scalar

Name of the protected model that you want to sign, specified as a character vector or string scalar. The protected model has a `.slxp` extension.

Example: `'my_model.slxp'`

#### **certificateFile** — Certificate file to use for signing

character vector | string scalar

Certificate file to use for signing the protected model, specified as a character vector or string scalar. The certificate must be a PKCS #12 file with the extension `.pfx` or `.p12`.

Example: `'my_cert.pfx'`

Example: `'InstitutionCertificate.p12'`

## **Version History**

**Introduced in R2020a**

### **See Also**

`Simulink.ModelReference.protect`

### **Topics**

“Sign a Protected Model”

## slConfigUIGetVal

Return current value for any model configuration parameter

### Syntax

```
value = slConfigUIGetVal(hDlg,hSrc,'OptionName')
```

### Description

`value = slConfigUIGetVal(hDlg,hSrc,'OptionName')` returns the value currently set in the dialog for any model configuration parameter.

The `slConfigUIGetVal` function is used in the context of a user-written `SelectCallback` function, which is triggered when you:

- Change System Target Files.
- Build the model.

### Examples

#### Get Configuration Option Value

The `slConfigUIGetVal` function returns the value of the **Configuration Parameters > Code Generation > Interface > Advanced parameters > Terminate function required** option.

```
function usertarget_selectcallback(hDlg,hSrc)

 disp(['*** Select callback triggered:',sprintf('\n'), ...
 ' Uncheck and disable "Terminate function required".']);

 disp(['Value of IncludeMdlTerminateFcn was ', ...
 slConfigUIGetVal(hDlg,hSrc,'IncludeMdlTerminateFcn')]);

 slConfigUISetVal(hDlg,hSrc,'IncludeMdlTerminateFcn','off');
 slConfigUISetEnabled(hDlg,hSrc,'IncludeMdlTerminateFcn',false);
 hSrc.refreshDialog;
```

### Input Arguments

#### hDlg — handle for STF callback functions

handle

Handle created in the context of a `SelectCallback` function and used by the System Target File Callback Interface functions. Pass this variable but do not set it or use it for another purpose.

Example: `hDlg`

#### hSrc — handle for STF callback functions

handle

Handle created in the context of a `SelectCallback` function and used by the System Target File Callback Interface functions. Pass this variable and use it to refresh the Configuration Parameters dialog box. Do not set it or use it for another purpose.

Example: `hSrc`

### **OptionName — TLC variable**

TLC variable

Quoted name of the TLC variable defined for a custom target configuration option.

Example: `'myTLCvariable'`

## **Output Arguments**

### **value — Option value**

option value

Current value of the specified option. The data type of the return value depends on the data type of the option.

## **Version History**

**Introduced in R2006b**

### **See Also**

`slConfigUISetEnabled` | `slConfigUISetVal`

### **Topics**

“Define and Display Custom Target Options”

“Custom Target Optional Features”

## slConfigUISetEnabled

Enable or disable any model configuration parameter

### Syntax

```
slConfigUISetEnabled(hDlg,hSrc,'OptionName',value)
```

### Description

`slConfigUISetEnabled(hDlg,hSrc,'OptionName',value)` is used in the context of a user-written `SelectCallback` function, which is triggered when the custom target is selected in the System Target File Browser in the Configuration Parameters dialog box. You use `slConfigUISetEnabled` to enable or disable a specified model configuration parameter. To refresh the Configuration Parameters dialog, use `hSrc.refreshDialog`.

### Examples

#### Disable Model Configuration Option

The `slConfigUISetEnabled` function disables the **Configuration Parameters > Code Generation > Interface > Advanced parameters > Terminate function required** option.

```
function usertarget_selectcallback(hDlg,hSrc)

 disp(['** Select callback triggered:',sprintf('\n'), ...
 ' Uncheck and disable "Terminate function required".']);

 disp(['Value of IncludeMdlTerminateFcn was ', ...
 slConfigUIGetVal(hDlg,hSrc,'IncludeMdlTerminateFcn')]);

 slConfigUISetVal(hDlg,hSrc,'IncludeMdlTerminateFcn','off');
 slConfigUISetEnabled(hDlg,hSrc,'IncludeMdlTerminateFcn',false);
 hSrc.refreshDialog;
```

### Input Arguments

#### hDlg — Handle for STF callback

handle

Handle created in the context of a `SelectCallback` function and used by the System Target File Callback Interface functions. Pass this variable but do not set it or use it for another purpose.

Example: `hDlg`

#### hSrc — Handle for STF callback

handle

Handle created in the context of a `SelectCallback` function and used by the System Target File Callback Interface functions. Pass this variable and use it to refresh the Configuration Parameters dialog box. Do not set it or use it for another purpose.

Example: hSrc

**'OptionName', value — TLC variable name and set enable**  
false | true

Quoted name and set enable of the TLC variable defined for a model configuration parameter.

Example: 'myConfigVariable', false

## **Version History**

**Introduced in R2006b**

### **See Also**

slConfigUIGetVal | slConfigUISetVal

### **Topics**

“Define and Display Custom Target Options”

“Custom Target Optional Features”

## slConfigUISetVal

Set value for any model configuration parameter

### Syntax

```
slConfigUISetVal(hDlg,hSrc,'OptionName',value)
```

### Description

`slConfigUISetVal(hDlg,hSrc,'OptionName',value)` is used in the context of a user-written `SelectCallback` function, which is triggered when the custom target is selected in the System Target File Browser in the Configuration Parameters dialog box. You use `slConfigUISetVal` to set the value of a specified target option.

### Examples

#### Set Configuration Option Value

The `slConfigUISetVal` function sets the value 'off' for the **Configuration Parameters > Code Generation > Interface > Advanced parameters > Terminate function required** option.

```
function usertarget_selectcallback(hDlg,hSrc)

 disp(['*** Select callback triggered:',sprintf('\n'), ...
 ' Uncheck and disable "Terminate function required".']);

 disp(['Value of IncludeMdlTerminateFcn was ', ...
 slConfigUIGetVal(hDlg,hSrc,'IncludeMdlTerminateFcn')]);

 slConfigUISetVal(hDlg,hSrc,'IncludeMdlTerminateFcn','off');
 slConfigUISetEnabled(hDlg,hSrc,'IncludeMdlTerminateFcn',false);
 hSrc.refreshDialog;
```

### Input Arguments

#### hDlg — Handle for STF callback

handle

Handle created in the context of a `SelectCallback` function and used by the System Target File Callback Interface functions. Pass this variable but do not set it or use it for another purpose.

Example: `hDlg`

#### hSrc — Handle for STF callback

handle

Handle created in the context of a `SelectCallback` function and used by the System Target File Callback Interface functions. Pass this variable and use it to refresh the Configuration Parameters dialog box. Do not set it or use it for another purpose.



Example: hSrc

**'OptionName', value — TLC variable name and value**

option value

Quoted name and value of the TLC variable defined for a model configuration parameter.

Example: 'myConfigVariable',1

## **Version History**

**Introduced in R2006b**

### **See Also**

slConfigUIGetVal | slConfigUISetEnabled

### **Topics**

“Define and Display Custom Target Options”

“Custom Target Optional Features”

## switchTarget

Select target for model configuration set

### Syntax

```
switchTarget(myConfigObj,systemTargetFile,[])
switchTarget(myConfigObj,systemTargetFile,targetOptions)
```

### Description

`switchTarget(myConfigObj,systemTargetFile,[])` changes the selected system target file for the active configuration set.

`switchTarget(myConfigObj,systemTargetFile,targetOptions)` sets the configuration parameters specified by `targetOptions`.

### Examples

#### Get ConfigSet, Default Options, and Switch Target

This example shows how to get the active configuration set for `model`, and change the system target file for the configuration set.

```
% Get configuration set for model
myConfigObj = getActiveConfigSet(model);
% Switch system target file
switchTarget(myConfigObj,'ert.tlc',[]);
```

#### Get ConfigSet, Set Options, Switch Target

This example shows how to get the active configuration set for the current model (`gcs`), set various `targetOptions`, then change the system target file selection.

```
% Get configuration set for current model
myConfigObj=getActiveConfigSet(gcs);

% Specify target options
targetOptions.TLCOptions = '-aVarName=1';
targetOptions.MakeCommand = 'make_rtw';
targetOptions.Description = 'my target';
targetOptions.TemplateMakefile = 'grt_default_tmf';

% Define a system target file
targetSystemFile='grt.tlc';

% Switch system target file
switchTarget(myConfigObj,targetSystemFile,targetOptions);
```

Use `targetOptions` to verify values (optional).

```
% Verify values (optional)
targetOptions

 TLCOptions: '-aVarName=1'
 MakeCommand: 'make_rtw'
 Description: 'my target'
 TemplateMakefile: 'grt_default_tmf'
```

### Get ConfigSet, Set Options for MSVC Solution Build, Switch Target to MSVC ERT

This example shows how to get the active configuration set for model, then change the system target file to the ERT Create Visual C/C++ Solution File for Embedded Coder.

```
model='rtwdemo_rtwintr0';
open_system(model);

% Get configuration set for model
myConfigObj = getActiveConfigSet(model);

% Specify target options for MSVC build
targetOptions.MakeCommand = 'make_rtw';
targetOptions.Description = ...
 'Create Visual C/C++ Solution File for Embedded Coder';
targetOptions.TemplateMakefile = 'RTW.MSVCCBuild';

% Switch system target file
switchTarget(myConfigObj,'ert.tlc',targetOptions);
```

### Get ConfigSet, Set Options for Toolchain Build, and Switch Target

Use options to select default ERT target file, instead of set\_param(model,'SystemTargetFile','ert.tlc').

```
% use switchTarget to select toolchain build of default ERT target
model='rtwdemo_rtwintr0';
open_system(model);

% Get configuration set for model
myConfigObj = getActiveConfigSet(model);

% Specify target options for toolchain build approach
targetOptions.MakeCommand = '';
targetOptions.Description = 'Embedded Coder';
targetOptions.TemplateMakefile = '';

% Switch system target file
switchTarget(myConfigObj,'ert.tlc',targetOptions);
```

## Input Arguments

**myConfigObj** — Configuration set object  
*object*

A configuration set object of `ConfigSet` or configuration reference object of `Simulink.ConfigSetRef`. Call `getActiveConfigSet` to get the configuration set object.

Example: `myConfigObj = getActiveConfigSet(model);`

**systemTargetFile — Name of system target file**

character vector

Specify the name of the system target file (such as `ert.tlc` for Embedded Coder or `grt.tlc` for Simulink Coder) as the name appears in the **System Target File Browser**.

Example: `systemTargetFile = 'ert.tlc';`

**targetOptions — Structure with field values that provide configuration parameter options**

struct

Structure with fields that define a code generation target options. You can choose to modify certain configuration parameters by filling in values in a structure field. If you do not want to use options, specify an empty structure (`[]`).

**Field Values in targetOptions**

Specify the structure field values of the `targetOptions`. If you choose not to specify options, use an empty structure (`[]`).

Example: `targetOptions = [];`

**TemplateMakefile — Character vector specifying file name of template makefile**

character vector

Example: `targetOptions.TemplateMakefile = 'RTW.MSVCBuild';`

**TLCOptions — Character vector specifying TLC argument**

character vector

Example: `targetOptions.TLCOptions = '-aVarName=1';`

**MakeCommand — Character vector specifying make command MATLAB language file**

character vector

Example: `targetOptions.MakeCommand = 'make_rtw';`

**Description — Character vector specifying description of the system target file**

character vector

Example: `targetOptions.Description = 'Create Visual C/C++ Solution File for Embedded Coder';`

## Version History

**Introduced in R2009b**

### See Also

`getActiveConfigSet` | `ConfigSet` | `Simulink.ConfigSetRef`

### Topics

“Select a System Target File Programmatically”

“Configure a System Target File”  
“Set Target Language Compiler Options”

## target Package

Manage target hardware and build tool information

### Description

Use these classes to manage target hardware and build tool information. For example, register new target hardware for code generation, set up target connectivity for external mode and processor-in-the-loop (PIL) simulations, or create custom CMake toolchain definitions for building generated code on your development computer.

### Classes

|                                   |                                                                                         |
|-----------------------------------|-----------------------------------------------------------------------------------------|
| target.AddOn                      | Describe add-on properties for target type                                              |
| target.Alias                      | Create alternative identifier for target object                                         |
| target.API                        | Describe API details                                                                    |
| target.APIImplementation          | Describe API implementation details                                                     |
| target.ApplicationExecutionTool   | Capture system command information to run application from MATLAB computer              |
| target.ApplicationStatus          | Describe status of application on target hardware                                       |
| target.Board                      | Provide hardware board details                                                          |
| target.Breakpoint                 | Provide breakpoint details for debugger                                                 |
| target.CMake                      | Specify CMake installation for building generated code                                  |
| target.CMakeBuildType             | Describe CMake build type or build configuration                                        |
| target.CMakeBuilder               | Configure how CMake builds generated code                                               |
| target.CMakeCacheEntry            | Configure a CMake cache entry                                                           |
| target.Command                    | Capture system command for execution on MATLAB computer                                 |
| target.BuildDependencies          | Describe C and C++ build dependencies to associate with target hardware                 |
| target.CommunicationChannel       | Describe communication channel properties                                               |
| target.CommunicationInterface     | Describe data I/O details for target hardware                                           |
| target.CommunicationProtocolStack | Describe communication protocol parameters                                              |
| target.Connection                 | Base class for target connection properties                                             |
| target.ConnectionProperties       | Describe target-specific connection properties                                          |
| target.DebugIOTool                | Debug byte stream I/O tool service interface                                            |
| target.EnvironmentConfiguration   | Configure system environment for toolchain                                              |
| target.ExecutionService           | Describe implementation of execution service for target application                     |
| target.ExecutionTool              | MATLAB service interface for tool that manages application execution on target hardware |
| target.ExternalMode               | Represent external mode protocol stack                                                  |
| target.ExternalModeConnectivity   | Base class for external mode connectivity options                                       |
| target.FloatingPointDataType      | Describe floating point data type implemented by compiler for target hardware           |
| target.Function                   | Provide function signature information                                                  |
| target.HardwareComponentSupport   | Describe support for a hardware component                                               |
| target.HostProcessExecutionTool   | Capture system command information to run target application from MATLAB computer       |

|                                    |                                                                                   |
|------------------------------------|-----------------------------------------------------------------------------------|
| target.LanguageImplementation      | Provide C and C++ compiler implementation details                                 |
| target.MainFunction                | Provide C and C++ dependencies for main function of target hardware application   |
| target.MATLABDependencies          | Describe MATLAB class and function dependencies                                   |
| target.Object                      | Base class for target types                                                       |
| target.PILProtocol                 | Describe PIL protocol implementation for target hardware                          |
| target.Port                        | Describe connection via target hardware port                                      |
| target.PortConnection              | Describe target connection port                                                   |
| target.Processor                   | Provide target processor information                                              |
| target.ProfilingFreezingOverhead   | Capture freezing and unfreezing instrumentation overhead                          |
| target.ProfilingFunctionOverhead   | Capture function instrumentation overhead                                         |
| target.ProfilingTaskOverhead       | Capture task instrumentation overhead                                             |
| target.RS232Channel                | Describe serial communication channel                                             |
| target.SystemCommandExecutionTool  | Capture system command information to run target application from MATLAB computer |
| target.TargetConnection            | Provide details about connecting MATLAB computer to target hardware               |
| target.TCPChannel                  | Describe TCP communication properties                                             |
| target.Timer                       | Provide timer details for processor                                               |
| target.Tools                       | Describe properties of tools for target hardware                                  |
| target.Toolchain                   | Capture high-level information about toolchain                                    |
| target.UDPChannel                  | Describe UDP communication                                                        |
| target.XCP                         | Describe XCP protocol stack for target hardware                                   |
| target.XCPExternalModeConnectivity | Represent connectivity options in external mode protocol stack                    |
| target.XCPPlatformAbstraction      | Specify XCP platform abstraction layer for target hardware                        |
| target.XCPTCPIPTransport           | Represent XCP TCP/IP transport protocol layer                                     |
| target.XCPTransport                | Base class for XCP transport protocol layer                                       |
| target.XCPSerialTransport          | Represent XCP serial transport protocol layer                                     |

## Functions

|                |                                                  |
|----------------|--------------------------------------------------|
| target.add     | Add target object to internal database           |
| target.create  | Create target object                             |
| target.export  | Export target object data                        |
| target.get     | Retrieve target objects from internal database   |
| target.remove  | Remove target object from internal database      |
| target.upgrade | Upgrade existing definitions of hardware devices |

## Version History

Introduced in R2019a

## See Also

### Topics

“Register New Hardware Devices”

“Customise Connectivity for XCP External Mode Simulations”

“Create Custom CMake Toolchain Definition”

## target.add

**Package:** target

Add target object to internal database

### Syntax

```
objectsAdded = target.add(targetObject)
objectsAdded = target.add(targetObject, Name, Value)
```

### Description

`objectsAdded = target.add(targetObject)` adds the specified target object to an internal database and returns a vector that contains the added objects. By default, the target data is available only for the current MATLAB session.

`objectsAdded = target.add(targetObject, Name, Value)` uses name-value arguments to controls persistence over MATLAB sessions and command-line output.

### Examples

#### Specify Hardware Implementation

To specify a hardware implementation that persists over MATLAB sessions, use the `target.create` and `target.add` functions.

```
myLangImp = target.create('LanguageImplementation', ...
 'Name', 'MyLanguageImplementation', ...
 'Copy', 'ARM Compatible-ARM Cortex');

myProc = target.create('Processor', 'Name', 'MyProcessor');
myProc.LanguageImplementations = myLangImp;
objectsAdded = target.add(myProc, ...
 'UserInstall', true, ...
 'SuppressOutput', true);
```

### Input Arguments

#### targetObject — Target object

object

Specify the target object that you want to add to the internal database.

Example: `target.add(myTargetObject)`;

#### Name-Value Pair Arguments

Specify optional pairs of arguments as `Name1=Value1, ..., NameN=ValueN`, where `Name` is the argument name and `Value` is the corresponding value. Name-value arguments must appear after other arguments, but the order of the pairs does not matter.



*Before R2021a, use commas to separate each name and value, and enclose Name in quotes.*

Example: `target.add(myTargetObject, 'UserInstall', true);`

### **UserInstall — Target data persistence**

false (default) | true

Control persistence of target data in an internal database:

- `true` -- Target data persists in internal database over multiple MATLAB sessions.
- `false` -- Target data is in internal database only for the current MATLAB session.

Example: `target.add(myTargetObject, 'UserInstall', true);`

Data Types: `logical`

### **SuppressOutput — Control command-line output**

false (default) | true

Control command-line output of function:

- `true` -- Suppress command-line output from the function.
- `false` -- Provide information about the objects that the function adds to internal database.

Example: `target.add(myTargetObject, 'SuppressOutput', true);`

Data Types: `logical`

## **Output Arguments**

### **objectsAdded — Objects added**

object vector

Target objects that the function adds to internal database.

## **Version History**

**Introduced in R2019a**

### **See Also**

`target.create` | `target.get` | `target.remove`

### **Topics**

“Register New Hardware Devices”

## target.AddOn class

**Package:** target

Describe add-on properties for target type

### Description

Use the `target.AddOn` class to capture custom properties that you can associate with these types of objects:

- `target.CommunicationChannel`
- `target.CommunicationProtocolStack`
- `target.Board`
- `target.Processor`
- `target.ConnectionProperties`

To extend the objects, assign the `target.AddOn` object to the `AddOns` property.

To create a `target.AddOn` object, use the `target.create` function.

### Properties

#### Name — Add-on object name

character vector | string

Name of the reusable add-on object.

Example: `arduinoAddOn.Name = 'ArduinoBoardProperties';`

#### Attributes:

|                        |                     |
|------------------------|---------------------|
| <code>GetAccess</code> | <code>public</code> |
| <code>SetAccess</code> | <code>public</code> |

### Methods

#### Public Methods

`addProperty` Add a custom property to `target.AddOn` object

### Examples

#### Part Number and Programmer for Arduino Board Definition

Add device-specific properties to a `target.Board` definition. Add information about the Arduino<sup>®</sup> part number and programmer to an Arduino board definition.

Create a board for Arduino Mega 2560.

```
mega = target.create('Board', ...
 'Manufacturer', 'Arduino', ...
 'Name', 'Mega 2560');
```

Create a `target.AddOn` object that specifies the Arduino board part number and programmer.

```
arduinoAddOn = target.create('AddOn');
arduinoAddOn.Name = 'ArduinoBoardProperties';
arduinoAddOn.addProperty('ArduinoPartNumber', 'String');
arduinoAddOn.addProperty('ArduinoProgrammer', 'String');
mega.AddOns = arduinoAddOn;
```

Specify the part number and programmer values.

```
mega.set('ArduinoPartNumber', 'm2560');
mega.set('ArduinoProgrammer', 'wiring');
```

You can parameterize the `avrdude` command for the deployment of an Arduino application.

```
command= target.create('Command');
command.String = 'avrdude';
command.Arguments = {'-p$(BOARD.Processor.ArduinoPartNumber)' ...
 '-c$(PROCESSOR.ArduinoProgrammer)' ...
 '-Uflash:w:$(EXE):i'};
mega.Tools.DeployTools(1).Commands = [command];
```

## Version History

Introduced in R2020b

### See Also

`target.create`

# addProperty

**Class:** target.AddOn

**Package:** target

Add a custom property to target.AddOn object

## Syntax

```
myAddOn.addProperty(propertyName, propertyType)
```

## Description

`myAddOn.addProperty(propertyName, propertyType)` adds the property `propertyName` of type `propertyType` to the object `myAddOn`.

## Input Arguments

### **propertyName** — Property name

character vector | string

Name of property that you want to add to object.

Example: `exampleAddOn.addProperty('myPrptyName', 'myPrptyType')`

### **propertyType** — Property type

double | string | object

Type of property that you want to add to object.

Example: `exampleAddOn.addProperty('myPrptyName', 'myPrptyType')`

## Examples

### **Add Property to target.AddOn Object**

For workflow examples that use this method, see “Examples” on page 3-0 .

## Version History

**Introduced in R2020b**

## See Also

target.AddOn

# target.Alias class

**Package:** target

Create alternative identifier for target object

## Description

Use the `target.Alias` class to create alternative identifiers for target objects. For example, if a target object has a long class identifier, you can create a `target.Alias` object that provides a short identifier for the target object.

To create a `target.Alias` object, use the `target.create` function.

## Properties

### Name — Alternative identifier

character vector | string

Alternative identifier for target object.

#### Attributes:

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

### For — Target object

object

Original target object.

#### Attributes:

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

## Examples

### Create Short Identifier for Target Object

For an example that uses this class, see “Create Alternative Identifier for Target Object”.

## Version History

Introduced in R2019a

## See Also

`target.create`

**Topics**

“Register New Hardware Devices”

# target.API class

**Package:** target

Describe API details

## Description

An API defines a set of entry-point functions for interaction with a software application or service. Use a `target.API` object to provide API details for target definition. Use this class with `target.APIImplementation` to describe how an API is used and built on target hardware.

To create a `target.API` object, use the `target.create` function.

## Properties

### Name — API name

character vector | string

Name of the API.

Example: `timerApi.Name = 'Linux Timer API';`

#### Attributes:

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

### Language — API language

`target.Language` object

Programming language of the API implementation.

#### Attributes:

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

### Functions — API Functions

`target.Function` object vector

Vector of `target.Function` objects that describe the set of entry-point functions that make up the API.

#### Attributes:

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

## Examples

### Describe rtiostream C API

This example provides implementation details for the `rtiostream C` API.

```
apiImp = target.create('APIImplementation', 'Name', ...
 'x86_rtiostream_Implementation');
apiImp.API = target.create('API', 'Name', 'rtiostream');
apiImp.BuildDependencies = target.create('BuildDependencies');
apiImp.BuildDependencies.SourceFiles = ...
 {fullfile('${MATLAB_ROOT}', 'toolbox', ...
 'coder', 'rtiostream', 'src', ...
 'rtiostreamtcpip', 'rtiostream_tcpip.c')});
apiImp.MainFunction = target.create('MainFunction', ...
 'Name', 'TCP RtIOStream Main');
apiImp.MainFunction.Arguments = {'-blocking', '1', '-port', '0'};
```

## Version History

Introduced in R2020b

### See Also

[target.create](#) | [target.APIImplementation](#) | [target.Function](#) | [target.LanguageImplementation](#)



# target.APIImplementation class

**Package:** target

Describe API implementation details

## Description

An API defines a set of entry-point functions for interaction with a software application or service. Use a `target.APIImplementation` object to provide details about how an API is used and built on target hardware.

To create a `target.APIImplementation` object, use the `target.create` function.

## Properties

### Name — API implementation name

character vector | string

Name of the `APIImplementation` object, which `target.get` uses as an identifier in data retrieval.

#### Attributes:

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

### API — API description

`target.API` object

Description of the API implementation definition.

#### Attributes:

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

### BuildDependencies — API implementation dependencies

`target.Dependencies` object

Source files, header files, and other dependencies that are needed for building and running the API on the target hardware.

#### Attributes:

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

### MainFunction — main function requirements for API implementation

`target.MainFunction` object

Capture run-time dependencies such as main function arguments, initialization code, and main function build dependencies.

**Attributes:**

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

**Examples****Describe rtiostream C API**

This example provides implementation details for the `rtiostream` C API.

```
apiImp = target.create('APIImplementation', 'Name', ...
 'x86 rtiostream Implementation');
apiImp.API = target.create('API', 'Name', 'rtiostream');
apiImp.BuildDependencies = target.create('BuildDependencies');
apiImp.BuildDependencies.SourceFiles = ...
 {fullfile('${MATLAB_ROOT}', 'toolbox', ...
 'coder', 'rtiostream', 'src', ...
 'rtiostreamtcpip', 'rtiostream_tcpip.c')};
apiImp.MainFunction = target.create('MainFunction', ...
 'Name', 'TCP RtIOStream Main');
apiImp.MainFunction.Arguments = {'-blocking', '1', '-port', '0'};
```

**Version History**

Introduced in R2020b

**See Also**

`target.create` | `target.API` | `target.BuildDependencies` | `target.MainFunction`

# target.ApplicationExecutionTool class

**Package:** target

Capture system command information to run application from MATLAB computer

## Description

Use the `target.ApplicationExecutionTool` class to capture system command information that is required to run an application from your development computer.

## Class Attributes

|                  |      |
|------------------|------|
| Abstract         | true |
| HandleCompatible | true |

For information on class attributes, see “Class Attributes”.

## Properties

### Name — Execution tool name

character vector | string

Name of the execution tool.

#### Attributes:

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

### Id — Object identifier

character vector | string

Value of the Name property.

#### Attributes:

|           |         |
|-----------|---------|
| GetAccess | public  |
| SetAccess | private |

## Version History

Introduced in R2020b

## See Also

`target.create` | `target.Command` | `target.HostProcessExecutionTool` | `target.SystemCommandExecutionTool`

## Topics

“Set Up PIL Connectivity by Using target Package” (Embedded Coder)

## target.ApplicationStatus class

**Package:** target

Describe status of application on target hardware

### Description

Use the `target.ApplicationStatus` enumeration class to describe the status of your target application. The enumeration class contains these members.

| Member  | Application Status                         |
|---------|--------------------------------------------|
| Running | Application running on target hardware     |
| Stopped | Application not running on target hardware |
| Unknown | Not known                                  |

### Creation

`target.ApplicationStatus.MemberName` creates an object of the enumeration class.

### Examples

#### PIL Target Connectivity with Debugger

For an example that uses the `target.ApplicationStatus` class, see “Use Debugger for PIL Target Connectivity” (Embedded Coder).

### Version History

**Introduced in R2021a**

### See Also

`target.ExecutionTool`

### Topics

“Define Enumeration Classes”

# target.Board class

**Package:** target

Provide hardware board details

## Description

Use a `target.Board` object to provide MATLAB with data about your target hardware board, for example, CPU, communication, and tool information.

To create a `target.Board` object, use the `target.create` function.

## Properties

### Name — Board name

character vector | string

Name of the `target.Board` object, which `target.get` uses as an identifier in data retrieval.

#### Attributes:

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

### Processors — Available processors

`target.Processor` object array

Array of `target.Processor` objects that provide descriptions of available processors for the board.

#### Attributes:

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

### CommunicationInterfaces — Available communication interfaces

`target.CommunicationInterfaces` object array

Array of `target.CommunicationInterface` objects that provide descriptions of available communication interfaces for the board.

#### Attributes:

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

### CommunicationProtocolStacks — Available communication protocols supported by board

`target.CommunicationProtocolStack` object array

Array of `target.CommunicationProtocolStack` that provide descriptions of the communication protocols for the board.

**Attributes:**

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

**Tools — Tooling for interaction with board**

`target.Tools` object

Collection of tooling descriptions associated with the board. For example, `ApplicationExecutionTool` to enable execution of applications on the target hardware.

**Attributes:**

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

**Examples****Create Board Description**

Create a description of a target hardware board. This code from “Set Up PIL Connectivity by Using target Package” (Embedded Coder) shows how to create the description.

Create a board object that provides MATLAB with a description of processor attributes.

```
hostTarget = target.create('Board', 'Name', 'Host Intel processor');
```

Specify the processor for the board, for example, by reusing a supported processor.

```
hostTarget.Processors = target.get('Processor', ...
 'Intel-x86-64 (Linux 64)');
```

**Create Communication Interface for Target Hardware**

Create a communication interface for the target hardware board. This code snippet from “Set Up PIL Connectivity by Using target Package” (Embedded Coder) shows how to create the interface.

```
comms = target.create('CommunicationInterface');

comms.Name = 'Linux TCP Interface';
comms.Channel = 'TCPChannel';
comms.APIImplementations = target.create('APIImplementation', ...
 'Name', 'x86 RTIOStream Implementation');
comms.APIImplementations.API = target.create('API', 'Name', 'RTIO Stream');

...

hostTarget.CommunicationInterfaces = comms;
```

**Specify PIL Protocol Information**

Specify PIL protocol information. This code snippet from “Set Up PIL Connectivity by Using target Package” (Embedded Coder) shows how to specify the information.

```
pilProtocol = target.create('PILProtocol');
pilProtocol.Name = 'Linux PIL Protocol';
pilProtocol.SendBufferSize = 50000;
```

```
pilProtocol.ReceiveBufferSize = 50000;
hostTarget.CommunicationProtocolStacks = pilProtocol;
```

## **Version History**

**Introduced in R2020b**

### **See Also**

`target.create` | `target.Processor`

### **Topics**

“Set Up PIL Connectivity by Using target Package” (Embedded Coder)

## target.Breakpoint class

**Package:** target

Provide breakpoint details for debugger

### Description

Use the `target.Breakpoint` class to provide breakpoint details for a debugger.

To create a `target.Breakpoint` object, use the `target.create` function.

### Properties

#### Function — Breakpoint function

string

Function that contains the breakpoint.

##### Attributes:

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

#### File — Breakpoint file

string

Path to the file that contains the breakpoint.

##### Attributes:

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

#### Line — Breakpoint line number

scalar

Line number of the breakpoint.

##### Attributes:

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

Data Types: `int32`

### Examples

#### PIL Target Connectivity with Debugger

For an example that uses the `target.Breakpoint` class, see “Use Debugger for PIL Target Connectivity” (Embedded Coder).



## **Version History**

**Introduced in R2021a**

### **See Also**

`target.create` | `target.DebugIOTool`

### **Topics**

“Use Debugger for PIL Target Connectivity” (Embedded Coder)

## target.BuildDependencies class

**Package:** target

Describe C and C++ build dependencies to associate with target hardware

### Description

Use the `target.BuildDependencies` object to:

- Describe C and C++ build dependencies, for example, source files and include paths.
- Associate the dependencies with your target hardware.

For example, you can use a `target.BuildDependencies` object to describe the build dependencies for a `target.APIImplementation` object.

### Properties

#### SourceFiles — Source file dependencies

cell array of character vectors | string array

Specify path to source files.

##### Attributes:

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

#### IncludeFiles — Include file dependencies

cell array of character vectors | string array

Include file dependencies.

##### Attributes:

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

#### IncludePaths — Header file include path dependencies

cell array of character vectors | string array

Header file include path dependencies.

##### Attributes:

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

#### Defines — Macro definition dependencies

cell array of character vectors | string array

Macro definition dependencies.

**Attributes:**

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

**StaticLibraries – Static library dependencies**

cell array of character vectors | string array

Static library dependencies.

**Attributes:**

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

**SharedLibraries – Shared library dependencies**

cell array of character vectors | string array

Shared library dependencies.

**Attributes:**

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

**Examples****Describe Implementation Build Dependencies for rtiostream C API**

This example shows how you can describe the implementation build dependencies for the `rtiostream` C API.

```
apiImp = target.create('APIImplementation', 'Name', ...
 'x86 rtiostream Implementation');
apiImp .API = target.create('API', 'Name', 'rtiostream');
apiImp .BuildDependencies = target.create('BuildDependencies');
apiImp .BuildDependencies.SourceFiles = ...
 {fullfile('${MATLAB_ROOT}', 'toolbox', ...
 'coder', 'rtiostream','src', ...
 'rtiostreamtcpip', 'rtiostream_tcpip.c')};
apiImp.MainFunction = target.create('MainFunction', ...
 'Name', 'TCP RtIOStream Main');
apiImp.MainFunction.Arguments = {'-blocking', '1', '-port', '0'};
```

**Version History**

Introduced in R2020b

**See Also**

target.create | target.APIImplementation

## target.CMake class

**Package:** target

Specify CMake installation for building generated code

### Description

Use a `target.CMake` object when you want to define a toolchain that uses a specific CMake installation instead of the version that ships with the software.

To create a `target.CMake` object, use the `target.create` function.

### Properties

#### Version — CMake version

string

Optional. Version of the CMake tool.

#### Attributes:

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

#### Command — Path to CMake executable file

`target.Command` object

An object that describes the full path to the CMake executable file.

#### Attributes:

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

#### HostOperatingSystemSupport — Platforms supported

`target.HostOperatingSystemSupport` object

An object that gives the platforms that the CMake installation can run on.

#### Attributes:

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

#### SupportedHardware — Target devices

`target.HardwareComponentSupport` object array

Optional. An object that gives the target devices that the CMake installation can build code for. If the property is empty, it is treated as a wildcard.

**Attributes:**

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

**Name — CMake tool name**

string

A unique name for your CMake tool installation.

Example: 'CMake with Third-Party Customizations'

**Attributes:**

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

**Examples****Use target.CMake to Specify CMake Installation**

This code snippet shows how you can use the `Tools` property of the `target.Toolchain` object and a `target.CMake` object to specify your CMake installation.

```
tc = target.create('Toolchain', 'Name', 'CMake/Ninja for all hosts');
tc.Builder = target.create('CMakeBuilder');
tc.Builder.Generator = 'Ninja';
tc.Builder.CommandLineCacheEntries(end+1) = ...
 target.create('CMakeCacheEntry', 'Name', 'CMAKE_C_COMPILER', 'Value', 'gcc');
tc.Builder.CommandLineCacheEntries(end+1) = ...
 target.create('CMakeCacheEntry', 'Name', 'CMAKE_CXX_COMPILER', 'Value', 'g++');
```

```
tc.Tools = target.create('CMake', 'Name', 'My CMake')
tc.Tools(1).Command.String = 'C:\pathToMyCMakeInstallation\cmake.exe'
```

**Version History**

Introduced in R2022b

**See Also**

[target.Toolchain](#) | [target.CMakeBuildType](#) | [target.CMakeBuilder](#) | [target.CMakeCacheEntry](#) | [target.EnvironmentConfiguration](#) | [target.HardwareComponentSupport](#) | [target.create](#)

**Topics**

“Create Custom CMake Toolchain Definition”

## target.CMakeCacheEntry class

**Package:** target

Configure a CMake cache entry

### Description

Use a `target.CMakeCacheEntry` object to define a CMake cache entry for the CMake tool. The software adds the cache entry to the command that invokes CMake, using one of these forms:

- `-D Name:Type=Value`
- `-D Name=Value`

`Name`, `Type`, and `Value` are object properties.

To create a `target.CMakeCacheEntry` object, use the `target.create` function.

### Properties

#### Name — Cache entry name

string

Name of the CMake cache entry.

If the string value has spaces, for example, `name With Spaces`, the software passes to the CMake tool the value with double quotes, that is, `"name With Spaces"`.

#### Attributes:

|                        |                     |
|------------------------|---------------------|
| <code>GetAccess</code> | <code>public</code> |
| <code>SetAccess</code> | <code>public</code> |

#### Type — Cache entry type

string

Optional. Type of the CMake cache entry.

If the string value has spaces, for example, `name With Spaces`, the software passes to the CMake tool the value with double quotes, that is, `"name With Spaces"`.

#### Attributes:

|                        |                     |
|------------------------|---------------------|
| <code>GetAccess</code> | <code>public</code> |
| <code>SetAccess</code> | <code>public</code> |

#### Value — Cache entry value

string

Value of the CMake cache entry.

If the string value has spaces, for example, `name With Spaces`, the software passes to the CMake tool the value with double quotes, that is, `"name With Spaces"`.

**Attributes:**

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

**Examples****Define CMake Cache Entries for CMake Tool**

This code snippet shows how you can use the `target.CMakeCacheEntry` object to define CMake cache entries for the CMake tool.

```
tc = target.create('Toolchain', 'Name', 'CMake/Ninja for all hosts');
tc.Builder = target.create('CMakeBuilder');
tc.Builder.Generator = 'Ninja';
tc.Builder.CommandLineCacheEntries(end+1) = ...
 target.create('CMakeCacheEntry', 'Name', 'CMAKE_C_COMPILER', 'Value', 'gcc');
tc.Builder.CommandLineCacheEntries(end+1) = ...
 target.create('CMakeCacheEntry', 'Name', 'CMAKE_CXX_COMPILER', 'Value', 'g++');
```

**Version History**

**Introduced in R2022b**

**See Also**

`target.Toolchain` | `target.CMake` | `target.CMakeBuildType` | `target.CMakeBuilder` |  
`target.EnvironmentConfiguration` | `target.HardwareComponentSupport` |  
`target.create`

**Topics**

“Create Custom CMake Toolchain Definition”

## target.CMakeBuilder class

**Package:** target

Configure how CMake builds generated code

### Description

Use a `target.CMakeBuilder` object to configure how CMake builds generated code.

To create a `target.CMakeBuilder` object, use the `target.create` function.

### Properties

#### CommandLineCacheEntries — Cache entries

`target.CMakeCacheEntry` object array

Optional. Array of additional CMake cache entries to pass to the CMake tool as part of the command line invocation. The software expands the entries in this form:

```
cmake -D name:type=value ...
```

#### Attributes:

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

#### Generator — CMake generator

string

Generator that CMake must use, that is, the *generator* value for the command `cmake -G generator`.

If the string value has no spaces, for example, `nameWithNoSpaces`, the software passes this command to the CMake tool:

```
cmake -G nameWithNoSpaces
```

If the string value has spaces, for example, `name With Spaces`, the software passes this command to the CMake tool:

```
cmake -G "name With Spaces"
```

#### Attributes:

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

#### GeneratorIsMultiConfig — Multi-configuration generator

true | false

Whether generator is multi-configuration:



- `true` -- CMake generator supports multiple configurations.
- `false` -- CMake generator supports single configuration

**Attributes:**

```
GetAccess public
SetAccess public
```

Data Types: `logical`

**PlatformName — Platform name**

`string`

Optional. Platform name for the generator, that is, the *platformName* value for the command `cmake -A platformName`.

If the string value has no spaces, for example, `nameWithNoSpaces`, the software passes this command to the CMake tool:

```
cmake -A nameWithNoSpaces
```

If the string value has spaces, for example, `name With Spaces`, the software passes this command to the CMake tool:

```
cmake -A "name With Spaces"
```

**Attributes:**

```
GetAccess public
SetAccess public
```

**SupportedBuildTypes — Supported build types**

`target.CMakeBuildType` object array

Build types or build configurations supported by generator and toolchain file.

The property is prepopulated with definitions of build types and build configurations that are available by default. If the `Generator` property is set to `Ninja Multi-Config`, the build type `MinSizeRel`, is not supported by default. Unless you define `MinSizeRel` in a toolchain file, you must remove it from the object array. This code snippet shows how you can remove `MinSizeRel`.

```
tc = target.create('Toolchain', 'Name', 'CMake/Ninja Multi-Config');
tc.Builder = target.create('CMakeBuilder');
tc.Builder.Generator = 'Ninja Multi-Config';
tc.Builder.GeneratorIsMultiConfig = true;
tc.Builder.CommandLineCacheEntries(end+1) = ...
 target.create('CMakeCacheEntry', 'Name', 'CMAKE_C_COMPILER', 'Value', 'gcc');
tc.Builder.CommandLineCacheEntries(end+1) = ...
 target.create('CMakeCacheEntry', 'Name', 'CMAKE_CXX_COMPILER', 'Value', 'g++');
tc.Builder.SupportedBuildTypes(strcmp({tc.Builder.SupportedBuildTypes}, 'MinSizeRel')) = [];
```

**Attributes:**

```
GetAccess public
SetAccess public
```

**ToolchainFile — Path to toolchain file**

`string`

Optional. Path to a CMake toolchain file, that is, the *toolChain* value for the command `cmake -D CMAKE_TOOLCHAIN_FILE=toolChain`.

If the string value has no spaces, for example, `nameWithNoSpaces`, the software passes this command to the CMake tool:

```
cmake -D CMAKE_TOOLCHAIN_FILE=nameWithNoSpaces
```

If the string value has spaces, for example, `name With Spaces`, the software passes this command to the CMake tool:

```
cmake -D CMAKE_TOOLCHAIN_FILE="name With Spaces"
```

**Attributes:**

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

**ToolsetSpecification — Tool set specification**

string

Optional. Tool set specification for generator, that is, the *toolSet* value for the command `cmake -T toolSet`.

If the string value has no spaces, for example, `nameWithNoSpaces`, the software passes this command to the CMake tool:

```
cmake -T nameWithNoSpaces
```

If the string value has spaces, for example, `name With Spaces`, the software passes this command to the CMake tool:

```
cmake -T "name With Spaces"
```

**Attributes:**

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

## Examples

### Use `target.CMakeBuilder` to Configure CMake Build

This code snippet from “Create Custom CMake Toolchain Definition” shows how you can use the `Builder` property of the `target.Toolchain` object and a `target.CMakeBuilder` object to configure how CMake builds generated code.

```
tc = target.create('Toolchain', 'Name', 'Example Custom CMake Toolchain');
tc.Builder = target.create('CMakeBuilder');
tc.Builder.Generator = 'Ninja';
tc.Builder.ToolchainFile = fullfile(pwd, 'ExampleCMakeToolchain.cmake');
tc.Builder.SupportedBuildTypes(end+1) = ...
 target.create('CMakeBuildType', ...
 'Name', 'FastMath', ...
 'GeneratesDebugSymbols', false, ...
 'DebugBuildType', 'FastMathWithDebug');
tc.Builder.SupportedBuildTypes(end+1) = ...
 target.create('CMakeBuildType', ...
```

```
'Name', 'FastMathWithDebug', ...
'GeneratesDebugSymbols', true);
```

## Version History

Introduced in R2022b

### See Also

[target.Toolchain](#) | [target.CMake](#) | [target.CMakeBuildType](#) | [target.CMakeCacheEntry](#) | [target.EnvironmentConfiguration](#) | [target.HardwareComponentSupport](#) | [target.create](#)

### Topics

“Create Custom CMake Toolchain Definition”

## target.CMakeBuildType class

**Package:** target

Describe CMake build type or build configuration

### Description

Use a `target.CMakeBuildType` object to describe a CMake build type (for single configuration generators) or build configuration (for multi-configuration generators) that is supported by a given combination of generator and CMake toolchain file. When you select the associated toolchain for the **Toolchain** configuration parameter, the build type is available as a **Build Configuration** option.

To create a `target.CMakeBuildType` object, use the `target.create` function.

### Properties

#### Name — Build type name

string

Name of CMake build type. For example, `Debug`, `Release`, `RelWithDebInfo`, and `MinSizeRel`.

#### Attributes:

|                        |                     |
|------------------------|---------------------|
| <code>GetAccess</code> | <code>public</code> |
| <code>SetAccess</code> | <code>public</code> |

Data Types: `string`

#### GeneratesDebugSymbols — Debug symbol generation

`true` | `false`

Whether the build type supports generation of debug symbols:

- `true` -- Supports generation of debug symbols
- `false` -- Does not support generation of debug symbols

#### Attributes:

|                        |                     |
|------------------------|---------------------|
| <code>GetAccess</code> | <code>public</code> |
| <code>SetAccess</code> | <code>public</code> |

Data Types: `logical`

#### DebugBuildType — Substitute build type

string

Substitute CMake build type for debug workflow. When a workflow requires debug symbols but the current CMake build type does not support the generation of debug symbols, use the property to provide a substitute build type that supports a debug workflow.

**Attributes:**

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

**Examples****Specify CMake Build Type**

This code snippet from “Create Custom CMake Toolchain Definition” shows how you can use the SupportedBuildTypes property of a target.CMakeBuilder object and a target.CMakeBuildType object to specify CMake build types for a combination of generator and CMake toolchain file.

```
tc = target.create('Toolchain', 'Name', 'Example Custom CMake Toolchain');
tc.Builder = target.create('CMakeBuilder');
tc.Builder.Generator = 'Ninja';
tc.Builder.ToolchainFile = fullfile(pwd, 'ExampleCMakeToolchain.cmake');
tc.Builder.SupportedBuildTypes(end+1) = ...
 target.create('CMakeBuildType', ...
 'Name', 'FastMath', ...
 'GeneratesDebugSymbols', false, ...
 'DebugBuildType', 'FastMathWithDebug');
tc.Builder.SupportedBuildTypes(end+1) = ...
 target.create('CMakeBuildType', ...
 'Name', 'FastMathWithDebug', ...
 'GeneratesDebugSymbols', true);
```

**Version History**

Introduced in R2022b

**See Also**

target.Toolchain | target.CMake | target.CMakeBuilder | target.CMakeCacheEntry |  
target.EnvironmentConfiguration | target.HardwareComponentSupport |  
target.create

**Topics**

“Create Custom CMake Toolchain Definition”

## target.Command class

**Package:** target

Capture system command for execution on MATLAB computer

### Description

Use the `target.Command` class to capture a system command for execution on your development computer.

To create a `target.Command` object, use the `target.create` function. Create the object and then use separate steps to specify properties. Or, create the object and specify properties in a single step.

```
commandObject = target.create('Command', ...
 stringPropertyValue, ...
 argumentsPropertyValue)
```

### Properties

#### String — Command string

string

Name of the application or script to call.

##### Attributes:

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

#### Arguments — Application or script arguments

string array | cell array of character vectors

String array or cell array of character vectors where each element represents a separate argument to the application or script defined in the `String` property.

##### Attributes:

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

### Examples

#### Create target.Command Objects

Create this `target.Command` object by providing an application file path and arguments for the application.

```
cmdObj = target.create('Command');
cmdObj.String = 'pathToavrdude';
cmdObj.Arguments = {'-p$(BOARD.Processor.ArduinoPartNumber)' ...
 '-c$(PROCESSOR.ArduinoProgrammer)' ...
 '-Uflash:w:$(EXE):i'};
```

You can create the object in a single step.

```
cmdObj = target.create('Command', ...
 'pathToavrdude', ...
 {'-p$(BOARD.Processor.ArduinoPartNumber)' ...
 '-c$(PROCESSOR.ArduinoProgrammer)' ...
 '-Uflash:w:(EXE):i'});
```

You can also specify the command and arguments by using a string. For example, to create a `target.Command` object for the command `echo` with arguments `-a` and `-b`, run:

```
cmdObj = target.create('Command', 'echo -a -b');
```

## Version History

**Introduced in R2020b**

### See Also

`target.create` | `target.ApplicationExecutionTool` |  
`target.HostProcessExecutionTool` | `target.SystemCommandExecutionTool`

### Topics

“Set Up PIL Connectivity by Using target Package” (Embedded Coder)

## target.CommunicationChannel class

**Package:** target

Describe communication channel properties

### Description

Use a `target.CommunicationChannel` object to describe communication channel properties for an I/O connection between two systems. You can use the object as part of a `target.Connection` object. `target.RS232Channel`, `target.TCPChannel`, and `target.UDPChannel` are examples of predefined communication channels.

### Properties

**Name — target.CommunicationChannel object name**

character vector | string

Name of `target.CommunicationChannel` object.

**Attributes:**

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

### Examples

#### Create Connection by Using TCP Communication Channel

This code from “Set Up PIL Connectivity by Using target Package” (Embedded Coder) shows how to specify the connection between your development computer and target hardware. In the example, the target application runs on your development computer as a separate process and uses a TCP communication channel through `localhost`.

```
connection = target.create('TargetConnection');
connection.Name = 'Host Process Connection';
connection.Target = hostTarget;
connection.CommunicationChannel = target.create('TCPChannel');
connection.CommunicationChannel.Name = ...
 'External Process TCPCommunicationChannel';
connection.CommunicationChannel.IPAddress = 'localhost';
connection.CommunicationChannel.Port = '0';
```

---

**Note** Using name-value arguments, you can create the connection object with this command:

```
timer = target.create('TargetConnection', ...
 'Name', 'Host Process Connection', ...
 'CommunicationType', 'TCPChannel', ...
```



```
'IPAddress', 'localhost', ...
'Port', '0')
```

---

## Version History

Introduced in R2020b

## See Also

[target.create](#) | [target.RS232Channel](#) | [target.TCPChannel](#) | [target.UDPChannel](#)

## Topics

“Set Up PIL Connectivity by Using target Package” (Embedded Coder)

## target.CommunicationInterface class

**Package:** target

Describe data I/O details for target hardware

### Description

Use the `target.CommunicationInterface` class to describe data transfer for your target hardware. Associate the communication channel for data transfer and the device driver API implementation with a `target.CommunicationInterface` object.

### Properties

#### Name — target.CommunicationInterface object name

character vector | string

Name of `target.CommunicationInterface` object.

#### Attributes:

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

#### Channel — Communication channel

character vector | string

Type of communication channel that connects to the target hardware. For example, if you define PIL connectivity by using a `target.TargetConnection` over a `target.RS232Channel`, set this property to 'RS232Channel'.

#### Attributes:

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

#### APIImplementations — Device driver API implementations for communication interface

`target.APIImplementations` object array

Details of the API implementations that use the communication interface channel to support data transfer to and from the target hardware. For example, an `rtiostream` API implementation for PIL connectivity.

#### Attributes:

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

## Examples

### Communication Interface for Target Hardware

Create the communication interface for the target hardware. This code snippet from “Set Up PIL Connectivity by Using target Package” (Embedded Coder) shows how to create the interface.

```
comms = target.create('CommunicationInterface');
comms.Name = 'Linux TCP Interface';
comms.Channel = 'TCPChannel';
comms.APIImplementations = target.create('APIImplementation', ...
 'Name', 'x86_rtiostream_Implementation');
comms.APIImplementations.API = target.create('API', 'Name', 'rtiostream');
comms.APIImplementations.BuildDependencies = target.create('BuildDependencies');
comms.APIImplementations.BuildDependencies.SourceFiles = ...
 {fullfile('${MATLABROOT}', ...
 'toolbox', ...
 'coder', ...
 'rtiostream', ...
 'src', ...
 'rtiostreamtcpip', ...
 'rtiostream_tcpip.c')};
comms.APIImplementations.MainFunction = target.create('MainFunction', ...
 'Name', 'TCP RtIOStream Main');
comms.APIImplementations.MainFunction.Arguments = {'-blocking', '1', '-port', '0'};
hostTarget.CommunicationInterfaces = comms;
```

## Version History

Introduced in R2020b

### See Also

[target.create](#) | [target.CommunicationChannel](#) | [target.APIImplementation](#)

### Topics

“Set Up PIL Connectivity by Using target Package” (Embedded Coder)

## target.CommunicationProtocolStack class

**Package:** target

Describe communication protocol parameters

### Description

To describe target-specific parameters for different protocols, you can associate a `target.CommunicationProtocolStack` object with a `target.Board` object. One example of `target.CommunicationProtocolStack` is `target.PILProtocol`.

To create a `target.CommunicationProtocolStack` object, use the `target.create` function.

### Properties

#### Name — API name

character vector | string

Name of the API.

#### Attributes:

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

### Examples

#### Specify PIL Communication Protocol Object for target.Board

Specify PIL protocol information. This code snippet from “Set Up PIL Connectivity by Using target Package” (Embedded Coder) shows how to specify the information.

```

pilProtocol = target.create('PILProtocol');
pilProtocol.Name = 'Linux PIL Protocol';
pilProtocol.SendBufferSize = 50000;
pilProtocol.ReceiveBufferSize = 50000;
hostTarget.CommunicationProtocolStacks = pilProtocol;

```

### Version History

Introduced in R2020b

### See Also

`target.create` | `target.PILProtocol`

### Topics

“Set Up PIL Connectivity by Using target Package” (Embedded Coder)

# target.Connection class

**Package:** target

Base class for target connection properties

## Description

Capture target connection properties by using a class derived from `target.Connection`. For example, use the `target.TargetConnection` class to describe a target connection from the development computer, inheriting properties from the `target.Connection` class.

## Class Attributes

|                  |      |
|------------------|------|
| Abstract         | true |
| HandleCompatible | true |

For information on class attributes, see “Class Attributes”.

## Properties

### Name — Connection object

character vector | string

Name of the connection object.

#### Attributes:

|           |         |
|-----------|---------|
| GetAccess | public  |
| SetAccess | private |

### CommunicationChannel — Communication channel description

`target.CommunicationChannel` object

Use this property to associate the connection with a specific `target.CommunicationChannel` that is used to determine common connection properties between the connected systems. For example, `target.RS232Channel`.

#### Attributes:

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

## Version History

Introduced in R2020b

## See Also

`target.create` | `target.TargetConnection` | `target.CommunicationChannel`

**Topics**

“Set Up PIL Connectivity by Using target Package” (Embedded Coder)

# target.ConnectionProperties class

**Package:** target

Describe target-specific connection properties

## Description

Use a `target.ConnectionProperties` object to describe connection properties that are required for the target hardware to connect to another system. The class is used as a base class for specific connection properties such as `target.Port`. You can extend the class to provide custom properties by using the `target.AddOn` class.

## Properties

### AddOns — Custom property add-on objects

`target.AddOns` object array

To provide additional custom properties, associate one or more `target.AddOn` objects with the `target.ConnectionProperties` object.

### Attributes:

|                        |                     |
|------------------------|---------------------|
| <code>GetAccess</code> | <code>public</code> |
| <code>SetAccess</code> | <code>public</code> |

## Methods

### Public Methods

`get` Get name of custom add-on property  
`set` Set property value

## Version History

Introduced in R2020b

## See Also

`target.create`

## get

**Class:** target.ConnectionProperties

**Package:** target

Get name of custom add-on property

### Syntax

```
value = get(propertyName)
```

### Description

`value = get(propertyName)` returns the name of a custom add-on property or `target.ConnectionProperties` property.

### Input Arguments

**propertyName** — Property name

string

Name of a custom add-on property or `target.ConnectionProperties` class property.

### Output Arguments

**Value** — Property value

string

Property value that corresponds to the `propertyName`.

### Version History

**Introduced in R2020b**

### See Also

`target.ConnectionProperties`



# set

**Class:** target.ConnectionProperties

**Package:** target

Set property value

## Syntax

```
set(propertyName,propertyValue)
```

## Description

set(propertyName,propertyValue) sets the name of a custom add-on property or target.ConnectionProperties property to a specified value.

## Input Arguments

**propertyName — Property name**

string

Name of a custom add-on property or target.ConnectionProperties class property.

**propertyValue — Property value**

string

Value for propertyName.

## Version History

**Introduced in R2020b**

## See Also

target.ConnectionProperties

## target.create

**Package:** target

Create target object

### Syntax

```
targetObject = target.create(targetType)
targetObject = target.create(targetType,Name,Value)
```

### Description

`targetObject = target.create(targetType)` creates and returns an object of the specified class.

`targetObject = target.create(targetType,Name,Value)` configures the object using one or more name-value arguments.

---

**Note** You can create an object and specify properties in one step for these classes:

- `target.Command`
  - `target.Connection`
  - `target.Timer`
- 

### Examples

#### Create New Hardware Implementation

For workflow examples that use this function, see:

- “Specify Hardware Implementation for New Device”
- “Create Hardware Implementation by Modifying Existing Implementation”
- “Create Hardware Implementation by Reusing Existing Implementation”

### Input Arguments

#### **targetType** — Target type

character vector | string

Specify class of object. For example, specifying:

- 'Processor' creates a `target.Processor` object.
- 'LanguageImplementation' creates a `target.LanguageImplementation` object.

- 'Alias' creates a `target.Alias` object.

For the full list of supported types, see `target`.

Example: 'Processor'

### Name-Value Pair Arguments

Specify optional pairs of arguments as `Name1=Value1, ..., NameN=ValueN`, where `Name` is the argument name and `Value` is the corresponding value. Name-value arguments must appear after other arguments, but the order of the pairs does not matter.

*Before R2021a, use commas to separate each name and value, and enclose Name in quotes.*

Example: `myProc = target.create('Processor', 'Name', 'myProcessor', 'Manufacturer', 'myProcessorManufacturer');`

### Copy — Copy existing target feature object

character vector | string

Create a target object by copying values from an existing target object. For example:

```
myLangImp = target.create('LanguageImplementation', ...
 'Name', 'myLanguageImplementation', ...
 'Copy', 'ARM Compatible-ARM Cortex');
```

### propertyName — Property name

character vector | string

Create the target object with properties that are set to values that you specify.

## Output Arguments

### targetObject — Target object

object

The object that is created and returned. For example, the object is a:

- `target.Processor` object if `targetType` is 'Processor'
- `target.LanguageImplementation` object if `targetType` is 'LanguageImplementation'
- `target.Alias` object if `targetType` is 'Alias'

## Version History

Introduced in R2019a

### See Also

`target.add` | `target.get` | `target.remove`

### Topics

"Register New Hardware Devices"

## target.DebugIOTool class

**Package:** target

Debug byte stream I/O tool service interface

### Description

To provide a service interface for a tool that starts and tracks an application on the target hardware through a debugger, define a subclass that derives from the `target.DebugIOTool` class. The tool controls the debugger's interaction with the executing application and reads and writes to memory through the debugger. The `target.DebugIOTool` class inherits from `target.ExecutionTool`.

### Properties

#### Breakpoints — Application breakpoints

`target.Breakpoint` object array

Application breakpoints that you must set in the debugger.

#### Attributes:

|                        |                     |
|------------------------|---------------------|
| <code>GetAccess</code> | <code>public</code> |
| <code>SetAccess</code> | <code>public</code> |

### Methods

#### Public Methods

|                                   |                                                       |
|-----------------------------------|-------------------------------------------------------|
| <code>close</code>                | Close target application harness                      |
| <code>getApplicationStatus</code> | Get status of target application                      |
| <code>getStandardError</code>     | Return standard error stream from target application  |
| <code>getStandardOutput</code>    | Return standard output stream from target application |
| <code>loadApplication</code>      | Load target application into harness                  |
| <code>open</code>                 | Open target application harness                       |
| <code>read</code>                 | Read specified byte stream from variable in memory    |
| <code>startApplication</code>     | Start execution of target application                 |
| <code>stopApplication</code>      | Stop execution of target application                  |
| <code>unloadApplication</code>    | Unload target application from harness                |
| <code>write</code>                | Write byte stream to variable in memory               |

### Examples

#### PIL Target Connectivity with Debugger

For an example that uses the `target.DebugIOTool` class, see “Use Debugger for PIL Target Connectivity” (Embedded Coder).

### Version History

Introduced in R2021a

## **See Also**

`target.ExecutionService` | `target.ExecutionTool`

## **Topics**

“Use Debugger for PIL Target Connectivity” (Embedded Coder)

“DebugIOTool Template” (Embedded Coder)

## read

**Class:** target.DebugIOTool

**Package:** target

Read specified byte stream from variable in memory

### Syntax

```
[variableData, errFlag] = myDebugIOTool.read(byteStream, variable)
```

### Description

`[variableData, errFlag] = myDebugIOTool.read(byteStream, variable)`, through the debugger, reads the specified byte stream from the variable in memory. The method returns the byte stream and an error flag.

### Input Arguments

**byteStream** — Byte stream

string

Byte stream to write to memory.

Example: `[vd,ef] = myDebugIOTool.read('myByteStream', myVariable)`

**variable** — Variable in memory

vector

Variable in memory.

Example: `[vd,ef] = myDebugIOTool.read('myByteStream', myVariable)`

Data Types: `uint64`

### Output Arguments

**variableData** — Byte stream

vector

Byte stream from variable in memory.

**errFlag** — Error flag

`true` | `false`

Outcome of the write operation:

- `true` -- Error occurred during write operation.
- `false` -- Write operation completed.

## **Version History**

Introduced in R2021a

### **See Also**

`target.DebugIOTool` | `write`

## write

**Class:** target.DebugIOTool

**Package:** target

Write byte stream to variable in memory

### Syntax

```
errFlag = myDebugIOTool.write(byteStream, variable)
```

### Description

`errFlag = myDebugIOTool.write(byteStream, variable)`, through the debugger, writes the specified byte stream to the variable in memory. The method returns an error flag.

### Input Arguments

**byteStream** — Byte stream

string

Byte stream to write to memory.

Example: `ef = myDebugIOTool.write('myByteStream', myVariable)`

**variable** — Variable in memory

vector

Destination variable in memory.

Example: `ef = myDebugIOTool.write('myByteStream', myVariable)`

Data Types: uint64

### Output Arguments

**errFlag** — Error flag

true | false

Outcome of the write operation:

- `true` -- Error occurred during write operation.
- `false` -- Write operation completed.

## Version History

Introduced in R2021a

### See Also

target.DebugIOTool | write



# target.EnvironmentConfiguration class

**Package:** target

Configure system environment for toolchain

## Description

Use a `target.EnvironmentConfiguration` object to configure the system environment for a toolchain. For example, configuration of environment variables and execution of vendor-provided setup scripts.

To create a `target.EnvironmentConfiguration` object, use the `target.create` function.

## Properties

### HostOperatingSystemSupport — Operating system supported

`target.HostOperatingSystemSupport` object

Operating system that the environment configuration applies to.

#### Attributes:

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

### SetupCommand — Script or batch file with setup commands

`target.Command` object

Optional. Setup shell script or batch file that the software calls before executing CMake configure or build commands.

On a Windows<sup>®</sup> computer, before invoking `cmake`, the software runs the `CALL` command from a batch file.

On a Linux<sup>®</sup> and Mac computers, before invoking `cmake`, the software runs the `source` or `.` command from a Bash shell script.

#### Attributes:

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

### SystemPaths — Paths to prepend to system path

string array

Optional. List of paths that must be prepended to the system path before executing `cmake configure` or build commands.

#### Attributes:

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

## Examples

### Configure System Environment for Toolchain

This code snippet from “Create Custom CMake Toolchain Definition” shows how you can use a `target.EnvironmentConfiguration` object to configure the system environment for a toolchain.

```
tc.EnvironmentConfiguration(1).HostOperatingSystemSupport.Linux = false;
tc.EnvironmentConfiguration(1).HostOperatingSystemSupport.Windows = true;
tc.EnvironmentConfiguration(1).HostOperatingSystemSupport.Mac = false;
tc.EnvironmentConfiguration(1).SystemPaths = ...
 {'$(MW_MINGW64_LOC)/bin', '$(MATLAB_ROOT)/toolbox/shared/coder/ninja/$(ARCH)'};

tc.EnvironmentConfiguration(2) = target.create('EnvironmentConfiguration');
tc.EnvironmentConfiguration(2).HostOperatingSystemSupport.Linux = true;
tc.EnvironmentConfiguration(2).HostOperatingSystemSupport.Windows = false;
tc.EnvironmentConfiguration(2).HostOperatingSystemSupport.Mac = true;
tc.EnvironmentConfiguration(2).SystemPaths = ...
 {'$(MATLAB_ROOT)/toolbox/shared/coder/ninja/$(ARCH)'};
```

## Version History

Introduced in R2022b

### See Also

[target.Toolchain](#) | [target.CMake](#) | [target.CMakeBuildType](#) | [target.CMakeBuilder](#) | [target.CMakeCacheEntry](#) | [target.HardwareComponentSupport](#) | [target.create](#)

### Topics

“Create Custom CMake Toolchain Definition”

# target.ExecutionService class

**Package:** target

Describe implementation of execution service for target application

## Description

Use the `target.ExecutionService` class, which inherits from `target.ApplicationExecutionTool`, to describe the execution service implementation for running an application on the target computer. The implementation uses MATLAB code.

To create a `target.ExecutionService` object, use the `target.create` function.

## Properties

### Name — Execution service name

character vector | string

The name of the target application execution service.

#### Attributes:

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

### APIImplementation — API implementation

target.APIImplementation object

A `target.APIImplementation` object that describes the MATLAB data model service implementation.

#### Attributes:

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

### HostOperatingSystemRequirements — Development computer operating system requirements

'All' (default) | 'Unix' | 'Linux' | 'MacOS' | 'Windows'

MathWorks® system requirements for operating system of development computer.

#### Attributes:

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

### Id — Object identifier

character vector | string

Value of the Name property.

**Attributes:**

|           |         |
|-----------|---------|
| GetAccess | public  |
| SetAccess | private |

**Examples****Use target.ExecutionService to Describe Application Execution**

For an example that uses the `target.ExecutionService` class to describe the application execution within a debugger, see “Use Debugger for PIL Target Connectivity” (Embedded Coder).

**Version History**

Introduced in R2021a

**See Also**

`target.create` | `target.ExecutionTool` | `target.ApplicationExecutionTool`

**Topics**

“Use Debugger for PIL Target Connectivity” (Embedded Coder)

# target.ExecutionTool class

**Package:** target

MATLAB service interface for tool that manages application execution on target hardware

## Description

Use the `target.ExecutionTool` class to provide a MATLAB service interface for a tool that manages the application execution on the target hardware.

## Properties

### Application — Target application

string

Name of application to run on target hardware, which is set by MATLAB at runtime.

#### Attributes:

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

### ApplicationCommandLineArguments — Command-line arguments

string array

Command-line arguments for the target application, which is set by MATLAB at runtime.

#### Attributes:

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

## Methods

### Public Methods

|                                   |                                                       |
|-----------------------------------|-------------------------------------------------------|
| <code>close</code>                | Close target application harness                      |
| <code>getApplicationStatus</code> | Get status of target application                      |
| <code>getStandardError</code>     | Return standard error stream from target application  |
| <code>getStandardOutput</code>    | Return standard output stream from target application |
| <code>loadApplication</code>      | Load target application into harness                  |
| <code>open</code>                 | Open target application harness                       |
| <code>startApplication</code>     | Start execution of target application                 |
| <code>stopApplication</code>      | Stop execution of target application                  |
| <code>unloadApplication</code>    | Unload target application from harness                |

## Examples

### Use target.ExecutionTool to Manage Application Execution

For an example that uses the `target.ExecutionTool` class to manage the application execution on the target hardware, see “Use Debugger for PIL Target Connectivity” (Embedded Coder).

## **Version History**

**Introduced in R2021a**

### **See Also**

`target.DebugIOTool`

### **Topics**

“Use Debugger for PIL Target Connectivity” (Embedded Coder)

# close

**Class:** target.ExecutionTool

**Package:** target

Close target application harness

## Syntax

```
errFlag = myExecutionTool.close()
```

## Description

`errFlag = myExecutionTool.close()` closes the harness for the target application (that is managed by the associated execution tool) if it exists. An example of an application harness is a simulator or debugger. The method returns an error flag.

## Output Arguments

**errFlag — Error flag**

true | false

Outcome of the operation:

- `true` -- An error occurred while closing the application harness.
- `false` -- Method completed without error. Application harness closed or does not exist.

## Version History

Introduced in R2021a

## See Also

target.ExecutionTool | open

## getApplicationStatus

**Class:** target.ExecutionTool

**Package:** target

Get status of target application

### Syntax

```
[applicationStatus, errFlag] = myExecutionTool.getApplicationStatus()
```

### Description

[applicationStatus, errFlag] = myExecutionTool.getApplicationStatus() returns the status of the target application (managed by the execution tool) and an outcome flag.

### Output Arguments

**applicationStatus** — Target application status

target.ApplicationStatus member

The status of the target application that is being managed by the execution tool.

**errFlag** — Error flag

true | false

Outcome of the operation:

- `true` -- An error occurred while trying to obtain status of target application.
- `false` -- Status of target application obtained without error.

### Version History

**Introduced in R2021a**

### See Also

target.ExecutionTool



# getStandardError

**Class:** target.ExecutionTool

**Package:** target

Return standard error stream from target application

## Syntax

```
[stdErrorStream, errFlag] = myExecutionTool.getStandardError()
```

## Description

[stdErrorStream, errFlag] = myExecutionTool.getStandardError() returns, as a string, the standard error stream from the target application that is being managed by the associated execution tool. The method also returns an error flag.

## Output Arguments

### **stdErrorStream — Standard error stream**

string

The standard error stream from the beginning of the execution of the target application.

### **errFlag — Error flag**

true | false

Outcome of the operation:

- `true` -- Error occurred while retrieving standard error stream from target application.
- `false` -- Standard error stream from target application returned.

## Version History

**Introduced in R2021a**

## See Also

target.ExecutionTool | getStandardOutput

## getStandardOutput

**Class:** target.ExecutionTool

**Package:** target

Return standard output stream from target application

### Syntax

```
[stdOutputStream, errFlag] = myExecutionTool.getStandardOutput()
```

### Description

[stdOutputStream, errFlag] = myExecutionTool.getStandardOutput() returns, as a string, the standard output stream from the target application that is being managed by the associated execution tool. The method also returns an error flag.

### Output Arguments

**stdOutputStream** — Standard output stream

string

The standard output stream from the beginning of the execution of the target application.

**errFlag** — Outcome flag

true | false

Outcome of the operation:

- `true` -- Error occurred while retrieving standard output stream from target application.
- `false` -- Standard output stream from target application returned.

### Version History

**Introduced in R2021a**

### See Also

target.ExecutionTool | getStandardError

# loadApplication

**Class:** target.ExecutionTool

**Package:** target

Load target application into harness

## Syntax

```
outcomeFlag = myExecutionTool.loadApplication()
```

## Description

`outcomeFlag = myExecutionTool.loadApplication()` loads the target application (managed by the associated execution tool) into the application harness if the harness exists. An example of an application harness is a simulator or debugger. The method returns an error flag.

## Output Arguments

**errFlag — Error flag**

true | false

Outcome of the operation:

- `true` -- An error occurred while loading the target application into the harness.
- `false` -- Target application loaded into the harness or the harness does not exist.

## Version History

Introduced in R2021a

## See Also

target.ExecutionTool | unloadApplication

## open

**Class:** target.ExecutionTool

**Package:** target

Open target application harness

### Syntax

```
errFlag = myExecutionTool.open()
```

### Description

`errFlag = myExecutionTool.open()` opens the harness for the target application (that is managed by the associated execution tool) if the harness exists. An example of a target application harness is a simulator or debugger. The method returns an error flag.

### Output Arguments

**errFlag — Error flag**

true | false

Outcome of the operation:

- `true` -- Error occurred while opening application harness.
- `false` -- Application harness opened or does not exist.

### Version History

Introduced in R2021a

### See Also

target.ExecutionTool | close

# startApplication

**Class:** target.ExecutionTool

**Package:** target

Start execution of target application

## Syntax

```
errFlag = myExecutionTool.startApplication()
```

## Description

`errFlag = myExecutionTool.startApplication()` starts the execution of the target application (that is managed by the associated execution tool) and returns an error flag.

## Output Arguments

**errFlag — Error flag**

true | false

Outcome of the operation:

- true -- Error occurred while trying to start target application.
- false -- Target application started.

## Version History

Introduced in R2021a

## See Also

target.ExecutionTool | stopApplication

## stopApplication

**Class:** target.ExecutionTool

**Package:** target

Stop execution of target application

### Syntax

```
errFlag = myExecutionTool.stopApplication()
```

### Description

`errFlag = myExecutionTool.stopApplication()` stops the execution of the target application (that is managed by the associated execution tool) and returns an error flag.

### Output Arguments

**errFlag — Error flag**

true | false

Outcome of the operation:

- `true` -- Error occurred while trying to stop target application.
- `false` -- Target application stopped.

### Version History

Introduced in R2021a

### See Also

target.ExecutionTool | startApplication

# unloadApplication

**Class:** target.ExecutionTool

**Package:** target

Unload target application from harness

## Syntax

```
outcomeFlag = myExecutionTool.unloadApplication()
```

## Description

`outcomeFlag = myExecutionTool.unloadApplication()` unloads the target application (managed by the associated execution tool) from the application harness if the harness exists. An example of an application harness is a simulator or debugger. The method returns an error flag.

## Output Arguments

**errFlag — Error flag**

true | false

Outcome of the operation:

- `true` -- An error occurred while unloading the target application from the harness.
- `false` -- Target application unloaded from the harness or the harness does not exist.

## Version History

Introduced in R2021a

## See Also

target.ExecutionTool | loadApplication

## target.export

**Package:** target

Export target object data

### Syntax

```
target.export(targetObject)
target.export(targetObject,Name,Value)
```

### Description

`target.export(targetObject)` exports the specified target object data to a MATLAB function, `registerTargets.m`. Use the generated file to share target feature data between sessions and computers. When you run `registerTargets.m`, it recreates the target object and adds the object to an internal database.

`target.export(targetObject,Name,Value)` exports the specified target object data using one or more name-value pair arguments.

### Examples

#### Share Hardware Device Data

You can share hardware device data across computers and users.

Specify two hardware devices.

```
langImp1 = target.create('LanguageImplementation', ...
 'Name', 'MyLanguageImplementation1', ...
 'Copy', 'ARM Compatible-ARM Cortex');
```

```
langImp2 = target.create('LanguageImplementation', ...
 'Name', 'MyLanguageImplementation2', ...
 'Copy', 'Atmel-AVR');
```

```
myProc1 = target.create('Processor','Name','MyProcessor1');
myProc1.LanguageImplementations = [langImp1, langImp2];
objectsAdded1 = target.add(myProc1, ...
 'UserInstall',true, ...
 'SuppressOutput',true);
```

```
myProc2 = target.create('Processor','Name','MyProcessor2');
objectsAdded2 = target.add(myProc2, ...
 'UserInstall',true, ...
 'SuppressOutput',true);
```

Run the `target.export` function.

```
target.export([myProc1, myProc2], 'FileName', 'exportMyProcFunction')
```



The function generates `exportMyProcFunction.m` in the current working folder. Use the generated function to share hardware device data across computers and users. For example, on another computer, run this command:

```
addedObjects = exportMyProcFunction;
```

The generated function recreates and adds the objects to an internal database.

If you want the hardware device data to persist over MATLAB sessions, run:

```
addedObjects = exportMyProcFunction('UserInstall',true);
```

## Input Arguments

### **targetObject** — Target object

object vector

Specify the target objects that you want to export.

Example: `target.export(myTargetObject)`;

### **Name-Value Pair Arguments**

Specify optional comma-separated pairs of `Name`, `Value` arguments. `Name` is the argument name and `Value` is the corresponding value. `Name` must appear inside quotes. You can specify several name and value pair arguments in any order as `Name1, Value1, ..., NameN, ValueN`.

Example: `target.export(myTargetObject, 'FileName', 'exportMyTargetFn')`;

### **FileName** — File name

character vector | string

Specify name of MATLAB function file that contains exported target data.

### **Overwrite** — Overwrite flag

false (default) | true

- `true` -- Overwrite MATLAB function file if it exists.
- `false` -- Generate error if MATLAB function file exists. File is not overwritten.

## Version History

Introduced in R2019b

### **See Also**

`target.add` | `target.create`

### **Topics**

“Register New Hardware Devices”

## target.ExternalMode class

**Package:** target

Represent external mode protocol stack

### Description

Use the `target.ExternalMode` class, which is a subclass of `target.CommunicationProtocolStack`, to specify the external mode protocol stack for your target hardware.

To create a `target.ExternalMode` object, use the `target.create` function. Create the object and then use separate steps to specify properties. Or, using name-value arguments, create the object and specify properties in a single step.

### Properties

#### Connectivities — External mode connectivity options

`target.ExternalModeConnectivity` object array

Provide connectivity options for the external mode protocol stack. The array can contain only one `target.ExternalModeConnectivity` object for a specific transport protocol. For example, the array can contain one object for XCP on TCP/IP and another object for XCP on Serial.

#### Attributes:

|                        |                     |
|------------------------|---------------------|
| <code>GetAccess</code> | <code>public</code> |
| <code>SetAccess</code> | <code>public</code> |

### Examples

#### Specify External Mode Protocol Stack for Target Hardware

This code snippet from “Customise Connectivity for XCP External Mode Simulations” shows how to specify the external mode protocol stack for your target hardware.

```
xcpPlatformAbstraction = target.create('XCPPlatformAbstraction', ...
 'Name', 'XCP Platform Abstraction');

xcpPlatformAbstraction.BuildDependencies.Defines = {'XCP_CUSTOM_PLATFORM'};
customPlatformAbstractionPath = 'pathToImplementationFolder';
xcpPlatformAbstraction.BuildDependencies.SourceFiles = ...
 {fullfile(customPlatformAbstractionPath, 'myXCPPlatform.c')};
xcpPlatformAbstraction.BuildDependencies.IncludePaths = ...
 {customPlatformAbstractionPath};

xcpTransport = target.create('XCPTCPIPTransport', ...
 'Name', 'XCP Transport');

xcpConfiguration = target.create('XCP', ...
 'Name', 'XCP Configuration', ...
 'XCPTransport', xcpTransport, ...
 'XCPPlatformAbstraction', xcpPlatformAbstraction);
```

```
extModeTCPConnectivity = ...
 target.create('XCPEExternalModeConnectivity', ...
 'Name', 'External Mode TCP Connectivity', ...
 'XCP', xcpConfiguration);

externalMode = target.create('ExternalMode', ...
 'Name', 'External Mode', ...
 'Connectivities', extModeTCPConnectivity);

board.CommunicationProtocolStacks = externalMode;
```

---

**Note** You can create the `target.ExternalMode` object in a single step.

```
externalMode = target.create('ExternalMode', ...
 'Name', 'External Mode', ...
 'XCPTransportLayer', 'TCP', ...
 'Defines', {'XCP_CUSTOM_PLATFORM'}, ...
 'SourceFiles', {fullfile('pathToImplementationFolder', 'myXCPPlatform.c')}, ...
 'IncludePaths', {'pathToImplementationFolder'});
```

---

## Version History

Introduced in R2021a

### See Also

[target.create](#) | [target.Board](#) | [target.CommunicationProtocolStack](#) | [target.XCP](#) | [target.ExternalModeConnectivity](#) | [target.XCPEExternalModeConnectivity](#)

### Topics

“Customise Connectivity for XCP External Mode Simulations”

## target.ExternalModeConnectivity class

**Package:** target

Base class for external mode connectivity options

### Description

The `target.ExternalModeConnectivity` class is a base class for representing connectivity options that are available in the external mode protocol stack. The `target.XCPExternalModeConnectivity` class is derived from this base class.

### Class Attributes

|                  |      |
|------------------|------|
| Abstract         | true |
| HandleCompatible | true |

For information on class attributes, see “Class Attributes”.

### Version History

**Introduced in R2021a**

### See Also

`target.create` | `target.Board` | `target.CommunicationProtocolStack` | `target.ExternalMode` | `target.XCPExternalModeConnectivity`

### Topics

“Customise Connectivity for XCP External Mode Simulations”

# target.FloatingPointDataType class

**Package:** target

Describe floating point data type implemented by compiler for target hardware

## Description

Use a `target.FloatingPointDataType` object to describe a floating point data type that is implemented by the target hardware compiler but is not specified by a C language standard.

To create a `target.FloatingPointDataType` object, use the `target.create` function.

The `target.FloatingPointDataType` class is a handle class.

## Properties

### Size — Size in bits

0 (default) | integer

Size of the data type, specified in bits.

#### Attributes:

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

### TypeName — Data type name

character vector | string scalar

Name of floating point data type.

#### Attributes:

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

### LiteralSuffix — Numeric literal suffix

character vector | string scalar

Describe the suffix appended to numeric literal in C or C++ code, which indicates data type. For example, some ARM<sup>®</sup> compilers support the use of the literal suffix `f16` for the `_Float16` data type, which allows the specification of literals of the data type in C or C++ code, say, `1.23f16`.

#### Attributes:

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

### Includes — Required C/C++ header files

cell of character vectors | string array

For the data type, specify the include files that are required in the C or C++ translation unit.

**Attributes:**

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

**SystemIncludes — Required C/C++ system header files**

cell of character vectors | string array

For the data type, specify the system include files that are required in the C or C++ translation unit.

**Attributes:**

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

**Name — Identifier**

string scalar

Identifier for data type description.

**Attributes:**

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

## Examples

### Specify Half-Precision ARM Data Type

Specify a 16-bit floating point ARM data type.

```
languageImplementation = target.create('LanguageImplementation', ...
 'Name', 'ARM with half', ...
 'Copy', 'ARM Compatible-ARM Cortex');

customHalf = target.create('FloatingPointDataType', ...
 'Name', 'ARM Half Float', ...
 'TypeName', '_Float16', ...
 'LiteralSuffix', 'f16', ...
 'Size', 16, ...
 'SystemIncludes', "arm_fp16.h");
languageImplementation.DataTypes.NonStandardDataTypes = [customHalf];
target.add(languageImplementation);
```

## Version History

Introduced in R2021b

### See Also

target.create | target.add | target.remove

# target.Function class

**Package:** target

Provide function signature information

## Description

Use the `target.Function` class, which inherits functionality from `target.Data`, to provide function signature information.

To create a `target.Function` object, use the `target.create` function.

## Properties

### ReturnType — Data type returned

character vector | string

Data type of value that the associated function returns.

#### Attributes:

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

### Name — Function name

character vector | string

Name of function.

#### Attributes:

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

## Examples

### Create Function Signature

Create the function signature for a timer by using the `target.Function` class.

Create the signature for a function that returns the data type `uint64` and the function name `timestamp_x86`.

```
timerSignature = target.create('Function');
timerSignature.Name = 'timestamp_x86';
timerSignature.ReturnType = 'uint64';
```

## Version History

**Introduced in R2020b**

**See Also**

`target.create`



# target.get

**Package:** target

Retrieve target objects from internal database

## Syntax

```
targetObject = target.get(targetType, targetObjectId)
tFOList = target.get(targetType)
tFOList = target.get(targetType, Name, Value)
```

## Description

`targetObject = target.get(targetType, targetObjectId)` retrieves a target object from an internal database.

`tFOList = target.get(targetType)` returns a list of *targetType* objects that are stored in the internal database.

`tFOList = target.get(targetType, Name, Value)` returns a list of *targetType* objects that have properties that match the name-value pairs.

## Examples

### Remove Target Object

This example shows how you can remove a `target.LanguageImplementation` object associated with an object identifier, *myLanguageImplementationID*.

Retrieve the object from the internal database.

```
objectToRemove = target.get('LanguageImplementation', myLanguageImplementationID);
```

Remove the object.

```
target.remove(objectToRemove);
```

### Create Board Description

This example shows how to create a `target.Board` object that provides MATLAB with a description of processor attributes. It uses `target.get` to retrieve the description of a supported processor.

Create a board object.

```
hostTarget = target.create('Board', 'Name', 'Host Intel processor');
```

Specify the processor for the board by reusing a supported processor.

```
hostTarget.Processors = target.get('Processor', ...
 'Intel-x86-64 (Linux 64)');
```

## Input Arguments

### **targetType** — Target type

character vector | string

Specify the class of the object that you want to retrieve. For example, to retrieve:

- A `target.Processor` object, specify `'Processor'`.
- A `target.LanguageImplementation` object, specify `'LanguageImplementation'`.

For the list of supported classes, see `target` Package.

### **targetObjectId** — Target object identifier

character vector | string

Specify the unique identifier of the object that you want to retrieve, that is, the `Id` property value of the object.

## Output Arguments

### **targetObject** — Target object

object

Retrieved target object. For example:

- If `targetType` is `'Processor'`, the returned object is a `target.Processor` object.
- If `targetType` is `'LanguageImplementation'`, the returned object is a `target.LanguageImplementation` object.

For the list of supported classes, see `target` Package.

### **tF0List** — Target object list

object vector

List of retrieved target objects.

## Version History

**Introduced in R2019a**

## See Also

`target.add` | `target.create` | `target.remove`

## Topics

“Register New Hardware Devices”

# target.HardwareComponentSupport class

**Package:** target

Describe support for a hardware component

## Description

Use a `target.HardwareComponentSupport` object to specify that a tool or toolchain applies to a particular target device.

To create a `target.HardwareComponentSupport` object, use the `target.create` function.

The `target.HardwareComponentSupport` class is a handle class.

## Properties

### Component — Supported target device

target object

Supported target device, for example, a `target.Processor` or a `target.Board` object.

#### Attributes:

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

## Examples

### Use target.HardwareComponentSupport to Specify Toolchain Support for Target Device

This code snippet shows how you can create a `target.HardwareComponentSupport` object and use it to define a toolchain that is available only when the target device Intel-x86-64 (Windows64) is selected.

```
tc = target.create('Toolchain', 'Name', 'My Toolchain');
tc.Builder = target.create('CMakeBuilder', 'Generator', 'Ninja');
tc.SupportedHardware = target.create('HardwareComponentSupport');
tc.SupportedHardware.Component = target.get('Processor', 'Intel-x86-64 (Windows64)');
```

## Version History

Introduced in R2022b

## See Also

`target.Toolchain` | `target.CMake` | `target.CMakeBuildType` | `target.CMakeBuilder` | `target.CMakeCacheEntry` | `target.EnvironmentConfiguration` | `target.create`

## Topics

“Create Custom CMake Toolchain Definition”

## target.HostProcessExecutionTool class

**Package:** target

Capture system command information to run target application from MATLAB computer

### Description

Use the `target.HostProcessExecutionTool` class to capture system command information that is required to run the target application from your development computer. Use this class to specify nonblocking commands. MATLAB runs a nonblocking command in the background and does not wait for the termination of the command.

### Properties

#### Name — Execution tool name

character vector | string

Name of the execution tool.

#### Attributes:

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

#### StartCommand — Command list to run application

`target.Command` object

A `target.Command` object that provides a system command for running the application. The command in the list starts the application process.

This property must not be empty.

#### Attributes:

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

#### StopCommand — Command list to stop application

`target.Command` object

A `target.Command` object that provides a system command to stop the application execution.

#### Attributes:

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

#### Id — Object identifier

character vector | string

Value of the Name property.

**Attributes:**

|           |         |
|-----------|---------|
| GetAccess | public  |
| SetAccess | private |

## **Version History**

**Introduced in R2020b**

### **See Also**

[target.create](#) | [target.ApplicationExecutionTool](#) | [target.Command](#) | [target.SystemCommandExecutionTool](#)

### **Topics**

[“Set Up PIL Connectivity by Using target Package” \(Embedded Coder\)](#)

## target.LanguageImplementation class

**Package:** target

Provide C and C++ compiler implementation details

### Description

Use the `target.LanguageImplementation` class to provide implementation details about the C and C++ compiler for your target hardware. For example, byte ordering.

To create a `target.LanguageImplementation` object, use the `target.create` function.

### Properties

#### AtomicFloatSize — Largest atomic float size

integer

Size in bits of the largest floating-point data type that you can atomically load and store on the hardware

##### Attributes:

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

Data Types: int32

#### AtomicIntegerSize — Largest atomic integer size

integer

Size in bits of the largest integer that you can atomically load and store on the hardware

##### Attributes:

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

Data Types: int32

#### Endianness — Byte ordering

'Little' (default) | 'Big' | 'Unspecified'

Byte ordering implemented by target hardware.

##### Attributes:

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

#### DataTypes — Data type definitions

target.DataTypes object

Provides C and C++ data type definitions through properties described in this table.



**Attributes:**

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

Data Types: int32

**Examples****Create New Hardware Implementation**

For examples that use this class, see:

- “Specify Hardware Implementation for New Device”
- “Create Hardware Implementation by Modifying Existing Implementation”
- “Create Hardware Implementation by Reusing Existing Implementation”

**Version History**

**Introduced in R2019a**

**See Also**

target.Processor | target.create

**Topics**

“Register New Hardware Devices”



# target.MainFunction class

**Package:** target

Provide C and C++ dependencies for main function of target hardware application

## Description

Use the `target.MainFunction` class to provide main function dependencies for an application main function that runs on your target hardware. For example, C and C++ initialization and termination code, include preprocessor directives, and specification of main function arguments for the application.

To create a `target.MainFunction` object, use the `target.create` function.

## Properties

### Name — Dependency collection

character vector | string

Name of the collection of main dependencies.

#### Attributes:

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

### Dependencies — Build dependencies

`target.BuildDependencies` object

Compiler build tool dependencies of the main function, which include header files, source files, and libraries.

#### Attributes:

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

### Arguments — Command-line arguments

string array

Capture run-time command-line argument dependencies.

#### Attributes:

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

### IncludeFiles — #include files

string array

Array of header files that must be included in a target main function by using the preprocessor directive `#include "path-spec"`.

**Attributes:**

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

**SystemIncludeFiles — System #include files**

string array

Array of header files that must be included in a target main function by using the preprocessor directive `#include <path-spec>`.

**Attributes:**

|           |           |
|-----------|-----------|
| GetAccess | public    |
| SetAccess | protected |

**InitializationCode — Target main initialization**

character vector | string

Formatted string of C or C++ code that the main function uses to initialize target resources.

**Attributes:**

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

**TerminationCode — Target main termination**

character vector | string

Formatted string of C or C++ code that the main function uses to terminate target resources.

**Attributes:**

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

## Examples

**Specify Target-Specific main Function Dependencies**

Create a `target.MainFunction` object and associate it with a `target.Board` object, which captures the main function dependencies for an Arduino board. Workflows, such as processor-in-the-loop (PIL), can use this information when generating a main function for an application that runs on the target hardware.

```
board = target.create('Board', 'Name', 'Arduino Board')
mainFunction = target.create('MainFunction');
mainFunction.Name = 'Arduino Main Dependencies';

mainFunction.IncludeFiles = { 'Arduino.h' };
mainFunction.InitializationCode = fileread('arduino_main_initialization.c');

board.MainFunctions = mainFunction;
```

In the code snippet, `arduino_main_initialization.c` contains C code. For example:

```
/* Initialize system */
init();
```

## Specify main Function Run-Time Arguments

This code snippet from “Set Up PIL Connectivity by Using target Package” (Embedded Coder) shows how you can create and use a `target.MainFunction` object to specify main function arguments that are required for an API implementation.

```
comms = target.create('CommunicationInterface');
comms.Name = 'Linux TCP Interface';
comms.Channel = 'TCPChannel';
comms.APIImplementations = target.create('APIImplementation', ...
 'Name', 'x86 rtiostream Implementation');
comms.APIImplementations.API = target.create('API', 'Name', 'rtiostream');
comms.APIImplementations.BuildDependencies = target.create('BuildDependencies');
comms.APIImplementations.BuildDependencies.SourceFiles = ...
 {fullfile('${MATLABROOT}', ...
 'toolbox', ...
 'coder', ...
 'rtiostream', ...
 'src', ...
 'rtiostreamtcpip', ...
 'rtiostream_tcpip.c')};
comms.APIImplementations.MainFunction = target.create('MainFunction', ...
 'Name', 'TCP RtIOStream Main');
comms.APIImplementations.MainFunction.Arguments = {'-blocking', '1', '-port', '0'};
hostTarget.CommunicationInterfaces = comms;
```

## Version History

Introduced in R2020b

## See Also

`target.create` | `target.Board` | `target.APIImplementation`

## Topics

“Set Up PIL Connectivity by Using target Package” (Embedded Coder)

## target.MATLABDependencies class

**Package:** target

Describe MATLAB class and function dependencies

### Description

Use the `target.MATLABDependencies` class to describe MATLAB class and function dependencies.

To create a `target.MATLABDependencies` object, use the `target.create` function.

### Properties

#### Classes — MATLAB classes

string array

MATLAB classes that make up the implementation dependencies.

#### Attributes:

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

#### Functions — MATLAB functions

string array

MATLAB functions that make up the implementation dependencies.

#### Attributes:

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

### Examples

#### MATLAB Dependencies of `target.DebugIOTool` Implementation

For an example that describes the MATLAB dependencies of an implementation of `target.DebugIOTool`, see “Use Debugger for PIL Target Connectivity” (Embedded Coder).

### Version History

Introduced in R2021a

### See Also

`target.create` | `target.API` | `target.APIImplementation` | `target.BuildDependencies`

### Topics

“Use Debugger for PIL Target Connectivity” (Embedded Coder)

# target.Object class

**Package:** target

Base class for target types

## Description

target.Object is an abstract base class that enables target types to inherit common functionality.

## Class Attributes

|                  |      |
|------------------|------|
| Abstract         | true |
| HandleCompatible | true |

For information on class attributes, see “Class Attributes”.

## Properties

### IsValid — Data validity

true | false

- true if object passes validation procedure.
- false otherwise.

### Attributes:

|           |         |
|-----------|---------|
| GetAccess | public  |
| SetAccess | private |

Data Types: logical

## Methods

### Public Methods

validate Validate data integrity of target feature object

## Examples

### Validate Hardware Device Data

For an example that uses this class, see “Validate Hardware Device Data”.

## Version History

Introduced in R2019b

## **See Also**

### **Topics**

“Register New Hardware Devices”

# validate

**Class:** target.Object

**Package:** target

Validate data integrity of target feature object

## Syntax

```
myTargetFeature.validate()
```

## Description

`myTargetFeature.validate()` runs a procedure to validate the data integrity of the object *myTargetFeature*. If the validation procedure fails, the method produces an error.

## Examples

### Validate Hardware Device Data

For an example that uses this method, see “Validate Hardware Device Data”.

## Version History

Introduced in R2019b

## See Also

### Topics

“Register New Hardware Devices”

## target.PILProtocol class

**Package:** target

Describe PIL protocol implementation for target hardware

### Description

Use the `target.PILProtocol` class, which inherits functionality from `target.CommunicationProtocolStack`, to describe the processor-in-the-loop (PIL) communication protocol implementation for your target hardware. For example, use this class to provide buffering information for data transfer and timeout information for I/O with the associated `target.Board` object.

To create a `target.PILProtocol` object, use the `target.create` function.

### Properties

#### Name — PIL protocol object name

character vector | string

Name of the PIL protocol object.

#### Attributes:

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

#### SendBufferSize — Send buffer size

scalar integer

Size of send buffer for caching communication data.

#### Attributes:

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

#### ReceiveBufferSize — Receive buffer size

scalar integer

Size of receive buffer for caching communication data.

#### Attributes:

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

#### SendTimeout — Send timeout

scalar integer

Timeout that is applied to a data send command, specified in seconds.



**Attributes:**

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

**ReceiveTimeout — Receive timeout**

scalar integer

Timeout that is applied to a data receive command, specified in seconds.

**Attributes:**

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

**OpenTimeout — Open timeout**

scalar integer

Timeout that is applied when opening PIL communications, specified in seconds.

**Attributes:**

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

**ByteInputOutputOnly — Bytes only**

scalar integer

Specify whether PIL communication sends and receives only bytes.

**Attributes:**

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

**Examples****Specify PIL Protocol Information**

Specify PIL protocol information. This code snippet from “Set Up PIL Connectivity by Using target Package” (Embedded Coder) shows how to specify the information.

```

pilProtocol = target.create('PILProtocol');
pilProtocol.Name = 'Linux PIL Protocol';
pilProtocol.SendBufferSize = 50000;
pilProtocol.ReceiveBufferSize = 50000;
hostTarget.CommunicationProtocolStacks = pilProtocol;

```

**Version History**

Introduced in R2020b

**See Also**

target.create | target.CommunicationProtocolStack

**Topics**

“Set Up PIL Connectivity by Using target Package” (Embedded Coder)

# target.Port class

**Package:** target

Describe connection via target hardware port

## Description

Use the `target.Port` class, which inherits from `target.ConnectionProperties`, to describe a connection via a port of the target hardware. For example, the serial COM port.

## Properties

### AddOns — Custom property add-on objects

`target.AddOns` object array

To provide additional custom properties, associate one or more `target.AddOn` objects with the `target.Port` object.

#### Attributes:

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

### PortNumber — Port number

string

Number of the port associated with the connection.

#### Attributes:

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

## Methods

### Public Methods

get Get name of custom add-on property  
set Set property value

## Version History

Introduced in R2021a

## See Also

`target.create` | `target.ConnectionProperties`

## target.PortConnection class

**Package:** target

Describe target connection port

### Description

Use the `target.PortConnection` class, which inherits functionality from `target.ConnectionProperties`, to describe a target connection port. For example, a serial COM port.

To create a `target.PortConnection` object, use the `target.create` function.

### Properties

#### Port — Port

character vector | string

Port number.

#### Attributes:

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

### Version History

**Introduced in R2020b**

### See Also

`target.create` | `target.ConnectionProperties`

# target.Processor class

**Package:** target

Provide target processor information

## Description

Use the `target.Processor` class to provide information about your target processor. For example, name, manufacturer, and language implementation.

To create a `target.Processor` object, use the `target.create` function.

## Properties

### Id — Object identifier

character vector | string

The object identifier is the hyphenated combination of the `Manufacturer` and `Name` property values. If the `Manufacturer` property is empty, the object identifier is the `Name` property value.

#### Attributes:

|                        |                      |
|------------------------|----------------------|
| <code>GetAccess</code> | <code>public</code>  |
| <code>SetAccess</code> | <code>private</code> |

### LanguageImplementations — Language implementation

object

Associated `target.LanguageImplementation` object.

#### Attributes:

|                        |                     |
|------------------------|---------------------|
| <code>GetAccess</code> | <code>public</code> |
| <code>SetAccess</code> | <code>public</code> |

### Name — Processor name

character vector | string

Name of the target processor.

Example: 'Cortex-A53'

#### Attributes:

|                        |                     |
|------------------------|---------------------|
| <code>GetAccess</code> | <code>public</code> |
| <code>SetAccess</code> | <code>public</code> |

### Manufacturer — Processor manufacturer

character vector | string

Optional description of the target processor manufacturer.

Example: 'ARM Compatible'

**Attributes:**

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

**Timers — Timers**

target.Counter object array

Provide timer information.

**Attributes:**

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

**Overheads — Profiling instrumentation overheads**

vector

Specify instrumentation overhead values for removal from execution-time measurements.

**Attributes:**

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

**NumberOfCores — Processor cores**

1 (default) | scalar

Number of physical cores in processor.

**Attributes:**

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

Data Types: uint

**NumberOfThreadsPerCore — Threads per processor core**

1 (default) | scalar

Number of threads per processor core.

**Attributes:**

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

Data Types: uint

**NumberOfLogicalCores — Logical cores**

scalar

Number of logical cores that processor provides, which is equal to NumberOfCores x NumberOfThreadsPerCore.

**Attributes:**

|           |         |
|-----------|---------|
| GetAccess | public  |
| SetAccess | private |

Data Types: uint

**Examples****Create New Hardware Implementation**

For examples that use this class, see:

- “Specify Hardware Implementation for New Device”
- “Create Hardware Implementation by Modifying Existing Implementation”
- “Create Hardware Implementation by Reusing Existing Implementation”

**Create Timer Object**

This example shows how you can create a timer object for your development computer.

Create the function signature for a timer. In this example, the function returns a uint64 data type and the function name `timestamp_x86`.

```
timerSignature = target.create('Function');
timerSignature.Name = 'timestamp_x86';
timerSignature.ReturnType = 'uint64';
```

Capture the function in an API object.

```
timerApi = target.create('API');
timerApi.Functions = timerSignature;
timerApi.Language = target.Language.C;
timerApi.Name = 'Linux Timer API';
```

Capture the dependencies of the function, that is, the source and header files that are required to run the function.

```
timerDependencies = target.create('BuildDependencies');
timerDependencies.IncludeFiles = {'host_timer_x86.h'};
timerDependencies.IncludePaths = ...
 {'$(MATLAB_ROOT)/toolbox/coder/profile/src'};
timerDependencies.SourceFiles = {'host_timer_x86.c'};
```

Create an object that combines the API and dependencies.

```
timerImplementation = target.create('APIImplementation');
timerImplementation.API = timerApi;
timerImplementation.BuildDependencies = timerDependencies;
timerImplementation.Name = 'Linux Timer Implementation';
```

Create the timer object and associate it with the timer information.

```
timer = target.create('Timer');
timer.APIImplementation = timerImplementation;
timer.Name = 'Linux Timer';
```

**Note** Using name-value arguments, you can create the timer object with this command.

```
timer = target.create('Timer', 'Name', 'Linux Timer', ...
 'FunctionName', 'timestamp_x86', ...
 'FunctionReturnType', 'uint64', ...
 'FunctionLanguage', target.Language.C, ...
 'SourceFiles', {'host_timer_x86.c'}, ...
 'IncludeFiles', {'host_timer_x86.h'}, ...
 'IncludePaths', {'$(MATLAB_ROOT)/toolbox/coder/profile/src'})
```

---

Assign the timer and add-ons to the processor object.

```
processor = target.get('Processor', 'Intel-x86-64 (Linux 64)');
processor.Timers = timer;
```

### Create Description for Intel Core Processor

Create a description for the Intel® Core™ i7-8550U processor, which is a processor that supports hyperthreading.

```
i7 = target.create('Processor', ...
 'Name', 'i7-8550U', ...
 'Manufacturer', 'Intel', ...
 'NumberOfCores', 4, ...
 'NumberOfThreadsPerCore', 2);
target.add(i7);
```

## Version History

Introduced in R2019a

### See Also

[target.LanguageImplementation](#) | [target.create](#)

### Topics

“Register New Hardware Devices”

“Generate Native Half-Precision C Code from Simulink Models” (Fixed-Point Designer)

“Specify Maximum Number of Threads to Run Parallel for-Loops in the Generated Code”



# target.ProfilingFreezingOverhead class

**Package:** target

Capture freezing and unfreezing instrumentation overhead

## Description

Use a `target.ProfilingFreezingOverhead` object to capture the instrumentation overhead for freezing and unfreezing a timer.

To create a `target.ProfilingFreezingOverhead` object, use the `target.create` function.

## Properties

### Value — Instrumentation overhead

scalar

Specify instrumentation overhead for freezing and unfreezing a timer.

#### Attributes:

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

Data Types: int

### Counter — Timer

`target.Timer` object

Object that provides the timer details for your processor.

#### Attributes:

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

Data Types: int

### MinimumBenchmarkIterations — Instrumentation overhead

100 (default) | scalar

Specify the minimum number of iterations that benchmark program performs to compute instrumentation overhead values.

#### Attributes:

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

Data Types: int

## Examples

### Specify Function Instrumentation Overhead

Manually specify the function instrumentation overhead for a timer.

Retrieve the `target.Processor` and `target.Timer` objects.

```
processor = target.get('Processor', 'myProcessorObjectId');
timer = target.get('Timer', 'myTimerObjectId');
```

Create a `target.ProfilingFreezingOverhead` object.

```
freezingOverhead = target.create('ProfilingFreezingOverhead', ...
 'Name', 'Timer Freezing Overhead');
freezingOverhead.Value = 30;
freezingOverhead.Counter = timer;
```

## Version History

Introduced in R2021a

### See Also

`target.ProfilingTaskOverhead` | `target.ProfilingFunctionOverhead`

# target.ProfilingFunctionOverhead class

**Package:** target

Capture function instrumentation overhead

## Description

Use a `target.ProfilingFunctionOverhead` object to capture the instrumentation overhead for profiling a function.

To create a `target.ProfilingFunctionOverhead` object, use the `target.create` function.

## Properties

### Value — Instrumentation overhead

scalar

Specify instrumentation overhead for profiling a function.

#### Attributes:

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

Data Types: int

### Counter — Timer

`target.Timer` object

Object that provides the timer details for your processor.

#### Attributes:

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

Data Types: int

### MinimumBenchmarkIterations — Instrumentation overhead

100 (default) | scalar

Specify the minimum number of iterations that benchmark program performs to compute instrumentation overhead values.

#### Attributes:

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

Data Types: int

## Examples

### Specify Function Instrumentation Overhead

Manually specify the function instrumentation overhead for a timer.

Retrieve the `target.Processor` and `target.Timer` objects.

```
processor = target.get('Processor', 'myProcessorObjectId');
timer = target.get('Timer', 'myTimerObjectId');
```

Create a `target.ProfilingFunctionOverhead` object.

```
functionOverhead = target.create('ProfilingFunctionOverhead', ...
 'Name', 'Timer Function Overhead');
functionOverhead.Value = 20;
functionOverhead.Counter = timer;
```

## Version History

Introduced in R2021a

### See Also

`target.ProfilingTaskOverhead` | `target.ProfilingFreezingOverhead`

# target.ProfilingTaskOverhead class

**Package:** target

Capture task instrumentation overhead

## Description

Use a `target.ProfilingTaskOverhead` object to capture the instrumentation overhead for profiling a task.

To create a `target.ProfilingTaskOverhead` object, use the `target.create` function.

## Properties

### Value — Instrumentation overhead

scalar

Specify instrumentation overhead for profiling a task.

#### Attributes:

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

Data Types: int

### Counter — Timer

`target.Timer` object

Object that provides the timer details for your processor.

#### Attributes:

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

Data Types: int

### MinimumBenchmarkIterations — Instrumentation overhead

100 (default) | scalar

Specify the minimum number of iterations that benchmark program performs to compute instrumentation overhead values.

#### Attributes:

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

Data Types: int

## Examples

### Specify Task Instrumentation Overhead

Manually specify the task instrumentation overhead for a timer.

Retrieve the `target.Processor` and `target.Timer` objects.

```
processor = target.get('Processor', 'myProcessorObjectId');
timer = target.get('Timer', 'myTimerObjectId');
```

Create a `target.ProfilingTaskOverhead` object.

```
taskOverhead = target.create('ProfilingTaskOverhead', ...
 'Name', 'Timer Task Overhead');
taskOverhead.Value = 10;
taskOverhead.Counter = timer;
```

## Version History

Introduced in R2021a

### See Also

`target.ProfilingFunctionOverhead` | `target.ProfilingFreezingOverhead`

# target.remove

**Package:** target

Remove target object from internal database

## Syntax

```
target.remove(targetObject)
target.remove(targetType, targetObjectId)
target.remove(targetObject, Name, Value)
```

## Description

`target.remove(targetObject)` removes the target object from an internal database.

`target.remove(targetType, targetObjectId)` removes the target object specified by class and identifier.

`target.remove(targetObject, Name, Value)` uses name-value arguments to remove associated objects and suppress command-line output.

## Examples

### Remove Target Object From Internal Database

You can specify and add a hardware device implementation to an internal database.

```
armv8 = target.create('LanguageImplementation', ...
 'Name', 'Armv8-A LP64', ...
 'Copy', 'ARM Compatible-ARM Cortex');

a53 = target.create('Processor', ...
 'Name', 'Cortex-A53', ...
 'Manufacturer', 'ARM Compatible');

a53.LanguageImplementations = armv8;

target.add(a53)
```

When a target object is no longer required, you can use the function to remove the object from the internal database.

To remove only the `target.Processor` object, run:

```
target.remove(a53)
```

Or:

```
target.remove('Processor', 'ARM Compatible-Cortex-A53');
```

To remove the `target.Processor` object and its associated `target.LanguageImplementation` object and suppress the command-line output, run:

```
target.remove(a53, ...
 'IncludeAssociations', true, ...
 'SuppressOutput', true);
```

## Input Arguments

### **targetObject** — Target object

object

Specify the target object that you want to remove.

### **targetType** — Target type

character vector | string

Specify the class of the target object that you want to remove. For example:

- If the class is `target.Processor`, specify `'Processor'`.
- If the class is `target.LanguageImplementation`, specify `'LanguageImplementation'`.

Example: `'Processor'`

### **targetObjectId** — Target object identifier

character vector | string

Specify the unique identifier of the object that you want to remove, that is, the `Id` property value of the object.

## Name-Value Pair Arguments

Specify optional pairs of arguments as `Name1=Value1, ..., NameN=ValueN`, where `Name` is the argument name and `Value` is the corresponding value. Name-value arguments must appear after other arguments, but the order of the pairs does not matter.

*Before R2021a, use commas to separate each name and value, and enclose Name in quotes.*

Example: `target.remove(myTargetObject, 'IncludeAssociations', true);`

### **IncludeAssociations** — Remove associated objects

false (default) | true

Remove associated objects from internal database:

- `true` -- Function removes `targetObject` and associated target objects from the internal database. If an associated object is referenced by another target object, the function does not remove the associated object. If `targetObject` is not saved in the internal database, the function does not remove associated target objects from the internal database.
- `false` -- Function removes only `targetObject` from the internal database.

Example: `target.remove(myTargetObject, 'IncludeAssociations', true);`

Data Types: logical



**SuppressOutput — Control command-line output**

false (default) | true

Control command-line output of function:

- `true` -- Suppress command-line output from the function.
- `false` -- Provide information about the objects that the function removes from the internal database.

Example: `target.remove(myTargetObject, 'SuppressOutput', true);`

Data Types: logical

**Version History**

Introduced in R2019a

**See Also**`target.add` | `target.create` | `target.get`**Topics**

"Register New Hardware Devices"

## target.RS232Channel class

**Package:** target

Describe serial communication channel

### Description

Use the `target.RS232Channel` class, which inherits functionality from `target.CommunicationChannel`, to describe properties of the serial communication channel.

To create a `target.RS232Channel` object, use the `target.create` function.

### Properties

#### BaudRate — Baud value

scalar integer

Baud value of the serial connection.

#### Attributes:

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

### Version History

Introduced in R2020b

### See Also

`target.create` | `target.CommunicationChannel`

# target.SystemCommandExecutionTool class

**Package:** target

Capture system command information to run target application from MATLAB computer

## Description

Use the `target.SystemCommandExecutionTool` to capture system command information that is required to run the target application from your development computer. Use this class to specify blocking commands. When MATLAB runs a blocking command, MATLAB waits until the command is terminated.

## Properties

### Name — Execution tool name

character vector | string

Name of the execution tool.

#### Attributes:

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

### StartCommand — Command list to run application

`target.Command` object

A `target.Command` object that provides a system command for running the application. The command in the list starts the application process.

This property must not be empty.

#### Attributes:

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

### StopCommand — Command list to stop application

`target.Command` object

A `target.Command` object that provides a system command to stop the application execution.

#### Attributes:

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

### Id — Object identifier

character vector | string

Value of the Name property.

**Attributes:**

|           |         |
|-----------|---------|
| GetAccess | public  |
| SetAccess | private |

## **Version History**

**Introduced in R2020b**

### **See Also**

[target.create](#) | [target.ApplicationExecutionTool](#) | [target.Command](#) | [target.HostProcessExecutionTool](#)

### **Topics**

[“Set Up PIL Connectivity by Using target Package” \(Embedded Coder\)](#)

# target.TargetConnection class

**Package:** target

Provide details about connecting MATLAB computer to target hardware

## Description

Use the `target.TargetConnection` class, which inherits functionality from `target.Connection`, to provide details about connecting your MATLAB computer to target hardware. For example, the communication channel and connection properties that are required for communication with your target hardware.

To create a `target.TargetConnection` object, use the `target.create` function. Create the object and then use separate steps to specify properties. Or, using name-value arguments, create the object and specify properties in a single step.

## Properties

### Name — Connection object

character vector | string

Name of connection object.

#### Attributes:

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

### CommunicationChannel — Communication channel type

`target.CommunicationChannel` object

Associate a `target.CommunicationChannel` object with your connection, which describes the type of channel that is used. For example, to specify serial or TCP channel properties, use `target.RS232Channel` or `target.TCPChannel` respectively.

If you use name-value arguments to create a `target.TargetConnection` object, for the `CommunicationChannel` property, specify these arguments.

| Name                | Description                                                                                                                                                                                     |
|---------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| 'CommunicationType' | Required. Type of predefined communication channel. Specifies one of these values: <ul style="list-style-type: none"> <li>'RS232Channel'</li> <li>'TCPChannel'</li> <li>'UDPChannel'</li> </ul> |
| 'IPAddress'         | Optional. If predefined communication channel is 'TCPChannel' or 'UDPChannel', specifies IP address property of <code>target.TCPChannel</code> or <code>target.UDPChannel</code> object.        |

| Name       | Description                                                                                                                                              |
|------------|----------------------------------------------------------------------------------------------------------------------------------------------------------|
| 'Port'     | Optional. If predefined communication channel is 'TCPChannel' or 'UDPChannel', specifies Port property of target.TCPChannel or target.UDPChannel object. |
| 'BaudRate' | Optional. If predefined communication channel is 'RS232Channel', specifies BaudRate property of target.RS232Channel object.                              |
| 'Parity'   | Optional. If predefined communication channel is 'RS232Channel', specifies Parity property of target.RS232Channel object.                                |

**Attributes:**

```
GetAccess public
SetAccess public
```

**Target — Connected target**

target.Board object

Associate a target.Board object with your connection, which describes the target hardware that is connected to the MATLAB computer.

**Attributes:**

```
GetAccess public
SetAccess public
```

**ConnectionProperties — MATLAB computer connection properties**

target.ConnectionProperties object

Associate a target.ConnectionProperties object with your connection that describes the MATLAB computer connection properties that are used to connect to the target hardware. For example, to specify the serial port, use a target.Port object.

If you use name-value arguments to create a target.TargetConnection object and the predefined communication channel type is 'RS232Channel', specifying the argument 'Port' sets the ConnectionProperties property to target.Port.

**Attributes:**

```
GetAccess public
SetAccess public
```

**TargetConnectionProperties — Target connection properties**

target.ConnectionProperties object

Associate a target.ConnectionProperties object with your connection that describes the target hardware connection properties that are used to connect to the MATLAB computer. For example, to specify the serial port, use a target.Port object.

If you use name-value arguments to create a target.TargetConnection object and the predefined communication channel type is 'RS232Channel', specifying the argument 'Port' sets the TargetConnectionProperties property to target.Port.

**Attributes:**

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

**Examples****Specify Connection Between Development Computer and Target Hardware**

This code from “Set Up PIL Connectivity by Using target Package” (Embedded Coder) shows how to specify the connection between your development computer and target hardware. In the example, the target application runs on your development computer as a separate process and uses a TCP communication channel through `localhost`.

```
connection = target.create('TargetConnection');
connection.Name = 'Host Process Connection';
connection.Target = hostTarget;
connection.CommunicationChannel = target.create('TCPChannel');
connection.CommunicationChannel.Name = ...
 'External Process TCPCommunicationChannel';
connection.CommunicationChannel.IPAddress = 'localhost';
connection.CommunicationChannel.Port = '0';
```

---

**Note** Using name-value arguments, you can create the connection object with this command:

```
timer = target.create('TargetConnection', ...
 'Name', 'Host Process Connection', ...
 'CommunicationType', 'TCPChannel', ...
 'IPAddress', 'localhost', ...
 'Port', '0')
```

---

**Version History**

Introduced in R2020b

**See Also**

`target.create` | `target.CommunicationChannel` | `target.ConnectionProperties` | `target.Board`

## target.TCPChannel class

**Package:** target

Describe TCP communication properties

### Description

Use the `target.TCPChannel`, which inherits functionality from `target.CommunicationChannel`, to describe TCP communication properties.

To create a `target.TCPChannel` object, use the `target.create` function.

### Properties

#### IPAddress — IP address

character vector | string

IP address of the TCP server.

#### Attributes:

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

#### Port — Port

scalar integer

TCP port.

#### Attributes:

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

### Examples

#### Create Connection by Using TCP Communication Channel

This code from “Set Up PIL Connectivity by Using target Package” (Embedded Coder) shows how to specify the connection between your development computer and target hardware. In the example, the target application runs on your development computer as a separate process and uses a TCP communication channel through `localhost`.

```
connection = target.create('TargetConnection');
connection.Name = 'Host Process Connection';
connection.Target = hostTarget;
connection.CommunicationChannel = target.create('TCPChannel');
connection.CommunicationChannel.Name = ...
 'External Process TCPCommunicationChannel';
connection.CommunicationChannel.IPAddress = 'localhost';
connection.CommunicationChannel.Port = '0';
```

---

**Note** Using name-value arguments, you can create the connection object with this command:



```
timer = target.create('TargetConnection', ...
 'Name', 'Host Process Connection', ...
 'CommunicationType', 'TCPChannel', ...
 'IPAddress', 'localhost', ...
 'Port', '0')
```

---

## Version History

Introduced in R2020b

### See Also

[target.create](#) | [target.CommunicationChannel](#) | [target.TargetConnection](#)

### Topics

“Set Up PIL Connectivity by Using target Package” (Embedded Coder)

## target.Timer class

**Package:** target

Provide timer details for processor

### Description

Use the `target.Timer` class to provide timer details for your processor. For example, information about the C or C++ function interface and implementation, frequency, and timer count direction. To provide information about instrumenting C or C++ code for profiling, you can associate the timer details with a `target.Processor` object.

To create a `target.Timer` object, use the `target.create` function. Create the object and then use separate steps to specify properties. Or, using name-value arguments, create the object and specify properties in a single step.

### Properties

#### Name — Timer name

character vector | string

Name of timer.

#### Attributes:

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

#### Direction — Count direction

'Up' | 'Down'

Direction of timer count.

#### Attributes:

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

#### APIImplementation — API implementation

`target.APIImplementation` object

Information about the API implementation, which is used to determine the current time.

If you use name-value arguments to create a `target.Timer` object, for the `APIImplementation` property, specify these arguments.

| Name                 | Description                                                                        |
|----------------------|------------------------------------------------------------------------------------|
| 'FunctionName'       | Required. Name property of <code>target.Function</code> object.                    |
| 'FunctionReturnType' | Required. <code>ReturnType</code> property of <code>target.Function</code> object. |

| Name               | Description                                                        |
|--------------------|--------------------------------------------------------------------|
| 'IncludeFiles'     | Required. IncludeFiles property of target.BuildDependencies object |
| 'FunctionLanguage' | Optional. Language property of target.API object.                  |
| 'SourceFiles'      | Optional. SourceFiles property of target.BuildDependencies object. |
| 'IncludePaths'     | Optional. IncludePaths property of target.BuildDependencies object |

**Attributes:**

GetAccess public  
SetAccess public

**Frequency — Frequency**

scalar

Frequency of the unit returned by the timer function. This value can be used to convert timer function output to seconds. The helper class `target.unit.Frequency` contains some common frequency units.

**Attributes:**

GetAccess public  
SetAccess public

Data Types: uint64

**Examples****Create Timer Object**

Create a timer object for your development computer.

Create the function signature for a timer. In this example, the function returns a uint64 data type and the function name `timestamp_x86`.

```
timerSignature = target.create('Function');
timerSignature.Name = 'timestamp_x86';
timerSignature.ReturnType = 'uint64';
```

Capture the function in an API object.

```
timerApi = target.create('API');
timerApi.Functions = timerSignature;
timerApi.Language = target.Language.C;
timerApi.Name = 'Linux Timer API';
```

Capture the dependencies of the function, that is, the source and header files that are required to run the function.

```
timerDependencies = target.create('BuildDependencies');
timerDependencies.IncludeFiles = {'host_timer_x86.h'};
timerDependencies.IncludePaths = ...
 {'$(MATLAB_ROOT)/toolbox/coder/profile/src'};
timerDependencies.SourceFiles = {'host_timer_x86.c'};
```

Create an object that combines the API and dependencies.

```
timerImplementation = target.create('APIImplementation');
timerImplementation.API = timerApi;
timerImplementation.BuildDependencies = timerDependencies;
timerImplementation.Name = 'Linux Timer Implementation';
```

Create the timer object and associate it with the timer information.

```
timer = target.create('Timer');
timer.APIImplementation = timerImplementation;
timer.Name = 'Linux Timer';
```

---

**Note** Using name-value arguments, you can create the timer object with this command.

```
timer = target.create('Timer', 'Name', 'Linux Timer', ...
 'FunctionName', 'timestamp_x86', ...
 'FunctionReturnType', 'uint64', ...
 'FunctionLanguage', target.Language.C, ...
 'SourceFiles', {'host_timer_x86.c'}, ...
 'IncludeFiles', {'host_timer_x86.h'}, ...
 'IncludePaths', {'$(MATLAB_ROOT)/toolbox/coder/profile/src'})
```

---

Assign the timer and add-ons to the processor object.

```
processor = target.get('Processor', 'Intel-x86-64 (Linux 64)');
processor.Timers = timer;
```

### Create Timer Object by Modifying Existing Object

You can create a new timer object by copying an existing timer object and modifying specific property values of the copy.

```
newTimer = target.create('Timer', ...
 'Copy', 'Linux Timer', ...
 'Name', 'NewTimerName', ...
 'FunctionName', 'newFunctionName');
```

## Version History

Introduced in R2020b

### See Also

[target.create](#) | [target.APIImplementation](#) | [target.Processor](#)

# target.Toolchain class

**Package:** target

Capture high-level information about toolchain

## Description

Use a `target.Toolchain` object to capture high-level information about a toolchain.

To create a `target.Toolchain` object, use the `target.create` function.

## Properties

### Builder — Builder configuration

`target.CMakeBuilder` object

An object that describes the configuration of a build automation tool.

#### Attributes:

|                        |                     |
|------------------------|---------------------|
| <code>GetAccess</code> | <code>public</code> |
| <code>SetAccess</code> | <code>public</code> |

### BuildRequirements — Build dependencies

`target.BuildDependencies` object

C and C++ build dependencies that you must associate with the toolchain. For example, specific preprocessor directives or libraries. When you specify this property, every build that uses the toolchain includes the dependencies.

#### Attributes:

|                        |                     |
|------------------------|---------------------|
| <code>GetAccess</code> | <code>public</code> |
| <code>SetAccess</code> | <code>public</code> |

### EnvironmentConfiguration — Environment configuration

`target.EnvironmentConfiguration` object array

An array of objects that provide system environment setup commands and paths that are required for the use of the toolchain. For example, vendor-supplied setup scripts. Use only one object for each operating system of a development computer.

#### Attributes:

|                        |                     |
|------------------------|---------------------|
| <code>GetAccess</code> | <code>public</code> |
| <code>SetAccess</code> | <code>public</code> |

### HostOperatingSystemSupport — Operating system support

`target.HostOperatingSystemSupport` object

Development computer operating systems that the toolchain can run on.

**Attributes:**

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

**Tools — Toolchain tools**`target.Tool` object array

Tools in the toolchain.

**Attributes:**

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

**SupportedHardware — Supported target devices**`target.HardwareComponentSupport` object array

Optional. Target devices for which the toolchain can build code.

**Attributes:**

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

**Name — Toolchain name**`string`

Name of the toolchain, in a form that you want workflows to display.

Example: 'CMake/Ninja for all hosts'

**Attributes:**

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

## Examples

**Use `target.Toolchain` to Configure CMake Code Build**

This code snippet from “Create Custom CMake Toolchain Definition” shows how you can create a `target.Toolchain` object and use it to configure the way CMake builds generated code.

```
tc = target.create('Toolchain', 'Name', 'Example Custom CMake Toolchain');
tc.Builder = target.create('CMakeBuilder');
tc.Builder.Generator = 'Ninja';
tc.Builder.ToolchainFile = fullfile(pwd, 'ExampleCMakeToolchain.cmake');
```

## Version History

Introduced in R2022b

## See Also

[target.CMake](#) | [target.CMakeBuildType](#) | [target.CMakeBuilder](#) |  
[target.CMakeCacheEntry](#) | [target.EnvironmentConfiguration](#) |  
[target.HardwareComponentSupport](#) | [target.create](#)

## Topics

[“Create Custom CMake Toolchain Definition”](#)

## target.Tools class

**Package:** target

Describe properties of tools for target hardware

### Description

Use the `target.Tools` class to capture properties of tools that enable your development computer to interact with the target hardware.

### Properties

#### DebugTools — Supported debuggers

`target.ApplicationExecutionTool` object vector

Descriptions of debugging tools that are supported for the target hardware.

**Attributes:**

|                        |                     |
|------------------------|---------------------|
| <code>GetAccess</code> | <code>public</code> |
| <code>SetAccess</code> | <code>public</code> |

#### ExecutionTools — Supported execution tools

`target.ApplicationExecutionTool` object vector

Descriptions of supported tools for executing applications on the target hardware.

**Attributes:**

|                        |                     |
|------------------------|---------------------|
| <code>GetAccess</code> | <code>public</code> |
| <code>SetAccess</code> | <code>public</code> |

### Examples

#### PIL Target Connectivity with Debugger

For an example that uses the `target.Tools` class, see “Use Debugger for PIL Target Connectivity” (Embedded Coder).

## Version History

Introduced in R2020b

### See Also

`target.create` | `target.Board`

### Topics

“Use Debugger for PIL Target Connectivity” (Embedded Coder)



# target.UDPChannel class

**Package:** target

Describe UDP communication

## Description

Use the `target.UDPChannel` class, which inherits functionality from `target.CommunicationChannel`, to describe User Datagram Protocol (UDP) communication.

To create a `target.UDPChannel` object, use the `target.create` function.

## Properties

### IPAddress — IP address

character vector | string

IP address of the UDP server.

#### Attributes:

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

### Port — Port

scalar integer

UDP port.

#### Attributes:

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

## Version History

Introduced in R2020b

## See Also

`target.create` | `target.CommunicationChannel` | `target.TargetConnection`

## target.upgrade

**Package:** target

Upgrade existing definitions of hardware devices

### Syntax

```
target.upgrade(upgraderForRegistrationMechanism, pathToRegistrationFile)
target.upgrade(___, Name, Value)
```

### Description

`target.upgrade(upgraderForRegistrationMechanism, pathToRegistrationFile)` uses an upgrade procedure to create objects from data definitions in current artifacts. The function creates `registerUpgradedTargets.m` in the current working folder.

To register the upgraded data definitions with MATLAB, run `registerUpgradedTargets()`.

For persistence across MATLAB sessions, run `registerUpgradedTargets('UserInstall', true)`.

`target.upgrade(___, Name, Value)` specifies additional options using one or more name-value pair arguments.

### Examples

#### Upgrade Hardware Device Data Definitions

For a workflow example that uses the function, see “Upgrade Data Definitions for Hardware Devices”.

### Input Arguments

#### **upgraderForRegistrationMechanism** — Upgrade procedure

'rtwTargetInfo' | 'sl\_customization'

Select upgrade procedure for current registration mechanism.

#### **pathToRegistrationFile** — Full file name

character vector | string

Specify file that contains current registration mechanism.

Example: `target.upgrade('rtwTargetInfo', 'myPath/mySubfolder/rtwTargetInfo.m')`

#### **Name-Value Pair Arguments**

Specify optional pairs of arguments as `Name1=Value1, ..., NameN=ValueN`, where `Name` is the argument name and `Value` is the corresponding value. Name-value arguments must appear after other arguments, but the order of the pairs does not matter.

*Before R2021a, use commas to separate each name and value, and enclose Name in quotes.*

Example: `target.upgrade('rtwTargetInfo', 'myPath/mySubfolder/  
rtwTargetInfo.m', 'ExportFileName', 'myNewFile')`

### **ExportToMATLABFunction — Export to MATLAB**

true (default) | false

- `true` -- Generate a MATLAB function that registers the upgraded definitions using `target.add`.
- `false` -- Do not generate a function.

### **ExportFileName — Generated function file name**

'registerUpgradedTargets.m' (default) | string

If `ExportToMATLABFunction` is `true`, the argument specifies the file name of the generated MATLAB function. Otherwise, the argument is ignored.

### **Overwrite — Overwrite existing file**

false (default) | true

- `true` -- If the file specified by `ExportFileName` exists, overwrite the file.
- `false` -- If the file specified by `ExportFileName` exists, the function produces an error.

If `ExportToMATLABFunction` is `false`, the argument is ignored.

## **Version History**

**Introduced in R2019b**

### **See Also**

`target.add` | `target.create`

### **Topics**

“Register New Hardware Devices”

## target.XCP class

**Package:** target

Describe XCP protocol stack for target hardware

### Description

Use the `target.XCP` class to describe the XCP protocol stack for the target hardware.

To create a `target.XCP` object, use the `target.create` function. Create the object and then use separate steps to specify properties. Or, using name-value arguments, create the object and specify properties in a single step.

### Properties

#### XCPTransport — XCP transport protocol

`target.XCPTransport` object

Specify the XCP transport protocol layer through a `target.XCPTCIPTransport` or a `target.XCPSerialTransport` object.

##### Attributes:

|                        |                     |
|------------------------|---------------------|
| <code>GetAccess</code> | <code>public</code> |
| <code>SetAccess</code> | <code>public</code> |

#### XCPPlatformAbstraction — XCP platform abstraction

`target.XCPPlatformAbstraction` object

Optional property to specify the XCP platform abstraction layer. If you do not specify a value, the software uses the default platform abstraction layer, which supports Linux, Windows, and Mac platforms.

##### Attributes:

|                        |                     |
|------------------------|---------------------|
| <code>GetAccess</code> | <code>public</code> |
| <code>SetAccess</code> | <code>public</code> |

### Examples

#### XCP Protocol Stack for Target Hardware

This code snippet from “Customise Connectivity for XCP External Mode Simulations” shows how you can provide a description of the XCP protocol stack for your target hardware.

```
xcpPlatformAbstraction = target.create('XCPPlatformAbstraction', ...
 'Name', 'XCP Platform Abstraction');

customPlatformAbstractionPath = 'pathToImplementationFolder';
xcpPlatformAbstraction.BuildDependencies.SourceFiles = ...
 {fullfile(customPlatformAbstractionPath, 'myXCPPlatform.c')};
xcpPlatformAbstraction.BuildDependencies.IncludePaths = ...
```

```
 {customPlatformAbstractionPath};
xcpTransport = target.create('XCPTCP/IPTransport', ...
 'Name', 'XCP Transport');
xcpConfiguration = target.create('XCP', ...
 'Name', 'XCP Configuration', ...
 'XCPTransport', xcpTransport, ...
 'XCPPlatformAbstraction', xcpPlatformAbstraction);
```

---

**Note** You can create the `target.XCP` object in a single step.

```
xcpConfiguration = target.create('XCP', ...
 'Name', 'XCP TCP/IP Configuration', ...
 'XCPTransportLayer', 'TCP', ...
 'SourceFiles', {fullfile('pathToImplementationFolder', 'myXCPPlatform.c')}, ...
 'IncludePaths', {'pathToImplementationFolder'});
```

---

## Version History

Introduced in R2021a

### See Also

[target.create](#) | [target.XCPTransport](#) | [target.XCPPlatformAbstraction](#)

### Topics

“Customise Connectivity for XCP External Mode Simulations”

## target.XCPExternalModeConnectivity class

**Package:** target

Represent connectivity options in external mode protocol stack

### Description

Use the `target.XCPExternalModeConnectivity` class, which is derived from `target.ExternalModeConnectivity`, to represent XCP connectivity options in the external mode protocol stack.

To create a `target.XCPExternalModeConnectivity` object, use the `target.create` function. Create the object and then use separate steps to specify properties. Or, using name-value arguments, create the object and specify properties in a single step.

### Properties

#### XCP — XCP configuration

`target.XCP` object

Specify XCP protocol stack for target hardware.

### Examples

#### Specify External Mode Protocol Stack for Target Hardware

This code snippet from “Customise Connectivity for XCP External Mode Simulations” shows how to specify the external mode protocol stack for your target hardware.

```
xcpPlatformAbstraction = target.create('XCPPlatformAbstraction', ...
 'Name', 'XCP Platform Abstraction');

xcpPlatformAbstraction.BuildDependencies.Defines = {'XCP_CUSTOM_PLATFORM'};
customPlatformAbstractionPath = 'pathToImplementationFolder';
xcpPlatformAbstraction.BuildDependencies.SourceFiles = ...
 {fullfile(customPlatformAbstractionPath, 'myXCPPlatform.c')};
xcpPlatformAbstraction.BuildDependencies.IncludePaths = ...
 {customPlatformAbstractionPath};

xcpTransport = target.create('XCPTCPIPTransport', ...
 'Name', 'XCP Transport');

xcpConfiguration = target.create('XCP', ...
 'Name', 'XCP Configuration', ...
 'XCPTransport', xcpTransport, ...
 'XCPPlatformAbstraction', xcpPlatformAbstraction);

extModeTCPConnectivity = ...
 target.create('XCPExternalModeConnectivity', ...
 'Name', 'External Mode TCP Connectivity', ...
 'XCP', xcpConfiguration);

externalMode = target.create('ExternalMode', ...
 'Name', 'External Mode', ...
 'Connectivities', extModeTCPConnectivity);
```

```
board.CommunicationProtocolStacks = externalMode;
```

---

**Note** You can create the `target.XCPExternalModeConnectivity` object in a single step.

```
extModeTCPConnectivity = target.create('XCPExternalModeConnectivity', ...
 'Name', 'External Mode TCP Connectivity', ...
 'XCPTransportLayer', 'TCP', ...
 'Defines', {'XCP_CUSTOM_PLATFORM'}, ...
 'SourceFiles', {fullfile('pathToImplementationFolder', 'myXCPPlatform.c')}, ...
 'IncludePaths', {'pathToImplementationFolder'});
```

---

## Version History

Introduced in R2021a

### See Also

`target.create` | `target.ExternalMode`

### Topics

“Customise Connectivity for XCP External Mode Simulations”

## target.XCPPlatformAbstraction class

**Package:** target

Specify XCP platform abstraction layer for target hardware

### Description

Use the `target.XCPPlatformAbstraction` class to specify the implementation of the “XCP Platform Abstraction Layer” for your target hardware. The layer provides:

- The implementation of a static memory allocator -- see “Memory Allocator”.
- Other target hardware-specific functionality -- see “Other Platform Abstraction Layer Functionality”.

To create a `target.XCPPlatformAbstraction` object, use the `target.create` function. Create the object and then use separate steps to specify properties. Or, using name-value arguments, create the object and specify properties in a single step.

If you do not create a `target.XCPPlatformAbstraction` object, the software uses the default platform abstraction layer, which supports Linux, Windows, and Mac platforms.

### Properties

#### BuildDependencies — Platform abstraction layer build dependencies

`target.BuildDependencies` object

Specify preprocessor directives, source files, and header files that are required for the implementation of the XCP platform abstraction layer.

#### Attributes:

|           |        |
|-----------|--------|
| GetAccess | public |
| SetAccess | public |

### Examples

#### Specify Communication Protocol Stack for Target Hardware

This code snippet from “Customise Connectivity for XCP External Mode Simulations” shows how to specify and use a custom implementation of the XCP platform abstraction layer.

```
xcpPlatformAbstraction = target.create('XCPPlatformAbstraction', ...
 'Name', 'XCP Platform Abstraction');

customPlatformAbstractionPath = 'pathToImplementationFolder';
xcpPlatformAbstraction.BuildDependencies.SourceFiles = ...
 {fullfile(customPlatformAbstractionPath, 'myXCPPlatform.c')};
xcpPlatformAbstraction.BuildDependencies.IncludePaths = ...
 {customPlatformAbstractionPath};

xcpTCPIPTransport = target.create('XCPTCPIPTransport', ...
 'Name', 'XCP TCPIP Transport');
```



```
xcpTCPIPConfiguration = target.create('XCP', ...
 'Name', 'XCP TCP/IP Configuration', ...
 'XCPTransport', xcpTCPIPTransport, ...
 'XCPPlatformAbstraction', xcpPlatformAbstraction);
```

---

**Note** You can create the `target.XCPPlatformAbstraction` object in a single step.

```
xcpPlatformAbstraction = target.create('XCPPlatformAbstraction', ...
 'Name', 'XCP Platform Abstraction', ...
 'SourceFiles', {fullfile('pathToImplementationFolder', 'myXCPPlatform.c')}, ...
 'IncludePaths', {'pathToImplementationFolder'});
```

---

## Version History

Introduced in R2021a

### See Also

`target.create` | `target.XCP`

### Topics

“Customise Connectivity for XCP External Mode Simulations”

## target.XCPTCPIPTransport class

**Package:** target

Represent XCP TCP/IP transport protocol layer

### Description

Use the `target.XCPTCPIPTransport` class, which inherits functionality from `target.XCPTTransport`, to represent the XCP TCP/IP transport protocol layer for your target hardware.

### Examples

#### XCP Protocol Stack for Target Hardware

This code snippet shows how you can use the `target.XCPTCPIPTransport` class to represent the XCP TCP/IP transport protocol layer for your target hardware.

```
xcpTCPIPTransport = ...
 target.create('XCPTCPIPTransport', ...
 'Name', 'XCP TCPIP Transport');
```

### Version History

Introduced in R2021a

### See Also

`target.create` | `target.XCP` | `target.XCPTTransport`

### Topics

“Customise Connectivity for XCP External Mode Simulations”

# target.XCPTransport class

**Package:** target

Base class for XCP transport protocol layer

## Description

The target.XCPTransport class is a base class for representing the XCP transport protocol layer on the target hardware. The target.XCPTCPIPTransport and target.XCPSerialTransport classes are derived from this class.

## Class Attributes

|                  |      |
|------------------|------|
| Abstract         | true |
| HandleCompatible | true |

For information on class attributes, see “Class Attributes”.

## Version History

**Introduced in R2021a**

## See Also

target.create | target.XCPTCPIPTransport | target.XCPSerialTransport

## Topics

“Customise Connectivity for XCP External Mode Simulations”

## target.XCPSerialTransport class

**Package:** target

Represent XCP serial transport protocol layer

### Description

Use the `target.XCPSerialTransport` class, which inherits functionality from `target.XCPTransport`, to represent the XCP serial transport protocol layer for your target hardware.

### Examples

#### XCP Serial Transport

This code snippet shows how you can use the `target.XCPSerialTransport` class to represent the XCP serial transport protocol layer for your target hardware.

```
xcpSerialTransport = ...
 target.create('XCPSerialTransport', ...
 'Name', 'XCP Serial Transport');
```

### Version History

Introduced in R2021a

### See Also

`target.create` | `target.XCP` | `target.XCPTransport`

### Topics

“Customise Connectivity for XCP External Mode Simulations”

# updateFilePathsAndExtensions

Update files in build information with missing paths and file extensions

## Syntax

```
updateFilePathsAndExtensions(buildinfo,extensions)
```

## Description

`updateFilePathsAndExtensions(buildinfo,extensions)` specifies the file name extensions (file types) to include in search and update processing.

Using paths from the build information, the `updateFilePathsAndExtensions` function checks whether file references in the build information require an updated path or file extension. Use this function to:

- Maintain build information for a toolchain that requires the use of file extensions.
- Update multiple customized instances of build information for a given model.

If you use `updateFilePathsAndExtensions`, you call it after you add files to the build information. This approach minimizes the potential performance impact of the required disk I/O.

## Examples

### Update File Paths and Extensions in Build Information

In your working folder, create the folder path `etcproj/etc`, add files `etc.c`, `test1.c`, and `test2.c` to the folder `etc`. For this example, the working folder is `w:\work\BuildInfo`. From the working folder, update build information `myBuildInfo` with missing paths or file extensions.

```
myBuildInfo = RTW.BuildInfo;
addSourcePaths(myBuildInfo,fullfile(pwd, ...
 'etcproj','/etc'),'test');
addSourceFiles(myBuildInfo,{'etc' 'test1' ...
 'test2'},',' 'test');
before = getSourceFiles(myBuildInfo,true,true);
```

```
>> before
```

```
before =
```

```
 '\etc' '\test1' '\test2'
```

```
updateFilePathsAndExtensions(myBuildInfo);
after = getSourceFiles(myBuildInfo,true,true);
```

```
>> after{:}
```

```
ans =
 'w:\work\BuildInfo\etcproj\etc\etc.c'

ans =
 'w:\work\BuildInfo\etcproj\etc\test1.c'

ans =
 'w:\work\BuildInfo\etcproj\etc\test2.c'
```

## Input Arguments

**buildinfo** — Name of build information object returned by `RTW.BuildInfo` object

**extensions** — File name extensions to include in search and update processing

' .c ' (default) | cell array of character vectors | string

The *extensions* argument specifies the file name extensions (file types) to include in search and update processing. The function checks files and updates paths and extensions based on the order in which you list the extensions in the cell array. For example, if you specify { ' .c ' ' .cpp ' } and a folder contains `myfile.c` and `myfile.cpp`, an instance of `myfile` is updated to `myfile.c`.

Example: ' .c ' ' .cpp '

## Version History

Introduced in R2006a

### See Also

`addIncludeFiles` | `addIncludePaths` | `addSourceFiles` | `addSourcePaths` | `updateFileSeparator`

### Topics

“Customize Post-Code-Generation Build Processing”

# updateFileSeparator

Update file separator character for file lists in build information

## Syntax

```
updateFileSeparator(buildinfo,separator)
```

## Description

`updateFileSeparator(buildinfo,separator)` changes instances of the current file separator (/ or \) in the build information to the specified file separator.

The default value for the file separator matches the value returned by the MATLAB command `filesep`. For template makefile (TMF) approach builds, you can override the default by defining a separator with the `MAKEFILE_FILESEP` macro in the template makefile. If the `GenerateMakefile` parameter is set, the code generator overrides the default separator and updates the build information after evaluating the `PostCodeGenCommand` configuration parameter.

## Examples

### Update File Separator in Build Information

Update object `myBuildInfo` to apply the Windows file separator.

```
myBuildInfo = RTW.BuildInfo;
updateFileSeparator(myBuildInfo, '\');
```

## Input Arguments

### **buildinfo** — RTW.BuildInfo object

object

RTW.BuildInfo object that contains information for compiling and linking generated code.

### **separator** — File separator character for path specifications in the build information

'\ ' | '/'

The separator argument specifies the file separator \ (Windows) or / (UNIX®) to use in file path specifications in the build information.

Example: '\'

## Version History

Introduced in R2006a

**See Also**

[addIncludeFiles](#) | [addIncludePaths](#) | [addSourceFiles](#) | [addSourcePaths](#) | [updateFilePathsAndExtensions](#)

**Topics**

“Customize Post-Code-Generation Build Processing”



# Simulink Coder Blocks

---

## Async Interrupt

Generate Versa Module Eurocard (VME) interrupt service routines (ISRs) that execute downstream subsystems or Task Sync blocks

**Library:** Simulink Coder / Asynchronous / Interrupt Templates



### Description

For each specified VME interrupt level in the example RTOS (VxWorks®), the Async Interrupt block generates an interrupt service routine (ISR) that calls one of the following:

- A function call subsystem
- A Task Sync block
- A Stateflow chart configured for a function call input event

---

**Note** Use the blocks in the Interrupt Templates block library (Async Interrupt and Task Sync) for simulation and code generation. These blocks provide starting point examples to help you develop custom blocks for a target environment.

---

### Assumptions and Limitations

- The block supports VME interrupts 1 through 7.
- The block uses these RTOS (VxWorks) system calls:
  - `sysIntEnable`
  - `sysIntDisable`
  - `intConnect`
  - `intLock`
  - `intUnlock`
  - `tickGet`

### Performance Considerations

Execution of large subsystems at interrupt level can have a significant impact on interrupt response time for interrupts of equal and lower priority in the system. Usually, it is best to keep ISRs as short as possible. Connect only function-call subsystems that contain a few blocks to an Async Interrupt block.

A better solution for large subsystems is using the Task Sync block to synchronize the execution of the function-call subsystem to an RTOS task. Place the Task Sync block between the Async Interrupt block and the function-call subsystem. The Async Interrupt block then uses the Task Sync block as the ISR. The ISR releases a synchronization semaphore (performs a `semGive`) to the task, and returns immediately from interrupt level. The example RTOS (VxWorks) then schedules and runs the task. See the description of the Task Sync block.

## Ports

### Input

#### Input — Simulated interrupt source

scalar | vector

A simulated interrupt source, specified as a scalar or vector.

### Output

#### Output — Control signal

scalar | vector

Control signals for these model elements, specified as a scalar or vector:

- Function-call subsystem
- Task Sync block
- Stateflow chart configured for a function call input event

## Parameters

#### VME interrupt number(s) — VME interrupt numbers for the interrupts to be installed

[1 2] (default) | integer array

An array of VME interrupt numbers for the interrupts to be installed. The valid range is 1 . . 7.

The width of the Async Interrupt block output signal corresponds to the number of VME interrupt numbers specified.

---

**Note** A model can contain more than one Async Interrupt block. However, if you use more than one Async Interrupt block, do not duplicate the VME interrupt numbers specified in each block.

---

#### VME interrupt vector offset(s) — Interrupt vector offset numbers corresponding to the VME interrupt numbers

[192 193] (default) | integer array

An array of unique interrupt vector offset numbers corresponding to the VME interrupt numbers entered for parameter **VME interrupt number(s)**. The Stateflow software passes the offsets to the RTOS (VxWorks) call `intConnect(INUM_TO_IVEC(offset), . . .)`.

#### Simulink task priority(s) — Priority of downstream blocks

[10 11] (default) | integer array

The Simulink priority of downstream blocks. Each output of the Async Interrupt block drives a downstream block (for example, a function-call subsystem). Specify an array of priorities corresponding to the VME interrupt numbers that you specify for parameter **VME interrupt number(s)**.

Parameter **Simulink task priority** values are required to generate a rate transition code (see “Rate Transitions and Asynchronous Blocks”). Simulink task priority values are also required to maintain

absolute time integrity when the asynchronous task must obtain real time from its base rate or its caller. The assigned priorities typically are higher than the priorities assigned to periodic tasks.

---

**Note** The Simulink software does not simulate asynchronous task behavior. The task priority of an asynchronous task is for code generation purposes only and is not honored during simulation.

---

#### **Preemption flag(s); preemptable-1; non-preemptable-0 — Selects preemption**

[0 1] (default) | integer array

Set this option to 1 if an output signal of the Async Interrupt block drives a Task Sync block.

Higher priority interrupts can preempt lower priority interrupts in the example RTOS (VxWorks). To lock out interrupts during the execution of an ISR, set the pre-emption flag to 0. This setting causes generation of `intLock()` and `intUnlock()` calls at the beginning and end of the ISR code. Use interrupt locking carefully, as it increases the interrupt response time of the system for interrupts at the `intLockLevelSet()` level and below. Specify an array of flags corresponding to the VME interrupt numbers entered for parameter **VME interrupt number(s)**.

---

**Note** The number of elements in the arrays specifying parameters **VME interrupt vector offset(s)** and **Simulink task priority** must match the number of elements in the array specified for parameter **VME interrupt number(s)**.

---

#### **Manage own timer — Select timer manager**

on (default) | off

If selected, the ISR generated by the Async Interrupt block manages its own timer by reading absolute time from the hardware timer. Specify the size of the hardware timer with parameter **Timer size**.

#### **Timer resolution (seconds) — Resolution of ISR timer**

1/60 (default)

The resolution of the ISRs timer. ISRs generated by the Async Interrupt block maintain their own absolute time counters. By default, these timers obtain their values from the RTOS (VxWorks) kernel by using the `tickGet` call. Parameter **Timer resolution** determines the resolution of these counters. The default resolution is 1/60 second. The `tickGet` resolution for your board support package (BSP) can be different. Determine the `tickGet` resolution for your BSP and enter it for parameter **Timer resolution**.

If you are targeting an RTOS other than the example RTOS (VxWorks), replace the `tickGet` call with an equivalent call to the target RTOS. Or, generate code to read the timer register on the target hardware. For more information, see “Timers in Asynchronous Tasks” and “Async Interrupt Block Implementation”.

#### **Timer size — Number of bits to store the clock tick**

32bits (default) | 16bits | 8bits | auto

The number of bits to store the clock tick for a hardware timer. The ISR generated by the Async Interrupt block uses the timer size when you select parameter **Manage own timer**. The size can be 32bits (the default), 16bits, 8bits, or auto. If you select auto, the code generator determines

the timer size based on the settings of parameters **Application lifespan (days)** and **Timer resolution**.

By default, timer values are stored as 32-bit integers. When parameter **Timer size** is set to **auto**, you can indirectly control the word size of the counters by setting parameter **Application lifespan (days)**. If you set **Application lifespan (days)** to a value that is too large for the code generator to handle as a 32-bit integer of the specified resolution, the code generator uses a second 32-bit integer to address overflows.

For more information, see “Control Memory Allocation for Time Counters”. See also “Timers in Asynchronous Tasks”.

### **Enable simulation input – Select add simulation input port**

on (default) | off

If selected, the Simulink software adds an input port to the Async Interrupt block. This port is for simulation only. Connect one or more simulated interrupt sources to the simulation input.

---

**Note** Before generating code, consider removing blocks that drive the simulation input to prevent the blocks from contributing to the generated code. Alternatively, you can use the Variant Source block with the **Variant control mode** parameter set to **sim codegen switching**, as explained in “Dual-Model Approach: Code Generation”. If you use the Variant Source block, the sample times of driving blocks contribute to the sample times supported in the generated code.

---

## **Version History**

**Introduced in R2006a**

### **See Also**

Task Sync

### **Topics**

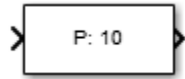
“Asynchronous Events”

“Asynchronous Events”

## Asynchronous Task Specification

Specify priority of asynchronous task represented by referenced model triggered by asynchronous interrupt

**Library:** Simulink Coder / Asynchronous



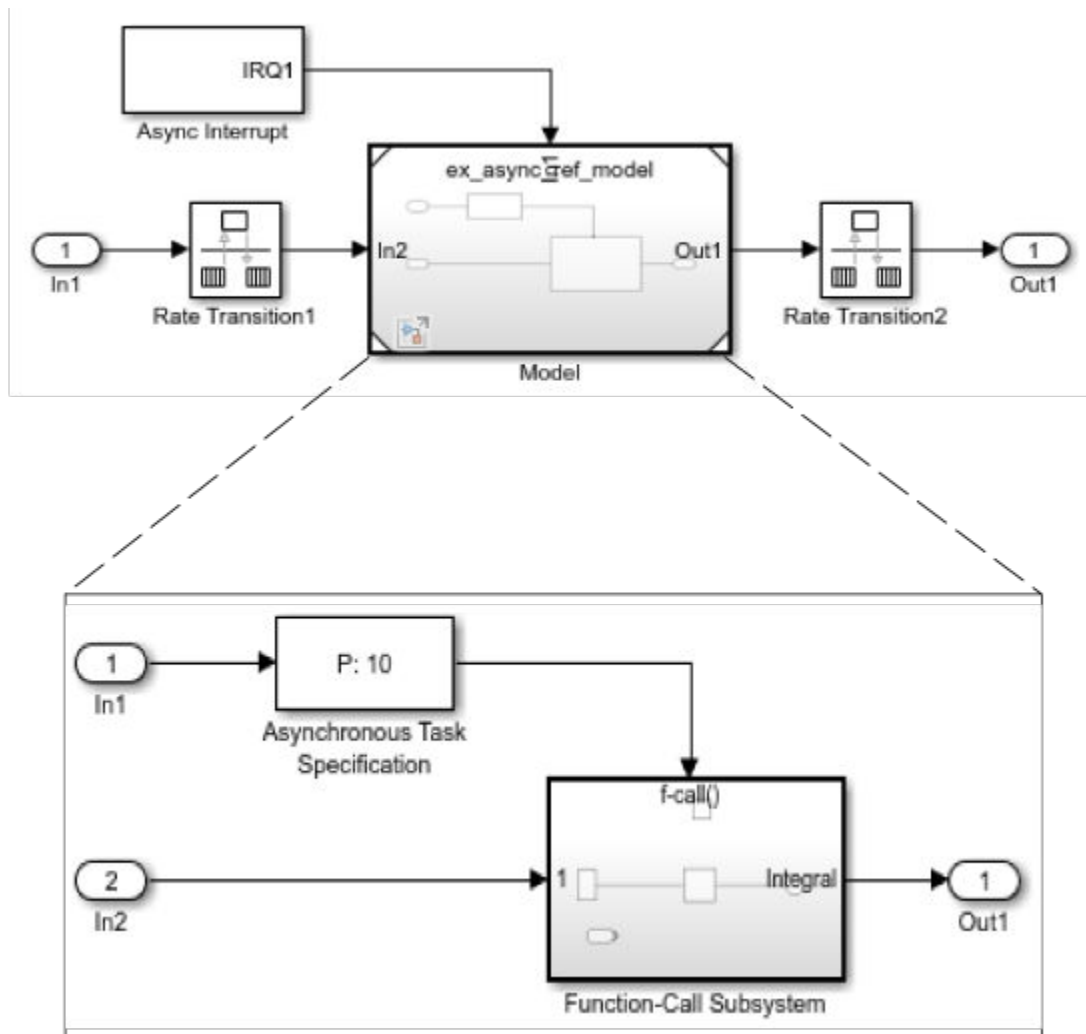
### Description

The Asynchronous Task Specification block specifies parameters, such as the task priority, of an asynchronous task represented by a function-call subsystem with a trigger from an asynchronous interrupt. Use this block to control scheduling of function-call subsystems with triggers from asynchronous events. You control the scheduling by assigning a priority to each function-call subsystem within a referenced model.

To use this block, follow the procedure in “Convert an Asynchronous Subsystem into a Model Reference”.

Observe in the figure:

- The block must reside in a referenced model between a root-level Inport block and a function-call subsystem. The Asynchronous Task Specification block must immediately follow and connect directly to the Inport block. The combination of these two blocks constitutes the modeling style known as JMAAB-B.
- The Inport block must receive an interrupt signal from an Async Interrupt block that is in the parent model.
- The Inport block must be configured to receive and send function-call trigger signals.



## Ports

### Input

#### Port\_1 – Interrupt input signal

scalar

Interrupt input signal received from a root-level Inport block.

### Output

#### Port\_1 – Interrupt signal with priority

scalar

Interrupt signal with specified task priority that triggers a function-call subsystem.

## Parameters

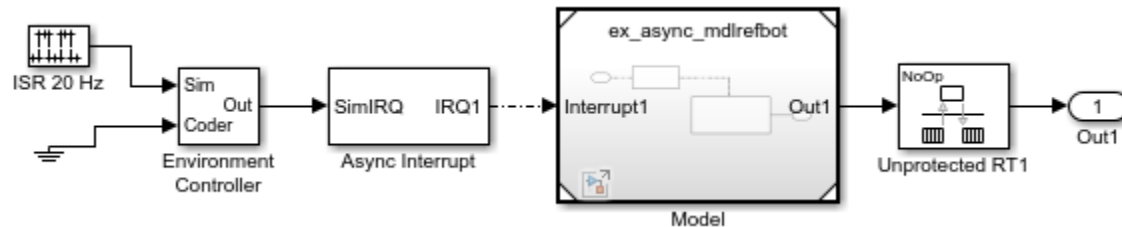
### Task priority – Priority of asynchronous task that calls function-call subsystem

10 (default)

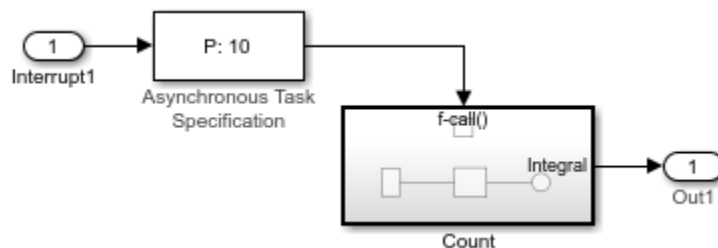
Specify an integer or [] as the priority of the asynchronous task that calls the connected function-call subsystem. The priority must be a value that generates relevant rate transition behaviors.

- If you specify an integer, it must match the priority value of the interrupt signal initiator in the parent model.
- If you specify [], the priority does not have to match the priority of the interrupt signal initiator in the top model. The rate transition algorithm is conservative (not optimized). The priority is unknown but static.

Consider the following model.



The referenced model has the following content.



If the **Task priority** parameter is set to 10, the Async Interrupt block in the parent model must also have a priority of 10. If the parameter is set to [], the priority of the Async Interrupt block can be a value other than 10.

## Version History

Introduced in R2011a

### See Also

#### Blocks

Inport | Function-Call Subsystem

#### Topics

“Asynchronous Events”

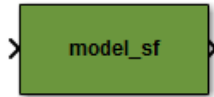


“Spawn and Synchronize Execution of RTOS Task”  
“Pass Asynchronous Events in RTOS as Input to a Referenced Model”  
“Convert an Asynchronous Subsystem into a Model Reference”  
“Rate Transitions and Asynchronous Blocks”  
“Asynchronous Support”  
“Asynchronous Events”  
“Model References”

## Generated S-Function

Represent model or subsystem as generated S-function code

**Library:** Simulink Coder / S-Function Target



### Description

An instance of the Generated S-Function block represents code that the code generator produces from its S-function system target file for a model or subsystem.

### Requirements

- The S-Function block must perform identically to the model or subsystem from which it was generated.
- Before creating the block, explicitly specify Inport block signal attributes, such as signal widths or sample times. The sole exception to this rule concerns sample times, as described in “Sample Time Propagation in Generated S-Functions”.
- Set the solver parameters of the Generated S-Function block to be the same as the parameters of the original model or subsystem. The generated S-function code operates identically to the original subsystem. For an exception to this rule, see “Solver Type for Top Models with Generated S-Functions”.

### Ports

#### Input

##### Input — S-function input

varies

See requirements.

#### Output Arguments

##### Output — S-function output

varies

See requirements.

### Parameters

#### Generated S-function name (model\_sf) — Name of S-function

model\_sf (default) | character vector

The name of the generated S-function. The code generator derives the name by appending `_sf` to the name of the model or subsystem from which the block is generated.

**Show module list — Select display module list**

off (default) | on

If selected, displays modules generated for the S-function.

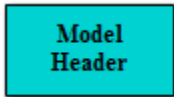
**Version History****Introduced in R2011b****See Also****Topics**

“Use S-Function Target for Model or Subsystem”

## Model Header

Specify external header code

**Library:** Simulink Coder / Custom Code



### Description

For a model that includes the Model Header block, the code generator adds external code that you specify to the header file (*model.h*) that it generates. You can specify code for the code generator to add near the top and bottom of the header file.

If you include this block in a referenced model, the code generator ignores the block for simulation target builds, but processes the block for other system target files.

---

**Note** This block is intended to address special case requirements for inserting custom code into the generated code. See the C Caller and C Function blocks, which are more typically used for integrating custom algorithmic code into a model.

---

### Parameters

#### **Top of Model Header — Code to add near top of generated header file**

no default

Specify code that you want the code generator to add near the top of the header file for the model. The code generator places the code in the section labeled `user_code (top of header file)`.

#### **Bottom of Model Header — Code to add at bottom of generated header file**

no default

Specify code that you want the code generator to add at the bottom of the header file for the model. The code generator places the code in the section labeled `user_code (bottom of header file)`.

## Version History

Introduced in R2006a

### See Also

[Model Source](#) | [System Derivatives](#) | [System Disable](#) | [System Enable](#) | [System Initialize](#) | [System Outputs](#) | [System Start](#) | [System Terminate](#) | [System Update](#)

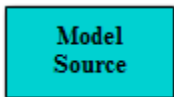
### Topics

“Place External C/C++ Code in Generated Code”

# Model Source

Specify external source code

**Library:** Simulink Coder / Custom Code



## Description

For a model that includes the Model Source block, the code generator adds external code that you specify to the source file (*model.c* or *model.cpp*) that it generates. You can specify code for the code generator to add near the top and bottom of the source file.

If you include this block in a referenced model, the code generator ignores the block for simulation target builds, but processes the block for other system target files.

---

**Note** This block is intended to address special case requirements for inserting custom code into the generated code. See the C Caller and C Function blocks, which are more typically used for integrating custom algorithmic code into a model.

---

## Parameters

### Top of Model Source — Code to add near top of generated source file

no default

Specify code that you want the code generator to add near the top of the source file for the model. The code generator places the code in the section labeled `user code (top of source file)`.

### Bottom of Model Source — Code to add at bottom of generated source file

no default

Specify code that you want the code generator to add at the bottom of the source file for the model. The code generator places the code in the section labeled `user code (bottom of source file)`.

## Version History

Introduced in R2006a

## See Also

Model Header | System Derivatives | System Disable | System Enable | System Initialize | System Outputs | System Start | System Terminate | System Update

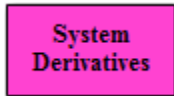
## Topics

“Place External C/C++ Code in Generated Code”

# System Derivatives

Specify external system derivative code

**Library:** Simulink Coder / Custom Code



## Description

For a model or nonvirtual subsystem that includes the System Derivatives block and a block that computes continuous states, the code generator adds external code, which you specify, to the `SystemDerivatives` function that it generates. You can specify code for the code generator to add to the declaration, execution, and exit sections of the function code.

If you include this block in a referenced model, the code generator ignores the block for simulation target builds, but processes the block for other system target files.

---

**Note** This block is intended to address special case requirements for inserting custom code into the generated code. See the C Caller and C Function blocks, which are more typically used for integrating custom algorithmic code into a model.

---

## Parameters

### **System Derivatives Function Declaration Code — Code to add to the declaration section of the generated function**

no default

Specify code that you want the code generator to add to the declaration section of the `SystemDerivatives` function for the model or subsystem.

### **System Derivatives Function Execution Code — Code to add to the execution section of the generated function**

no default

Specify code that you want the code generator to add to the execution section of the `SystemDerivatives` function for the model or subsystem.

### **System Derivatives Function Exit Code — Code to add to the exit section of the generated function**

no default

Specify code that you want the code generator to add to the exit section of the `SystemDerivatives` function for the model or subsystem.

## Version History

Introduced in R2006a

## **See Also**

Model Header | Model Source | System Disable | System Enable | System Initialize | System Outputs | System Start | System Terminate | System Update

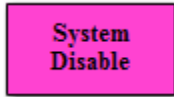
## **Topics**

“Place External C/C++ Code in Generated Code”

## System Disable

Specify external system disable code

**Library:** Simulink Coder / Custom Code



### Description

For a model or nonvirtual subsystem that includes the System Disable block and a block that uses a SystemDisable function, the code generator adds external code, which you specify, to the SystemDisable function that it generates. You can specify code for the code generator to add to the declaration, execution, and exit sections of the function code.

If you include this block in a referenced model, the code generator ignores the block for simulation target builds, but processes the block for other system target files.

---

**Note** This block is intended to address special case requirements for inserting custom code into the generated code. See the C Caller and C Function blocks, which are more typically used for integrating custom algorithmic code into a model.

---

### Parameters

#### **System Disable Function Declaration Code — Code to add to the declaration section of the generated function**

no default

Specify code that you want the code generator to add to the declaration section of the SystemDisable function for the model or subsystem.

#### **System Disable Function Execution Code — Code to add to the execution section of the generated function**

no default

Specify code that you want the code generator to add to the execution section of the SystemDisable function for the model or subsystem.

#### **System Disable Function Exit Code — Code to add to the exit section of the generated function**

no default

Specify code that you want the code generator to add to the exit section of the SystemDisable function for the model or subsystem.

### Version History

**Introduced in R2006a**



## **See Also**

Model Header | Model Source | System Derivatives | System Enable | System Initialize | System Outputs | System Start | System Terminate | System Update

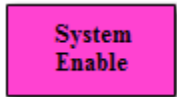
## **Topics**

“Place External C/C++ Code in Generated Code”

## System Enable

Specify external system enable code

**Library:** Simulink Coder / Custom Code



### Description

For a model or nonvirtual subsystem that includes the System Enable block and a block that uses a SystemEnable function, the code generator adds external code, which you specify, to the SystemEnable function that it generates. You can specify code for the code generator to add to the declaration, execution, and exit sections of the function code.

If you include this block in a referenced model, the code generator ignores the block for simulation target builds, but processes the block for other system target files.

---

**Note** This block is intended to address special case requirements for inserting custom code into the generated code. See the C Caller and C Function blocks, which are more typically used for integrating custom algorithmic code into a model.

---

### Parameters

#### **System Enable Function Declaration Code — Code to add to the declaration section of the generated function**

no default

Specify code that you want the code generator to add to the declaration section of the SystemEnable function for the model or subsystem.

#### **System Enable Function Execution Code — Code to add to the execution section of the generated function**

no default

Specify code that you want the code generator to add to the execution section of the SystemEnable function for the model or subsystem.

#### **System Enable Function Exit Code — Code to add to the exit section of the generated function**

no default

Specify code that you want the code generator to add to the exit section of the SystemEnable function for the model or subsystem.

### Version History

**Introduced in R2006a**

## **See Also**

Model Header | Model Source | System Derivatives | System Disable | System Initialize | System Outputs | System Start | System Terminate | System Update

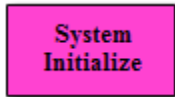
## **Topics**

“Place External C/C++ Code in Generated Code”

## System Initialize

Specify external system initialization code

**Library:** Simulink Coder / Custom Code



### Description

For a model or nonvirtual subsystem that includes the System Initialize block and a block that uses a `SystemInitialize` function, the code generator adds external code, which you specify, to the `SystemInitialize` function that it generates. You can specify code for the code generator to add to the declaration, execution, and exit sections of the function code.

If you include this block in a referenced model, the code generator ignores the block for simulation target builds, but processes the block for other system target files.

---

**Note** This block is intended to address special case requirements for inserting custom code into the generated code. See the C Caller and C Function blocks, which are more typically used for integrating custom algorithmic code into a model.

---

### Parameters

#### **System Initialize Function Declaration Code — Code to add to the declaration section of the generated function**

no default

Specify code that you want the code generator to add to the declaration section of the `SystemInitialize` function for the model or subsystem.

#### **System Initialize Function Execution Code — Code to add to the execution section of the generated function**

no default

Specify code that you want the code generator to add to the execution section of the `SystemInitialize` function for the model or subsystem.

#### **System Initialize Function Exit Code — Code to add to the exit section of the generated function**

no default

Specify code that you want the code generator to add to the exit section of the `SystemInitialize` function for the model or subsystem.

### Version History

**Introduced in R2006a**

## **See Also**

Model Header | Model Source | System Derivatives | System Disable | System Enable | System Outputs | System Start | System Terminate | System Update

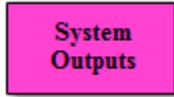
## **Topics**

“Place External C/C++ Code in Generated Code”

## System Outputs

Specify external system outputs code

**Library:** Simulink Coder / Custom Code



### Description

For a model or nonvirtual subsystem that includes the System Outputs block and a block that uses a SystemOutputs function, the code generator adds external code, which you specify, to the SystemOutputs function that it generates. You can specify code for the code generator to add to the declaration, execution, and exit sections of the function code.

If you include this block in a referenced model, the code generator ignores the block for simulation target builds, but processes the block for other system target files.

---

**Note** This block is intended to address special case requirements for inserting custom code into the generated code. See the C Caller and C Function blocks, which are more typically used for integrating custom algorithmic code into a model.

---

### Parameters

#### **System Outputs Function Declaration Code — Code to add to the declaration section of the generated function**

no default

Specify code that you want the code generator to add to the declaration section of the SystemOutputs function for the model or subsystem.

#### **System Outputs Function Execution Code — Code to add to the execution section of the generated function**

no default

Specify code that you want the code generator to add to the execution section of the SystemOutputs function for the model or subsystem.

#### **System Outputs Function Exit Code — Code to add to the exit section of the generated function**

no default

Specify code that you want the code generator to add to the exit section of the SystemOutputs function for the model or subsystem.

### Version History

**Introduced in R2006a**

**See Also**

Model Header | Model Source | System Derivatives | System Disable | System Enable | System Initialize | System Start | System Terminate | System Update

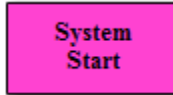
**Topics**

“Place External C/C++ Code in Generated Code”

## System Start

Specify external system startup code

**Library:** Simulink Coder / Custom Code



### Description

For a model or nonvirtual subsystem that includes the System Start block and a block that uses a SystemStart function, the code generator adds external code, which you specify, to the SystemStart function that it generates. You can specify code for the code generator to add to the declaration, execution, and exit sections of the function code.

If you include this block in a referenced model, the code generator ignores the block for simulation target builds, but processes the block for other system target files.

---

**Note** This block is intended to address special case requirements for inserting custom code into the generated code. See the C Caller and C Function blocks, which are more typically used for integrating custom algorithmic code into a model.

---

### Parameters

#### **System Start Function Declaration Code — Code to add to the declaration section of the generated function**

no default

Specify code that you want the code generator to add to the declaration section of the SystemStart function for the model or subsystem.

#### **System Start Function Execution Code — Code to add to the execution section of the generated function**

no default

Specify code that you want the code generator to add to the execution section of the SystemStart function for the model or subsystem.

#### **System Start Function Exit Code — Code to add to the exit section of the generated function**

no default

Specify code that you want the code generator to add to the exit section of the SystemStart function for the model or subsystem.

### Version History

**Introduced in R2006a**



**See Also**

Model Header | Model Source | System Derivatives | System Disable | System Enable | System Initialize | System Outputs | System Terminate | System Update

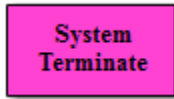
**Topics**

“Place External C/C++ Code in Generated Code”

# System Terminate

Specify external system termination code

**Library:** Simulink Coder / Custom Code



## Description

For a model or nonvirtual subsystem that includes the System Terminate block and a block that uses a `SystemTerminate` function, the code generator adds external code, which you specify, to the `SystemTerminate` function that it generates. You can specify code for the code generator to add to the declaration, execution, and exit sections of the function code.

If you include this block in a referenced model, the code generator ignores the block for simulation target builds, but processes the block for other system target files.

---

**Note** This block is intended to address special case requirements for inserting custom code into the generated code. See the C Caller and C Function blocks, which are more typically used for integrating custom algorithmic code into a model.

---

## Parameters

### **System Terminate Function Declaration Code — Code to add to the declaration section of the generated function**

no default

Specify code that you want the code generator to add to the declaration section of the `SystemTerminate` function for the model or subsystem.

### **System Disable Terminate Execution Code — Code to add to the execution section of the generated function**

no default

Specify code that you want the code generator to add to the execution section of the `SystemTerminate` function for the model or subsystem.

### **System Disable Terminate Exit Code — Code to add to the exit section of the generated function**

no default

Specify code that you want the code generator to add to the exit section of the `SystemTerminate` function for the model or subsystem.

## Version History

**Introduced in R2006a**

## **See Also**

Model Header | Model Source | System Derivatives | System Disable | System Enable | System Initialize | System Outputs | System Start | System Update

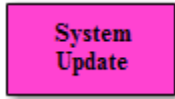
## **Topics**

“Place External C/C++ Code in Generated Code”

# System Update

Specify external system update code

**Library:** Simulink Coder / Custom Code



## Description

For a model or nonvirtual subsystem that includes the System Update block and a block that uses a SystemUpdate function, the code generator adds external code, which you specify, to the SystemUpdate function that it generates. You can specify code for the code generator to add to the declaration, execution, and exit sections of the function code.

If you include this block in a referenced model, the code generator ignores the block for simulation target builds, but processes the block for other system target files.

---

**Note** This block is intended to address special case requirements for inserting custom code into the generated code. See the C Caller and C Function blocks, which are more typically used for integrating custom algorithmic code into a model.

---

## Parameters

### **System Update Function Declaration Code — Code to add to the declaration section of the generated function**

no default

Specify code that you want the code generator to add to the declaration section of the SystemUpdate function for the model or subsystem.

### **System Update Function Execution Code — Code to add to the execution section of the generated function**

no default

Specify code that you want the code generator to add to the execution section of the SystemUpdate function for the model or subsystem.

### **System Update Function Exit Code — Code to add to the exit section of the generated function**

no default

Specify code that you want the code generator to add to the exit section of the SystemUpdate function for the model or subsystem.

## Version History

**Introduced in R2006a**

**See Also**

Model Header | Model Source | System Derivatives | System Disable | System Enable | System Initialize | System Outputs | System Start | System Terminate

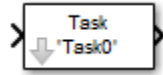
**Topics**

“Place External C/C++ Code in Generated Code”

## Task Sync

Run code of downstream function-call subsystem or Stateflow chart by spawning an example RTOS (VxWorks) task

**Library:** Simulink Coder / Asynchronous / Interrupt Templates



### Description

The Task Sync block spawns an example RTOS (VxWorks) task that calls a function-call subsystem or Stateflow chart. Typically, you place the Task Sync block between an Async Interrupt block and a function-call subsystem block or Stateflow chart. Alternatively, you could connect the Task Sync block to the output port of a Stateflow diagram that has an event, `Output to Simulink`, configured as a function call.

The Task Sync block:

- Uses the RTOS (VxWorks) system call `taskSpawn` to spawn an independent task. When the task is activated, it calls the downstream function-call subsystem code or Stateflow chart. The block calls `taskDelete` to delete the task during model termination.
- Creates a semaphore to synchronize the connected subsystem with execution of the block.
- Wraps the spawned task in an infinite `for` loop. In the loop, the spawned task listens for the semaphore by using `semTake`. The first call to `semTake` specifies `NO_WAIT`. This setting lets the task determine whether a second `semGive` has occurred before the completion of the function-call subsystem or chart. This sequence indicates that the interrupt rate is too fast or the task priority is too low.
- Generates synchronization code (for example, `semGive()`). This code lets the spawned task run. The task in turn calls the connected function-call subsystem code. The synchronization code can run at interrupt level. The connection between the Async Interrupt and Task Sync blocks accomplishes this operation and triggers execution of the Task Sync block within an ISR.
- Supplies absolute time if blocks in the downstream algorithmic code require it. The time comes from the timer maintained by the Async Interrupt block or comes from an independent timer maintained by the task associated with the Task Sync block.

When you design your application, consider when timer and signal input values could be taken for the downstream function-call subsystem that is connected to the Task Sync block. By default, the time and input data are read when the RTOS (VxWorks) activates the task. For this case, the data (input and time) are synchronized to the task itself. If you select the **Synchronize the data transfer of this task with the caller task** option and the Task Sync block driver is an Async Interrupt block, the time and input data are read when the interrupt occurs (that is, within the ISR). For this case, data is synchronized with the caller of the Task Sync block.

---

**Note** Use the blocks in the Interrupt Templates block library (Async Interrupt and Task Sync) for simulation and code generation. These blocks provide starting point examples to help you develop custom blocks for a target environment.

---

## Ports

### Input

#### Input — Call from interrupt block

call

A call from an Async Interrupt block.

### Output Arguments

#### Output — Call to function-call subsystem

call

A call to a function-call subsystem.

## Parameters

#### Taskname (10 characters or less) — Task function name

Task0 (default) | character vector

The first argument passed to the `taskSpawn` system call in the RTOS. The RTOS (VxWorks) uses this name as the task function name. This name also serves as a debugging aid. Routines use the task name to identify the task from which they are called.

#### Simulink task priority (0–255) — RTOS task priority

50 (default) | integer

The RTOS task priority assigned to the function-call subsystem task when spawned. RTOS (VxWorks) priorities range from 0 to 255, with 0 representing the highest priority.

---

**Note** The Simulink software does not simulate asynchronous task behavior. The task priority of an asynchronous task is for code generation purposes only and is not honored during simulation.

---

#### Stack size (bytes) — Maximum size for stack of the task

1024 (default) | integer

Maximum size to which the stack of the task can grow. The stack size is allocated when the RTOS (VxWorks) spawns the task. Choose a stack size based on the number of local variables in the task. Determine the size by examining the generated code for the task (and functions that are called from the generated code).

#### Synchronize the data transfer of this task with the caller task — Select synchronization

off (default) | on

If not selected (the default),

- The block maintains a timer that provides absolute time values required by the computations of downstream blocks. The timer is independent of the timer maintained by the Async Interrupt block that calls the Task Sync block.

- A **Timer resolution** option appears.
- The **Timer size** option specifies the word size of the time counter.

If selected,

- The block does not maintain an independent timer and does not display the **Timer resolution** field.
- Downstream blocks that require timers use the timer maintained by the Async Interrupt block that calls the Task Sync block (see “Timers in Asynchronous Tasks”). The timer value is read at the time the asynchronous interrupt is serviced. Data transfers to blocks called by the Task Sync block execute within the task associated with the Async Interrupt block. Therefore, data transfers are synchronized with the caller.

#### **Timer resolution (seconds) — Resolution for timer of the block**

1/60 (default)

The resolution of the timer of the block in seconds. This option appears only if **Synchronize the data transfer of this task with the caller task** is not selected. By default, the block gets the timer value by calling the tickGet function in the RTOS (VxWorks). The default resolution is 1/60 second.

#### **Timer size — Number of bits to store clock tick**

32bits (default) | 16bits | 8bits | auto

The number of bits to store the clock tick for a hardware timer. The size can be 32bits (the default), 16bits, 8bits, or auto. If you select auto, the code generator determines the timer size based on the settings of **Application lifespan (days)** and **Timer resolution**.

By default, timer values are stored as 32-bit integers. When **Timer size** is auto, you can indirectly control the word size of the counters by setting the **Application lifespan (days)** option. If you set **Application lifespan (days)** to a value that is too large for the code generator to handle as a 32-bit integer of the specified resolution, it uses a second 32-bit integer to address overflows.

For more information, see “Control Memory Allocation for Time Counters”. See also “Timers in Asynchronous Tasks”.

## **Version History**

**Introduced in R2006a**

### **See Also**

Async Interrupt

### **Topics**

“Asynchronous Events”



# Simulation Target Parameters

---

- “Target library” on page 5-2
- “Auto tuning” on page 5-3

## Target library

### Description

Specify the target deep learning library used during simulation. To enable this parameter, select C++ for the **Language**.

**Category:** Simulation Target

### Settings

**Default:** MKL - DNN if **GPU acceleration** is off. cuDNN if **GPU acceleration** is on.

#### MKL - DNN

Use this option for simulation that uses the Intel Math Kernel Library for Deep Neural Networks (Intel MKL-DNN).

#### cuDNN

Use this option for simulation that uses the CUDA<sup>®</sup> Deep Neural Network library (cuDNN).

#### TensorRT

Use this option for simulation that takes advantage of the NVIDIA<sup>®</sup> TensorRT - high performance deep learning inference optimizer and run-time library.

### Dependencies

- MKL - DNN is available when **GPU acceleration** on the **Simulation Target** pane is disabled and **Language** is set to C++.
- cuDNN or TensorRT requires a GPU Coder™ license.
- cuDNN or TensorRT is available when **GPU acceleration** on the **Simulation Target** pane is enabled.

### Command-Line Information

**Parameter:** SimDLTargetLibrary

**Type:** character vector

**Value:** 'MKL-DNN' | 'cuDNN' | 'TensorRT'

**Default:** MKL - DNN

### See Also

### Related Examples

- “Model Configuration Parameters: Simulation Target”
- “GPU Code Generation for Deep Learning Networks Using MATLAB Function Block” (GPU Coder)

# Auto tuning

## Description

Use auto tuning for cuDNN library.

**Category:** Simulation Target

## Settings

**Default:** On

**On**

Use this option to enable auto tuning feature. Enabling auto tuning allows the cuDNN library to find the fastest convolution algorithms. This increases performance for larger networks such as SegNet and ResNet.

**Off**

Disable auto tuning for the cuDNN library.

## Dependencies

- This parameter requires a GPU Coder license.
- To enable this parameter, select C++ for the **Language** and cuDNN for **Target library**.

## Command-Line Information

**Parameter:** SimDLAutoTuning

**Value:** 'on' | 'off'

**Default:** 'on'

## See Also

## Related Examples

- “Model Configuration Parameters: Simulation Target”
- “GPU Code Generation for Deep Learning Networks Using MATLAB Function Block” (GPU Coder)



# GPU Acceleration Parameters

---

- “Model Configuration Parameters: GPU Acceleration” on page 6-2
- “Simulation Target: GPU Acceleration Tab Overview” on page 6-3
- “Custom compute capability” on page 6-4
- “Dynamic memory allocation threshold” on page 6-5
- “Stack size per GPU thread” on page 6-6
- “Include error checks in generated code” on page 6-7
- “Additional compiler flags” on page 6-8

## Model Configuration Parameters: GPU Acceleration

The **Simulation Target > GPU Acceleration** category includes parameters for configuring GPU-specific settings of the generated code.

These parameters require a GPU Coder license.

On the Configuration Parameters dialog box, the following configuration parameters are on the **Simulation Target > GPU Acceleration** pane.

| Parameter                                            | Description                                                                                        |
|------------------------------------------------------|----------------------------------------------------------------------------------------------------|
| "Custom compute capability" on page 6-4              | Specify the name of the NVIDIA virtual GPU architecture for code generation.                       |
| "Dynamic memory allocation threshold" on page 6-5    | Specify the size above which the private variables are allocated on the heap instead of the stack. |
| "Stack size per GPU thread" on page 6-6              | Specify the maximum stack limit per GPU thread.                                                    |
| "Include error checks in generated code" on page 6-7 | Add run-time error-checking functionality to the generated CUDA code.                              |
| "Additional compiler flags" on page 6-8              | Specify additional flags to the nvcc compiler.                                                     |

### See Also

#### More About

- "Model Configuration Parameters: Simulation Target"
- "Simulation Acceleration by Using GPU Coder" (GPU Coder)

## Simulation Target: GPU Acceleration Tab Overview

Set up GPU-specific information about simulation acceleration for a model's active configuration set, including device memory settings, code profiling and analysis, and device architecture and compiler.

These parameters require a GPU Coder license.

### See Also

### More About

- “Model Configuration Parameters: GPU Acceleration” on page 6-2
- “Simulation Acceleration by Using GPU Coder” (GPU Coder)

## Custom compute capability

### Description

Specify the name of the NVIDIA virtual GPU architecture for code generation.

**Category:** Simulation Target > GPU Acceleration

### Settings

**Default:** ''

Specify the name of the NVIDIA virtual GPU architecture for which the CUDA input files must be compiled.

For example, to specify a virtual architecture type `-arch=compute_50`. You can specify a real architecture using `-arch=sm_50`. For more information, see the *Options for Steering GPU Code Generation* topic in the CUDA Toolkit documentation.

### Dependencies

- This parameter requires a GPU Coder license.
- This parameter is enabled by **GPU acceleration** on the **Simulation Target** pane.

### Command-Line Information

**Parameter:** SimGPUCustomComputeCapability

**Type:** character vector

**Value:** '' or a valid user-specified virtual architecture specification

**Default:** ''

### See Also

### Related Examples

- “Model Configuration Parameters: GPU Acceleration” on page 6-2
- “Simulation Acceleration by Using GPU Coder” (GPU Coder)



# Dynamic memory allocation threshold

## Description

Specify the memory allocation threshold.

**Category:** Simulation Target > GPU Acceleration

## Settings

**Default:** 200

Specify the size above which the private variables are allocated on the heap instead of the stack, as an integer value.

## Dependencies

- This parameter requires a GPU Coder license.
- This parameter is enabled by **GPU acceleration** on the **Simulation Target** pane.

## Command-Line Information

**Parameter:** SimGPUMallocThreshold

**Type:** integer

**Value:** any valid value

**Default:** 200

## See Also

## Related Examples

- “Model Configuration Parameters: GPU Acceleration” on page 6-2
- “Simulation Acceleration by Using GPU Coder” (GPU Coder)

## Stack size per GPU thread

### Description

Specify the stack limit per GPU thread.

**Category:** Simulation Target > GPU Acceleration

### Settings

**Default:** 1024

Specify the maximum stack limit per GPU thread as an integer value.

### Dependencies

- This parameter requires a GPU Coder license.
- This parameter is enabled by **GPU acceleration** on the **Simulation Target** pane.

### Command-Line Information

#### Command-Line Information

**Parameter:** SimGPUStackLimitPerThread

**Type:** integer

**Value:** any valid value

**Default:** 1024

### See Also

### Related Examples

- “Model Configuration Parameters: GPU Acceleration” on page 6-2
- “Simulation Acceleration by Using GPU Coder” (GPU Coder)

# Include error checks in generated code

## Description

Add run-time error-checking functionality to the generated CUDA code.

**Category:** Simulation Target > GPU Acceleration

## Settings

**Default:** Off

**On**

Generates code with error-checking for CUDA API and kernel calls and performs run-time checks.

**Off**

The generated CUDA code does not contain error-checking functionality.

## Dependencies

- This parameter requires a GPU Coder license.
- This parameter is enabled by **GPU acceleration** on the **Simulation Target** pane.

## Command-Line Information

**Parameter:** SimGPUErrorChecks

**Type:** character vector

**Value:** 'on' | 'off'

**Default:** 'off'

## See Also

## Related Examples

- “Model Configuration Parameters: GPU Acceleration” on page 6-2
- “Simulation Acceleration by Using GPU Coder” (GPU Coder)

## Additional compiler flags

### Description

Specify additional flags to the NVIDIA `nvcc` compiler.

**Category:** Simulation Target > GPU Acceleration

### Settings

**Default:** ''

Pass additional flags to the GPU compiler. For example, `--fmad=false` instructs the `nvcc` compiler to disable contraction of floating-point multiply and add to a single Floating-Point Multiply-Add (FMAD) instruction.

For similar NVIDIA compiler options, see the topic on *NVCC Command Options* in the CUDA Toolkit documentation.

### Dependencies

- This parameter requires a GPU Coder license.
- This parameter is enabled by **GPU acceleration** on the **Simulation Target** pane.

### Command-Line Information

**Parameter:** SimGPUCompilerFlags

**Type:** character vector

**Value:** '' or a valid user-specified flag

**Default:** ''

### See Also

### Related Examples

- “Model Configuration Parameters: GPU Acceleration” on page 6-2
- “Simulation Acceleration by Using GPU Coder” (GPU Coder)

# Code Generation Parameters: Code Generation

---

## Model Configuration Parameters: Code Generation

The **Code Generation** category includes parameters for defining the code generation process including target selection. It also includes parameters for inserting comments and pragmas into the generated code for data and functions. These parameters require a Simulink Coder license. Additional parameters available with an ERT-based target require an Embedded Coder license. Generating CUDA C++ code for NVIDIA GPUs requires a GPU Coder license.

These configuration parameters appear in the **Configuration Parameters > Code Generation** general category.

| Parameter                                | Description                                                                                        |
|------------------------------------------|----------------------------------------------------------------------------------------------------|
| System target file                       | Specify which target file configuration will be used.                                              |
| "Browse" on page 7-9                     | Browse file configuration options.                                                                 |
| Shared coder dictionary (Embedded Coder) | Shared coder dictionary that contains code interface configuration.                                |
| Language                                 | Specify C or C++ code generation.                                                                  |
| Language standard                        | Specify the language standard for your execution environment.                                      |
| "Generate GPU code" on page 7-12         | Use GPU Coder for CUDA code generation.<br>This parameter requires a GPU Coder license.            |
| "Description" on page 7-14               | A description of the target file.                                                                  |
| Generate code only                       | Specify code generation versus an executable build.                                                |
| Package code and artifacts               | Specify whether to automatically package generated code and artifacts for relocation.              |
| Zip file name                            | Specify the name of the .zip file in which to package generated code and artifacts for relocation. |
| Compiler optimization level              | Control compiler optimizations for building generated code.                                        |
| Custom compiler optimization flags       | Specify custom compiler optimization flags.                                                        |
| Toolchain                                | Specify the toolchain to use when building an executable or library.                               |
| Build configuration                      | Specify compiler optimization or debug settings for toolchain.                                     |
| Toolchain details                        | Display or customize build configuration settings.                                                 |
| Generate makefile                        | Enable generation of a makefile based on a template makefile.                                      |
| Make command                             | Specify a make command and optionally append makefile options.                                     |

| Parameter                                                              | Description                                                                  |
|------------------------------------------------------------------------|------------------------------------------------------------------------------|
| Template makefile                                                      | Specify the template makefile from which to generate the makefile.           |
| Select objective                                                       | Select a code generation objective to use with the Code Generation Advisor.  |
| Prioritized objectives (Embedded Coder)                                | List of prioritized code generation objectives.                              |
| “Set Objectives” (Embedded Coder)                                      | Open Configuration Set Objectives dialog box.                                |
| “Set Objectives — Code Generation Advisor Dialog Box” (Embedded Coder) | Select and prioritize code generation objectives.                            |
| Check model before generating code                                     | Choose whether to run Code Generation Advisor checks before generating code. |
| “Check Model” on page 7-34                                             | Check whether the model meets code generation objectives.                    |

These configuration parameters are under the **Advanced parameters**.

| Parameter                                        | Description                                                                                                   |
|--------------------------------------------------|---------------------------------------------------------------------------------------------------------------|
| Custom FFT library callback                      | Specify a callback class for FFTW library calls in code generated for FFT functions in MATLAB code.           |
| Custom BLAS library callback                     | Specify BLAS library callback class for BLAS calls in code generated from MATLAB code.                        |
| Custom LAPACK library callback                   | Specify LAPACK library callback class for LAPACK calls in code generated from MATLAB code.                    |
| Verbose build                                    | Display code generation progress.                                                                             |
| Retain .rtw file                                 | Specify <i>model.rtw</i> file retention.                                                                      |
| Profile TLC                                      | Profile the execution time of TLC files.                                                                      |
| Enable TLC assertion                             | Produce the TLC stack trace.                                                                                  |
| Start TLC coverage when generating code          | Generate the TLC execution report.                                                                            |
| Start TLC debugger when generating code          | Specify use of the TLC debugger                                                                               |
| Show Custom Hardware App in Simulink Toolstrip   | Read-only internal parameter for Simulink toolstrip.                                                          |
| Show Embedded Hardware App in Simulink Toolstrip | Read-only internal parameter for Simulink toolstrip.                                                          |
| “Package” (Embedded Coder)                       | Specify a package that contains memory sections you want to apply to model-level functions and internal data. |
| “Refresh package list” (Embedded Coder)          | Add user-defined packages that are on the search path to list of packages.                                    |
| “Initialize/Terminate” (Embedded Coder)          | Specify whether to apply a memory section to Initialize/Start and Terminate functions.                        |

| Parameter                             | Description                                                           |
|---------------------------------------|-----------------------------------------------------------------------|
| "Execution" (Embedded Coder)          | Specify whether to apply a memory section to execution functions.     |
| "Shared utility" (Embedded Coder)     | Specify whether to apply memory sections to shared utility functions. |
| "Constants" (Embedded Coder)          | Specify whether to apply a memory section to constants.               |
| "Inputs/Outputs" (Embedded Coder)     | Specify whether to apply a memory section to root input and output.   |
| "Internal data" (Embedded Coder)      | Specify whether to apply a memory section to internal data.           |
| "Parameters" (Embedded Coder)         | Specify whether to apply a memory section to parameters.              |
| "Validation results" (Embedded Coder) | Display the results of memory section validation.                     |

The following parameters under **Advanced parameters** are infrequently used and have no other documentation.

| Parameter                                          | Description                                                                                                                                                                                                                                                                                                                   |
|----------------------------------------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| PostCodeGenCommand<br><i>character vector</i> - '' | Add the specified post code generation command to the model build process.                                                                                                                                                                                                                                                    |
| TLCOptions<br><i>character vector</i> - ''         | Specify additional TLC command-line options.<br><br>When you use Embedded Coder for a component model that is configured with a service interface, you cannot specify -<br>aInlineSetEventsForThisBaseRateFcn=TLC_FALSE, -<br>aSuppressMultiTaskScheduler=TLC_FALSE, -<br>aRateBasedStepFcn=TLCFALSE, -<br>(wrapper function) |

The following parameters are for MathWorks use only.

| Parameter                                       | Description                                                                                                                                                                                |
|-------------------------------------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Comment                                         | For MathWorks use only.                                                                                                                                                                    |
| PreserveName                                    | For MathWorks use only.                                                                                                                                                                    |
| PreserveNameWithParent                          | For MathWorks use only.                                                                                                                                                                    |
| SignalNamingFcn                                 | For MathWorks use only.                                                                                                                                                                    |
| TargetTypeEmulationWarnSuppressLevel<br>int - 0 | For MathWorks use only.<br><br>When greater than or equal to 2, suppress warning messages that the code generator displays when emulating integer sizes in rapid prototyping environments. |

The Configuration Parameters dialog box also includes other code generation parameters:



- “Model Configuration Parameters: Code Generation Optimization” on page 19-2
- “Model Configuration Parameters: Code Generation Report” on page 8-2
- “Model Configuration Parameters: Comments” on page 9-2
- “Model Configuration Parameters: Code Generation Identifiers” on page 10-2
- “Model Configuration Parameters: Code Generation Custom Code” on page 11-2
- “Model Configuration Parameters: Code Generation Interface” on page 12-2

## **See Also**

### **More About**

- “Model Configuration”
- “Control Data and Function Placement in Memory by Inserting Pragmas” (Embedded Coder)

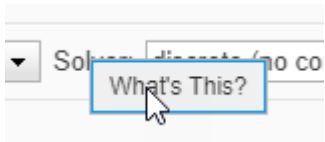
## Code Generation: General Tab Overview

Set up general information about code generation for a model's active configuration set, including target selection, documentation, and build process parameters.

To open the **Code Generation** pane, select **Configuration Parameters > Code Generation**.

### To get help on an option

- 1 Right-click the option's text label.
- 2 Select **What's This** from the popup menu.



### See Also

### Related Examples

- "Model Configuration Parameters: Code Generation" on page 7-2

# System target file

File that controls code generation stage of build process

**Model Configuration Pane:** Code Generation

## Description

The **System target file** parameter specifies the file that controls the code generation stage of the build process. The file:

- Defines variables that are used during the build process.
- Provides the main entry point to the TLC program that generates code.
- Defines information that appears in the System Target File Browser.
- Defines model configuration parameters that specify code generation and build process information for a specific target environment.
- Provides a mechanism for inheriting parameter definitions from another system target file.

## Settings

`grt.tlc` (default)

`grt.tlc`

Specifies the system target file to use for code generation. You can specify the system target file in these ways:

- Use the System Target File Browser. Click **Browse**, which lets you select a preset target configuration consisting of a system target file, template makefile, and make command.
- Enter the name of a system target file in this field.

## Tips

- The System Target File Browser lists system target files found on the MATLAB path. Some system target files require additional licensed products.
- Using ERT-based system target files such as `ert.tlc` to generate code requires an Embedded Coder license.
- When you switch from a system target file that is not ERT-based to a file that is ERT-based, the configuration parameter **Default parameter behavior** sets to **Inlined** by default. However, you can change the setting of **Default parameter behavior** later. For more information, see [Default parameter behavior](#).
- To configure your model for rapid simulation, select `rsim.tlc`.
- To configure your model for Simulink Real-Time™, select `slrealtime.tlc`.

## Recommended Settings

| Application       | Setting                                                  |
|-------------------|----------------------------------------------------------|
| Debugging         | No impact                                                |
| Traceability      | No impact                                                |
| Efficiency        | No impact                                                |
| Safety precaution | No impact<br>ERT based (requires Embedded Coder license) |

## Programmatic Use

**Parameter:** SystemTargetFile

**Type:** character vector

**Value:** valid system target file

**Default:** 'grt.tlc'

## Version History

**Introduced in R2006a**

## See Also

### Topics

“Model Configuration Parameters: Code Generation” on page 7-2

“Compare System Target File Support Across Products”

## Browse

### Description

Open the System Target File Browser, which lets you select a preset target configuration consisting of a system target file, template makefile, and make command. The value you select is filled into **System target file**.

**Category:** Code Generation

### Tips

- The System Target File Browser lists system target files found on the MATLAB path. Some system target files require additional licensed products, such as the Embedded Coder product.
- To configure your model for rapid simulation, select `rsim.tlc`.
- To configure your model for Simulink Real-Time, select `slrealtime.tlc`.

### See Also

### Related Examples

- “Model Configuration Parameters: Code Generation” on page 7-2
- “Configure a System Target File”
- “Compare System Target File Support Across Products”

## Language

Programming language of generated code

**Model Configuration Pane:** Code Generation

### Description

The **Language** parameter specifies whether the code generator produces C or C++ code.

### Dependencies

Selecting C++ enables and selects the value C++ class for the **Code interface packaging** parameter on the **Code Generation > Interface** pane.

### Settings

C (default) | C++

C

Generates C code and places the generated files in your build folder.

C++

Generates C++ code and places the generated files in your build folder.

If you set the **Code interface packaging** parameter to C++ class, the code generator produces a C++ class interface. The generated interface encapsulates required model data into C++ class attributes and model entry-point functions into C++ class methods.

If you set **Code interface packaging** to a value other than C++ class, the code generator produces C++ compatible .cpp files that contain model interface code enclosed within an extern "C" link directive.

You might need to configure the Simulink Coder software to use a compiler before you build a system.

### Recommended Settings

| Application       | Setting   |
|-------------------|-----------|
| Debugging         | No impact |
| Traceability      | No impact |
| Efficiency        | No impact |
| Safety precaution | No impact |

### Programmatic Use

**Parameter:** TargetLang

**Type:** character vector

**Value:** 'C' | 'C++'

**Default:** 'C'

## **Version History**

**Introduced in R2007a**

### **See Also**

#### **Topics**

"Model Configuration Parameters: Code Generation" on page 7-2

"Select C or C++ Programming Language"

"Select and Configure C or C++ Compiler"

"Configure Generated C Function Interface for Model Entry-Point Functions" (Embedded Coder)

## Generate GPU code

### Description

Use GPU Coder for CUDA code generation.

**Category:** Code Generation

### Settings

**Default:** Off

**On**

Enables code generation by using GPU Coder.

**Off**

Disables code generation by using GPU Coder.

### Dependencies

- This parameter requires a GPU Coder license.
- To enable this parameter, select C++ for the **Language** and `grt.tlc` or `ert.tlc` for **System target file**.
- Enabling **Generate GPU code** selects **Support long long** and **Support long long** parameters on the **Hardware Implementation** pane.
- For an GRT-based system target file, enabling **Generate GPU code** changes the following parameters on the **Code Generation > Optimization** pane:
  - Selects None for **Leverage target hardware instruction set extensions**.
  - Enables **Use memset to initialize floats and doubles to 0.0**.
- For an ERT-based system target file, enabling **Generate GPU code** changes the following parameters on the **Code Generation > Optimization** pane:
  - Disables **Generate parallel for-loops**.
  - Selects <empty> for **Disable incompatible optimizations**.
- For an ERT-based system target file, enabling **Generate GPU code** selects **Terminate function required** parameter on the **Code Generation > Interface** pane.

### Command-Line Information

**Parameter:** GenerateGPUCode

**Type:** character vector

**Value:** 'CUDA' | 'none'

**Default:** 'CUDA'



## See Also

### Related Examples

- “Model Configuration Parameters: Code Generation” on page 7-2
- “Code Generation from Simulink Models with GPU Coder” (GPU Coder)

## Description

### Description

This field displays the description of the system target file. You can use this description to differentiate between two system target files that have the same file name. To change the value of this description, click the Browse button.

**Category:** Code Generation

### See Also

### Related Examples

- “Model Configuration Parameters: Code Generation” on page 7-2
- “Browse” on page 7-9

# Language standard

Language standard supported by compiler

**Model Configuration Pane:** Code Generation

## Description

The **Language standard** parameter specifies the language standard supported by your compiler.

## Dependencies

- C++03 is available for use only if you select C++ for the **Language** parameter.
- When you change the value of the **Language** parameter, the **Language standard** is updated to C99 (ISO) for C and C++11 (ISO) for C++.

## Settings

C99 (ISO) if **Language** is set to C or C++11 (ISO) if **Language** is set to C++ (default) | C89/C90 (ANSI) | C++03 (ISO)

C89/C90 (ANSI)

Generates code that conforms to the ISO<sup>®</sup>/IEC 9899:1990 C language standard.

C99 (ISO)

Generates code that conforms to the ISO/IEC 9899:1999 C language standard.

C++03 (ISO)

Generates code that conforms to the ISO/IEC 14882:2003 C++ language standard.

C++11 (ISO)

Generates code that conforms to the ISO/IEC 14882:2011 C++ language standard.

## Tips

- Before setting this parameter, verify that your compiler supports the standard you want to use. If you select a parameter value that your compiler does not support, compiler errors can occur.
- If you are using a compiler that does not support ISO/IEC 9899:1999 C, set this parameter to C89/C90 (ANSI).
- The build process checks whether the specified language standard and toolchain are compatible. If they are not compatible, a warning occurs during code generation and the build process continues.
- If you use a Linux GCC compiler for the build process, the software uses the compiler default language standard to compile the generated code. Depending on the compiler version, the default language standard varies. For more information, see C++ Standards Support in GCC.

For example, if you use the GCC compiler version 8.x and set the parameter **Language standard** to C++03, the software uses the C++14 language standard during compilation. The usage of C++14 enables building the generated code that integrates custom code that uses C++11 or C++14 features.

If you want to enforce the language standard specified in the parameter on the compilation process, then you must add language standard specific compiler flags manually. If your model is configured to use a toolchain for building code, use this procedure:

- 1 In the Configuration Parameters dialog box, set **Build configuration** to Specify.
- 2 Under **Toolchain details**, at the end of the C Compiler and C++ Compiler **Options** field entries, manually add these compiler flags:
  - When the **Language standard** is set to C99 (ISO), add the flag `-std=c99 -pedantic`.
  - When the **Language standard** is set to C89/90 (ANSI), add the flag `-ansi -pedantic`.
  - When the **Language standard** is set to C++03, add the flag `-std=c++03 -pedantic`.
  - When the **Language standard** is set to C++11, add the flag `-std=c++11 -pedantic`.

## Recommended Settings

| Application       | Setting       |
|-------------------|---------------|
| Debugging         | No impact     |
| Traceability      | No impact     |
| Efficiency        | Valid library |
| Safety precaution | No impact     |

## Programmatic Use

**Parameter:** TargetLangStandard

**Type:** character vector

**Value:** 'C89/C90 (ANSI)' | 'C99 (ISO)' | 'C++03 (ISO)' | 'C++11 (ISO)'

**Default:** For C, 'C99 (ISO)'; for C++ 'C++11 (ISO)'

## Version History

Introduced in R2014a

## See Also

### Topics

“Model Configuration Parameters: Code Generation Interface” on page 12-2

“Specify Single-Precision Data Type for Embedded Application”

“Run-Time Environment Configuration”

# Toolchain

Toolchain to use when building executable program or library

**Model Configuration Pane:** Code Generation

## Description

The **Toolchain** parameter specifies the toolchain that CMake or the code generator uses to build an executable program or library.

---

**Note** This parameter appears when the model is configured with a system target file that specifies toolchain-based code generation, as described in “Configure CMake Build Process” and “Configure Toolchain (ToolchainInfo) or Template Makefile Build Process”.

---

## Settings

Automatically locate an installed toolchain (default)

The list of available toolchains depends on your development computer platform. The list can include custom toolchains that you added.

When **Toolchain** is set to Automatically locate an installed toolchain, the code generator:

- 1 Searches your development computer for installed toolchains.
- 2 Selects the compiler that you specified last by using the `mex -setup` command. The build process uses the compiler to compile generated C or C++ code.
- 3 Displays the name of the selected toolchain immediately below the **Toolchain** field.

## Tip

Click **Validate Toolchain** to verify that the registration information for the toolchain is valid. When the validation process is complete, a **Validation report** window displays the results. The Validation report states whether the toolchain registration passed or failed and provides status for each step and build tool in the validation process. If the tool chain definition omits a build tool, validation skips the unspecified tool. To fix a failure (for example, the build tool definition omits a required build tool, such as the compiler or linker), edit the toolchain definition and repeat the registration process.

## Recommended Settings

| Application       | Setting   |
|-------------------|-----------|
| Debugging         | No impact |
| Traceability      | No impact |
| Efficiency        | No impact |
| Safety precaution | No impact |

## **Programmatic Use**

**Parameter:** Toolchain

**Type:** character vector

**Value:** 'Automatically locate an installed toolchain' | A valid toolchain name

**Default:** 'Automatically locate an installed toolchain'

## **Version History**

**Introduced in R2013b**

## **See Also**

### **Topics**

“Model Configuration Parameters: Code Generation” on page 7-2

“Configure CMake Build Process”

“Create Custom CMake Toolchain Definition”

“Toolchain Configuration”

“Add Custom Toolchains to MATLAB® Coder™ Build Process”

# Build configuration

Build configuration defined by toolchain

**Model Configuration Pane:** Code Generation

## Description

The **Build configuration** parameter specifies compiler optimization or debug settings for the specified toolchain.

---

**Note** This parameter appears when the model is configured with a system target file that specifies toolchain-based code generation, as described in “Configure Toolchain (ToolchainInfo) or Template Makefile Build Process”.

---

## Dependencies

Selecting `Specify` displays a table of tools with editable options. Use this table to customize settings for the current model. See Toolchain details.

## Settings

Faster Builds (default) | Faster RunsDebug | Specify

### Faster Builds

Optimizes for shorter build times.

### Faster Runs

Optimizes for executable program that runs faster.

### Debug

Optimizes for debugging.

### Specify

Displays a table of tools with editable options. Use the table to customize settings for the current model. See Toolchain details.

This interaction helps synchronize the **Toolchain** value and **Build configuration** settings that you specify manually.

Modifying the setting of **Build configuration**, can change the **Toolchain** value. The Automatically locate an installed toolchain is the only value for **Toolchain** that is affected by changing the **Build configuration** to `Specify`.

- Changing the setting of **Build configuration** to `Specify`, changes the **Toolchain** value Automatically locate an installed toolchain (default) to the value of the toolchain that was located (for example, Microsoft Visual C++ 2012 v11.0 |(64-bit Windows)).
- Changing **Build configuration** from `Specify` to another value does not change the **Toolchain** value.

## Tip

Click **Show settings** to display a table of tools with options for the current build configuration. See Toolchain details.

Customize the toolchain options for the `Specify` build configuration. These options only apply to the current project.

To extract macro definitions (including compiler optimization flags) from the generated makefile for toolchain approach builds on Windows or UNIX systems, see the `model.bat` description in “Manage Build Process Files”.

## Recommended Settings

| Application       | Setting     |
|-------------------|-------------|
| Debugging         | Debug       |
| Traceability      | No impact   |
| Efficiency        | Faster Runs |
| Safety precaution | No impact   |

## Programmatic Use

**Parameter:** BuildConfiguration

**Type:** character vector

**Value:** 'Faster Builds' | 'Faster Runs' | 'Debug' | 'Specify'

**Default:** 'Faster Builds'

## Version History

Introduced in R2013b

## See Also

### Topics

“Model Configuration Parameters: Code Generation” on page 7-2

“Toolchain Configuration”

“Add Custom Toolchains to MATLAB® Coder™ Build Process”

“Control Compiler Optimizations”



# Toolchain details

Baseline toolchain settings

**Model Configuration Pane:** Code Generation

## Description

The **Toolchain details** parameters display and customize toolchain build configuration settings.

---

**Note** These parameters appear when the model is configured with a system target file that specifies toolchain-based code generation, as described in “Configure CMake Build Process” and “Configure Toolchain (ToolchainInfo) or Template Makefile Build Process”.

---

## Dependencies

To display a table of tools and options for the current build configuration, click **Toolchain details**.

## Settings

depends on tools and toolchain

The **Tool** column can include:

- C Compiler, Linker, Shared Library Linker, C++ Compiler, C++ Linker, C++ Shared Library Linker, Archiver, Download, Execute, and Make Tool. Content of the **Options** column can vary by tool and toolchain and can contain macros. To create a custom build configuration, set **Build configuration** to **Specify**. Consult third-party toolchain documentation for more information about options you can use with a specific tool.
- **CMake Configure** and **CMake Build**. If **Build configuration** is **Specify**, use the **Options** column as follows:
  - **CMake Configure** -- Specify additional command-line arguments to pass to CMake when generating the builder artifacts for the downstream tools.
  - **CMake Build** -- Specify additional command-line arguments to pass to CMake when using it in build mode.

## Recommended Settings

| Application       | Setting |
|-------------------|---------|
| Debugging         |         |
| Traceability      |         |
| Efficiency        |         |
| Safety precaution |         |

## **Programmatic Use**

**Parameter:** CustomToolchainOptions

**Type:** character vector

**Value:** Specify the baseline toolchain settings. Use a new-line-delineated character vector to specify each option and its values.

**Default:** ''

## **Version History**

**Introduced in R2013b**

## **See Also**

### **Topics**

“Model Configuration Parameters: Code Generation” on page 7-2

“Toolchain Configuration”

“Configure CMake Build Process”

“Create Custom CMake Toolchain Definition”

“Add Custom Toolchains to MATLAB® Coder™ Build Process”

# Compiler optimization level

Control application of compiler optimizations

**Model Configuration Pane:** Code Generation

## Description

The **Compiler optimization level** parameter controls whether the build process applies compiler optimizations.

---

**Note** This parameter appears when the model is configured with a system target file that specifies toolchain-based code generation, as described in “Configure Toolchain (ToolchainInfo) or Template Makefile Build Process”.

---

## Dependencies

This parameter enables **Custom compiler optimization flags**.

## Settings

Optimizations off (faster builds) (default) | Optimizations on (faster runs) | Custom

Optimizations off (faster builds)

Customizes compilation during the build process to minimize compilation time.

Optimizations on (faster runs)

Customizes compilation during the makefile build process to minimize run time.

Custom

Allows you to specify custom compiler optimization flags to be applied during the makefile build process. Select this setting for generating code for these types of simulations:

- Accelerator
- Rapid accelerator
- Model reference simulation target
- Normal mode for Stateflow and the MATLAB Function block
- MATLAB System block

## Tips

- Target-independent values `Optimizations on (faster runs)` and `Optimizations off (faster builds)` allow you to easily toggle compiler optimizations on and off during code development.
- `Custom` allows you to enter custom compiler optimization flags at Simulink GUI level, rather than editing compiler flags into template makefiles (TMFs) or supplying compiler flags to make commands.

- If you specify compiler options for your makefile build using OPT\_OPTS, MEX\_OPTS (except MEX\_OPTS="-v"), or MEX\_OPT\_FILE, the value of **Compiler optimization level** is ignored and a warning is issued about the ignored parameter.

## Recommended Settings

| Application       | Setting                                                          |
|-------------------|------------------------------------------------------------------|
| Debugging         | Optimizations off (faster builds)                                |
| Traceability      | Optimizations off (faster builds)                                |
| Efficiency        | Optimizations on (faster runs) (execution), No impact (ROM, RAM) |
| Safety precaution | No impact                                                        |

## Programmatic Use

**Parameter:** RTWCompilerOptimization

**Type:** character vector

**Value:** 'off' | 'on' | 'custom'

**Default:** 'off'

## Version History

Introduced in R2007b

## See Also

### Topics

"Model Configuration Parameters: Code Generation" on page 7-2

Custom compiler optimization flags

"Control Compiler Optimizations"

# Custom compiler optimization flags

Compiler optimization flags

**Model Configuration Pane:** Code Generation

## Description

The **Custom compiler optimization flags** parameter specifies compiler optimization flags to apply when building the generated code for your model.

---

**Note** This parameter appears when the model is configured with a system target file that specifies template makefile-based code generation, as described in “Configure Toolchain (ToolchainInfo) or Template Makefile Build Process”.

---

## Dependencies

This parameter is enabled by selecting the value `Custom` for the parameter **Compiler optimization level**.

## Settings

' ' (default)

Specify compiler optimization flags without quotes, for example, `-O2`.

## Recommended Settings

See **Compiler optimization level**.

## Programmatic Use

**Parameter:** `RTWCustomCompilerOptimizations`

**Type:** character vector

**Value:** ' ' | user-specified flags

**Default:** ' '

## Version History

Introduced in R2007b

## See Also

### Topics

“Model Configuration Parameters: Code Generation” on page 7-2

Compiler optimization level

“Control Compiler Optimizations”

## Generate makefile

Enable generation of makefile to use for compiling generated code

**Model Configuration Pane:** Code Generation

### Description

The **Generate makefile** parameter enables generation of a makefile based on a specified template makefile. The build process uses the generated make file to compile the generated code.

---

**Note** This parameter appears when the model is configured with a system target file that specifies template makefile-based code generation, as described in “Configure Toolchain (ToolchainInfo) or Template Makefile Build Process”.

---

### Dependencies

This parameter enables:

- **Make command**
- **Template makefile**

### Settings

on (default) | off

On

Generates a makefile for a model during the build process.

Off

Suppresses the generation of a makefile. You must set up post code generation build processing, including compilation and linking, as a user-defined command.

### Recommended Settings

| Application       | Setting   |
|-------------------|-----------|
| Debugging         | No impact |
| Traceability      | No impact |
| Efficiency        | No impact |
| Safety precaution | No impact |

### Programmatic Use

**Parameter:** GenerateMakefile

**Type:** character vector

**Value:** 'on' | 'off'

**Default:** 'on'

## **Version History**

**Introduced in R2007a**

### **See Also**

#### **Topics**

“Model Configuration Parameters: Code Generation” on page 7-2

“Customize Post-Code-Generation Build Processing”

“Customize Build Process with STF\_make\_rtw\_hook File”

“Target Development and the Build Process”

## Make command

Make command and options for initiating build process

**Model Configuration Pane:** Code Generation

### Description

The **Make command** parameter specifies the make command and makefile options to use to initiate the build process.

---

**Note** This parameter appears when the model is configured to use a template makefile-based code generation system target file, as described in “Configure Toolchain (ToolchainInfo) or Template Makefile Build Process”.

---

### Dependencies

This parameter is enabled by **Generate makefile**.

### Settings

make\_rtw (default)

An internal MATLAB command used by the code generator to control the build process. The specified make command is invoked when you start a build.

- Each target has an associated make command, automatically supplied when you select a system target file.
- Some third-party targets supply a make command. See the vendor documentation.
- You can supply makefile options in the **Make command** field. The code generator passes the options to the command-line invocation of the `make` utility, which adds them to the overall flags passed to the compiler. Append the options after the make command, as this example shows:

```
make_rtw OPTS="-DMYDEFINE=1"
```

The syntax for makefile options varies for different compilers.

### Tip

- Most targets use the default command.
- You should not invoke `make_rtw` or other internal make commands directly from MATLAB code. To initiate a model build from MATLAB code, use documented build commands such as `slbuild` or `slbuild`.



## Recommended Settings

| Application       | Setting           |
|-------------------|-------------------|
| Debugging         | No impact         |
| Traceability      | No impact         |
| Efficiency        | No impact         |
| Safety precaution | No recommendation |

## Programmatic Use

**Parameter:** MakeCommand

**Type:** character vector

**Value:** valid make command MATLAB language file

**Default:** 'make\_rtw'

## Version History

Introduced in R2007a

## See Also

### Topics

“Model Configuration Parameters: Code Generation” on page 7-2

“Template Makefiles and Make Options”

“Customize Build Process with STF\_make\_rtw\_hook File”

“Target Development and the Build Process”

## Template makefile

Template makefile to use to generate makefile for specified system target file

**Model Configuration Pane:** Code Generation

### Description

The **Template makefile parameter** specifies the template makefile from which to generate the makefile.

---

**Note** This parameter appears when the model is configured to use a template makefile-based code generation system target file, as described in “Configure Toolchain (ToolchainInfo) or Template Makefile Build Process”.

---

### Dependencies

This parameter is enabled by **Generate makefile**.

### Settings

grt\_default\_tmf (default)

Determines which compiler runs, during the make phase of the build, to compile the generated code. You can specify a template makefile in the following ways:

- Generate a value by selecting a system target file.
- Explicitly enter the file name and extension of a custom template makefile. The file must be on the MATLAB path.

### Tips

- If you do not include a filename extension for a custom template makefile, the code generator attempts to find and execute a MATLAB language file.
- You can customize your build process by modifying an existing template makefile or by providing your own template makefile.

### Recommended Settings

| Application       | Setting   |
|-------------------|-----------|
| Debugging         | No impact |
| Traceability      | No impact |
| Efficiency        | No impact |
| Safety precaution | No impact |

## **Programmatic Use**

**Parameter:** TemplateMakefile

**Type:** character vector

**Value:** valid template makefile filename

**Default:** 'grt\_default\_tmf'

## **Version History**

**Introduced in R2006a**

## **See Also**

### **Topics**

“Model Configuration Parameters: Code Generation” on page 7-2

“Template Makefiles and Make Options”

“Compare System Target File Support Across Products”

## Select objective

Code generation objective

**Model Configuration Pane:** Code Generation

### Description

Parameter **Select objective** allows you select a code generation objective for reviewing model configuration parameter settings by using the Code Generation Advisor.

### Dependencies

This parameter name appears only for GRT-based targets. For ERT-based targets, the parameter **Prioritized objectives** lists the code generation objectives.

### Settings

Unspecified (default) | Debugging | Execution efficiency

#### Unspecified

Does not use the Code Generation Advisor to optimize code generation settings.

#### Debugging

Uses the Code Generation Advisor to optimize code generation settings for debugging the code generation build process.

#### Execution efficiency

Use the Code Generation Advisor to optimize code generation settings to achieve fast execution time.

### Recommended Settings

| Application       | Setting                              |
|-------------------|--------------------------------------|
| Debugging         | Debugging                            |
| Traceability      | Not applicable for GRT-based targets |
| Efficiency        | Execution efficiency                 |
| Safety precaution | No recommendation                    |

### Programmatic Use

**Parameter:** ObjectivePriorities

**Type:** cell array of character vectors or string array

**Value:** {' '} | {'Debugging'} | {'Execution efficiency'}

**Default:** {' '}

### Version History

**Introduced in R2009a**

## See Also

### Topics

“Model Configuration Parameters: Code Generation” on page 7-2

Prioritized objectives (Embedded Coder)

“Configure Model for Code Generation Objectives by Using Code Generation Advisor” (Embedded Coder)

“Application Objectives Using Code Generation Advisor”

## Check Model

### Description

Run the Code Generation Advisor checks.

**Category:** Code Generation

### Settings

- 1 Specify code generation objectives using the **Select objective** parameter (available with GRT-based targets) or in the Configuration Set Objectives dialog box, by clicking **Set Objectives** (available with ERT-based targets).
- 2 Click **Check Model**. The Code Generation Advisor runs the code generation objectives checks and provide suggestions for changing your model to meet the objectives.

### Dependency

You must specify objectives before checking the model.

### See Also

#### Related Examples

- “Model Configuration Parameters: Code Generation” on page 7-2
- “Configure Model for Code Generation Objectives by Using Code Generation Advisor” (Embedded Coder)
- “Application Objectives Using Code Generation Advisor”

# Check model before generating code

Choose whether to run Code Generation Advisor checks

**Model Configuration Pane:** Code Generation

## Description

The **Check model before generating code** parameter specifies whether to run Code Generation Advisor checks before initiating code generation.

## Settings

Off (default) | On (proceed with warnings) | On (stop for warnings)

### Off

Generates code without checking whether the model meets code generation objectives. The code generation report summary and file headers indicate the specified objectives and that the validation was not run.

### On (proceed with warnings)

Checks whether the model meets code generation objectives by using the Code Generation Objectives checks in the Code Generation Advisor. If the Code Generation Advisor reports a warning, the code generator continues producing code. The code generation report summary and file headers indicate the specified objectives and the validation result.

### On (stop for warnings)

Checks whether the model meets code generation objectives by using the Code Generation Objectives checks in the Code Generation Advisor. If the Code Generation Advisor reports a warning, the code generator does not continue producing code.

## Recommended Settings

| Application       | Setting                                              |
|-------------------|------------------------------------------------------|
| Debugging         | On (proceed with warnings) or On (stop for warnings) |
| Traceability      | On (proceed with warnings) or On (stop for warnings) |
| Efficiency        | On (proceed with warnings) or On (stop for warnings) |
| Safety precaution | On (proceed with warnings) or On (stop for warnings) |

## Programmatic Use

**Parameter:** CheckMdlBeforeBuild

**Type:** character vector

**Value:** 'Off' | 'Warning' | 'Error'

**Default:** 'Off'

## **Version History**

**Introduced in R2009a**

### **See Also**

#### **Topics**

“Model Configuration Parameters: Code Generation” on page 7-2

“Configure Model for Code Generation Objectives by Using Code Generation Advisor” (Embedded Coder)

“Application Objectives Using Code Generation Advisor”



# Generate code only

Generate code versus an executable program

**Model Configuration Pane:** Code Generation

## Description

The **Generated code only** parameter instructs the code generator to stop the build process after generating code.

## Settings

off (default) | on

On

Generates code and a makefile, but does not invoke the make command.

Off

Generates code and builds an executable program file.

## Tip

**Generate code only** generates a makefile only if you select **Generate makefile**.

## Recommended Settings

| Application       | Setting   |
|-------------------|-----------|
| Debugging         | Off       |
| Traceability      | No impact |
| Efficiency        | No impact |
| Safety precaution | No impact |

## Programmatic Use

**Parameter:** GenCodeOnly

**Type:** character vector

**Value:** 'on' | 'off'

**Default:** 'off'

## Version History

Introduced in R2006a

## See Also

### Topics

“Model Configuration Parameters: Code Generation” on page 7-2

“Customize Post-Code-Generation Build Processing”

# Package code and artifacts

Package generated code and artifacts in ZIP file

**Model Configuration Pane:** Code Generation

## Description

The **Package code and artifacts** parameter specifies whether to execute the `packNGo` function after the build process completes. That function packages generated code and artifacts in a ZIP file that you can use to relocate the files to an alternative development system.

## Dependencies

Selecting this parameter enables **Zip file name** and clearing this parameter disables **Zip file name**.

## Settings

off (default) | on

On

After code generation, to package generated code and artifacts for relocation, the build process runs this `packNGo` command:

```
packNGo(pwd, ...
 'IncludeReport', true, ...
 'packType', 'hierarchical', ...
 'fileName', zipName, ...
 'nestedZipFiles', false);
```

Off

The build process does not run the `packNGo` command after code generation.

## Recommended Settings

| Application       | Setting   |
|-------------------|-----------|
| Debugging         | No impact |
| Traceability      | No impact |
| Efficiency        | No impact |
| Safety precaution | No impact |

## Programmatic Use

**Parameter:** PackageGeneratedCodeAndArtifacts

**Type:** character vector

**Value:** 'on' | 'off'

**Default:** 'off'

## **Version History**

**Introduced in R2012b**

### **See Also**

#### **Topics**

"Model Configuration Parameters: Code Generation" on page 7-2

"Relocate or Share Generated Code"

"Limitations"

## Zip file name

Name of ZIP file

**Model Configuration Pane:** Code Generation

### Description

The **Zip file name** parameter specifies the name of the ZIP file in which to package generated code and artifacts for relocation.

### Dependencies

This parameter is enabled by **Package code and artifacts**.

### Settings

' ' (default)

Specifies the name of the ZIP file into which to package generated code and artifacts for relocation. You can specify or omit the `.zip` file extension. If you do not specify the extension or if you specify an extension other than `.zip`, the ZIP utility adds the `.zip` extension. If you do not specify a value, the build process uses file name `model.zip`, where `model` is the name of the top model for which code is being generated.

### Recommended Settings

| Application       | Setting   |
|-------------------|-----------|
| Debugging         | No impact |
| Traceability      | No impact |
| Efficiency        | No impact |
| Safety precaution | No impact |

### Programmatic Use

**Parameter:** PackageName

**Type:** character vector

**Value:** valid name for a `.zip` file

**Default:** 'off'

### Version History

Introduced in R2012b

### See Also

#### Topics

“Model Configuration Parameters: Code Generation” on page 7-2

“Relocate or Share Generated Code”  
“Limitations”

# Custom FFT library callback

Callback for custom FFT library usage

**Model Configuration Pane:** Code Generation

## Description

The **Custom FFT library callback** parameter specifies a callback class for FFTW library calls in the code generated for FFT functions in MATLAB code. This parameter applies to MATLAB code in a MATLAB Function block, a Stateflow chart, or a System object™ associated with a MATLAB System block.

To improve the execution speed of FFT functions, the code generator produces calls to the FFTW library that you specify in the callback class.

## Settings

' ' (default)

Specifies the name of an FFT library callback class. If this parameter is empty, the code generator uses its own algorithms for FFT functions instead of calling the FFTW library.

## Tip

Specify only the name of the class. Do not specify the name of the class definition file.

## Recommended Settings

| Application       | Setting   |
|-------------------|-----------|
| Debugging         | No impact |
| Traceability      | No impact |
| Efficiency        | No impact |
| Safety precaution | No impact |

## Programmatic Use

**Parameter:** CustomFFTCallback

**Type:** character vector

**Value:** class name

**Default:** ' '

## Limitation

The class definition file must be in a folder on the MATLAB path.

## Version History

**Introduced in R2017b**

## **See Also**

### **Topics**

“Model Configuration Parameters: Code Generation” on page 7-2

“Speed Up Fast Fourier Transforms in Code Generated from a MATLAB Function Block”

### **External Websites**

[www.fftw.org](http://www.fftw.org)



# Custom BLAS library callback

Callback for custom BLAS library usage

**Model Configuration Pane:** Code Generation

## Description

The **Custom BLAS library callback** parameter specifies a BLAS library callback class for BLAS calls in code generated from MATLAB code. This parameter applies to MATLAB code in a MATLAB Function block, a Stateflow chart, or a System object associated with a MATLAB System block.

## Settings

' ' (default) | on

Specifies the name of a BLAS callback class that derives from `coder.BLASCallback`. If you specify a BLAS callback class, for certain low-level vector and matrix operations, the code generator produces BLAS calls by using the CBLAS C interface to your BLAS library. The callback class provides the CBLAS header and data type information and the information required to link to your BLAS library. If this parameter is empty, the code generator produces code for the vector and matrix functions instead of a BLAS call.

## Tip

Specify only the name of the class. Do not specify the name of the class definition file.

## Recommended Settings

| Application       | Setting   |
|-------------------|-----------|
| Debugging         | No impact |
| Traceability      | No impact |
| Efficiency        | No impact |
| Safety precaution | No impact |

## Programmatic Use

**Parameter:** CustomBLASCallback

**Type:** character vector

**Value:** class name

**Default:** ' '

## Limitation

The class definition file must be in a folder on the MATLAB path.

## **Version History**

**Introduced in R2018b**

### **See Also**

#### **Topics**

“Model Configuration Parameters: Code Generation” on page 7-2

“Speed Up Matrix Operations in Code Generated from a MATLAB Function Block”

# Custom LAPACK library callback

Callback for custom LAPACK library usage

**Model Configuration Pane:** Code Generation

## Description

The **Custom LAPACK library callback** parameter specifies a LAPACK library callback class for LAPACK calls in code generated from MATLAB code. This parameter applies to MATLAB code in a MATLAB Function block, a Stateflow chart, or a System object associated with a MATLAB System block.

## Settings

' ' (default)

Specify the name of a LAPACK callback class that derives from `coder.LAPACKCallback`. If you specify a LAPACK callback class, for certain linear algebra functions, the code generator produces LAPACK calls by using the LAPACKE C interface to your LAPACK library. The callback class provides the name of your LAPACKE header file and the information required to link to your LAPACK library. If this parameter is empty, the code generator produces code for linear algebra functions instead of a LAPACK call.

## Tip

Specify only the name of the class. Do not specify the name of the class definition file.

## Recommended Settings

| Application       | Setting   |
|-------------------|-----------|
| Debugging         | No impact |
| Traceability      | No impact |
| Efficiency        | No impact |
| Safety precaution | No impact |

## Programmatic Use

**Parameter:** CustomLAPACKCallback

**Type:** character vector

**Value:** class name

**Default:** ' '

## Limitation

The class definition file must be in a folder on the MATLAB path.

## **Version History**

**Introduced in R2016a**

### **See Also**

#### **Topics**

“Model Configuration Parameters: Code Generation” on page 7-2

“Speed Up Linear Algebra in Code Generated from a MATLAB Function Block”

## Verbose build

Enable display of build process stages and compiler output

**Model Configuration Pane:** Code Generation

### Description

The **Verbose build** parameter displays this information in the MATLAB Command Window during the build process:

- Messages that inform you about progress
- Compiler output

### Settings

on (default) | off

On

Displays progress information and compiler output.

Off

Does not display progress information and compiler output.

### Recommended Settings

| Application       | Setting           |
|-------------------|-------------------|
| Debugging         | On                |
| Traceability      | No impact         |
| Efficiency        | No impact         |
| Safety precaution | No recommendation |

### Programmatic Use

**Parameter:** RTWVerbose

**Type:** character vector

**Value:** 'on' | 'off'

**Default:** 'on'

### Version History

Introduced in R2006a

### See Also

#### Topics

“Model Configuration Parameters: Code Generation” on page 7-2

“Configure Model for Debugging”

## Retain .rtw file

Retain generated *model*.rtw file

**Model Configuration Pane:** Code Generation

### Description

The **Retain .rtw file** parameter instructs the code generator to retain the generated *model*.rtw file in the current build folder at the end of the build process. Retaining the *model*.rtw file is useful if you need to check the file content after making changes to a system target file.

### Settings

off (default) | on

On

Retains the *model*.rtw file in the current build folder.

Off

Deletes the *model*.rtw from the build folder at the end of the build process.

### Recommended Settings

| Application       | Setting   |
|-------------------|-----------|
| Debugging         | On        |
| Traceability      | No impact |
| Efficiency        | No impact |
| Safety precaution | No impact |

### Programmatic Use

**Parameter:** RetainRTWFile

**Type:** character vector

**Value:** 'on' | 'off'

**Default:** 'off'

### Version History

Introduced in R2006a

### See Also

#### Topics

“Model Configuration Parameters: Code Generation” on page 7-2

“Configure Model for Debugging”

# Profile TLC

Profile execution of TLC files used to generate code for model

**Model Configuration Pane:** Code Generation

## Description

The **Profile TLC** parameter instructs the TLC profiler to analyze the execution time of TLC files during code generation and capture the results in an HTML report.

## Settings

off (default) | on

On

Profiles the performance of TLC code.

Off

Does not profile the performance of TLC code.

## Recommended Settings

| Application       | Setting   |
|-------------------|-----------|
| Debugging         | On        |
| Traceability      | No impact |
| Efficiency        | No impact |
| Safety precaution | No impact |

## Programmatic Use

**Parameter:** ProfileTLC

**Type:** character vector

**Value:** 'on' | 'off'

**Default:** 'off'

## Version History

Introduced in R2007a

## See Also

### Topics

“Model Configuration Parameters: Code Generation” on page 7-2

“Configure Model for Debugging”

## Start TLC debugger when generating code

During code generation, start TLC debugger

**Model Configuration Pane:** Code Generation

### Description

The **Start TLC debugger when generating code** parameter instructs the code generator to start the TLC debugger when the TLC program starts executing. TLC breakpoint statements invoke the TLC debugger regardless of this parameter setting.

### Settings

off (default) | off

On

Starts the TLC debugger during code generation.

Off

Does not start the TLC debugger during code generation.

### Tips

- You can also start the TLC debugger by entering the `-dc` argument into the **System target file** field.
- To invoke the debugger and run a debugger script, enter the `-df filename` argument into the **System target file** field.

### Recommended Settings

| Application       | Setting   |
|-------------------|-----------|
| Debugging         | On        |
| Traceability      | No impact |
| Efficiency        | No impact |
| Safety precaution | No impact |

### Programmatic Use

**Parameter:** TLCDebug

**Type:** character vector

**Value:** 'on' | 'off'

**Default:** 'off'

### Version History

Introduced in R2006a



## **See Also**

### **Topics**

“Model Configuration Parameters: Code Generation” on page 7-2

“Configure Model for Debugging”

## Start TLC coverage when generating code

Log coverage of TLC code during code generation

**Model Configuration Pane:** Code Generation

### Description

The **Start TLC coverage when generating code** parameter instructs the code generator to log the number of times each line of TLC code executes and captures the information in a TLC execution report.

### Settings

off (default) | on

On

Logs TLC coverage data.

Off

Does not log TLC coverage data.

### Tip

You can also generate the TLC execution report by entering the `-dg` argument into the **System target file** field.

### Recommended Settings

| Application       | Setting   |
|-------------------|-----------|
| Debugging         | On        |
| Traceability      | No impact |
| Efficiency        | No impact |
| Safety precaution | No impact |

### Programmatic Use

**Parameter:** TLCCoverage

**Type:** character vector

**Value:** 'on' | 'off'

**Default:** 'off'

### Version History

Introduced in R2006a

## **See Also**

### **Topics**

“Model Configuration Parameters: Code Generation” on page 7-2

“Configure Model for Debugging”

## Enable TLC assertion

Produce TLC stack trace

**Model Configuration Pane:** Code Generation

### Description

The **Enable TLC assertion** parameter instructs the code generator to produce a TLC stack trace when the evaluation of the argument for an assert directive is false.

### Settings

off (default) | on

On

Halts the build process if a user-supplied TLC file contains an `%assert` directive that evaluates to FALSE.

Off

Ignores TLC assertion code during the build process.

### Recommended Settings

| Application       | Setting           |
|-------------------|-------------------|
| Debugging         | On                |
| Traceability      | No impact         |
| Efficiency        | No impact         |
| Safety precaution | No recommendation |

### Programmatic Use

**Parameter:** TLCAssert

**Type:** character vector

**Value:** 'on' | 'off'

**Default:** 'off'

### Version History

Introduced in R2006a

### See Also

#### Topics

“Model Configuration Parameters: Code Generation” on page 7-2

“Configure Model for Debugging”

# Show Custom Hardware App in Simulink Toolstrip

Show Custom Hardware App in Simulink Toolstrip

**Model Configuration Pane:** Code Generation

## Description

The **Show Custom Hardware App in Simulink Toolstrip** parameter is a read-only internal parameter for the Simulink toolstrip.

## Settings

off (default) | on

On

Activates the Run on Custom Hardware app.

Off

Does not activate the Run on Custom Hardware app.

## Recommended Settings

| Application       | Setting           |
|-------------------|-------------------|
| Debugging         | On                |
| Traceability      | No impact         |
| Efficiency        | No impact         |
| Safety precaution | No recommendation |

## Programmatic Use

**Parameter:** ShowCustomHardwareApp

**Type:** character vector

**Value:** 'on' | 'off'

**Default:** 'off'

## Version History

**Introduced in R2019b**

# Show Embedded Hardware App in Simulink Toolstrip

Show Embedded Hardware App in Simulink Toolstrip

**Model Configuration Pane:** Code Generation

## Description

The **Show Embedded Hardware App in Simulink Toolstrip** parameter is a read-only internal parameter for the Simulink toolstrip.

## Settings

off (default) | on

On

Activates the Run on Hardware Board app.

Off

Does not activate the Run on Hardware Board app.

## Recommended Settings

| Application       | Setting           |
|-------------------|-------------------|
| Debugging         | On                |
| Traceability      | No impact         |
| Efficiency        | No impact         |
| Safety precaution | No recommendation |

## Programmatic Use

**Parameter:** ShowEmbeddedHardwareApp

**Type:** character vector

**Value:** 'on' | 'off'

**Default:** 'off'

## Version History

Introduced in R2019b

# Code Generation Parameters: Report

---

## Model Configuration Parameters: Code Generation Report

The **Code Generation > Report** category includes parameters for generating and customizing the code generation report. These parameters require a Simulink Coder license. Additional parameters available with an ERT-based target require an Embedded Coder license.

On the Configuration Parameters dialog box, the following configuration parameters are on the **Code Generation > Report** pane.

| Parameter                                     | Description                                                                                                             |
|-----------------------------------------------|-------------------------------------------------------------------------------------------------------------------------|
| Create code generation report                 | Document generated code in an HTML report.                                                                              |
| Open report automatically                     | Specify whether to display code generation reports automatically.                                                       |
| Generate model Web view (Embedded Coder)      | Include the model Web view in the code generation report to navigate between the code and model within the same window. |
| Generate static code metrics (Embedded Coder) | Include static code metrics report in the code generation report.                                                       |

These configuration parameters are under the **Advanced parameters**.

| Parameter                                                           | Description                                                                                                                                                                                                      |
|---------------------------------------------------------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Code-to-model (Embedded Coder)                                      | Include hyperlinks in the code generation report that link code to the corresponding Simulink blocks, Stateflow objects, and MATLAB functions in the model diagram.                                              |
| Model-to-code (Embedded Coder)                                      | Link Simulink blocks, Stateflow objects, and MATLAB functions in a model diagram to corresponding code segments in a generated HTML report so that the generated code for a block can be highlighted on request. |
| “Configure” (Embedded Coder)                                        | Open the <b>Model-to-code navigation</b> dialog box for specifying a build folder containing previously-generated model code to highlight.                                                                       |
| Eliminated / virtual blocks (Embedded Coder)                        | Include summary of eliminated and virtual blocks in code generation report.                                                                                                                                      |
| Traceable Simulink blocks (Embedded Coder)                          | Include summary of Simulink blocks in code generation report.                                                                                                                                                    |
| Traceable Stateflow objects (Embedded Coder)                        | Include summary of Stateflow objects in code generation report.                                                                                                                                                  |
| Traceable MATLAB functions (Embedded Coder)                         | Include summary of MATLAB functions in code generation report.                                                                                                                                                   |
| Summarize which blocks triggered code replacements (Embedded Coder) | Include code replacement report summarizing replacement functions used and their associated blocks in the code generation report.                                                                                |



## **See Also**

### **More About**

- “Report Generation”
- “Model Configuration”

## Code Generation: Report Tab Overview

Control the code generation report that the code generator automatically creates.

### Configuration

To create a code generation report during the build process, select the **Create code generation report** parameter.

### See Also

### Related Examples

- “Model Configuration Parameters: Code Generation Report” on page 8-2
- “Generate Code Generation Report”
- “Reports for Code Generation”
- “HTML Code Generation Report Extensions” (Embedded Coder)

# Create code generation report

Document generated code in an HTML report

**Model Configuration Pane:** Code Generation / Report

## Description

The **Create code generation report** parameter generates an HTML report that provides traceability between the code and elements of the model..

## Dependencies

This parameter enables

- **Open report automatically** on page 8-8
- **Code-to-model** (Embedded Coder) (ERT target)
- **Model-to-code** (Embedded Coder) (ERT target)
- **Eliminated / virtual blocks** (Embedded Coder) (ERT target)
- **Traceable Simulink blocks** (Embedded Coder) (ERT target)
- **Traceable Stateflow objects** (Embedded Coder) (ERT target)
- **Traceable MATLAB functions** (Embedded Coder) (ERT target)

## Settings

off (default) | on

On

Generates a summary of code generation source files in an HTML report. Places the report files in an `html` subfolder within the build folder. In the report,

- The **Summary** section lists version and date information. The **Configuration Settings at the Time of Code Generation** link opens a noneditable view of the Configuration Parameters dialog that shows the Simulink model settings, including TLC options, at the time of code generation.
- The **Subsystem Report** section contains information on nonvirtual subsystems in the model.
- The **Code Interface Report** section provides information about the generated code interface, including model entry point functions and input/output data (requires an Embedded Coder license and the ERT target).
- The **Traceability Report** section allows you to account for **Eliminated / Virtual Blocks** that are untraceable, versus the listed **Traceable Simulink Blocks / Stateflow Objects / MATLAB Scripts**, providing a complete mapping between model elements and code (requires an Embedded Coder license and the ERT system target file).
- The **Static Code Metrics Report** section provides statistics of the generated code. Metrics are estimated from static analysis of the generated code.

- The **Code Replacements Report** section allows you to account for code replacement library (CRL) functions that were used during code generation, providing a mapping between each replacement instance and the Simulink block that triggered the replacement.

In the **Generated Files** section, you can click the names of source code files generated from your model to view their contents in a MATLAB Web browser window. In the displayed source code,

- Global variable instances are hyperlinked to their definitions.
- If you selected the traceability option **Code-to-model**, hyperlinks within the displayed source code let you view the blocks or subsystems from which the code was generated. Click on the hyperlinks to view the relevant blocks or subsystems in a Simulink model window (requires an Embedded Coder license and the ERT system target file).
- If you selected the traceability option **Model-to-code**, you can view the generated code for a block in the model. To highlight a block's generated code in the HTML report, right-click the block and select **C/C++ Code > Navigate to C/C++ Code** (requires an Embedded Coder license and the ERT system target file).
- If you set the **Code coverage tool** parameter on the **Code Generation > Verification** pane, you can view the code coverage data and annotations in the generated code in the HTML Code Generation Report (requires an Embedded Coder license and the ERT system target file).

Off

Does not generate a summary of files.

## Recommended Settings

| Application       | Setting           |
|-------------------|-------------------|
| Debugging         | On                |
| Traceability      | On                |
| Efficiency        | No impact         |
| Safety precaution | No recommendation |

## Programmatic Use

**Parameter:** GenerateReport

**Type:** character vector

**Value:** 'on' | 'off'

**Default:** 'off'

## Version History

Introduced before R2006a

## See Also

### Topics

“Model Configuration Parameters: Code Generation Report” on page 8-2

“Reports for Code Generation”

“HTML Code Generation Report Extensions” (Embedded Coder)

“Configure Code Coverage with Third-Party Tools” (Embedded Coder)

## Open report automatically

Display code generation reports automatically

**Model Configuration Pane:** Code Generation / Report

### Description

The **Open report automatically** parameter specifies whether to open code generation reports automatically when you generate code.

### Dependencies

This parameter is enabled by **Create code generation report**.

### Settings

off (default) | on

On

Displays the code generation report automatically in a new browser window.

Off

Does not display the code generation report, but the report is still available in the html folder.

### Recommended Settings

| Application       | Setting   |
|-------------------|-----------|
| Debugging         | On        |
| Traceability      | On        |
| Efficiency        | No impact |
| Safety precaution | No impact |

### Programmatic Use

**Parameter:** LaunchReport

**Type:** character vector

**Value:** 'on' | 'off'

**Default:** 'off'

### Version History

Introduced before R2006a

### See Also

#### Topics

“Model Configuration Parameters: Code Generation Report” on page 8-2

“Reports for Code Generation”

“HTML Code Generation Report Extensions” (Embedded Coder)





# **Code Generation Parameters: Comments**

## Model Configuration Parameters: Comments

The **Code Generation > Comments** category includes parameters for configuring the comments in the generated code. These parameters require a Simulink Coder license. Additional parameters available with an ERT-based target require an Embedded Coder license.

Code Comments are generated automatically or you can add them to the code.

Code comments have the following uses:

- Enhance the readability and traceability of code
- Convey information among users
- Enhance code search in code base

Code Comments can be classified into Auto generated and Custom comments. Auto generated comments are automatically generated by the software during code generation and the user adds Custom comments.

On the Configuration Parameters dialog box, the following configuration parameters are on the **Code Generation > Comments** pane.

### Auto generated comments

| Parameter                                          | Description                                                                                       |
|----------------------------------------------------|---------------------------------------------------------------------------------------------------|
| Include comments                                   | Specify which comments are in generated files.                                                    |
| Simulink block comments                            | Specify whether to insert Simulink block comments.                                                |
| Trace to model using (Embedded Coder)              | Specify format of comments for Simulink blocks, Stateflow elements and MATLAB function blocks.    |
| Stateflow object comments                          | Specify whether to insert Stateflow object comments.                                              |
| MATLAB source code as comments                     | Specify whether to insert MATLAB source code as comments.                                         |
| Show eliminated blocks                             | Specify whether to insert eliminated block's comments.                                            |
| Verbose comments for 'Model default' storage class | Reduce code size or improve code traceability by controlling the generation of comments.          |
| Operator annotations (Embedded Coder)              | Specify whether to include operator annotations for Polyspace® in the generated code as comments. |

### Custom comments

| Parameter                                    | Description                                                                       |
|----------------------------------------------|-----------------------------------------------------------------------------------|
| Simulink block descriptions (Embedded Coder) | Specify whether to insert descriptions of blocks into generated code as comments. |

| Parameter                                           | Description                                                                                                                             |
|-----------------------------------------------------|-----------------------------------------------------------------------------------------------------------------------------------------|
| Stateflow object descriptions (Embedded Coder)      | Specify whether to insert descriptions of Stateflow objects into generated code as comments.                                            |
| Simulink data object descriptions (Embedded Coder)  | Specify whether to insert descriptions of Simulink data objects into generated code as comments.                                        |
| Requirements in block comments (Embedded Coder)     | Specify whether to include requirement descriptions assigned to Simulink blocks in generated code as comments.                          |
| Custom comments (MPT objects only) (Embedded Coder) | Specify whether to include custom comments for module packaging tool (MPT) signal and parameter data objects in generated code.         |
| MATLAB user comments (Embedded Coder)               | Specify whether to include MATLAB user comments as comments.                                                                            |
| Custom comments function (Embedded Coder)           | Specify a file that contains comments to be included in generated code for module packing tool (MPT) signal and parameter data objects. |

The following configuration parameters are under the **Advanced parameters**.

| Parameter                                  | Description                                                                    |
|--------------------------------------------|--------------------------------------------------------------------------------|
| Comment style (Embedded Coder)             | Specify a multi-line or single-line comment style for generated C or C++ code. |
| Insert Polyspace comments (Embedded Coder) | Specify whether to insert code comments for Polyspace block annotations.       |

- The code generation software automatically inserts comments into the generated code for custom blocks. Therefore, you do not need to include block comments in the associated TLC file for a custom block.

---

**Note** If you have existing TLC files with manually inserted comments for block descriptions, the code generation process emits these comments instead of the automatically generated comments. Consider removing existing block comments from your TLC files. Manually inserted comments might be poorly formatted in the generated code and code-to-model traceability might not work.

---

- For virtual blocks or blocks that have been removed due to block reduction, comments are not generated.
- When you configure the code generator to produce code that includes comments, the code generator includes text for model parameters, block names, signal names, and Stateflow object names in the generated code comments. If the text includes characters that are unrepresented in the character set encoding for the model, the code generator replaces the characters with XML escape sequences. For example, the code generator replaces the Japanese full-width Katakana letter  $\text{ア}$  with the escape sequence `&#x30A2;`. For more information, see “Internationalization and Code Generation”.
- When you set the model configuration parameter **Default parameter behavior** to `Tunable`, the code generator adds different comments about numeric block parameters in the generated code depending on the numeric value of the block parameter and the output data type. For instance, code generator adds:

- `Computed Parameter` as a comment when the numeric value of the block parameter needs type conversion to match the output data type.
- `Expression` as a comment when the numeric value of the block parameter matches the output data type without type conversion.

Simulink interprets the data type of a numeric parameter as double unless you explicitly specify otherwise. Generate code for the following model:

```
// Parameters (auto storage)
struct P_test_parameter_T_ {
 real_T Constant1_Value; // Expression: 200
 // Referenced by: '<Root>/Constant1'

 real_T Constant2_Value; // Computed Parameter: Constant2_Value
 // Referenced by: '<Root>/Constant2'

 int32_T Constant3_Value; // Computed Parameter: Constant3_Value
 // Referenced by: '<Root>/Constant3'
};
```

When the constant value is 200 and the output data type is double, the code generator adds `Expression` as a comment. Simulink interprets the data type of the constant value as double and without type conversion it matches the output data type.

When the constant value is `uint8(200)` and the output data type is double, the code generator adds `Computed Parameter` as a comment. The constant value requires type conversion to match the output data type.

When the constant value is 500 and the output data type is `int32`, the code generator adds `Computed Parameter` as a comment. The constant value requires type conversion to match the output data type.

## See Also

### More About

- “Configure Code Comments”
- “Verify Generated Code by Using Code Tracing” (Embedded Coder)

## Code Generation: Comments Tab Overview

Control the comments that the code generator creates and inserts into the generated code.

### See Also

### Related Examples

- “Model Configuration Parameters: Comments” on page 9-2

## Include comments

Include comments in generated code

**Model Configuration Pane:** Code Generation / Comments

### Description

Specify which comments are in generated files.

### Dependencies

This parameter enables:

- **Simulink block comments** on page 9-8
- **Stateflow object comments** on page 9-10
- **MATLAB source code as comments** on page 9-12
- **Show eliminated blocks** on page 9-14
- **Verbose comments for 'Model default' storage class** on page 9-15

### Settings

on (default) | off

On

Places comments in the generated files based on the selections in the **Auto generated comments** pane.

Off

Omits comments from the generated files.

---

**Note** This parameter does not apply to copyright notice comments in the generated code.

---

### Recommended Settings

| Application       | Setting           |
|-------------------|-------------------|
| Debugging         | On                |
| Traceability      | On                |
| Efficiency        | No impact         |
| Safety precaution | No recommendation |

### Programmatic Use

**Parameter:** GenerateComments

**Type:** character vector

**Value:** 'on' | 'off'

**Default:** 'on '

## **Version History**

**Introduced before R2006a**

### **See Also**

#### **Topics**

“Model Configuration Parameters: Comments” on page 9-2

“Configure Code Comments”

“Verify Generated Code by Using Code Tracing” (Embedded Coder)

## Simulink block comments

Include Simulink block comments

**Model Configuration Pane:** Code Generation / Comments

### Description

Specify whether to insert Simulink block comments.

### Dependencies

- **Include comments** on page 9-6 enables this parameter.
- This parameter enables **Trace to model using** (Embedded Coder).

### Settings

on (default) | off

On

Inserts automatically generated comments that describe a block's code. The comments precede generated code in the generated file.

Off

Suppresses comments.

### Recommended Settings

| Application       | Setting           |
|-------------------|-------------------|
| Debugging         | On                |
| Traceability      | On                |
| Efficiency        | No impact         |
| Safety precaution | No recommendation |

### Programmatic Use

**Parameter:** SimulinkBlockComments

**Type:** character vector

**Value:** 'on' | 'off'

**Default:** 'on'

### Version History

Introduced before R2006a



## **See Also**

### **Topics**

“Model Configuration Parameters: Comments” on page 9-2

“Trace Simulink Model Elements in Generated Code” (Embedded Coder)

## Stateflow object comments

Include Stateflow object comments

**Model Configuration Pane:** Code Generation / Comments

### Description

Specify whether to insert Stateflow object comments.

### Dependencies

- **Include comments** on page 9-6 enables this parameter.
- This parameter enables **Trace to model using** (Embedded Coder).

### Settings

off (default) | on

On

Inserts automatically generated comments that contain Stateflow object IDs or MATLAB code line locations. The comments precede the generated code in the generated file. For example,

```
/* Entry 'First': '<S2>:2' */
rtY.Out1 = 1;
```

'<S2>:2' is a hyperlinked traceability tag that facilitates tracing of generated code to corresponding Stateflow element.

Off

Suppresses comments.

### Recommended Settings

| Application       | Setting           |
|-------------------|-------------------|
| Debugging         | On                |
| Traceability      | On                |
| Efficiency        | No impact         |
| Safety precaution | No recommendation |

### Programmatic Use

**Parameter:** StateflowObjectComments

**Type:** character vector

**Value:** 'on' | 'off'

**Default:** 'off'

## **Version History**

**Introduced in R2017b**

### **See Also**

#### **Topics**

"Model Configuration Parameters: Comments" on page 9-2

"Trace Stateflow Elements in Generated Code" (Embedded Coder)

## MATLAB source code as comments

Include MATLAB source code as comments

**Model Configuration Pane:** Code Generation / Comments

### Description

Specify whether to insert MATLAB source code as comments.

### Dependencies

**Include comments** on page 9-6 enables this parameter.

### Settings

off (default) | on

On

Inserts MATLAB source code as comments in the generated code. The comment appears after the traceability tag and precedes the associated generated code. For example,

```
/* '<S2>:1:22' xb1 = x-1; */
xb1 = x;
```

Selecting this parameter adds the MATLAB code `xb1 = x-1;` in the traceability comment.

Includes the function signature in the function banner.

Off

Suppresses comments and does not include the function signature in the function banner.

### Recommended Settings

| Application       | Setting           |
|-------------------|-------------------|
| Debugging         | On                |
| Traceability      | On                |
| Efficiency        | No impact         |
| Safety precaution | No recommendation |

### Programmatic Use

**Parameter:** MATLABSourceComments

**Type:** character vector

**Value:** 'on' | 'off'

**Default:** 'off'

### Version History

**Introduced in R2010b**

## See Also

### Topics

“Model Configuration Parameters: Comments” on page 9-2

“Include MATLAB Code as Comments in the Generated Code” (Embedded Coder)

## Show eliminated blocks

Include eliminated blocks' comments

**Model Configuration Pane:** Code Generation / Comments

### Description

Specify whether to insert eliminated blocks' comments.

### Dependencies

**Include comments** on page 9-6 enables this parameter.

### Settings

on (default) | off

On

Inserts statements in the generated code from blocks eliminated as the result of optimizations (such as parameter inlining).

Off

Suppresses statements.

### Recommended Settings

| Application       | Setting           |
|-------------------|-------------------|
| Debugging         | On                |
| Traceability      | On                |
| Efficiency        | No impact         |
| Safety precaution | No recommendation |

### Programmatic Use

**Parameter:** ShowEliminatedStatement

**Type:** character vector

**Value:** 'on' | 'off'

**Default:** 'on'

### Version History

Introduced before R2006a

### See Also

#### Topics

“Model Configuration Parameters: Comments” on page 9-2

# Verbose comments for 'Model default' storage class

Reduce code size or improve code traceability

**Model Configuration Pane:** Code Generation / Comments

## Description

Reduce code size or improve code traceability by controlling the generation of comments. The comments appear interleaved in the code that initializes the fields of the model parameter structure, which appears in the *model\_data.c* file or the *model.c* file. Each comment indicates the name of a parameter object (Simulink.Parameter) or MATLAB variable and the blocks that use the object or variable to set parameter values.

Parameter objects and MATLAB variables appear in the model parameter structure under either of these conditions:

- You apply the storage class `Model default` to the object or variable and, in the Code Mappings editor, you set the storage class of the corresponding category of data to the default setting, `Default`.
- You apply the storage class `Auto` to the object or variable and set the model configuration parameter **Default parameter behavior** to `Tunable`. In the Code Mappings editor, you set the storage class of the corresponding category of data to the default setting, `Default`.

For more information about parameter representation in the generated code, see “How Generated Code Stores Internal Signal, State, and Parameter Data”.

## Dependencies

**Include comments** on page 9-6 enables this parameter.

## Settings

on (default) | off

**Default:** On

On

Generate comments regardless of the number of parameter values stored in the parameter structure. Use this setting to improve traceability between the generated code and the parameter objects or variables that the model uses.

Off

Generate comments only if the parameter structure contains fewer than 1000 parameter values. An array parameter with  $n$  elements represents  $n$  values. For large models, use this setting to reduce the size of the generated file.

## Recommended Settings

| Application       | Setting           |
|-------------------|-------------------|
| Debugging         | On                |
| Traceability      | On                |
| Efficiency        | No impact         |
| Safety precaution | No recommendation |

## Programmatic Use

**Parameter:** ForceParamTrailComments

**Type:** character vector

**Value:** 'on' | 'off'

**Default:** 'on'

## Version History

Introduced before R2006a

## See Also

### Topics

“Model Configuration Parameters: Comments” on page 9-2

“How Generated Code Stores Internal Signal, State, and Parameter Data”



# **Code Generation Parameters: Identifiers**

---

## Model Configuration Parameters: Code Generation Identifiers

The **Code Generation > Identifiers** category includes parameters for configuring the comments in the generated code. These parameters require a Simulink Coder license. Additional parameters available with an ERT-based target require an Embedded Coder license.

On the Configuration Parameters dialog box, the following configuration parameters are on the **Code Generation > Identifiers** pane.

| Parameter                                              | Description                                                                                                                              |
|--------------------------------------------------------|------------------------------------------------------------------------------------------------------------------------------------------|
| Global variables (Embedded Coder)                      | Customize generated global variable identifiers.                                                                                         |
| Global types (Embedded Coder)                          | Customize generated global type identifiers.                                                                                             |
| Field name of global types (Embedded Coder)            | Customize generated field names of global types.                                                                                         |
| Subsystem methods (Embedded Coder)                     | Customize generated function names for reusable subsystems.                                                                              |
| Subsystem method arguments (Embedded Coder)            | Customize generated function argument names for reusable subsystems.                                                                     |
| Local temporary variables (Embedded Coder)             | Customize generated local temporary variable identifiers.                                                                                |
| Local block output variables (Embedded Coder)          | Customize generated local block output variable identifiers.                                                                             |
| Constant macros (Embedded Coder)                       | Customize generated constant macro identifiers.                                                                                          |
| Shared utilities identifier format (Embedded Coder)    | Customize shared utility identifiers.                                                                                                    |
| Minimum mangle length (Embedded Coder)                 | Specify the minimum number of characters for generating name-mangling text to help avoid name collisions.                                |
| Maximum identifier length                              | Specify maximum number of characters in generated function, type definition, variable names.                                             |
| System-generated identifiers (Embedded Coder)          | Specify whether the code generator uses shorter, more consistent names for the \$N token in system-generated identifiers.                |
| Generate scalar inlined parameters as (Embedded Coder) | Control expression of scalar inlined parameter values in the generated code.                                                             |
| Use the same reserved names as Simulation Target       | Specify whether to use the same reserved names as those specified in the <b>Simulation Target</b> pane.                                  |
| Reserved names                                         | Enter the names of variables or functions in the generated code that match the names of variables or functions specified in custom code. |

The following configuration parameters are under the **Advanced parameters**.

| Parameter                                                      | Description                                                                                                                                                                                                               |
|----------------------------------------------------------------|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Shared checksum length (Embedded Coder)                        | Specify character length of \$C token.                                                                                                                                                                                    |
| EMX array utility functions identifier format (Embedded Coder) | Customize generated identifiers for emxArray (embeddable mxArray) utility functions.                                                                                                                                      |
| EMX array types identifier format (Embedded Coder)             | Customize generated identifiers for emxArray (embeddable mxArray ) types.                                                                                                                                                 |
| Custom token text (Embedded Coder)                             | Specify text to insert for \$U token.                                                                                                                                                                                     |
| Duplicate enumeration member names                             | Select the diagnostic action to take if the code generator detects two enumeration types with same member names. This parameter applies to only enumeration with imported data scope and the same storage type and value. |
| Signal naming (Embedded Coder)                                 | Specify rules for naming signals in generated code.                                                                                                                                                                       |
| M-function (Embedded Coder)                                    |                                                                                                                                                                                                                           |
| Parameter naming (Embedded Coder)                              | Specify rule for naming parameters in generated code.                                                                                                                                                                     |
| M-function (Embedded Coder)                                    |                                                                                                                                                                                                                           |
| #define naming (Embedded Coder)                                | Specify rule for naming #define parameters (defined with storage class Define (Custom)) in generated code.                                                                                                                |
| M-function (Embedded Coder)                                    |                                                                                                                                                                                                                           |

## See Also

### More About

- “Code Appearance”
- “Model Configuration”

## Code Generation: Identifiers Tab Overview

Select the automatically generated identifier naming rules.

### See Also

### Related Examples

- “Model Configuration Parameters: Code Generation Identifiers” on page 10-2
- “Construction of Generated Identifiers”
- “Identifier Name Collisions and Mangling”
- “Specify Identifier Length to Avoid Naming Collisions”
- “Specify Reserved Names for Generated Identifiers”
- “Customize Generated Identifier Naming Rules” (Embedded Coder)

# Maximum identifier length

Specify maximum number of characters in identifiers

**Model Configuration Pane:** Code Generation / Identifiers

## Description

Specify maximum number of characters in generated function, type definition, variable names.

## Settings

31 (default) | integer

**Minimum:** 31

**Maximum:** 256

You can use this parameter to limit the number of characters in function, type definition, and variable names.

## Tips

- Consider increasing identifier length for models having a deep hierarchical structure.
- When generating code from a model that uses model referencing, the **Maximum identifier length** must be large enough to accommodate the root model name, and possibly, the name-mangling text. A code generation error occurs if **Maximum identifier length** is too small.
- This parameter must be the same for both top-level and referenced models.
- When a name conflict occurs between a symbol within the scope of a higher level model and a symbol within the scope of a referenced model, the symbol from the referenced model is preserved. Name mangling is performed on the symbol from the higher level model.

## Recommended Settings

| Application       | Setting     |
|-------------------|-------------|
| Debugging         | Valid value |
| Traceability      | >30         |
| Efficiency        | No impact   |
| Safety precaution | >30         |

## Programmatic Use

**Parameter:** MaxIdLength

**Type:** integer

**Value:** valid value

**Default:** 31

## **Version History**

**Introduced before R2006a**

### **See Also**

#### **Topics**

"Model Configuration Parameters: Code Generation Identifiers" on page 10-2

"Construction of Generated Identifiers"

"Identifier Name Collisions and Mangling"

"Identifier Format Control" (Embedded Coder)

# Use the same reserved names as Simulation Target

Specify whether to use reserved names from the Simulation Target pane

**Model Configuration Pane:** Code Generation / Identifiers

## Description

Specify whether to use the same reserved names as those specified in the **Simulation Target** pane.

## Settings

off (default) | on

On

Enables using the same reserved names as those specified in the **Simulation Target** pane.

Off

Disables using the same reserved names as those specified in the **Simulation Target** pane.

## Recommended Settings

| Application       | Setting   |
|-------------------|-----------|
| Debugging         | No impact |
| Traceability      | No impact |
| Efficiency        | No impact |
| Safety precaution | No impact |

## Programmatic Use

**Parameter:** UseSimReservedNames

**Type:** character vector

**Value:** 'on' | 'off'

**Default:** 'off'

## Version History

Introduced in R2008b

## See Also

### Topics

"Model Configuration Parameters: Code Generation Identifiers" on page 10-2

## Reserved names

Avoid name conflicts with custom code

**Model Configuration Pane:** Code Generation / Identifiers

### Description

Enter the names of variables or functions in the generated code that match the names of variables or functions specified in custom code.

### Settings

{ } (default) | array

This action changes the names of variables or functions in the generated code to avoid name conflicts with identifiers in custom code. Reserved names must be shorter than 256 characters.

### Tips

- Do not enter code generator keywords since these names cannot be changed in the generated code. For a list of keywords to avoid, see “Reserved Keywords”.
- Start each reserved name with a letter or an underscore to prevent error messages.
- Each reserved name must contain only letters, numbers, or underscores.
- Separate the reserved names using commas or spaces.
- You can also specify reserved names by using the command line:

```
config_param_object.set_param('ReservedNameArray', {'abc', 'xyz'})
```

where `config_param_object` is the object handle to the model settings in the Configuration Parameters dialog box.

### Recommended Settings

| Application       | Setting   |
|-------------------|-----------|
| Debugging         | No impact |
| Traceability      | No impact |
| Efficiency        | No impact |
| Safety precaution | No impact |

### Programmatic Use

**Parameter:** ReservedNameArray

**Type:** cell array of character vectors or string array

**Value:** reserved names shorter than 256 characters

**Default:** { }



## **Version History**

**Introduced in R2008b**

### **See Also**

#### **Topics**

“Model Configuration Parameters: Code Generation Identifiers” on page 10-2

## Duplicate enumeration member names

Specify the action to take if the code generator detects two enumeration types with same member names

**Model Configuration Pane:** Code Generation / Identifiers

### Description

Select the diagnostic action to take if the code generator detects two enumeration types with same member names. This parameter applies to only enumeration with imported data scope and the same storage type and value.

### Settings

error (default) | none | warning

none

When the code generator detects two enumeration types with the same member names, the code generation proceeds.

warning

When the code generator detects two enumeration types with the same member names, the software issues a warning message and the code generation proceeds.

error

When the code generator detects two enumeration types with the same member names, the software issues an error message and terminates the code generation.

### Examples

#### Handle Duplicate Enumeration Member Names

Consider these enumerations:

```
typedef int32_T enumA;
#define a (0)
#define p (1)

typedef int32_T enumB;
#define b (0)
#define p (1)
```

The enumerations have the same `int32` storage type. The enumeration member `p` with value `1` is the same for `enumA` and `enumB`.

Generate an error or warning message or allow code generation for duplicate enumeration member names by using the **Duplicate enumeration member names** configuration parameter.

## Recommended Settings

| Application       | Setting   |
|-------------------|-----------|
| Debugging         | No impact |
| Traceability      | No impact |
| Efficiency        | No impact |
| Safety precaution | No impact |

## Programmatic Use

**Parameter:** EnumMemberNameClash

**Type:** character vector

**Value:** 'none' | 'warning' | 'error'

**Default:** 'error'

## Version History

Introduced in R2019b

## See Also

### Topics

“Use Enumerated Data in Generated Code”

“Use Enumerated Data in Simulink Models”

“Model Configuration Parameters: Code Generation Identifiers” on page 10-2



# Code Generation Parameters: Custom Code

---

## Model Configuration Parameters: Code Generation Custom Code

The **Code Generation > Custom Code** category includes parameters for inserting custom C code into the generated code. These parameters require a Simulink Coder license.

On the Configuration Parameters dialog box, the following configuration parameters are on the **Code Generation > Custom Code** pane.

| Parameter                                              | Description                                                                                                          |
|--------------------------------------------------------|----------------------------------------------------------------------------------------------------------------------|
| Use the same custom code settings as Simulation Target | Specify whether to use the same custom code settings as those in the <b>Simulation Target &gt; Custom Code</b> pane. |
| Additional code                                        | Specify custom code to include near the top of the generated model source file.                                      |
| Include headers                                        | Specify custom code to include near the top of the generated model header file.                                      |
| Initialize code                                        | Specify custom code to include in the generated model initialize function.                                           |
| Terminate code                                         | Specify custom code to include in the generated model terminate function.                                            |
| Include directories                                    | Specify a list of include folders to add to the include path.                                                        |
| Source files                                           | Specify a list of additional source files to compile and link with the generated code.                               |
| Libraries                                              | Specify a list of additional libraries to link with the generated code.                                              |
| Defines                                                | Specify preprocessor macro definitions to be added to the compiler command line.                                     |

### See Also

### More About

- “Model Configuration”

## Code Generation: Custom Code Tab Overview

Enter custom code to include in generated model files and create a list of additional folders, source files, and libraries to use when building the model.

### Configuration

- 1 Select the type of information to include from the list on the left side of the pane.
- 2 Enter custom code or enter text to identify a folder, source file, or library.
- 3 Click **Apply**.

### See Also

#### Related Examples

- “Model Configuration Parameters: Code Generation Custom Code” on page 11-2
- “Integrate External Code by Using Model Configuration Parameters”

## Use the same custom code settings as Simulation Target

Use custom code settings from the Simulation Target > Custom Code pane

**Model Configuration Pane:** Code Generation / Custom Code

### Description

Specify whether to use the same custom code settings as those in the **Simulation Target > Custom Code** pane.

### Settings

off (default) | on

On

Enables using the same custom code settings as those in the **Simulation Target > Custom Code** pane.

Off

Disables using the same custom code settings as those in the **Simulation Target > Custom Code** pane.

### Recommended Settings

| Application       | Setting   |
|-------------------|-----------|
| Debugging         | No impact |
| Traceability      | No impact |
| Efficiency        | No impact |
| Safety precaution | No impact |

### Programmatic Use

**Parameter:** RTWUseSimCustomCode

**Type:** character vector

**Value:** 'on' | 'off'

**Default:** 'off'

### Version History

Introduced in R2008b

### See Also

#### Topics

“Model Configuration Parameters: Code Generation Custom Code” on page 11-2



“Integrate External Code by Using Model Configuration Parameters”

## Additional code

Include custom code in the generated model source file

**Model Configuration Pane:** Code Generation / Custom Code

### Description

Specify custom code to include near the top of the generated model source file.

### Settings

' ' (default) | string

The code generator places code near the top of the generated *model.c* or *model.cpp* file, outside of any function.

### Recommended Settings

| Application       | Setting   |
|-------------------|-----------|
| Debugging         | No impact |
| Traceability      | No impact |
| Efficiency        | No impact |
| Safety precaution | No impact |

### Programmatic Use

**Parameter:** CustomSourceCode

**Type:** character vector

**Value:** C code

**Default:** ' '

### Version History

Introduced before R2006a

### See Also

#### Topics

“Model Configuration Parameters: Code Generation Custom Code” on page 11-2

“Integrate External Code by Using Model Configuration Parameters”

# Include headers

Include custom code in the generated model header file

**Model Configuration Pane:** Code Generation / Custom Code

## Description

Specify custom code to include near the top of the generated model header file.

## Settings

' ' (default) | string

The code generator places this code near the top of the generated `model.h` header file. If you are including a header file, in your custom header file add `#ifndef` code. This avoids linker errors and multiple inclusions. For example, in `rtwtypes.h` the following `#include` guards are added:

```
#ifndef RTW_HEADER_rtwtypes_h_
#define RTW_HEADER_rtwtypes_h_
...
#endif /* RTW_HEADER_rtwtypes_h_ */
```

## Recommended Settings

| Application       | Setting   |
|-------------------|-----------|
| Debugging         | No impact |
| Traceability      | No impact |
| Efficiency        | No impact |
| Safety precaution | No impact |

## Programmatic Use

**Parameter:** CustomHeaderCode

**Type:** character vector

**Value:** C code

**Default:** ' '

## Version History

Introduced before R2006a

## See Also

### Topics

“Model Configuration Parameters: Code Generation Custom Code” on page 11-2

“Integrate External Code by Using Model Configuration Parameters”

## Initialize code

Include custom code in the generated model initialize function

**Model Configuration Pane:** Code Generation / Custom Code

### Description

Specify custom code to include in the generated model initialize function.

### Settings

' ' (default) | string

The code generator places code inside the model's initialize function in the *model.c* or *model.cpp* file.

### Recommended Settings

| Application       | Setting   |
|-------------------|-----------|
| Debugging         | No impact |
| Traceability      | No impact |
| Efficiency        | No impact |
| Safety precaution | No impact |

### Programmatic Use

**Parameter:** CustomInitializer

**Type:** character vector

**Value:** C code

**Default:** ' '

### Version History

Introduced before R2006a

### See Also

#### Topics

“Model Configuration Parameters: Code Generation Custom Code” on page 11-2

“Integrate External Code by Using Model Configuration Parameters”

## Terminate code

Include custom code in the generated model terminate function

**Model Configuration Pane:** Code Generation / Custom Code

### Description

Specify custom code to include in the generated model terminate function.

### Dependencies

A terminate function is generated only if you select the **Terminate function required** check box.

### Settings

' ' (default) | string

Specify code to appear in the model's generated terminate function in the *model.c* or *model.cpp* file.

### Recommended Settings

| Application       | Setting   |
|-------------------|-----------|
| Debugging         | No impact |
| Traceability      | No impact |
| Efficiency        | No impact |
| Safety precaution | No impact |

### Programmatic Use

**Parameter:** CustomTerminator

**Type:** character vector

**Value:** C code

**Default:** ' '

### Version History

Introduced before R2006a

### See Also

#### Topics

“Model Configuration Parameters: Code Generation Custom Code” on page 11-2

“Integrate External Code by Using Model Configuration Parameters”

## Include directories

Add folders to the include path

**Model Configuration Pane:** Code Generation / Custom Code

### Description

Specify a list of include folders to add to the include path.

### Settings

' ' (default) | string

Enter a space-separated list of include folders to add to the include path when compiling the generated code.

- Specify absolute or relative paths to the folders.
- Relative paths must be relative to the folder containing your model files, not relative to the build folder.
- The order in which you specify the folders is the order in which they are searched for header, source, and library files.

---

**Note** If a folder path contains one or more spaces, you must enclose the path in double quotes. For example, this **Include directories** field entry, which specifies three folder paths, uses double quotes for the second and third paths:

```
C:\Project "C:\Custom Files" "C:\Library Files"
```

To specify the same folder paths from the command line, run:

```
set_param('mymodel', 'CustomInclude', ...
 'C:\Project "C:\Custom Files" "C:\Library Files"')
```

---

### Recommended Settings

| Application       | Setting   |
|-------------------|-----------|
| Debugging         | No impact |
| Traceability      | No impact |
| Efficiency        | No impact |
| Safety precaution | No impact |

### Programmatic Use

**Parameter:** CustomInclude

**Type:** character vector

**Value:** folder path

**Default:** ''

## **Version History**

**Introduced before R2006a**

### **See Also**

#### **Topics**

“Model Configuration Parameters: Code Generation Custom Code” on page 11-2

“Integrate External Code by Using Model Configuration Parameters”

## Source files

Compile and link additional source files with the generated code

**Model Configuration Pane:** Code Generation / Custom Code

### Description

Specify a list of additional source files to compile and link with the generated code.

### Settings

' ' (default) | string

Enter a space-separated list of source files to compile and link with the generated code.

### Tip

You can specify just the file name if the file is in the current MATLAB folder or in one of the include folders.

### Recommended Settings

| Application       | Setting   |
|-------------------|-----------|
| Debugging         | No impact |
| Traceability      | No impact |
| Efficiency        | No impact |
| Safety precaution | No impact |

### Programmatic Use

**Parameter:** CustomSource

**Type:** character vector

**Value:** file name

**Default:** ' '

### Limitation

This parameter does not support Windows file names that contain embedded spaces.

### Version History

**Introduced before R2006a**

### See Also

#### Topics

“Model Configuration Parameters: Code Generation Custom Code” on page 11-2



“Integrate External Code by Using Model Configuration Parameters”

## Libraries

Link additional libraries with the generated code

**Model Configuration Pane:** Code Generation / Custom Code

### Description

Specify a list of additional libraries to link with the generated code.

### Settings

' ' (default) | string

Enter a space-separated list of static library files to link with the generated code.

### Tip

You can specify just the file name if the file is in the current MATLAB folder or in one of the include folders.

### Recommended Settings

| Application       | Setting   |
|-------------------|-----------|
| Debugging         | No impact |
| Traceability      | No impact |
| Efficiency        | No impact |
| Safety precaution | No impact |

### Programmatic Use

**Parameter:** CustomLibrary

**Type:** character vector

**Value:** library file name

**Default:** ' '

### Limitation

This parameter does not support Windows file names that contain embedded spaces.

### Version History

**Introduced before R2006a**

### See Also

#### Topics

“Model Configuration Parameters: Code Generation Custom Code” on page 11-2

“Integrate External Code by Using Model Configuration Parameters”

## Defines

Add preprocessor macro definitions to the compiler command line

**Model Configuration Pane:** Code Generation / Custom Code

### Description

Specify preprocessor macro definitions to be added to the compiler command line.

### Settings

' ' (default) | string

Enter a list of macro definitions for the compiler command line. Specify the parameters with a space-separated list of macro definitions. If a makefile is generated, these macro definitions are added to the compiler command line in the makefile. The list can include simple definitions (for example, -DDEF1), definitions with a value (for example, -DDEF2=1), and definitions with a space in the value (for example, -DDEF3="my value"). Definitions can omit the -D (for example, -DF00=1 and F00=1 are equivalent). If the toolchain uses a different flag for definitions, the code generator overrides the -D and uses the appropriate flag for the toolchain.

### Recommended Settings

| Application       | Setting   |
|-------------------|-----------|
| Debugging         | No impact |
| Traceability      | No impact |
| Efficiency        | No impact |
| Safety precaution | No impact |

### Programmatic Use

**Parameter:** CustomDefine

**Type:** character vector

**Value:** preprocessor macro definition

**Default:** ' '

### Version History

Introduced in R2016a

### See Also

#### Topics

"Model Configuration Parameters: Code Generation Custom Code" on page 11-2

"Integrate External Code by Using Model Configuration Parameters"

# Code Generation Parameters: Interface

---

## Model Configuration Parameters: Code Generation Interface

The **Code Generation > Interface** category includes parameters for configuring the interface of the generated code. These parameters require a Simulink Coder license. Additional parameters available with an ERT-based target require an Embedded Coder license. Generating code for deep learning models using NVIDIA CUDA deep neural network library (cuDNN) or TensorRT high performance inference libraries for NVIDIA GPUs requires a GPU Coder license.

On the Configuration Parameters dialog box, the following configuration parameters are on the **Code Generation > Interface** pane.

| Parameter                                                                      | Description                                                                                                                                                                                               |
|--------------------------------------------------------------------------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| “Code replacement library” on page 12-9                                        | Specify a code replacement library the code generator uses when producing code for a model.                                                                                                               |
| “Code replacement libraries” (Embedded Coder)                                  | Specify multiple code replacement libraries the code generator use when producing code for a model.                                                                                                       |
| “Shared code placement” on page 12-11                                          | Specify the location for generating utility functions, exported data type definitions, and declarations of exported data with custom storage class.                                                       |
| “Support: floating-point numbers” (Embedded Coder)                             | Specify whether to generate floating-point data and operations.                                                                                                                                           |
| “Support: non-finite numbers” on page 12-13                                    | Specify whether to generate non-finite data and operations on non-finite data.                                                                                                                            |
| “Support: complex numbers” (Embedded Coder)                                    | Specify whether to generate complex data and operations.                                                                                                                                                  |
| “Support: absolute time” (Embedded Coder)                                      | Specify whether to generate and maintain integer counters for absolute and elapsed time values.                                                                                                           |
| “Support: continuous time” (Embedded Coder)                                    | Specify whether to generate code for blocks that use continuous time.<br><br>This parameter does not apply when you use Embedded Coder for a component model that is configured with a service interface. |
| “Support: variable-size signals” (Embedded Coder)                              | Specify whether to generate code for models that use variable-size signals.                                                                                                                               |
| “Code interface packaging” on page 12-15                                       | Select the packaging for the generated C or C++ code interface.                                                                                                                                           |
| “Multi-instance code error diagnostic” on page 12-18                           | Select the severity level for diagnostics displayed when a model violates requirements for generating multi-instance code.                                                                                |
| “Pass root-level I/O as” (Embedded Coder)                                      | Control how root-level model input and output are passed to the reusable <code>model_step</code> function.                                                                                                |
| “Remove error status field in real-time model data structure” (Embedded Coder) | Specify whether to log or monitor error status.                                                                                                                                                           |

| Parameter                                                                      | Description                                                                                                                                                                                                       |
|--------------------------------------------------------------------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| "Include model types in model class" (Embedded Coder)                          | Specify whether to generate model type definitions in a model class.                                                                                                                                              |
| "Array layout" on page 12-46                                                   | Specify layout of array data for code generation as column-major or row-major                                                                                                                                     |
| "External functions compatibility for row-major code generation" on page 12-48 | Select diagnostic action if Simulink encounters a function that has no specified array layout                                                                                                                     |
| "Generate C API for: signals" on page 12-20                                    | Generate C API data interface code with a signals structure.                                                                                                                                                      |
| "Generate C API for: parameters" on page 12-21                                 | Generate C API data interface code with parameter tuning structures.                                                                                                                                              |
| "Generate C API for: states" on page 12-22                                     | Generate C API data interface code with a states structure.                                                                                                                                                       |
| "Generate C API for: root-level I/O" on page 12-23                             | Generate C API data interface code with a root-level I/O structure.                                                                                                                                               |
| "ASAP2 interface" on page 12-24                                                | Generate code for the ASAP2 data interface.                                                                                                                                                                       |
| "External mode" on page 12-25                                                  | Generate code for the external mode data interface. When using Embedded Coder for a component model that is configured with a service interface, this parameter is not relevant and, therefore, is not supported. |
| "Transport layer" on page 12-26                                                | Specify the transport protocol for communications.                                                                                                                                                                |
| "MEX-file arguments" on page 12-28                                             | Specify arguments to pass to an external mode interface MEX-file for communicating with executing targets.                                                                                                        |
| "Static memory allocation" on page 12-30                                       | Control memory buffer for external mode communication.                                                                                                                                                            |
| "Static memory buffer size" on page 12-41                                      | Specify the memory buffer size for external mode communication.                                                                                                                                                   |
| "Automatically allocate static memory" on page 12-32                           | Automatically allocate static memory for buffers used in external mode communication.                                                                                                                             |
| "Maximum duration" on page 12-34                                               | Specify, in base rate steps, maximum duration that software must consider when determining size of static memory required for external mode communication.                                                        |
| "Target library" on page 12-36                                                 | Specify the target deep learning library used during code generation.<br><br>cuDNN or TensorRT requires a GPU Coder license.                                                                                      |
| "ARM Compute Library version" on page 12-38                                    | Specify the version of ARM Compute Library.                                                                                                                                                                       |
| "ARM Compute Library architecture" on page 12-39                               | Specify the ARM architecture supported in the target hardware.                                                                                                                                                    |

| Parameter                   | Description                                                                                                                                                                      |
|-----------------------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| "Auto tuning" on page 12-40 | Use auto tuning for cuDNN library. Enabling auto tuning allows the cuDNN library to find the fastest convolution algorithms.<br><br>This parameter requires a GPU Coder license. |

These configuration parameters are under the **Advanced parameters**.

| Parameter                                                                 | Description                                                                                                                                                                                                                                                                     |
|---------------------------------------------------------------------------|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| "Support non-inlined S-functions" (Embedded Coder)                        | Specify whether to generate code for non-inlined S-functions.<br><br>This parameter does not apply when you use Embedded Coder for a component model that is configured with a service interface.                                                                               |
| "Maximum word length" on page 12-50                                       | Specify a maximum word length, in bits, for which the code generation process generates system-defined multiword type definitions.                                                                                                                                              |
| "Buffer size of dynamically-sized string (bytes)" on page 12-45           | Number of bytes of the character buffer generated for dynamic string signals without maximum length.                                                                                                                                                                            |
| "Multiword type definitions" (Embedded Coder)                             | Specify whether to use system-defined or user-defined type definitions for multiword data types in generated code.                                                                                                                                                              |
| "Classic call interface" on page 12-52                                    | Specify whether to generate model function calls compatible with the main program module of the GRT target in models created before R2012a.<br><br>This parameter does not apply when you use Embedded Coder for a component model that is configured with a service interface. |
| "Use dynamic memory allocation for model initialization" (Embedded Coder) | Control how the generated code allocates memory for model data.                                                                                                                                                                                                                 |
| "Single output/update function" on page 12-54                             | Specify whether to generate the <i>model_step</i> function.<br><br>This parameter does not apply when you use Embedded Coder for a component model that is configured with a service interface.                                                                                 |
| "Terminate function required" (Embedded Coder)                            | Specify whether to generate the <i>model_terminate</i> function.                                                                                                                                                                                                                |



| Parameter                                                                      | Description                                                                                                                                                                                                                                               |
|--------------------------------------------------------------------------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| “Combine signal/state structures” (Embedded Coder)                             | Specify whether to combine global block signals and global state data into one data structure in the generated code<br><br>You cannot clear this parameter when you use Embedded Coder for a component model that is configured with a service interface. |
| “Generate separate internal data per entry-point function” (Embedded Coder)    | Generate a model's block signals (block I/O) and discrete states (DWork) acting at the same rate into the same data structure.                                                                                                                            |
| “MAT-file logging” on page 12-56                                               | Specify MAT-file logging.<br><br>This parameter does not apply when you use Embedded Coder for a component model that is configured with a service interface.                                                                                             |
| “MAT-file variable name modifier” (Embedded Coder)                             | Select the text to add to MAT-file variable names.                                                                                                                                                                                                        |
| “Existing shared code” (Embedded Coder)                                        | Specify folder that contains existing shared code                                                                                                                                                                                                         |
| “Remove disable function” (Embedded Coder)                                     | Remove unreachable (dead-code) instances of the <code>disable</code> functions from the generated code for ERT-based systems that include model referencing hierarchies.                                                                                  |
| “Remove reset function” (Embedded Coder)                                       | Remove unreachable (dead-code) instances of the <code>reset</code> functions from the generated code for ERT-based systems that include model referencing hierarchies.                                                                                    |
| “LUT object struct order for even spacing specification” on page 12-43         | Change the order of the fields in the generated structure for a lookup table object whose specification parameter is set to even spacing.                                                                                                                 |
| “LUT object struct order for explicit value specification” on page 12-44       | Change the order of the fields in the generated structure for a lookup table object whose specification parameter is set to explicit value.                                                                                                               |
| “Generate destructor” (Embedded Coder)                                         | Specify whether to generate a destructor for the C++ model class.                                                                                                                                                                                         |
| “Use dynamic memory allocation for model block instantiation” (Embedded Coder) | Specify whether generated code uses the operator <code>new</code> , during model object registration, to instantiate objects for referenced models configured with a C++ class interface.                                                                 |
| “Ignore custom storage classes” (Embedded Coder)                               | Specify whether to apply or ignore custom storage classes.                                                                                                                                                                                                |
| “Ignore test point signals” (Embedded Coder)                                   | Specify allocation of memory buffers for test points.                                                                                                                                                                                                     |
| “Implement each data store block as a unique access point” (Embedded Coder)    | Create unique variables for each read/write operation of a Data Store Memory block.                                                                                                                                                                       |

| Parameter                 | Description                                       |
|---------------------------|---------------------------------------------------|
| Generate full file banner | Generate full header banner including time stamp. |

The following parameters under the **Advanced parameters** are infrequently used and have no other documentation.

| Parameter                                                | Description                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |
|----------------------------------------------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| GenerateSharedConstants                                  | Control whether the code generator generates code with shared constants and shared functions. Default is <code>on</code> . When turned <code>off</code> , the code generator does not generate shared constants.                                                                                                                                                                                                                                                                                             |
| InferredTypesCompatibility                               | For compatibility with legacy code including <code>tmwtypes.h</code> , specify that the code generator creates a preprocessor directive <code>#define __TMWYPES__</code> inside <code>model.h</code> .                                                                                                                                                                                                                                                                                                       |
| TargetLibSuffix<br><i>character vector - ''</i>          | Control the suffix used for naming a target's dependent libraries (for example, <code>_target.lib</code> or <code>_target.a</code> ). If specified, the character vector must include a period ( <code>.</code> ). (For generated model reference libraries, the library suffix defaults to <code>_rtwlib.lib</code> on Windows systems and <code>_rtwlib.a</code> on UNIX systems.)<br><br>This parameter does not apply for model builds that use the toolchain approach, see "Library Control Parameters" |
| TargetPreCompLibLocation<br><i>character vector - ''</i> | Control the location of precompiled libraries. If you do not set this parameter, the code generator uses the location specified in <code>rtwmakecfg.m</code> .                                                                                                                                                                                                                                                                                                                                               |
| IsERTTarget                                              | Indicates whether or not the currently selected target is derived from the ERT target.                                                                                                                                                                                                                                                                                                                                                                                                                       |
| CPPClassGenCompliant                                     | Indicates whether the target supports the ability to generate and configure C++ class interfaces to model code.                                                                                                                                                                                                                                                                                                                                                                                              |
| ConcurrentExecutionCompliant                             | Indicates whether the target supports concurrent execution                                                                                                                                                                                                                                                                                                                                                                                                                                                   |
| UseToolchainInfoCompliant                                | Indicate a custom target is toolchain-compliant.                                                                                                                                                                                                                                                                                                                                                                                                                                                             |
| ModelStepFunctionPrototypeControlCompliant               | Indicates whether the target supports the ability to control the function prototypes of initialize and step functions that are generated for a Simulink model.<br><br>This parameter does not apply when you use Embedded Coder for a component model that is configured with a service interface.                                                                                                                                                                                                           |

| Parameter                                             | Description                                                                                                                                                                                                                                                                                                                                                                             |
|-------------------------------------------------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| ParMdlRefBuildCompliant                               | Indicates if the model is configured for parallel builds when building a model that includes referenced models.                                                                                                                                                                                                                                                                         |
| CompOptLevelCompliant<br>off, on                      | Set in <code>SelectCallback</code> for a target to indicate whether the target supports the ability to use the <b>Compiler optimization level</b> parameter to control the compiler optimization level for building generated code.<br><br>Default is <code>off</code> for custom targets and <code>on</code> for targets provided with the Simulink Coder and Embedded Coder products. |
| ModelReferenceCompliant<br>character vector - off, on | Set in <code>SelectCallback</code> for a target to indicate whether the target supports model reference.                                                                                                                                                                                                                                                                                |

The following parameters are for MathWorks use only.

| Parameter         | Description             |
|-------------------|-------------------------|
| ExtModeTesting    | For MathWorks use only. |
| ExtModeIntrfLevel | For MathWorks use only. |
| ExtModeMexFile    | For MathWorks use only. |

## See Also

## More About

- “Model Configuration”

## **Code Generation: Interface Tab Overview**

Select the target software environment, output variable name modifier, and data exchange interface.

### **See Also**

### **Related Examples**

- “Model Configuration Parameters: Code Generation Interface” on page 12-2
- “Run-Time Environment Configuration”

# Code replacement library

## Description

Specify a code replacement library that the code generator uses when producing code for a model.

**Category:** Code Generation > Interface

## Settings

**Default:** None

None

Does not use a code replacement library.

*Named code replacement libraries*

Generates calls to a specific platform, compiler, or standards code replacement library. The list of named libraries depends on system target file.

## Tips

- Before setting this parameter, verify that your compiler supports the library that you want to use. If you select a parameter value that your compiler does not support, compiler errors can occur.
- If you set parameter **Shared code placement** to `Shared location` or you generate code for models in a model reference hierarchy,
  - Models that are sharing the location or are in the model hierarchy must specify the same code replacement library (same name, tables, and table entries).
  - If you change the name or contents of the code replacement library and rebuild the model from the same folder as the previous build, the code generator reports a checksum warning (see “Manage the Shared Utility Code Checksum”). The warning prompts you to remove the existing folder and stop or stop code generation.
- If both of the following conditions exist for a model that contains Stateflow charts, the Simulink software regenerates code for the charts and recompiles the generated code.
  - You *do not* set parameter **Shared code placement** to `Shared location`.
  - You change the code replacement library name or contents before regenerating code.

## Dependencies

- This parameter appears only for GRT-based targets. For ERT-based targets, use the parameter “Code replacement libraries” (Embedded Coder).

## Command-Line Information

**Parameter:** CodeReplacementLibrary

**Type:** character vector

**Value:** 'None' | 'GNU C99 extensions'

**Default:** 'None '

## Recommended Settings

| Application       | Setting       |
|-------------------|---------------|
| Debugging         | No impact     |
| Traceability      | No impact     |
| Efficiency        | Valid library |
| Safety precaution | No impact     |

## See Also

### Related Examples

- “Model Configuration Parameters: Code Generation Interface” on page 12-2
- “Run-Time Environment Configuration”
- “What Is Code Replacement Customization?” (Embedded Coder)
- “Develop a Code Replacement Library” (Embedded Coder)

# Shared code placement

## Description

Specify the location for generating utility functions, exported data type definitions, and declarations of exported data with custom storage class.

**Category:** Code Generation > Interface

## Settings

**Default:** Auto

### Auto

The code generator places utility code within the `codegenFolder/slprj/target/_sharedutils` (or `codegenFolder/targetSpecific/_shared`) folder for a model that contains Existing Shared Code (Embedded Coder) or at least one of the following blocks:

- Model blocks
- Simulink Function blocks
- Function Caller blocks
- Calls to Simulink Functions from Stateflow or MATLAB Function blocks
- Stateflow graphical functions when you select the **Export Chart Level Functions** parameter

If a model does not contain one of the above blocks or Existing Shared Code (Embedded Coder), the code generator places utility code in the build folder (generally, the folder that contains `model.c` or `model.cpp`).

### Shared location

Directs code for utilities to be placed within the `codegenFolder/slprj/target/_sharedutils` (or `codegenFolder/targetSpecific/_shared`) folder.

## Command-Line Information

**Parameter:** UtilityFuncGeneration

**Type:** character vector

**Value:** 'Auto' | 'Shared location'

**Default:** 'Auto'

## Recommended Settings

| Application  | Setting                                  |
|--------------|------------------------------------------|
| Debugging    | Shared location (GRT)<br>No impact (ERT) |
| Traceability | Shared location (GRT)<br>No impact (ERT) |

| Application       | Setting                                             |
|-------------------|-----------------------------------------------------|
| Efficiency        | No impact (execution, RAM)<br>Shared location (ROM) |
| Safety precaution | No impact                                           |

### See Also

### Related Examples

- “Model Configuration Parameters: Code Generation Interface” on page 12-2
- “Run-Time Environment Configuration”
- “Manage Build Process Folders”
- “Sharing Utility Code”



## Support: non-finite numbers

### Description

Specify whether to generate non-finite data and operations on non-finite data.

**Category:** Code Generation > Interface

### Settings

**Default:** on

On

Generates non-finite data (for example, NaN and Inf) and related operations.

Off

Does not generate non-finite data and operations. If you clear this option, an error occurs if the code generator encounters non-finite data or expressions. The error message reports offending blocks and parameters.

---

**Note** Code generation is optimized with the assumption that non-finite data are absent. However, if your application produces non-finite numbers through signal data or MATLAB code, the behavior of the generated code might be inconsistent with simulation results when processing non-finite data.

---

### Dependencies

- For ERT-based targets, parameter **Support: floating-point numbers** enables **Support: non-finite numbers**.
- If **off** for top model, must be **off** for referenced models.
- When you select parameter **MAT-File Logging**, you must also select **Support: non-finite numbers** and, if you use an ERT-based system target file, **Support: floating-point numbers**.

### Command-Line Information

**Parameter:** SupportNonFinite

**Type:** character vector

**Value:** 'on' | 'off'

**Default:** 'on'

### Recommended Settings

| Application  | Setting   |
|--------------|-----------|
| Debugging    | No impact |
| Traceability | No impact |

| <b>Application</b> | <b>Setting</b>                        |
|--------------------|---------------------------------------|
| Efficiency         | Off (execution, ROM), No impact (RAM) |
| Safety precaution  | No recommendation                     |

### See Also

### Related Examples

- “Model Configuration Parameters: Code Generation Interface” on page 12-2

# Code interface packaging

## Description

Select the packaging for the generated C or C++ code interface.

**Category:** Code Generation > Interface

## Settings

**Default:** Nonreusable function if parameter **Language** is set to C; C++ class if **Language** is set to C++

### C++ class

Generate a C++ class interface to model code. The generated interface encapsulates required model data into C++ class attributes and model entry point functions into C++ class methods.

For a model configured with a service interface, this parameter setting is not relevant and, therefore, is not supported.

### Nonreusable function

Generate nonreusable code. Model data structures are statically allocated and accessed by model entry point functions directly in the model code.

### Reusable function

Generate reusable, multi-instance code that is reentrant, as follows:

- For a GRT-based model, the generated *model.c* source file contains an allocation function that dynamically allocates model data for each instance of the model. For an ERT-based model, you can use parameter **Use dynamic memory allocation for model initialization** to control whether an allocation function is generated.
- The generated code passes the real-time model data structure in, by reference, as an argument to *model\_step* and the other model entry point functions.
- The real-time model data structure is exported with the *model.h* header file.

For an ERT-based model,

- If the model is configured with a service interface, this setting is not supported.
- You can use parameter **Pass root-level I/O as** to control how root-level input and output arguments are passed to the reusable model entry-point functions. They can be included in the real-time model data structure that is passed to the functions, passed as individual arguments, or passed as references to an input structure and an output structure.

## Tips

- Entry points are exported with *model.h*. To call the entry-point functions from handwritten code, add an `#include model.h` directive to the code.
- When you select Reusable function, the code generator generates a pointer to the real-time model object (*model\_M*).

- When you select `Reusable` function, the code generator can generate code that compiles but is not reentrant. For example, if a signal, DWork structure, or parameter data has a storage class other than `Auto`, global data structures are generated.

## Dependencies

- The value `C++ class` is available only if parameter **Language** is set to `C++`.
- Selecting `Reusable` function or `C++ class` enables parameter **Multi-instance code error diagnostic**.
- For an ERT-based system target file, selecting `Reusable` function enables parameters **Pass root-level I/O as** and **Use dynamic memory allocation for model initialization**.
- To enable parameter **Classic call interface**, select `Nonreusable` function.
- For an ERT-based system target file, selecting `C++ class` enables the following model configuration controls for customizing the model class interface:
  - **Data Member Visibility/Access Control** subpane
  - Parameters **Generate destructor** and **Use dynamic memory allocation for model block instantiation**
- For an ERT-based system target file, you can select `Reusable` function with the static `ert_main.c` module, if you do the following:
  - Set parameter **Pass root-level I/O as** to `Part of model data structure`.
  - Select parameter **Use dynamic memory allocation for model initialization**.
- For an ERT-based system target file, you cannot select `Reusable` function if you are:
  - Customizing the `model_step` function prototype
  - Selecting subsystem block parameter **Function with separate data**
  - Using a subsystem that
    - Has multiple ports that share source
    - Has a port that is used by multiple instances of the subsystem and has different sample times, data types, complexity, frame status, or dimensions across the instances
    - Has output marked as a global signal
    - For each instance contains identical blocks with different names or parameter settings
- Selecting `Reusable` function does not change the code generated for function-call subsystems.

## Command-Line Information

**Parameter:** `CodeInterfacePackaging`

**Type:** character vector

**Value:** `'C++ class' | 'Nonreusable function' | 'Reusable function'`

**Default:** `'Nonreusable function'` if `TargetLang` is set to `'C'`; `'C++ class'` if `TargetLang` is set to `'C++'`

## Recommended Settings

| Application       | Setting                        |
|-------------------|--------------------------------|
| Debugging         | No impact                      |
| Traceability      | No impact                      |
| Efficiency        | Reusable function or C++ class |
| Safety precaution | No impact                      |

## See Also

`model_step`

## Related Examples

- “Model Configuration Parameters: Code Generation Interface” on page 12-2
- “Configure Generated C Function Interface for Model Entry-Point Functions”
- “Generate Reentrant Code from Top Models”
- “Combine Code Generated for Multiple Models or Multiple Instances of a Model”
- “Generate Reentrant Code from Top Models”
- “Generate C++ Class Interface to Model or Subsystem Code”
- “Interactively Configure C++ Interface” (Embedded Coder)
- “Generate Reentrant Code from Subsystems”
- “S-Functions for Code Reuse”
- “Static Main Program Module” (Embedded Coder)
- “Configure Generated C Function Interface for Model Entry-Point Functions” (Embedded Coder)
- “Generate Modular Function Code for Nonvirtual Subsystems” (Embedded Coder)
- “Generate Component Source Code for Export to External Code Base” (Embedded Coder)

## Multi-instance code error diagnostic

### Description

Select the severity level for diagnostics displayed when a model violates requirements for generating multi-instance code.

**Category:** Code Generation > Interface

### Settings

**Default:** Error

None

Proceed with build without displaying a diagnostic message.

Warning

Proceed with build after displaying a warning message.

Error

Abort build after displaying an error message.

Under certain conditions, the software can:

- Generate code that compiles but is not reentrant. For example, if a signal or DWork structure has a storage class other than `Auto`, global data structures are generated.
- Be unable to generate valid and compilable code. For example, if the model contains an S-function that is not code-reuse compliant or a subsystem triggered by a wide function-call trigger, the code generator produces invalid code, displays an error message, and terminates the build.

### Dependencies

This parameter is enabled by setting parameter **Code interface packaging** to `Reusable function` or `C++ class`.

### Command-Line Information

**Parameter:** MultiInstanceErrorCode

**Type:** character vector

**Value:** 'None' | 'Warning' | 'Error'

**Default:** 'Error'

### Recommended Settings

| Application  | Setting          |
|--------------|------------------|
| Debugging    | Warning or Error |
| Traceability | No impact        |
| Efficiency   | None             |

| <b>Application</b> | <b>Setting</b> |
|--------------------|----------------|
| Safety precaution  | No impact      |

## See Also

### Related Examples

- “Model Configuration Parameters: Code Generation Interface” on page 12-2
- “Configure Generated C Function Interface for Model Entry-Point Functions”
- “Generate Reentrant Code from Top Models”
- “Generate C++ Class Interface to Model or Subsystem Code”
- “Generate Subsystem Code as Separate Function and Files”
- “Generate Reentrant Code from Subsystems”
- “Generate Reentrant Code from Subsystems”
- “Generate Modular Function Code for Nonvirtual Subsystems” (Embedded Coder)

## Generate C API for: signals

### Description

Generate C API data interface code with a signals structure.

**Category:** Code Generation > Interface

### Settings

**Default:** off

On

Generates C API interface to global block outputs.

Off

Does not generate C API signals.

### Command-Line Information

**Parameter:** RTWCAPISignals

**Type:** character vector

**Value:** 'on' | 'off'

**Default:** 'off'

### Recommended Settings

| Application       | Setting                                                            |
|-------------------|--------------------------------------------------------------------|
| Debugging         | No impact                                                          |
| Traceability      | No impact                                                          |
| Efficiency        | No impact                                                          |
| Safety precaution | No impact during development<br>Off for production code generation |

### See Also

#### Related Examples

- “Model Configuration Parameters: Code Generation Interface” on page 12-2
- “Exchange Data Between Generated and External Code Using C API”



## Generate C API for: parameters

### Description

Generate C API data interface code with parameter tuning structures.

**Category:** Code Generation > Interface

### Settings

**Default:** off

On

Generates C API interface to global block parameters.

Off

Does not generate C API parameters.

### Command-Line Information

**Parameter:** RTWCAPIParams

**Type:** character vector

**Value:** 'on' | 'off'

**Default:** 'off'

### Recommended Settings

| Application       | Setting                                                            |
|-------------------|--------------------------------------------------------------------|
| Debugging         | No impact                                                          |
| Traceability      | No impact                                                          |
| Efficiency        | No impact                                                          |
| Safety precaution | No impact during development<br>Off for production code generation |

### See Also

### Related Examples

- “Model Configuration Parameters: Code Generation Interface” on page 12-2
- “Exchange Data Between Generated and External Code Using C API”

## Generate C API for: states

### Description

Generate C API data interface code with a states structure.

**Category:** Code Generation > Interface

### Settings

**Default:** off

On

Generates C API interface to discrete and continuous states.

Off

Does not generate C API states.

### Command-Line Information

**Parameter:** RTWCAPIStates

**Type:** character vector

**Value:** 'on' | 'off'

**Default:** 'off'

### Recommended Settings

| Application       | Setting                                                            |
|-------------------|--------------------------------------------------------------------|
| Debugging         | No impact                                                          |
| Traceability      | No impact                                                          |
| Efficiency        | No impact                                                          |
| Safety precaution | No impact during development<br>Off for production code generation |

### See Also

#### Related Examples

- “Model Configuration Parameters: Code Generation Interface” on page 12-2
- “Exchange Data Between Generated and External Code Using C API”

## Generate C API for: root-level I/O

### Description

Generate C API data interface code with a root-level I/O structure.

**Category:** Code Generation > Interface

### Settings

**Default:** off

On

Generates a C API interface to root-level inputs and outputs.

Off

Does not generate a C API interface to root-level inputs and outputs.

### Command-Line Information

**Parameter:** RTWCAPIRootIO

**Type:** character vector

**Value:** 'on' | 'off'

**Default:** 'off'

### Recommended Settings

| Application       | Setting                                                            |
|-------------------|--------------------------------------------------------------------|
| Debugging         | No impact                                                          |
| Traceability      | No impact                                                          |
| Efficiency        | No impact                                                          |
| Safety precaution | No impact during development<br>Off for production code generation |

### See Also

### Related Examples

- “Model Configuration Parameters: Code Generation Interface” on page 12-2
- “Exchange Data Between Generated and External Code Using C API”

## ASAP2 interface

### Compatibility Considerations

ASAP2 interface is no longer available on the configuration pane and can be enabled only by using command line arguments. To generate an a2l file, see “Generate ASAP2 and CDF Calibration Files”.

### Description

Generate code for the ASAP2 data interface.

**Category:** Code Generation > Interface

### Settings

**Default:** off



On

Generates code for the ASAP2 data interface.



Off

Does not generate code for the ASAP2 data interface.

### Command-Line Information

**Parameter:** GenerateASAP2

**Type:** character vector

**Value:** 'on' | 'off'

**Default:** 'off'

### Recommended Settings

| Application       | Setting                                                            |
|-------------------|--------------------------------------------------------------------|
| Debugging         | No impact                                                          |
| Traceability      | No impact                                                          |
| Efficiency        | No impact                                                          |
| Safety precaution | No impact during development<br>Off for production code generation |

### See Also

### Related Examples

- “Model Configuration Parameters: Code Generation Interface” on page 12-2
- “Export ASAP2 File for Data Measurement and Calibration”

## External mode

### Description

Generate code for the external mode data interface. When using Embedded Coder for a component model that is configured with a service interface, this parameter is not supported.

**Category:** Code Generation > Interface

### Settings

**Default:** off

On

Generates code for the external mode data interface.

Off

Does not generate code for the external mode data interface.

### Command-Line Information

**Parameter:** ExtMode

**Type:** character vector

**Value:** 'on' | 'off'

**Default:** 'off'

### Recommended Settings

| Application       | Setting                                                            |
|-------------------|--------------------------------------------------------------------|
| Debugging         | No impact                                                          |
| Traceability      | No impact                                                          |
| Efficiency        | No impact                                                          |
| Safety precaution | No impact during development<br>Off for production code generation |

### See Also

### Related Examples

- “Model Configuration Parameters: Code Generation Interface” on page 12-2
- “External Mode Simulations for Parameter Tuning, Signal Monitoring, and Code Execution Profiling”
- “External Mode Simulation by Using XCP Communication”
- “External Mode Simulation with TCP/IP or Serial Communication”

## Transport layer

### Description

Specify the transport protocol for communications.

**Category:** Code Generation > Interface

### Settings

**Default:** tcpip

tcpip

Use a TCP/IP transport mechanism. Selecting this parameter sets parameter **MEX-file name** to `ext_comm`.

serial

Use a serial transport mechanism. Selecting this parameter sets parameter **MEX-file name** to `ext_serial_win32_comm`.

XCP on TCP/IP

Use XCP protocol with TCP/IP transport layer. Selecting this parameter sets parameter **MEX-file name** to `ext_xcp`.

XCP on Serial

Use XCP protocol with serial transport layer. Selecting this parameter sets parameter **MEX-file name** to `ext_xcp`.

*customTransportLayer*

Use custom transport layer.

### Tips

The Configuration Parameters dialog box displays parameter **MEX-file name** next to **Transport layer**. You cannot edit the value for **MEX-file name**. The value is specified either in `matlabroot/toolbox/simulink/simulink/extmode_transports.m` for targets provided by MathWorks, or in an `sl_customization.m` file for custom targets and transport mechanisms.

The command-line parameter is an index. To get the transport layer index, use these commands:

```
cs = getActiveConfigSet(modelName);
index = Simulink.ExtMode.Transports.getExtModeTransportIndex(cs, transportLayer);
```

*transportLayer* is one of these values:

- 'tcpip'
- 'serial'
- 'XCP on TCP/IP'
- 'XCP on Serial'
- *customTransportLayer*

To select the transport layer:

```
set_param(cs, 'ExtModeTransport', index)
```

To determine the transport layer:

```
transportLayerName = Simulink.ExtMode.Transports.getExtModeTransport(cs, index)
```

## Dependency

Selecting parameter **External mode** enables this parameter.

## Command-Line Information

**Parameter:** ExtModeTransport

**Type:** integer

**Value:** See “Tips” on page 12-26

**Default:** 0

## Recommended Settings

| Application       | No impact |
|-------------------|-----------|
| Debugging         | No impact |
| Traceability      | No impact |
| Efficiency        | No impact |
| Safety precaution | No impact |

## See Also

### Related Examples

- “Model Configuration Parameters: Code Generation Interface” on page 12-2
- “External Mode Simulation by Using XCP Communication”
- “External Mode Simulation with TCP/IP or Serial Communication”
- “Customize XCP Server Software”
- “Create a Transport Layer for TCP/IP or Serial External Mode Communication”

## MEX-file arguments

### Description

Specify arguments to pass to an external mode interface MEX-file for communicating with executing targets.

**Category:** Code Generation > Interface

### Settings

**Default:** ''

For XCP communication with a TCP/IP transport layer, there are four optional arguments:

- Network name of your target processor -- For example, 'localhost' if the target process is your development computer or the IP address '148.27.151.12'.
- Verbosity level -- 0 for no information or 1 to display detailed information during data transfer.
- Port number of TCP/IP server -- An integer value between 256 and 65535, with a default of 17725. The selected port must not be used by another TCP/IP service that runs on the target hardware.
- Symbols file name -- File format is PDB for Windows or ELF for Linux.

For XCP communication with a serial transport layer, there are four optional arguments:

- Verbosity level -- 0 for no information or 1 for detailed information.
- Serial port ID -- On Windows, 'COM1' or 1 for COM1, 'COM2' or 2 for COM2, etc. On Linux, '/dev/ttyS0', etc.
- Baud -- 1200, 2400, 4800, 9600, 14400, 19200, 38400, 57600 (default), or 115200.
- Symbols file name -- File format is PDB for Windows or ELF for Linux.

For TCP/IP interfaces, `ext_comm` allows three optional arguments:

- Network name of your target processor -- For example, 'myComputer' or '148.27.151.12'.
- Verbosity level -- 0 for no information or 1 to display detailed information during data transfer.
- Port number of TCP/IP server -- An integer value between 256 and 65535, with a default of 17725. The selected port must not be used by another TCP/IP service that runs on the target hardware.

For a serial transport, `ext_serial_win32_comm` allows three optional arguments:

- Verbosity level -- 0 for no information or 1 for detailed information.
- Serial port ID -- 1 for COM1, etc.
- Baud -- 1200, 2400, 4800, 9600, 14400, 19200, 38400, 57600 (default), or 115200.

Specify the arguments in the list order. For example, if you want to specify the verbosity level (the second argument), then you must also specify the network name of the target processor (the first argument). You can use white space or commas as argument delimiters.



```
'148.27.151.12' 1 30000
```

## Dependency

Selecting parameter **External mode** enables this parameter.

## Command-Line Information

**Parameter:** ExtModeMexArgs

**Type:** character vector

**Value:** valid arguments

**Default:** ''

## Recommended Settings

| Application       | Setting   |
|-------------------|-----------|
| Debugging         | No impact |
| Traceability      | No impact |
| Efficiency        | No impact |
| Safety precaution | No impact |

## See Also

### Related Examples

- “Model Configuration Parameters: Code Generation Interface” on page 12-2
- “External Mode Simulation by Using XCP Communication”
- “External Mode Simulation with TCP/IP or Serial Communication”

## Static memory allocation

### Description

Control memory buffer for external mode communication.

**Category:** Code Generation > Interface

### Settings

**Default:** off

On

Enables parameter **Static memory buffer size** for allocating dynamic memory.

Off

Uses a static memory buffer for external mode simulation instead of allocating dynamic memory (calls to `malloc`).

### Tips

To determine how much memory to allocate, select verbose mode on the target. That selection displays the amount of memory the target tries to allocate and the amount of memory available.

### Dependencies

- Setting parameter **Transport layer** to `tcpip` or `serial` enables this parameter. This parameter is disabled if **Transport layer** is set to `XCP` on `TCP/IP` or `XCP` on `Serial`.
- This parameter enables parameter **Static memory buffer size**.

### Command-Line Information

**Parameter:** `ExtModeStaticAlloc`

**Type:** character vector

**Value:** `'on'` | `'off'`

**Default:** `'off'`

### Recommended Settings

| Application       | Setting   |
|-------------------|-----------|
| Debugging         | No impact |
| Traceability      | No impact |
| Efficiency        | No impact |
| Safety precaution | No impact |

## See Also

### Related Examples

- “Model Configuration Parameters: Code Generation Interface” on page 12-2
- “External Mode Simulation with TCP/IP or Serial Communication”
- “External Mode Simulation by Using XCP Communication”
- “Control Memory Allocation for Communication Buffers in Target”
- “Memory Allocation for Communication Buffers During XCP External Mode Simulation”
- “XCP Platform Abstraction Layer”

## Automatically allocate static memory

### Description

Automatically allocate static memory for buffers used in external mode communication.

**Category:** Code Generation > Interface

### Settings

**Default:** on

On

When an external mode simulation runs, the software uses model information, including the **Maximum duration** value, to determine and allocate the static memory required for external mode communication buffers.

Off

Use the **Static memory buffer size** field to specify memory allocation for external mode communication.

### Dependencies

- Setting **Transport layer** to XCP on TCP/IP or XCP on Serial enables this parameter.
- Enabling this parameter enables **Maximum duration**.
- Disabling this parameter enables **Static memory buffer size**.

### Command-Line Information

**Parameter:** ExtModeAutomaticAllocSize

**Type:** character vector

**Value:** 'on' | 'off'

**Default:** 'on'

### Recommended Settings

| Application       | Setting   |
|-------------------|-----------|
| Debugging         | No impact |
| Traceability      | No impact |
| Efficiency        | No impact |
| Safety precaution | No impact |

## See Also

### Related Examples

- “Model Configuration Parameters: Code Generation Interface” on page 12-2
- “External Mode Simulation by Using XCP Communication”
- “Memory Allocation for Communication Buffers During XCP External Mode Simulation”
- “Customize XCP Server Software”
- “XCP Platform Abstraction Layer”

## Maximum duration

### Description

Specify the maximum value of `ExtModeTrigDuration` that the software must consider when determining the size of static memory required for external mode communication. When `ExtModeSendContiguousSamples` is 'on', memory requirements change depending on the value of `ExtModeTrigDuration`; when allocating memory automatically, the software allocates enough memory to run a simulation for all possible values of `ExtModeTrigDuration` in the range [1, `ExtModeMaxTrigDuration`] without generating a memory error.

**Category:** Code Generation > Interface

### Settings

**Default:** 10

Maximum duration in base rate steps.

### Dependency

Selecting parameter **Automatically allocate static memory** enables this parameter.

### Command-Line Information

**Parameter:** `ExtModeMaxTrigDuration`

**Type:** integer

**Value:** valid value

**Default:** 10

### Recommended Settings

| Application       | Setting   |
|-------------------|-----------|
| Debugging         | No impact |
| Traceability      | No impact |
| Efficiency        | No impact |
| Safety precaution | No impact |

### See Also

### Related Examples

- “Model Configuration Parameters: Code Generation Interface” on page 12-2
- “External Mode Simulation by Using XCP Communication”
- “Memory Allocation for Communication Buffers During XCP External Mode Simulation”
- “Run XCP External Mode Simulation From Command Line” (Embedded Coder)

- “Customize XCP Server Software”
- “XCP Platform Abstraction Layer”

## Target library

### Description

Specify the target deep learning library used during code generation.

**Category:** Code Generation > Interface

### Settings

**Default:** None

MKL - DNN

Use this option for generating code that uses the Intel Math Kernel Library for Deep Neural Networks (Intel MKL-DNN).

ARM Compute

Use this option for generating code that uses the ARM Compute Library.

cuDNN

Use this option for generating code that uses the CUDA Deep Neural Network library (cuDNN).

TensorRT

Use this option for generating code that takes advantage of the NVIDIA TensorRT - high performance deep learning inference optimizer and run-time library.

### Dependencies

- To enable this parameter, select C++ for the **Language** and `grt.tlc` or `ert.tlc` for **System target file**.
- MKL - DNN or ARM Compute is available when **GPU acceleration** on the **Code Generation** pane is disabled.
- cuDNN or TensorRT requires a GPU Coder license.
- cuDNN or TensorRT is available when **GPU acceleration** on the **Code Generation** pane is enabled.
- When the **Target library** is MKL - DNN, the **Language standard** parameter on the **Code Generation** pane is set to C++11 (ISO).

### Command-Line Information

**Parameter:** DLTargetLibrary

**Type:** character vector

**Value:** 'None' | 'MKL-DNN' | 'ARM Compute' | 'cuDNN' | 'TensorRT'

**Default:** 'None'



## See Also

### Related Examples

- “Model Configuration Parameters: Code Generation Interface” on page 12-2
- “GPU Code Generation for Deep Learning Networks Using MATLAB Function Block” (GPU Coder)

## ARM Compute Library version

### Description

Specify the version of ARM Compute Library.

**Category:** Code Generation > Interface

### Settings

**Default:** 20.02.1

Version of ARM Compute Library used on the target hardware, specified as a character vector. If you set this parameter to a version later than '20.02.1', the software is set to the default value of '20.02.1'.

### Dependencies

To enable this parameter, select ARM Compute for **Target Library**.

### Command-Line Information

**Parameter:** DLArmComputeVersion

**Type:** character vector

**Value:** '20.02.1' | '19.05'

**Default:** '20.02.1'

### See Also

### Related Examples

- “Model Configuration Parameters: Code Generation Interface” on page 12-2
- “GPU Code Generation for Deep Learning Networks Using MATLAB Function Block” (GPU Coder)

# ARM Compute Library architecture

## Description

Specify the ARM architecture supported in the target hardware.

**Category:** Code Generation > Interface

## Settings

**Default:** Unspecified

ARM architecture supported in the target hardware, specified as a character vector. The specified architecture must be the same as the architecture for the ARM Compute Library on the target hardware.

## Dependencies

To enable this parameter, select ARM Compute for **Target Library**.

## Command-Line Information

**Parameter:** DLArmComputeArch

**Type:** character vector

**Value:** 'Unspecified' | 'armv8' | 'armv7'

**Default:** 'Unspecified'

## See Also

## Related Examples

- “Model Configuration Parameters: Code Generation Interface” on page 12-2
- “GPU Code Generation for Deep Learning Networks Using MATLAB Function Block” (GPU Coder)

## Auto tuning

### Description

Use auto tuning for cuDNN library.

**Category:** Code Generation > Interface

### Settings

**Default:** On

**On**

Use this option to enable auto tuning feature. Enabling auto tuning allows the cuDNN library to find the fastest convolution algorithms. This increases performance for larger networks such as SegNet and ResNet.

**Off**

Disable auto tuning for the cuDNN library.

### Dependencies

- This parameter requires a GPU Coder license.
- To enable this parameter, select C++ for the **Language** and cuDNN for **Target library**.

### Command-Line Information

**Parameter:** DLAutoTuning

**Value:** 'on' | 'off'

**Default:** 'on'

### See Also

### Related Examples

- “Model Configuration Parameters: Code Generation Interface” on page 12-2
- “GPU Code Generation for Deep Learning Networks Using MATLAB Function Block” (GPU Coder)

## Static memory buffer size

### Description

Specify the memory buffer size for external mode communication.

**Category:** Code Generation > Interface

### Settings

**Default:** 1000000

Enter the number of bytes to preallocate for external mode communication buffers in the target application.

### Tips

- If you enter too small a value for your application, the external mode simulation produces an out-of-memory error.
- If you set **Transport layer** to XCP on TCP/IP or XCP on Serial and clear the **Automatically allocate static memory** check box, you can use this parameter to specify memory allocation for external mode communication buffers.

### Dependency

If parameter **Transport layer** is not set to XCP on TCP/IP or XCP on Serial, selecting the **Static memory allocation** check box enables this parameter.

If parameter **Transport layer** is set to XCP on TCP/IP or XCP on Serial, clearing the **Automatically allocate static memory** check box enables this parameter.

### Command-Line Information

**Parameter:** ExtModeStaticAllocSize

**Type:** integer

**Value:** valid value

**Default:** 1000000

### Recommended Settings

| Application       | Setting   |
|-------------------|-----------|
| Debugging         | No impact |
| Traceability      | No impact |
| Efficiency        | No impact |
| Safety precaution | No impact |

## **See Also**

### **Related Examples**

- “Model Configuration Parameters: Code Generation Interface” on page 12-2
- “External Mode Simulation with TCP/IP or Serial Communication”
- “External Mode Simulation by Using XCP Communication”
- “Control Memory Allocation for Communication Buffers in Target”
- “Memory Allocation for Communication Buffers During XCP External Mode Simulation”

## LUT object struct order for even spacing specification

### Description

Change the order of the fields in the generated structure for a lookup table object whose specification parameter is set to even spacing.

**Category:** Code Generation > Interface > Advanced Parameters

### Settings

**Default:** Size,Breakpoints,Table

Size,Breakpoints,Table

Display structure in the order size, breakpoints, table.

Size,Table,Breakpoints

Display structure in the order size, table, breakpoints.

### Command-Line Information

**Parameter:** LUTObjectStructOrderEvenSpacing

**Type:** character vector

**Value:** 'Size,Breakpoints,Table' | 'Size,Table,Breakpoints'

**Default:** 'Size,Breakpoints,Table'

### Recommended Settings

| Application       | Setting   |
|-------------------|-----------|
| Debugging         | No impact |
| Traceability      | No impact |
| Efficiency        | No impact |
| Safety precaution | No impact |

## LUT object struct order for explicit value specification

### Description

Change the order of the fields in the generated structure for a lookup table object whose specification parameter is set to explicit value.

**Category:** Code Generation > Interface > Advanced Parameters

### Settings

**Default:** Size,Breakpoints,Table

Size,Breakpoints,Table

Display structure in the order size, breakpoints, table.

Size,Table,Breakpoints

Display structure in the order size, table, breakpoints.

### Command-Line Information

**Parameter:** LUTObjectStructOrderExplicitValues

**Type:** character vector

**Value:** 'Size,Breakpoints,Table' | 'Size,Table,Breakpoints'

**Default:** 'Size,Breakpoints,Table'

### Recommended Settings

| Application       | Setting   |
|-------------------|-----------|
| Debugging         | No impact |
| Traceability      | No impact |
| Efficiency        | No impact |
| Safety precaution | No impact |



## Buffer size of dynamically-sized string (bytes)

### Description

Number of bytes of the character buffer generated for dynamic string signals without maximum length.

**Category:** Code Generation > Interface

### Settings

**Default:** 256

### Command-Line Information

**Parameter:** DynamicStringBufferSize

**Type:** character vector

**Value:** scalar

**Default:** 256

### Recommended Settings

| Application       | Setting   |
|-------------------|-----------|
| Debugging         | No impact |
| Traceability      | No impact |
| Efficiency        | No impact |
| Safety precaution | No impact |

## Array layout

### Description

Specify the layout of array data for code generation as column-major or row-major.

**Category:** Code Generation > Interface

### Settings

**Default:** Column-major

#### Column-major

Generate code in column-major array layout. For example, consider matrix A, which is a 4x3 matrix:

```
A =
 1 2 3
 4 5 6
 7 8 9
 10 11 12
```

In column-major array layout, the elements of the columns are contiguous in memory. A is represented in the generated code as:

```
1 4 7 10 2 5 8 11 3 6 9 12
```

#### Row-major

Generate code in row-major array layout. For example, for matrix A, in row-major array layout, the elements of the rows are contiguous. A is represented in the generated code as:

```
1 2 3 4 5 6 7 8 9 10 11 12
```

Select parameter **Use algorithms optimized for row-major array layout** to enable efficient row-major algorithms.

### Command-Line Information

**Parameter:** ArrayLayout

**Type:** character vector

**Value:** 'Column-major' | 'Row-major'

**Default:** 'Column-major'

### Recommended Settings

| Application  | Setting   |
|--------------|-----------|
| Debugging    | No impact |
| Traceability | No impact |
| Efficiency   | No impact |

---

| <b>Application</b> | <b>Setting</b> |
|--------------------|----------------|
| Safety precaution  | No impact      |

## See Also

### Related Examples

- “Model Configuration Parameters: Code Generation Interface” on page 12-2
- “Code Generation of Matrices and Arrays”

## External functions compatibility for row-major code generation

### Description

Select the diagnostic action if Simulink encounters a function that has no specified array layout.

**Category:** Code Generation > Interface

### Settings

**Default:** error

none

The code generator produces code without generating an error or warning.

warning

The code generator builds the model and displays a warning message.

error

The code generator terminates the build and displays an error message.

### Dependencies

To enable this parameter, set parameter **Array layout** on page 12-46 to Row-major.

This parameter works only if your S-function or custom C function has a multidimensional array.

### Command-Line Information

**Parameter:** UnsupportedSFcnMsg

**Type:** character vector

**Value:** 'none' | 'warning' | 'error'

**Default:** 'error'

### Recommended Settings

| Application       | Setting   |
|-------------------|-----------|
| Debugging         | warning   |
| Traceability      | No impact |
| Efficiency        | No impact |
| Safety precaution | error     |

### See Also

### Related Examples

- “Model Configuration Parameters: Code Generation Interface” on page 12-2

- “Generate Row-Major Code for S-Functions”
- “Code Generation of Matrices and Arrays”

## Maximum word length

### Description

Specify a maximum word length, in bits, for which the code generation process generates system-defined multiword type definitions.

**Category:** Code Generation > Interface

### Settings

**Default:** 256 for ERT targets, 2048 for GRT targets

Specify a maximum word length, in bits, for which the code generation process generates multiword type definitions into the file `multiword_types.h`. All multiword type definitions up to and including this number of bits are generated. If you select 0, multiword type definitions are not generated into the file `multiword_types.h`.

The maximum word length for multiword types only determines the type definitions generated and does not impact the efficiency of the generated code. If the maximum word length for multiword types is set to 0 or too small, an error occurs when the generated code is compiled. This error is caused by the generated code using a type that does not have the required type definition. To resolve the error, increase the maximum word length and regenerate the code. If the maximum word length for multiword types is larger than required, then `multiword_types.h` might contain unused type definitions. Unused type definitions do not consume target resources.

### Tips

- Adding a model to a model hierarchy or changing an existing model in the hierarchy can result in updates to the shared `multiword_types.h` file during code generation. These updates occur when the new model uses multiword types of length greater than those of the other models. You must then recompile and, depending on your development process, reverify previously generated code. To prevent updates to `multiword_types.h`, determine a maximum word length sufficiently big to cover the needs of all models in the hierarchy. Configure every model in the hierarchy to use that same maximum word length.
- The majority of embedded designs do not need multiword types. By setting maximum word length for multiword types to 0, you can prevent use of multiword variables on the target. If you use multiword variables with a maximum word length that is 0 or smaller than required, you are alerted with an error when the generated code is compiled.

### Dependencies

- This parameter requires an Embedded Coder license when generating code.
- This parameter is enabled by selecting the value `User defined` for the parameter **Multiword type definitions**.

### Command-Line Information

**Parameter:** MultiwordLength

**Type:** integer

**Value:** valid quantity of bits representing a word size

**Default:** 256 for ERT targets, 2048 for GRT targets

## Recommended Settings

| Application       | Setting           |
|-------------------|-------------------|
| Debugging         | No impact         |
| Traceability      | No impact         |
| Efficiency        | No impact         |
| Safety precaution | No recommendation |

## See Also

### Related Examples

- “Model Configuration Parameters: Code Generation Interface” on page 12-2

## Classic call interface

### Description

Specify whether to generate model function calls compatible with the main program module of the GRT system target file in models created before R2012a. When using Embedded Coder for a component model that is configured with a service interface, this parameter is not supported.

**Category:** Code Generation > Interface

### Settings

**Default:** off (except on for GRT models created before R2012a)

On

Generates model function calls that are compatible with the main program module of the GRT system target file (`grt_main.c` or `grt_main.cpp`) in models created before R2012a.

This option provides a quick way to use code generated in the current release with a GRT-based custom target that has a main program module based on pre-R2012a `grt_main.c` or `grt_main.cpp`.

Off

Disables the classic call interface.

### Tips

The following are unsupported:

- Data type replacement
- **Code interface packaging** set to Reusable function or C++ class.
- Nonvirtual subsystem option **Function with separate data**

### Dependencies

- Setting **Code interface packaging** to C++ class disables this option.
- Selecting this option disables the incompatible option **Single output/update function**. Clearing this option enables (but does not select) **Single output/update function**.

### Command-Line Information

**Parameter:** GRTInterface

**Type:** character vector

**Value:** 'on' | 'off'

**Default:** 'off' (except 'on' for GRT models created before R2012a)



## Recommended Settings

| Application       | Setting                               |
|-------------------|---------------------------------------|
| Debugging         | No impact                             |
| Traceability      | Off                                   |
| Efficiency        | Off (execution, ROM), No impact (RAM) |
| Safety precaution | No recommendation                     |

## See Also

### Related Examples

- “Model Configuration Parameters: Code Generation Interface” on page 12-2
- “Use Discrete and Continuous Time” (Embedded Coder)

## Single output/update function

### Description

Specify whether to generate the *model\_step* function. When using Embedded Coder for a component model that is configured with a service interface, this parameter is not supported.

**Category:** Code Generation > Interface

### Settings

**Default:** on

On

Generates the *model\_step* function for a model. This function contains the output and update function code for the blocks in the model and is called by *rt\_OneStep* to execute processing for one clock period of the model at interrupt level.

Off

Does not combine output and update function code into a single function, and instead generates the code in separate *model\_output* and *model\_update* functions.

### Tips

Errors or unexpected behavior can occur if a Model block is part of a cycle, the Model block is a direct feedthrough block, and an algebraic loop results. For more information about direct feed through, see “Algebraic Loop Concepts”.

Simulink Coder ignores this parameter for a referenced model if any of the following conditions apply to that model:

- Is multi-rate
- Has a continuous sample time
- Is logging states (using the **States** or **Final states** parameters in the **Configuration Parameters** > **Data Import/Export** pane)

### Dependencies

- Setting **Code interface packaging** to C++ `class` forces on and disables this option.
- This option and **Classic call interface** are mutually incompatible and cannot both be selected through the GUI. Selecting **Classic call interface** forces off and disables this option and clearing **Classic call interface** enables (but does not select) this option.
- When you use this option, you must clear the option **Minimize algebraic loop occurrences** on the **Model Referencing** pane.
- If you customize *ert\_main.c* or *.cpp* to read model outputs after each base-rate model step, selecting both parameters **Support: continuous time** and **Single output/update function** can cause output values read from *ert\_main* for a continuous output port to differ from the

corresponding output values in the logged data for the model. This is because, while logged data is a snapshot of output at major time steps, output read from `ert_main` after the base-rate model step potentially reflects intervening minor time steps. The following table lists workarounds that eliminate the discrepancy.

| Work Around                                                                                                                                                                                                                                                                                                                                                                                                                                                                  | Customized ert_main.c | Customized ert_main.cpp |
|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-----------------------|-------------------------|
| Separate the generated output and update functions (clear the <b>Single output/update function</b> parameter), and insert code in <code>ert_main</code> to read model output values reflecting only the major time steps. For example, in <code>ert_main</code> , between the <code>model_output</code> call and the <code>model_update</code> call, read the model <code>External_outputs</code> global data structure (defined in <code>model.h</code> ).                  | X                     |                         |
| Select the <b>Single output/update function</b> parameter and insert code in the generated <code>model.c</code> or <code>.cpp</code> file to return model output values reflecting only major time steps. For example, in the model step function, between the output code and the update code, save the value of the model <code>External_outputs</code> global data structure (defined in <code>model.h</code> ). Then, restore the value after the update code completes. | X                     | X                       |
| Place a Zero-Order Hold block before the continuous output port.                                                                                                                                                                                                                                                                                                                                                                                                             | X                     | X                       |

## Command-Line Information

**Parameter:** `CombineOutputUpdateFcns`

**Type:** character vector

**Value:** 'on' | 'off'

**Default:** 'on'

## Recommended Settings

| Application       | Setting           |
|-------------------|-------------------|
| Debugging         | On                |
| Traceability      | On                |
| Efficiency        | On                |
| Safety precaution | No recommendation |

## See Also

### Related Examples

- “Model Configuration Parameters: Code Generation Interface” on page 12-2
- “rt\_OneStep and Scheduling Considerations” (Embedded Coder)

## MAT-file logging

### Description

Specify MAT-file logging. When using Embedded Coder for a component model that is configured with a service interface, this parameter is not relevant and, therefore, is not supported.

**Category:** Code Generation > Interface

### Settings

**Default:** on for the GRT target, off for ERT-based targets

On

Enable MAT-file logging. When you select this option, the generated code saves to MAT-files simulation data specified in one of the following ways:

- **Configuration Parameters > Data Import/Export** (see “Model Configuration Parameters: Data Import/Export”)
- To Workspace blocks
- To File blocks
- Scope blocks with the **Log data to workspace** parameter enabled

In simulation, this data would be written to the MATLAB workspace, as described in “Export Simulation Data” and “Configure Signal Data for Logging”. Setting MAT-file logging redirects the data to a MAT-file instead. The file is named *model.mat*, where *model* is the name of your model.

Off

Disable MAT-file logging. Clearing this option has the following benefits:

- Eliminates overhead associated with supporting a file system, which typically is not a requirement for embedded applications
- Eliminates extra code and memory usage required to initialize, update, and clean up logging variables
- Under certain conditions, eliminates code and storage associated with root output ports
- Omits the comparison between the current time and stop time in the *model\_step*, allowing the generated program to run indefinitely, regardless of the stop time setting

### Dependencies

- When you select **MAT-file logging**, you must also select the configuration parameters **Support: non-finite numbers** and, if you use an ERT-based system target file, **Support: floating-point numbers**.
- Selecting this option enables **MAT-file variable name modifier**.
- For ERT-based system target files, clear this parameter if you are using exported function calls.

## Limitations

- The code generator does not support MAT-file logging for custom data types (data types that are not built into Simulink).
- MAT-file logging does not support file-scoped data, for example, data items to which you apply the built-in storage class `FileScope`.
- In a referenced model, only the following data logging features are supported:
  - To File blocks
  - State logging — the software stores the data in the MAT-file for the top model.
- In the context of the Embedded Coder product, MAT-file logging does not support the following IDEs: Analog Devices® VisualDSP++®, Texas Instruments™ Code Composer Studio™, Wind River® DIAB/GCC.
- MAT-file logging does not support Outport blocks to which you apply the storage class `ImportedExternPointer` or storage classes that yield nonaddressable data in the generated code. For example, the storage class `GetSet` causes the Outport to appear in the generated code as a function call, which is not addressable. This limitation applies whether you apply the storage class directly by using, for example, the Model Data Editor, or by resolving the Outport to a `Simulink.Signal` object that uses the storage class. As a workaround, apply the storage class to the signal that enters the Outport block.

## Command-Line Information

**Parameter:** `MatFileLogging`

**Type:** character vector

**Value:** 'on' | 'off'

**Default:** 'on' for the GRT target, 'off' for ERT-based targets

## Recommended Settings

| Application       | Setting   |
|-------------------|-----------|
| Debugging         | On        |
| Traceability      | No impact |
| Efficiency        | Off       |
| Safety precaution | Off       |

## See Also

### Related Examples

- “Model Configuration Parameters: Code Generation Interface” on page 12-2
- “Log Program Execution Results”
- “Log Data for Analysis”
- “Virtualized Output Ports Optimization” (Embedded Coder)

## Target derived from slrealtime

Indicates whether or not the currently selected target is derived from the `slrealtime` target

**Model Configuration Pane:** Code Generation / Interface

### Description

Indicates whether or not the currently selected target is derived from the `slrealtime` target. When you select a system target file (such as `slrealtime.tlc`), the selection defines the run-time environment and the code generation features.

### Dependencies

The value for this configuration parameter is set by the value of the System target file configuration parameter.

**Option:** SystemTargetFile

### Settings

on | off

When Target derived from `slrealtime` is enabled, the code generation target is derived from the `slrealtime.tlc` system target file.

### Examples

#### Get Target derived from slrealtime

- To get the `isSLRTtarget` parameter value for model `slrt_ex_osc` that is open in the Simulink Editor, type in the MATLAB Command Window:

```
get_param('slrt_ex_osc','IsSLRTtarget')
```

### Recommended Settings

| Application       | Setting |
|-------------------|---------|
| Debugging         | on      |
| Traceability      | on      |
| Efficiency        | on      |
| Safety precaution | on      |

### Programmatic Use

**Parameter:** IsSLRTtarget

**Type:** character vector

**Value:** 'off' | 'on'

**Default:** 'on'

## **Version History**

**Introduced in R2022b**

### **See Also**

“Compare System Target File Support Across Products”

## Generate full file banner

Include code generation information in file banner

**Model Configuration Pane:** Code Generation / Interface

### Description

Specify whether to include additional code generation information in the header file banner.

### Settings

on (default) | off

**Default:** on

On

Includes additional code generation information in the banner of the generated header file. The additional information includes:

- Date and timestamp of code generation
- Selected target for code generation
- Selected hardware for code generation
- Code generation objectives
- Validation result

The banner also includes this basic information:

- Name of the header file
- Name of the model for which you generated code
- Model version number
- Simulink Coder version, release number, and release date

Off

Does not include code generation details in the generated header file banner. The banner still includes:

- Name of the header file
- Name of the model for which you generated code
- Model version number
- Simulink Coder version, release number, and release date

### Examples

#### Control Information in Header File Banner

Compare the banner in the generated header file when you set **Generate full file banner** to different values. For this example, use the model `rtwdemo_roll`.



Here is the header file banner that generated using the default **Generate full file banner** value on:

```

/*
 * rtwdemo_roll.h
 *
 * Code generation for model "rtwdemo_roll".
 *
 * Model version : 6.0
 * Simulink Coder version : 9.8 (R2022b) 13-May-2022
 * C source code generated on : Mon Jun 13 13:31:11 2022
 *
 * Target selection: ert.tlc
 * Embedded hardware selection: Intel->x86-64 (Windows64)
 * Code generation objectives:
 * 1. Execution efficiency
 * 2. Traceability
 * 3. Safety precaution
 * 4. RAM efficiency
 * Validation result: Not run
 */

```

Here is the header file banner that generated using the **Generate full file banner** value off:

```

/*
 * rtwdemo_roll.h
 *
 * Code generation for model "rtwdemo_roll".
 *
 * Model version : 6.0
 * Simulink Coder version : 9.8 (R2022b) 13-May-2022
 *
 */

```

## Recommended Settings

| Application       | Setting   |
|-------------------|-----------|
| Debugging         | No impact |
| Traceability      | No impact |
| Efficiency        | No impact |
| Safety precaution | No impact |

## Programmatic Use

**Parameter:** GenerateFullHeader

**Type:** character vector

**Value:** 'on' | 'off'

**Default:** 'on'

## Version History

Introduced before R2006a

## **See Also**

### **Topics**

Custom File Processing (Embedded Coder)

# **Code Generation Parameters: GPU Code**

---

## Model Configuration Parameters: GPU Code

The **Code Generation > GPU Code** category includes parameters for configuring GPU-specific settings of the generated code.

These parameters require a GPU Coder license.

On the Configuration Parameters dialog box, the following configuration parameters are on the **Code Generation > GPU Code** pane.

| Parameter                                              | Description                                                                                                    |
|--------------------------------------------------------|----------------------------------------------------------------------------------------------------------------|
| "GPU index" on page 13-4                               | Specify the CUDA device to target.                                                                             |
| "Compute capability" on page 13-5                      | Specify the minimum compute capability for which CUDA code is generated.                                       |
| "Custom compute capability" on page 13-7               | Specify the name of the NVIDIA virtual GPU architecture for code generation.                                   |
| "Memory mode" on page 13-8                             | Specify the Memory allocation ( <code>malloc</code> ) mode to be used in the generated CUDA code.              |
| "Maximum blocks per kernel" on page 13-10              | Specify the maximum number of CUDA blocks created during a kernel launch.                                      |
| "Dynamic memory allocation threshold" on page 13-11    | Specify the size above which the private variables are allocated on the heap instead of the stack.             |
| "Memory Manager" on page 13-12                         | Select the GPU memory manager for efficient memory allocation, management, and improving run-time performance. |
| "Stack size per GPU thread" on page 13-13              | Specify the maximum stack limit per GPU thread.                                                                |
| "Include error checks in generated code" on page 13-14 | Add run-time error-checking functionality to the generated CUDA code.                                          |
| "Kernel name prefix" on page 13-15                     | Specify custom kernel name prefixes.                                                                           |
| "Additional compiler flags" on page 13-16              | Specify additional flags to the <code>nvcc</code> compiler.                                                    |
| "cuBLAS" on page 13-17                                 | Replacement of math function calls with NVIDIA cuBLAS library calls.                                           |
| "cuSOLVER" on page 13-18                               | Replacement of math function calls with NVIDIA cuSOLVER library calls.                                         |
| "cuFFT" on page 13-19                                  | Replacement of math function calls with NVIDIA cuFFT library calls.                                            |

### See Also

#### More About

- "Model Configuration"
- "Code Generation from Simulink Models with GPU Coder" (GPU Coder)

## Code Generation: GPU Code Tab Overview

Set up GPU-specific information about code generation for a model's active configuration set, including device memory settings, CUDA libraries, code profiling and analysis, and device architecture and compiler.

These parameters require a GPU Coder license.

### See Also

### More About

- “Model Configuration Parameters: GPU Code” on page 13-2
- “Code Generation from Simulink Models with GPU Coder” (GPU Coder)

## GPU index

### Description

Specify the CUDA device to target.

**Category:** Code Generation > GPU Code

### Settings

**Default:** -1

In a multi GPU environment such as NVIDIA Drive platforms, specify the CUDA device to target.

---

**Note** GPU index can be used with `gpuArray` only if `gpuDevice` and GPU index point to the same GPU. If `gpuDevice` points to a different GPU, a `CUDA_ERROR_INVALID_VALUE` runtime error is thrown.

---

### Dependencies

- This parameter requires a GPU Coder license.
- To enable this parameter, select **Generate GPU code** on the **Code Generation** pane.

### Command-Line Information

**Parameter:** GPUDeviceID

**Type:** integer

**Value:** -1 or a valid user-specified index value

**Default:** -1

### See Also

### Related Examples

- “Model Configuration Parameters: GPU Code” on page 13-2
- “Code Generation from Simulink Models with GPU Coder” (GPU Coder)

# Compute capability

## Description

Specify the minimum compute capability of the GPU device for which CUDA code is generated.

**Category:** Code Generation > GPU Code

## Settings

**Default:** 3.5

Select the minimum compute capability for code generation. The compute capability identifies the features supported by the GPU hardware. It is used by applications at run time to determine which hardware features, instructions are available on the GPU device. If you specify custom compute capability, GPU Coder ignores this setting.

To see the CUDA compute capability requirements for code generation, consult the following table.

| Target                                                               | Compute Capability                                             |
|----------------------------------------------------------------------|----------------------------------------------------------------|
| CUDA MEX                                                             | See “GPU Computing Requirements” (Parallel Computing Toolbox). |
| Source code, static or dynamic library, and executables              | 3.2 or higher.                                                 |
| Deep learning applications in 8-bit integer precision                | 6.1, 6.3 or higher.                                            |
| Deep learning applications in half-precision (16-bit floating point) | 5.3, 6.0, 6.2 or higher.                                       |

## Dependencies

- This parameter requires a GPU Coder license.
- To enable this parameter, select **Generate GPU code** on the **Code Generation** pane.

## Command-Line Information

**Parameter:** GPUComputeCapability

**Type:** character vector

**Value:** '3.2' | '3.5' | '3.7' | '5.0' | '5.2' | '5.3' | '6.0' | '6.1' | '6.2' | '7.0' | '7.1' | '7.2' | '7.5' |

**Default:** '3.5'

## See Also

## Related Examples

- “Model Configuration Parameters: GPU Code” on page 13-2

- “Code Generation from Simulink Models with GPU Coder” (GPU Coder)



# Custom compute capability

## Description

Specify the name of the NVIDIA virtual GPU architecture for code generation.

**Category:** Code Generation > GPU Code

## Settings

**Default:** ''

Specify the name of the NVIDIA virtual GPU architecture for which the CUDA input files must be compiled.

For example, to specify a virtual architecture type `-arch=compute_50`. You can specify a real architecture using `-arch=sm_50`. For more information, see the *Options for Steering GPU Code Generation* topic in the CUDA Toolkit documentation.

## Dependencies

- This parameter requires a GPU Coder license.
- To enable this parameter, select **Generate GPU code** on the **Code Generation** pane.

## Command-Line Information

**Parameter:** GPUCustomComputeCapability

**Type:** character vector

**Value:** '' or a valid user-specified virtual architecture specification

**Default:** ''

## See Also

## Related Examples

- “Model Configuration Parameters: GPU Code” on page 13-2
- “Code Generation from Simulink Models with GPU Coder” (GPU Coder)

## Memory mode

### Description

Specify the memory allocation (`malloc`) mode to use in the generated CUDA code.

**Category:** Code Generation > GPU Code

### Settings

**Default:** `discrete`

`discrete`

The generated code uses the `cudaMalloc` API for transferring data between the CPU and the GPU. From the programmers point-of-view, the discrete mode has a traditional memory architecture with separate CPU and GPU global memory address space.

`unified`

The generated code uses the `cudaMallocManaged` API that uses a shared (unified) CPU and GPU global memory address space.

For NVIDIA embedded targets only. See “Deprecating support for unified memory allocation mode on host” (GPU Coder).

### Dependencies

- This parameter requires a GPU Coder license.
- To enable this parameter, select **Generate GPU code** on the **Code Generation** pane.

### Command-Line Information

**Parameter:** `GPUMallocMode`

**Type:** character vector

**Value:** `'discrete' | 'unified'`

**Default:** `'discrete'`

### Compatibility Considerations

#### Deprecating support for unified memory allocation mode on host

In a future release, support for the unified memory allocation (`cudaMallocManaged`) mode will be removed when targeting NVIDIA GPU devices on the host development computer. When targeting GPU devices on the host, select `'discrete'` for the **Memory mode** parameter.

You can continue to use unified memory allocation mode when targeting NVIDIA embedded platforms.

## See Also

### Related Examples

- “Model Configuration Parameters: GPU Code” on page 13-2
- “Code Generation from Simulink Models with GPU Coder” (GPU Coder)

## Maximum blocks per kernel

### Description

Specify the maximum number of CUDA blocks created during a kernel launch.

Because GPU devices have limited streaming multiprocessor (SM) resources, limiting the number of blocks for each kernel can avoid performance losses from scheduling, loading and unloading of blocks.

If the number of iterations in a loop is greater than the maximum number of blocks per kernel, the code generator creates CUDA kernels with striding.

When you specify the maximum number of blocks for each kernel, the code generator creates 1-D kernels. To force the code generator to create 2-D or 3-D kernels, use the `coder.gpu.kernel` pragma. The `coder.gpu.kernel` pragma takes precedence over the maximum number of kernels for each CUDA block.

**Category:** Code Generation > GPU Code

### Settings

**Default:** 0

Specify the maximum number of CUDA blocks created during a kernel launch.

### Dependencies

- This parameter requires a GPU Coder license.
- To enable this parameter, select **Generate GPU code** on the **Code Generation** pane.

### Command-Line Information

**Parameter:** GPUMaximumBlocksPerKernel

**Type:** integer

**Value:** any valid value

**Default:** 0

### See Also

### Related Examples

- “Model Configuration Parameters: GPU Code” on page 13-2
- “Code Generation from Simulink Models with GPU Coder” (GPU Coder)

# Dynamic memory allocation threshold

## Description

Specify the memory allocation threshold.

**Category:** Code Generation > GPU Code

## Settings

**Default:** 200

Specify the size above which the private variables are allocated on the heap instead of the stack, as an integer value.

## Dependencies

- This parameter requires a GPU Coder license.
- To enable this parameter, select **Generate GPU code** on the **Code Generation** pane.

## Command-Line Information

**Parameter:** GPUMallocThreshold

**Type:** integer

**Value:** any valid value

**Default:** 200

## See Also

## Related Examples

- “Model Configuration Parameters: GPU Code” on page 13-2
- “Code Generation from Simulink Models with GPU Coder” (GPU Coder)

## Memory Manager

### Description

Select the GPU memory manager for efficient memory allocation, management, and improving run-time performance.

**Category:** Code Generation > GPU Code

### Settings

**Default:** Off

**On**

The GPU memory manager creates a collection of large GPU memory pools and manages allocation and deallocation of chunks of memory blocks within these pools. By creating large memory pools, the memory manager reduces the number of calls to the CUDA memory APIs, improving run-time performance. You can use the GPU memory manager for MEX and standalone CUDA code generation.

**Off**

Disable the use GPU memory manager for memory allocation and management.

### Dependencies

- This parameter requires a GPU Coder license.
- To enable this parameter, select **Generate GPU code** on the **Code Generation** pane.

### Command-Line Information

**Parameter:** GPUEnableMemoryManager

**Type:** character vector

**Value:** 'on' | 'off'

**Default:** 'off'

### See Also

### Related Examples

- “Model Configuration Parameters: GPU Code” on page 13-2
- “Code Generation from Simulink Models with GPU Coder” (GPU Coder)

# Stack size per GPU thread

## Description

Specify the stack limit per GPU thread.

**Category:** Code Generation > GPU Code

## Settings

**Default:** 1024

Specify the maximum stack limit per GPU thread as an integer value.

## Dependencies

- This parameter requires a GPU Coder license.
- To enable this parameter, select **Generate GPU code** on the **Code Generation** pane.

## Command-Line Information

### Command-Line Information

**Parameter:** GPUStackLimitPerThread

**Type:** integer

**Value:** any valid value

**Default:** 1024

## See Also

## Related Examples

- “Model Configuration Parameters: GPU Code” on page 13-2
- “Code Generation from Simulink Models with GPU Coder” (GPU Coder)

## Include error checks in generated code

### Description

Add run-time error-checking functionality to the generated CUDA code.

**Category:** Code Generation > GPU Code

### Settings

**Default:** Off

**On**

Generates code with error-checking for CUDA API and kernel calls and performs run-time checks.

**Off**

The generated CUDA code does not contain error-checking functionality.

### Dependencies

- This parameter requires a GPU Coder license.
- To enable this parameter, select **Generate GPU code** on the **Code Generation** pane.

### Command-Line Information

**Parameter:** GPUErrorChecks

**Type:** character vector

**Value:** 'on' | 'off'

**Default:** 'off'

### See Also

### Related Examples

- “Model Configuration Parameters: GPU Code” on page 13-2
- “Code Generation from Simulink Models with GPU Coder” (GPU Coder)



# Kernel name prefix

## Description

Specify custom kernel name prefixes.

**Category:** Code Generation > GPU Code

## Settings

**Default:** ''

Specify a custom name prefix for all the kernels in the generated code. For example, using the value 'CUDA\_' creates kernels with names CUDA\_kernel1, CUDA\_kernel2, and so on. If no name is provided, GPU Coder prepends the kernel name with the name of the entry-point function. Kernel names can contain upper-case letters, lowercase letters, digits 0-9, and underscore character \_. GPU Coder removes unsupported characters from the kernel names and appends alpha to prefixes that do not begin with an alphabetic letter.

## Dependencies

- This parameter requires a GPU Coder license.
- To enable this parameter, select **Generate GPU code** on the **Code Generation** pane.

## Command-Line Information

**Parameter:** GpuKernelNamePrefix

**Type:** character vector

**Value:** '' or a valid user-specified name

**Default:** ''

## See Also

## Related Examples

- “Model Configuration Parameters: GPU Code” on page 13-2
- “Code Generation from Simulink Models with GPU Coder” (GPU Coder)

## Additional compiler flags

### Description

Specify additional flags to the NVIDIA `nvcc` compiler.

**Category:** Code Generation > GPU Code

### Settings

**Default:** ''

Pass additional flags to the GPU compiler. For example, `--fmad=false` instructs the `nvcc` compiler to disable contraction of floating-point multiply and add to a single Floating-Point Multiply-Add (FMAD) instruction.

For similar NVIDIA compiler options, see the topic on *NVCC Command Options* in the CUDA Toolkit documentation.

### Dependencies

- This parameter requires a GPU Coder license.
- To enable this parameter, select **Generate GPU code** on the **Code Generation** pane.

### Command-Line Information

**Parameter:** GPUCompilerFlags

**Type:** character vector

**Value:** '' or a valid user-specified flag

**Default:** ''

### See Also

### Related Examples

- “Model Configuration Parameters: GPU Code” on page 13-2
- “Code Generation from Simulink Models with GPU Coder” (GPU Coder)

# cuBLAS

## Description

Replacement of math function calls with NVIDIA cuBLAS library calls.

**Category:** Code Generation > GPU Code

## Settings

**Default:** On

**On**

Allows GPU Coder to replace appropriate math function calls with calls to the cuBLAS library. For functions that have no replacements in CUDA, GPU Coder uses portable MATLAB functions and attempts to map them to the GPU.

**Off**

Disable the use of the cuBLAS library in the generated code.

## Dependencies

- This parameter requires a GPU Coder license.
- To enable this parameter, select **Generate GPU code** on the **Code Generation** pane.

## Command-Line Information

**Parameter:** GPUcuBLAS

**Type:** character vector

**Value:** 'on' | 'off'

**Default:** 'on'

## See Also

## Related Examples

- “Model Configuration Parameters: GPU Code” on page 13-2
- “Code Generation from Simulink Models with GPU Coder” (GPU Coder)

## cuSOLVER

### Description

Replacement of math function calls with NVIDIA cuSOLVER library calls.

**Category:** Code Generation > GPU Code

### Settings

**Default:** On

**On**

Allows GPU Coder to replace appropriate math function calls with calls to the cuSOLVER library. For functions that have no replacements in CUDA, GPU Coder uses portable MATLAB functions and attempts to map them to the GPU.

**Off**

Disable the use of the cuSOLVER library in the generated code.

### Dependencies

- This parameter requires a GPU Coder license.
- To enable this parameter, select **Generate GPU code** on the **Code Generation** pane.

### Command-Line Information

**Parameter:** GPUcuSOLVER

**Type:** character vector

**Value:** 'on' | 'off'

**Default:** 'on'

### See Also

### Related Examples

- “Model Configuration Parameters: GPU Code” on page 13-2
- “Code Generation from Simulink Models with GPU Coder” (GPU Coder)

# cuFFT

## Description

Replacement of math function calls with NVIDIA cuFFT library calls.

**Category:** Code Generation > GPU Code

## Settings

**Default:** On

**On**

Allows GPU Coder to replace appropriate `fft` calls with calls to the cuFFT library.

**Off**

Disables use of the cuFFT library in the generated code. With this option, GPU Coder uses C FFTW libraries where available or generates kernels from portable MATLAB `fft` code.

## Dependencies

- This parameter requires a GPU Coder license.
- To enable this parameter, select **Generate GPU code** on the **Code Generation** pane.

## Command-Line Information

**Parameter:** GPUcuFFT

**Type:** character vector

**Value:** 'on' | 'off'

**Default:** 'on'

## See Also

## Related Examples

- “Model Configuration Parameters: GPU Code” on page 13-2
- “Code Generation from Simulink Models with GPU Coder” (GPU Coder)



# Simulink Coder Parameters: Advanced Parameters

---

## Use Simulink Coder Features

### Description

Enable “Simulink Coder” features for models deployed to “Simulink Supported Hardware”.

---

**Note** If you enable this parameter in a model where Simulink Coder is not installed or available in the environment, a question dialog box prompts you to update the model to build without Simulink Coder features.

---

**Category:** Hardware Implementation

### Settings

On

Enable the Simulink Coder features.

Off

Disable the Simulink Coder features.



Indicates that this parameter is enabled. To disable it, first disable the “Use Embedded Coder Features” (Embedded Coder) parameter.

### Dependencies

This parameter requires a Simulink Coder or Embedded Coder license.

### Command-Line Information

**Parameter:** UseSimulinkCoderFeatures

**Value:** 'on' or 'off'

**Default:** 'on'

### See Also

### Related Examples

- “Model Configuration”



# Configuration Parameters for Simulink Models

---

- “Code Generation Pane: RSim Target” on page 15-2
- “Code Generation Pane: S-Function Target” on page 15-5
- “Code Generation Pane: Tornado Target” on page 15-8
- “Recommended Settings Summary for Model Configuration Parameters” on page 15-22

## Code Generation Pane: RSim Target

The **Code Generation > RSim Target** pane includes these parameters when the Simulink Coder product is installed on your system and you specify the `rsim.tlc` system target file.

Parameter loading

Enable RSim executable to load parameters from a MAT-file

Solver

Solver selection: auto

Storage classes

Force storage classes to AUTO

### In this section...

“Code Generation: RSim Target Tab Overview” on page 15-2  
 “Enable RSim executable to load parameters from a MAT-file” on page 15-2  
 “Solver selection” on page 15-3  
 “Force storage classes to AUTO” on page 15-4

## Code Generation: RSim Target Tab Overview

Set configuration parameters for rapid simulation.

### Configuration

This tab appears only if you specify `rsim.tlc` as the System target file.

### See Also

- “Configure and Build Model for Rapid Simulation”
- “Run Rapid Simulations”
- “Code Generation Pane: RSim Target” on page 15-2

## Enable RSim executable to load parameters from a MAT-file

Specify whether to load RSim parameters from a MAT-file.

### Settings

**Default:** on

On

Enables RSim to load parameters from a MAT-file.



Disables RSim from loading parameters from a MAT-file.

#### Command-Line Information

**Parameter:** RSIM\_PARAMETER\_LOADING

**Type:** character vector

**Value:** 'on' | 'off'

**Default:** 'on'

#### Recommended Settings

| Application       | Setting   |
|-------------------|-----------|
| Debugging         | No impact |
| Traceability      | No impact |
| Efficiency        | No impact |
| Safety precaution | No impact |

#### See Also

“Create a MAT-File That Includes a Model Parameter Structure”

## Solver selection

Instruct the target how to select the solver.

#### Settings

**Default:** auto

auto

Lets the code generator choose the solver. The code generator uses the Simulink solver module if you specify a variable-step solver on the Solver pane. Otherwise, the code generator uses a built-in solver.

Use Simulink solver module

Instructs the code generator to use the variable-step solver that you specify on the **Solver** pane.

Use fixed-step solvers

Instructs the code generator to use the fixed-step solver that you specify on the **Solver** pane.

#### Command-Line Information

**Parameter:** RSIM\_SOLVER\_SELECTION

**Type:** character vector

**Value:** 'auto' | 'usesolvermodule' | 'usefixstep'

**Default:** 'auto'

#### Recommended Settings

| Application | Setting   |
|-------------|-----------|
| Debugging   | No impact |

| Application       | Setting   |
|-------------------|-----------|
| Traceability      | No impact |
| Efficiency        | No impact |
| Safety precaution | No impact |

## Force storage classes to AUTO

Specify whether to retain your storage class settings in a model or to use the automatic settings.

### Settings

**Default:** on

On

Forces the Simulink software to determine storage classes.

Off

Causes the model to retain storage class settings.

### Tips

- Turn this parameter on for flexible custom code interfacing.
- Turn this parameter off to retain storage class settings such as `ExportedGlobal` or `ImportExtern`.

### Command-Line Information

**Parameter:** `RSIM_STORAGE_CLASS_AUTO`

**Type:** character vector

**Value:** 'on' | 'off'

**Default:** 'on'

### Recommended Settings

| Application       | Setting   |
|-------------------|-----------|
| Debugging         | No impact |
| Traceability      | No impact |
| Efficiency        | No impact |
| Safety precaution | No impact |

## Code Generation Pane: S-Function Target

The **Code Generation > S-Function Target** pane includes the following parameters when the Simulink Coder product is installed on your system and you specify the `rtwsfcn.tlc` system target file.

- Create new model
- Use value for tunable parameters
- Include custom source code

### In this section...

“Code Generation S-Function Target Tab Overview” on page 15-5  
 “Create new model” on page 15-5  
 “Use value for tunable parameters” on page 15-6  
 “Include custom source code” on page 15-6

## Code Generation S-Function Target Tab Overview

Control code generated for the S-function target (`rtwsfcn.tlc`).

### Configuration

This tab appears only if you specify the S-function target (`rtwsfcn.tlc`) as the System target file.

### See Also

- “Use S-Function Target for Model or Subsystem”
- “Code Generation Pane: S-Function Target” on page 15-5

## Create new model

Create a new model containing the generated S-function block.

### Settings

**Default:** on

- On  
Creates a new model, separate from the current model, containing the generated S-function block.
- Off  
Generates code but a new model is not created.

**Command-Line Information****Parameter:** CreateModel**Type:** character vector**Value:** 'on' | 'off'**Default:** 'on'**See Also**

“Use S-Function Target for Model or Subsystem”

**Use value for tunable parameters**

Use the variable value instead of the variable name in generated block mask edit fields for tunable parameters.

**Settings****Default:** off On

Uses variable values for tunable parameters instead of the variable name in the generated block mask edit fields.

 Off

Uses variable names for tunable parameters in the generated block mask edit fields.

**Command-Line Information****Parameter:** UseParamValues**Type:** character vector**Value:** 'on' | 'off'**Default:** 'off'**See Also**

“Use S-Function Target for Model or Subsystem”

**Include custom source code**

Include custom source code in the code generated for the S-function.

**Settings****Default:** off On

Include provided custom source code in the code generated for the S-function.

 Off

Do not include custom source code in the code generated for the S-function.

**Command-Line Information**

**Parameter:** AlwaysIncludeCustomSrc

**Type:** character vector

**Value:** 'on' | 'off'

**Default:** 'off'

**See Also**

“Use S-Function Target for Model or Subsystem”

## Code Generation Pane: Tornado Target

The **Code Generation > Tornado Target** pane includes the following parameters when the Simulink Coder product is installed on your system and you specify the `tornado.tlc` system target file.

**Software environment**

Code replacement library:

Shared code placement:

**Tornado**

MAT-file Logging

Code Format

StethoScope

Download to VxWorks target

**VxWorks**

Base task priority

Task stack size

**External mode options**

External mode

### In this section...

“Code Generation: Tornado Target Tab Overview” on page 15-9

“Language standard” on page 15-9

“Code replacement library” on page 15-10

“Shared code placement” on page 15-11

“MAT-file logging” on page 15-12

“MAT-file variable name modifier” on page 15-13

“Code Format” on page 15-14

“StethoScope” on page 15-15

“Download to VxWorks target” on page 15-15

“Base task priority” on page 15-16

“Task stack size” on page 15-17

“External mode” on page 15-17

“Transport layer” on page 15-18

“MEX-file arguments” on page 15-19



**In this section...**

“Static memory allocation” on page 15-20

“Static memory buffer size” on page 15-21

## Code Generation: Tornado Target Tab Overview

Control generated code for the Tornado target.

### Configuration

This tab appears only if you specify `tornado.tlc` as the System target file.

### See Also

- *Tornado User's Guide* from Wind River Systems
- *StethoScope User's Guide* from Wind River Systems
- “Asynchronous Support”
- “Code Generation Pane: Tornado Target” on page 15-8

## Language standard

Specify a language standard for your model.

### Settings

**Default:** C99 (ISO)

C89/C90 (ANSI)

Generates code that conforms to the ISO/IEC 9899:1990 C language standard.

C99 (ISO)

Generates code that conforms to the ISO/IEC 9899:1999 C language standard.

C++03 (ISO)

Generates code that conforms to the ISO/IEC 14882:2003 C++ language standard.

### Tips

- The build process checks whether the specified language standard and toolchain are compatible. If they are not compatible, a warning occurs during code generation and the build process continues.
- When you change the value of parameter **Language**, the language standard updates to ISO/IEC 9899:1999 C (C99 (ISO)) for C and ISO/IEC 14882:2003 C++ (C++11 (ISO)) for C++.

### Dependencies

The C++03 (ISO) language standard is available for use only if you set parameter **Language** to C++.

**Command-Line Information****Parameter:** TargetLangStandard**Type:** character vector**Value:** 'C89/C90 (ANSI)' | 'C99 (ISO)' | 'C++03 (ISO)'**Default:** 'C99 (ISO)'**Recommended Settings**

| Application       | Setting       |
|-------------------|---------------|
| Debugging         | No impact     |
| Traceability      | No impact     |
| Efficiency        | Valid library |
| Safety precaution | No impact     |

**See Also**

"Run-Time Environment Configuration"

**Code replacement library**

Specify a code replacement library the code generator uses when producing code for a model.

**Settings****Default:** None

None

Does not use a code replacement library.

Named code replacement library

Generates calls to a specific platform, compiler, or standards code replacement library. The list of named libraries depends on:

- Installed support packages.
- System target file, language, language standard, and device vendor configuration.
- Whether you created and registered code replacement libraries, using the Embedded Coder product.

For more information about selections for this parameter, see "Code replacement library" on page 12-9.

**Tip**

Before setting this parameter, verify that your compiler supports the library you want to use. If you select a parameter value that your compiler does not support, compiler errors can occur.

**Command-Line Information****Parameter:** CodeReplacementLibrary**Type:** character vector

**Value:** 'None' | 'GNU C99 extensions' | 'Intel IPP for x86-64 (Windows)' | 'Intel IPP/SSE for x86-64 (Windows)' | 'Intel IPP for x86-64 (Windows for MinGW compiler)' | 'Intel IPP/SSE for x86-64 (Windows for MinGW compiler)' | 'Intel IPP for x86/Pentium (Windows)' | 'Intel IPP/SSE x86/Pentium (Windows)' | 'Intel IPP for x86-64 (Linux)' | 'Intel IPP/SSE with GNU99 extensions for x86-64 (Linux)'  
**Default:** 'None'

### Recommended Settings

| Application       | Setting       |
|-------------------|---------------|
| Debugging         | No impact     |
| Traceability      | No impact     |
| Efficiency        | Valid library |
| Safety precaution | No impact     |

### See Also

“Run-Time Environment Configuration”

## Shared code placement

Specify the location for generating utility functions, exported data type definitions, and declarations of exported data with custom storage class.

### Settings

**Default:** Auto

Auto

Operates as follows:

- When the model contains Model blocks, places utility code within the `slprj/target/_sharedutils` folder.
- When the model does not contain Model blocks, places utility code in the build folder (generally, in `model.c` or `model.cpp`).

Shared location

Directs code for utilities to be placed within the `slprj` folder in your working folder.

### Command-Line Information

**Parameter:** UtilityFuncGeneration

**Type:** character vector

**Value:** 'Auto' | 'Shared location'

**Default:** 'Auto'

### Recommended Settings

| Application | Setting         |
|-------------|-----------------|
| Debugging   | Shared location |

| Application       | Setting                                             |
|-------------------|-----------------------------------------------------|
| Traceability      | Shared location                                     |
| Efficiency        | No impact (execution, RAM)<br>Shared location (ROM) |
| Safety precaution | No impact                                           |

### See Also

- “Run-Time Environment Configuration”
- “Sharing Utility Code”

## MAT-file logging

Specify whether to enable MAT-file logging.

### Settings

**Default:** off

On

Enables MAT-file logging. When you select this option, the generated code saves to MAT-files simulation data specified in one of the following ways:

- Configuration Parameters dialog box, **Data Import/Export** pane (see “Model Configuration Parameters: Data Import/Export”)
- To Workspace blocks
- Scope blocks with block parameter **Log data to workspace** enabled

In simulation, this data would be written to the MATLAB workspace, as described in “Export Simulation Data” and “Configure Signal Data for Logging”. Setting MAT-file logging redirects the data to a MAT-file instead. The file is named *model.mat*, where *model* is the name of your model.

Off

Disables MAT-file logging. Clearing this option has the following benefits:

- Eliminates overhead associated with supporting a file system, which typically is not required for embedded applications
- Eliminates extra code and memory usage required to initialize, update, and clean up logging variables
- Under certain conditions, eliminates code and storage associated with root output ports
- Omits the comparison between the current time and stop time in the *model\_step*, allowing the generated program to run indefinitely, regardless of the stop time setting

### Dependencies

Selecting this parameter enables parameter **MAT-file variable name modifier**.

**Limitation**

MAT-file logging does not support file-scoped data, for example, data items to which you apply the built-in custom storage class `FileScope`.

MAT-file logging does not work in a referenced model, and code is not generated to implement it.

**Command-Line Information**

**Parameter:** `MatFileLogging`

**Type:** character vector

**Value:** 'on' | 'off'

**Default:** 'off'

**Recommended Settings**

| Application       | Setting   |
|-------------------|-----------|
| Debugging         | On        |
| Traceability      | No impact |
| Efficiency        | Off       |
| Safety precaution | Off       |

**See Also**

- “Log Program Execution Results”
- “Log Data for Analysis”
- “Virtualized Output Ports Optimization” (Embedded Coder)

**MAT-file variable name modifier**

Select the text to add to the MAT-file variable names.

**Settings**

**Default:** `rt_`

`rt_`

Adds prefix text.

`_rt`

Adds suffix text.

`none`

Does not add text.

**Dependency**

If you have an Embedded Coder license, this parameter is enabled by parameter **MAT-file logging**.

**Command-Line Information**

**Parameter:** `LogVarNameModifier`

**Type:** character vector

**Value:** 'none' | 'rt\_' | '\_rt'  
**Default:** 'rt\_'

**Recommended Settings**

| Application       | Setting   |
|-------------------|-----------|
| Debugging         | No impact |
| Traceability      | No impact |
| Efficiency        | No impact |
| Safety precaution | No impact |

**See Also**

- “Log Program Execution Results”
- “Log Data for Analysis”

**Code Format**

Specify the code format (generated code features).

**Settings**

**Default:** RealTime

RealTime

Specifies the Real-Time code generation format.

RealTimeMalloc

Specifies the Real-Time Malloc code generation format.

**Command-Line Information**

**Parameter:** CodeFormat

**Type:** character vector

**Value:** 'RealTime' | 'RealTimeMalloc'

**Default:** 'RealTime'

**Recommended Settings**

| Application       | Setting   |
|-------------------|-----------|
| Debugging         | No impact |
| Traceability      | No impact |
| Efficiency        | No impact |
| Safety precaution | No impact |

**See Also**

“Compare System Target File Support Across Products”

## StethoScope

Specify whether to enable StethoScope, an optional data acquisition and data monitoring tool.

### Settings

**Default:** off

On

Enables StethoScope.

Off

Disables StethoScope.

### Tips

You can optionally monitor and change the parameters of the executing real-time program using either StethoScope or Simulink External mode, but not both with the same compiled image.

### Dependencies

Enabling parameter **StethoScope** disables parameter **External mode**, and vice versa.

### Command-Line Information

**Parameter:** StethoScope

**Type:** character vector

**Value:** 'on' | 'off'

**Default:** 'off'

### Recommended Settings

| Application       | Setting   |
|-------------------|-----------|
| Debugging         | On        |
| Traceability      | No impact |
| Efficiency        | Off       |
| Safety precaution | Off       |

### See Also

- *Tornado User's Guide* from Wind River Systems
- *StethoScope User's Guide* from Wind River Systems

## Download to VxWorks target

Specify whether to automatically download the generated program to the VxWorks target.

### Settings

**Default:** off

On

Automatically downloads the generated program to VxWorks after each build.

Off

Does not automatically download to VxWorks, you must download generated programs manually.

### Tips

- Automatic download requires specifying the target name and host name in the makefile.
- Before every build, reset VxWorks by pressing **Ctrl+X** on the host console or power-cycling the VxWorks chassis. This clears dangling processes or stale data that exists in VxWorks when the automatic download occurs.

### Command-Line Information

**Parameter:** DownloadToVxWorks

**Type:** character vector

**Value:** 'on' | 'off'

**Default:** 'off'

### Recommended Settings

| Application       | Setting   |
|-------------------|-----------|
| Debugging         | No impact |
| Traceability      | No impact |
| Efficiency        | No impact |
| Safety precaution | Off       |

### See Also

- *Tornado User's Guide* from Wind River Systems
- "Asynchronous Support"

## Base task priority

Specify the priority with which the base rate task for the model is to be spawned.

### Settings

**Default:** 30

### Tips

- For a multirate, multitasking model, the code generator increments the priority of each subrate task by one.
- The value you specify for this option will be overridden by a base priority specified in a call to the `rt_main()` function spawned as a task.



**Command-Line Information****Parameter:** BasePriority**Type:** integer**Value:** valid value**Default:** 30**Recommended Settings**

| Application       | Setting                                                       |
|-------------------|---------------------------------------------------------------|
| Debugging         | No impact                                                     |
| Traceability      | No impact                                                     |
| Efficiency        | Might impact efficiency, depending on other task's priorities |
| Safety precaution | No impact                                                     |

**See Also**

- *Tornado User's Guide* from Wind River Systems
- "Asynchronous Support"

**Task stack size**

Stack size in bytes for each task that executes the model.

**Settings****Default:** 16384**Command-Line Information****Parameter:** TaskStackSize**Type:** integer**Value:** valid value**Default:** 16384**Recommended Settings**

| Application       | Setting                                          |
|-------------------|--------------------------------------------------|
| Debugging         | No impact                                        |
| Traceability      | No impact                                        |
| Efficiency        | Larger stack may waste space                     |
| Safety precaution | Larger stack reduces the possibility of overflow |

**See Also**

- *Tornado User's Guide* from Wind River Systems
- "Asynchronous Support"

**External mode**

Specify whether to enable communication between the Simulink model and an application based on a client/server architecture.

### Settings

**Default:** on

On

Enables External mode. The client (Simulink model) transmits messages requesting the server (application) to accept parameter changes or to upload signal data. The server responds by executing the request.

Off

Disables External mode.

### Dependencies

Selecting this parameter enables these parameters:

- **Transport layer**
- **MEX-file arguments**
- **Static memory allocation**

### Command-Line Information

**Parameter:** ExtMode

**Type:** character vector

**Value:** 'on' | 'off'

**Default:** 'on'

### Recommended Settings

| Application       | Setting   |
|-------------------|-----------|
| Debugging         | No impact |
| Traceability      | No impact |
| Efficiency        | No impact |
| Safety precaution | No impact |

### See Also

“External Mode Simulations for Parameter Tuning, Signal Monitoring, and Code Execution Profiling”

## Transport layer

Specify the transport protocol for External mode communications.

### Settings

**Default:** tcpip

tcpip

Applies a TCP/IP transport mechanism. The MEX-file name is `ext_comm`.

### Tip

You cannot edit the value of the **MEX-file name** parameter displayed next to parameter **Transport layer**. For system target files provided by MathWorks, the value is specified in `matlabroot/toolbox/simulink/simulink/extmode_transports.m`.

### Dependency

This parameter is enabled by parameter **External mode**.

### Command-Line Information

**Parameter:** ExtModeTransport

**Type:** integer

**Value:** 0

**Default:** 0

### Recommended Settings

| Application       | Setting   |
|-------------------|-----------|
| Debugging         | No impact |
| Traceability      | No impact |
| Efficiency        | No impact |
| Safety precaution | No impact |

### See Also

“External Mode Simulation with TCP/IP or Serial Communication”

## MEX-file arguments

Specify arguments to pass to an External mode interface MEX-file for communicating with executing targets.

### Settings

**Default:** ''

For TCP/IP interfaces, `ext_comm` allows three optional arguments:

- Network name of your target (for example, 'myputer' or '148.27.151.12')
- Verbosity level (0 for no information or 1 for detailed information)
- TCP/IP server port number (an integer value between 256 and 65535, with a default of 17725)

### Dependency

This parameter is enabled by parameter **External mode**.

**Command-Line Information****Parameter:** ExtModeMexArgs**Type:** character vector**Value:** valid arguments**Default:** ''**Recommended Settings**

| Application       | Setting   |
|-------------------|-----------|
| Debugging         | No impact |
| Traceability      | No impact |
| Efficiency        | No impact |
| Safety precaution | No impact |

**See Also**

- “External Mode Simulation with TCP/IP or Serial Communication”
- “Choose Communication Protocol for Client and Server”

**Static memory allocation**

Control the memory buffer for External mode communication.

**Settings****Default:** off
 On

Enables parameter **Static memory buffer size** for allocating dynamic memory.

 Off

Uses a static memory buffer for External mode instead of allocating dynamic memory (calls to malloc).

**Tip**

To determine how much memory you need to allocate, select verbose mode on the target to display the amount of memory it tries to allocate and the amount of memory available.

**Dependencies**

- This parameter is enabled by parameter **External mode**.
- This parameter enables parameter **Static memory buffer size**.

**Command-Line Information****Parameter:** ExtModeStaticAlloc**Type:** character vector**Value:** 'on' | 'off'**Default:** 'off'

## Recommended Settings

| Application       | Setting   |
|-------------------|-----------|
| Debugging         | No impact |
| Traceability      | No impact |
| Efficiency        | No impact |
| Safety precaution | No impact |

## See Also

“Control Memory Allocation for Communication Buffers in Target”

## Static memory buffer size

Specify the memory buffer size for External mode communication.

### Settings

**Default:** 1000000

Enter the number of bytes to preallocate for External mode communications buffers in the target.

### Tips

- If you enter too small a value for your application, External mode issues an out-of-memory error.
- To determine how much memory you need to allocate, select verbose mode on the target to display the amount of memory it tries to allocate and the amount of memory available.

### Dependency

This parameter is enabled by parameter **Static memory allocation**.

### Command-Line Information

**Parameter:** ExtModeStaticAllocSize

**Type:** integer

**Value:** valid value

**Default:** 1000000

## Recommended Settings

| Application       | Setting   |
|-------------------|-----------|
| Debugging         | No impact |
| Traceability      | No impact |
| Efficiency        | No impact |
| Safety precaution | No impact |

## See Also

“Control Memory Allocation for Communication Buffers in Target”

## **Recommended Settings Summary for Model Configuration Parameters**

The following table summarizes the impact of each configuration parameter on debugging, traceability, efficiency, and safety considerations, and indicates the factory default configuration settings for the GRT and ERT targets, unless otherwise specified.

For parameters that are available only when an ERT target is specified, see “Recommended Settings Summary for Model Configuration Parameters” (Embedded Coder).

For additional details, click the links in the Configuration Parameter column.

## Mapping Application Requirements to the Solver Pane

| Configuration Parameter                                       | Settings for Building Code |                                                                                               |            |                                                                                                                                       | Factory Default                                                   |
|---------------------------------------------------------------|----------------------------|-----------------------------------------------------------------------------------------------|------------|---------------------------------------------------------------------------------------------------------------------------------------|-------------------------------------------------------------------|
|                                                               | Debugging                  | Traceability                                                                                  | Efficiency | Safety precaution                                                                                                                     |                                                                   |
| <b>Start time</b>                                             | No impact                  | No impact                                                                                     | No impact  | 0.0                                                                                                                                   | 0.0 seconds                                                       |
| <b>Stop time</b>                                              | No impact                  | No impact                                                                                     | No impact  | A positive value                                                                                                                      | 10.0 seconds                                                      |
| <b>Type</b>                                                   | Fixed-step                 | Fixed-step                                                                                    | Fixed-step | Fixed-step                                                                                                                            | Variable-step (you must change to Fixed-step for code generation) |
| <b>Solver</b>                                                 | No impact                  | No impact                                                                                     | No impact  | Discrete (no continuous states)                                                                                                       | ode3 (Bogacki-Shampine)                                           |
| <b>Periodic sample time constraint</b>                        | No impact                  | No impact                                                                                     | No impact  | Specified or Ensure sample time independent                                                                                           | Unconstrained                                                     |
| <b>Sample time properties</b>                                 | No impact                  | No impact                                                                                     | No impact  | Period, offset, and priority of each sample time in the model; faster sample times must have higher priority than slower sample times | ' '                                                               |
| <b>Treat each discrete rate as a separate task"</b>           | No impact                  | No impact                                                                                     | No impact  | No impact                                                                                                                             | On                                                                |
| <b>Automatically handle rate transition for data transfer</b> | No impact                  | No impact (for simulation and during development)<br><br>Off (for production code generation) | No impact  | Off                                                                                                                                   | Off                                                               |

## Mapping Application Requirements to the Data Import/Export Pane

| Configuration Parameter                                      | Settings for Building Code |              |                   |                   | Factory Default |
|--------------------------------------------------------------|----------------------------|--------------|-------------------|-------------------|-----------------|
|                                                              | Debugging                  | Traceability | Efficiency        | Safety precaution |                 |
| <b>Input</b>                                                 | No impact                  | No impact    | No recommendation | No recommendation | Off             |
| <b>Initial State</b>                                         | No impact                  | No impact    | No recommendation | No recommendation | Off             |
| <b>Time</b>                                                  | No impact                  | No impact    | No recommendation | No recommendation | On              |
| <b>States</b>                                                | No impact                  | No impact    | No recommendation | No recommendation | Off             |
| <b>Output</b>                                                | No impact                  | No impact    | No recommendation | No recommendation | On              |
| <b>Final states</b>                                          | No impact                  | No impact    | No recommendation | No recommendation | Off             |
| <b>Signal logging</b>                                        | No impact                  | No impact    | No recommendation | No recommendation | On              |
| <b>Inspect signal logs when simulation is paused/stopped</b> | No impact                  | No impact    | No recommendation | No recommendation | Off             |
| <b>Limit data points to last</b>                             | No impact                  | No impact    | No recommendation | No recommendation | On              |
| <b>Decimation</b>                                            | No impact                  | No impact    | No recommendation | No recommendation | 1               |
| <b>Format</b>                                                | No impact                  | No impact    | No recommendation | No recommendation | Array           |
| <b>Output options</b>                                        | No impact                  | No impact    | No recommendation | No recommendation | Refine output   |
| <b>Refine factor</b>                                         | No impact                  | No impact    | No recommendation | No recommendation | 1               |



| Configuration Parameter | Settings for Building Code |              |                   |                   | Factory Default |
|-------------------------|----------------------------|--------------|-------------------|-------------------|-----------------|
|                         | Debugging                  | Traceability | Efficiency        | Safety precaution |                 |
| <b>Output times</b>     | No impact                  | No impact    | No recommendation | No recommendation | ' [] '          |

### Mapping Application Requirements to the Math and Data Types Pane

| Configuration Parameter                                   | Settings for Building Code |              |                                                                                    |                   | Factory Default |
|-----------------------------------------------------------|----------------------------|--------------|------------------------------------------------------------------------------------|-------------------|-----------------|
|                                                           | Debugging                  | Traceability | Efficiency                                                                         | Safety precaution |                 |
| <b>Default for underspecified data type</b>               | No impact                  | No impact    | single                                                                             | No impact         | double          |
| <b>Use division for fixed-point net slope computation</b> | No impact                  | No impact    | On (when target hardware supports efficient division)<br><br>Off (otherwise)       | No impact         | off             |
| <b>Application lifespan (days)</b>                        | No impact                  | No impact    | Finite value                                                                       | inf               | auto            |
| <b>Use memset to initialize floats and doubles to 0.0</b> | No impact                  | No impact    | On (when target hardware supports efficient multiplication)<br><br>Off (otherwise) | No recommendation | Off             |

\*The command-line value is reverse of the listed value.

**Mapping Application Requirements to the Optimization Pane**

| Configuration Parameter                                                                      | Settings for Building Code     |              |                                                           |                   | Factory Default                |
|----------------------------------------------------------------------------------------------|--------------------------------|--------------|-----------------------------------------------------------|-------------------|--------------------------------|
|                                                                                              | Debugging                      | Traceability | Efficiency                                                | Safety precaution |                                |
| <b>Default parameter behavior</b>                                                            | Tunable (GRT)<br>Inlined (ERT) | Inlined      | Inlined                                                   | No impact         | Tunable (GRT)<br>Inlined (ERT) |
| <b>Loop unrolling threshold</b>                                                              | No impact                      | No impact    | >0                                                        | No impact         | 5                              |
| <b>Maximum stack size (bytes)</b>                                                            | No impact                      | No impact    | No impact                                                 | No impact         | Inherit from target            |
| <b>Use memcpy for vector assignment</b>                                                      | No impact                      | No impact    | On                                                        | No impact         | On                             |
| <b>Memcpy threshold (bytes)</b>                                                              | No impact                      | No impact    | Accept default or determine target-specific optimal value | No impact         | 64                             |
| <b>Inline invariant signals</b>                                                              | Off                            | Off          | On                                                        | No impact         | Off                            |
| <b>Remove code from floating-point to integer conversions that wraps out-of-range values</b> | Off                            | Off          | On (execution, ROM)<br>No impact (RAM)                    | No impact         | Off                            |
| <b>Use bitsets for storing state configuration</b>                                           | Off                            | Off          | Off (execution, ROM)<br>On (RAM)                          | No impact         | Off                            |
| <b>Use bitsets for storing Boolean data</b>                                                  | Off                            | Off          | Off (execution, ROM)<br>On (RAM)                          | No impact         | Off                            |

**Mapping Application Requirements to the Diagnostics Pane: Solver Tab**

| Configuration Parameter                          | Settings for Building Code |              |            |                   | Factory Default |
|--------------------------------------------------|----------------------------|--------------|------------|-------------------|-----------------|
|                                                  | Debugging                  | Traceability | Efficiency | Safety precaution |                 |
| <b>Algebraic loop</b>                            | error                      | No impact    | No impact  | error             | warning         |
| <b>Minimize algebraic loop</b>                   | No impact                  | No impact    | No impact  | error             | warning         |
| <b>Block priority violation</b>                  | No impact                  | No impact    | No impact  | error             | warning         |
| <b>Consecutive zero crossings violation</b>      | No impact                  | No impact    | No impact  | warning or error  | error           |
| <b>Unspecified inheritability of sample time</b> | No impact                  | No impact    | No impact  | error             | warning         |
| <b>Solver data inconsistency</b>                 | warning                    | No impact    | none       | No impact         | warning         |
| <b>Automatic solver parameter selection</b>      | No impact                  | No impact    | No impact  | error             | warning         |

**Mapping Application Requirements to the Diagnostics Pane: Sample Time Tab**

| Configuration Parameter                                                     | Settings for Building Code |              |            |                   | Factory Default |
|-----------------------------------------------------------------------------|----------------------------|--------------|------------|-------------------|-----------------|
|                                                                             | Debugging                  | Traceability | Efficiency | Safety precaution |                 |
| <b>Source block specifies -1 sample time</b>                                | No impact                  | No impact    | No impact  | error             | none            |
| <b>Multitask rate transition</b>                                            | No impact                  | No impact    | No impact  | error             | error           |
| <b>Single task rate transition</b>                                          | No impact                  | No impact    | No impact  | none or error     | none            |
| <b>Multitask conditionally executed subsystem</b>                           | No impact                  | No impact    | No impact  | error             | error           |
| <b>Tasks with equal priority</b>                                            | No impact                  | No impact    | No impact  | none or error     | warning         |
| <b>Enforce sample times specified by Signal Specification blocks" /&gt;</b> | No impact                  | No impact    | No impact  | error             | warning         |

## Mapping Application Requirements to the Diagnostics Pane: Data Validity Tab

| Configuration Parameter                         | Settings for Building Code |                  |            |                   | Factory Default                                                  |
|-------------------------------------------------|----------------------------|------------------|------------|-------------------|------------------------------------------------------------------|
|                                                 | Debugging                  | Traceability     | Efficiency | Safety precaution |                                                                  |
| <b>Signal resolution</b>                        | No impact                  | No impact        | No impact  | Explicit only     | Explicit only                                                    |
| <b>Division by singular matrix</b>              | No impact                  | No impact        | No impact  | error             | none                                                             |
| <b>Underspecified data types</b>                | No impact                  | No impact        | No impact  | error             | none                                                             |
| <b>Simulation range checking</b>                | warning or error           | warning or error | none       | error             | none                                                             |
| <b>Wrap on overflow</b>                         | No impact                  | No impact        | No impact  | error             | warning                                                          |
| <b>Saturate on overflow</b>                     | No impact                  | No impact        | No impact  | error             | warning                                                          |
| <b>Inf or NaN block output</b>                  | No impact                  | No impact        | No impact  | error             | none                                                             |
| <b>"rt" prefix for identifiers</b>              | No impact                  | No impact        | No impact  | error             | error                                                            |
| <b>Detect downcast</b>                          | No impact                  | No impact        | No impact  | error             | error                                                            |
| <b>Detect overflow</b>                          | No impact                  | No impact        | No impact  | error             | error                                                            |
| <b>Detect underflow</b>                         | No impact                  | No impact        | No impact  | error             | none                                                             |
| <b>Detect precision loss</b>                    | No impact                  | No impact        | No impact  | error             | error                                                            |
| <b>Detect loss of tunability</b>                | No impact                  | No impact        | No impact  | error             | warning for GRT-based targets<br><br>error for ERT-based targets |
| <b>Detect read before write</b>                 | No impact                  | No impact        | No impact  | error             | Enable all as warnings                                           |
| <b>Detect write after read</b>                  | No impact                  | No impact        | No impact  | error             | Enable all as warning                                            |
| <b>Detect write after write</b>                 | No impact                  | No impact        | No impact  | error             | Enable all as errors                                             |
| <b>Multitask data store</b>                     | No impact                  | No impact        | No impact  | error             | warning                                                          |
| <b>Duplicate data store names</b>               | warning                    | No impact        | none       | No impact         | none                                                             |
| <b>Check undefined subsystem initial output</b> | No impact                  | No impact        | No impact  | On                | On                                                               |

**Mapping Application Requirements to the Diagnostics Pane: Type Conversion Tab**

| Configuration Parameter                                    | Settings for Building Code |              |            |                   | Factory Default |
|------------------------------------------------------------|----------------------------|--------------|------------|-------------------|-----------------|
|                                                            | Debugging                  | Traceability | Efficiency | Safety precaution |                 |
| <b>Unnecessary type conversions</b>                        | No impact                  | No impact    | No impact  | warning           | none            |
| <b>Vector/matrix block input conversion</b>                | No impact                  | No impact    | No impact  | error             | none            |
| <b>32-bit integer to single precision float conversion</b> | No impact                  | No impact    | No impact  | warning           | warning         |

**Mapping Application Requirements to the Diagnostics Pane: Connectivity Tab**

| Configuration Parameter                            | Settings for Building Code |              |            |                   | Factory Default |
|----------------------------------------------------|----------------------------|--------------|------------|-------------------|-----------------|
|                                                    | Debugging                  | Traceability | Efficiency | Safety precaution |                 |
| <b>Signal label mismatch</b>                       | No impact                  | No impact    | No impact  | error             | none            |
| <b>Unconnected block input ports</b>               | No impact                  | No impact    | No impact  | error             | none            |
| <b>Unconnected block output ports</b>              | No impact                  | No impact    | No impact  | error             | none            |
| <b>Unconnected line</b>                            | No impact                  | No impact    | No impact  | error             | none            |
| <b>Unspecified bus object at root Output block</b> | No impact                  | No impact    | No impact  | error             | warning         |
| <b>Element name mismatch</b>                       | No impact                  | No impact    | No impact  | error             | warning         |
| <b>Bus signal treated as vector</b>                | No impact                  | No impact    | No impact  | error             | none            |
| <b>Context-dependent inputs</b>                    | No impact                  | No impact    | No impact  | error             | error           |

**Mapping Application Requirements to the Diagnostics Pane: Compatibility Tab**

| Configuration Parameter           | Settings for Building Code |              |            |                   | Factory Default |
|-----------------------------------|----------------------------|--------------|------------|-------------------|-----------------|
|                                   | Debugging                  | Traceability | Efficiency | Safety precaution |                 |
| <b>S-function upgrades needed</b> | No impact                  | No impact    | No impact  | error             | none            |

**Mapping Application Requirements to the Diagnostics Pane: Model Referencing Tab**

| Configuration Parameter                              | Settings for Building Code |              |            |                   | Factory Default |
|------------------------------------------------------|----------------------------|--------------|------------|-------------------|-----------------|
|                                                      | Debugging                  | Traceability | Efficiency | Safety precaution |                 |
| <b>Model block version mismatch</b>                  | No impact                  | No impact    | No impact  | No recommendation | none            |
| <b>Port and parameter mismatch</b>                   | No impact                  | No impact    | No impact  | error             | none            |
| <b>Invalid root Inport/ Outport block connection</b> | No impact                  | No impact    | No impact  | error             | none            |
| <b>Unsupported data logging</b>                      | No impact                  | No impact    | No impact  | error             | warning         |

**Mapping Application Requirements to the Diagnostics Pane: Saving Tab**

| Configuration Parameter                                   | Settings for Building Code |              |            |                   | Factory Default |
|-----------------------------------------------------------|----------------------------|--------------|------------|-------------------|-----------------|
|                                                           | Debugging                  | Traceability | Efficiency | Safety precaution |                 |
| <b>Block diagram contains disabled library links</b>      | No impact                  | No impact    | No impact  | No impact         | warning         |
| <b>Block diagram contains parameterized library links</b> | No impact                  | No impact    | No impact  | No impact         | none            |

**Mapping Application Requirements to the Diagnostics Pane: Stateflow Tab**

| Configuration Parameter                                  | Settings for Building Code |              |                                                                                                |                   | Factory Default |
|----------------------------------------------------------|----------------------------|--------------|------------------------------------------------------------------------------------------------|-------------------|-----------------|
|                                                          | Debugging                  | Traceability | Efficiency                                                                                     | Safety precaution |                 |
| <b>Unused data and events</b>                            | warning                    | No impact    | No impact (for simulation and during development)<br><br>none (for production code generation) | warning           | warning         |
| <b>Unexpected backtracking</b>                           | warning                    | No impact    | No impact                                                                                      | error             | warning         |
| <b>Invalid input data access in chart initialization</b> | warning                    | No impact    | No impact                                                                                      | error             | warning         |
| <b>No unconditional default transitions</b>              | warning                    | No impact    | No impact (for simulation and during development)<br><br>none (for production code generation) | error             | warning         |
| <b>Transition outside natural parent</b>                 | warning                    | No impact    | No impact (for simulation and during development)<br><br>none (for production code generation) | error             | warning         |

**Mapping Application Requirements to the Hardware Implementation Pane**

| Configuration Parameter | Settings for Building Code |              |            |                                                                                                                                                                                                                                   | Factory Default                                                                                                                                                                     |
|-------------------------|----------------------------|--------------|------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
|                         | Debugging                  | Traceability | Efficiency | Safety precaution                                                                                                                                                                                                                 |                                                                                                                                                                                     |
| <b>Device vendor</b>    | No impact                  | No impact    | No impact  | Select your <b>Device vendor</b> and <b>Device type</b> if they are available in the drop-down list. If your <b>Device vendor</b> and <b>Device type</b> are not available, set device-specific values by using Custom Processor. | None if specified system target file is <code>ert.tlc</code> , <code>realtime.tlc</code> , or <code>autosar.tlc</code> . Otherwise, Determine by Code Generation system target file |
| <b>Device vendor</b>    | No impact                  | No impact    | No impact  | Select your <b>Device vendor</b> and <b>Device type</b> if they are available in the drop-down list. If your <b>Device vendor</b> and <b>Device type</b> are not available, set device-specific values by using Custom Processor. | Intel                                                                                                                                                                               |
| <b>Device type</b>      | No impact                  | No impact    | No impact  | Select your <b>Device vendor</b> and <b>Device type</b> if they are available in the drop-down list. If your <b>Device vendor</b> and <b>Device type</b> are not available, set device-specific values by using Custom Processor. | x86-64 (Windows64)                                                                                                                                                                  |



| Configuration Parameter             | Settings for Building Code |              |                 |                                                                                                                                                                                                                                                                                                                                  | Factory Default                                                                             |
|-------------------------------------|----------------------------|--------------|-----------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|---------------------------------------------------------------------------------------------|
|                                     | Debugging                  | Traceability | Efficiency      | Safety precaution                                                                                                                                                                                                                                                                                                                |                                                                                             |
| <b>Number of bits: char</b>         | No impact                  | No impact    | Target specific | No recommendation for simulation without code generation. For simulation with code generation, select your <b>Device vendor</b> and <b>Device type</b> if they are available in the drop-down list. If your <b>Device vendor</b> and <b>Device type</b> are not available, set device-specific values by using Custom Processor. | char 8, short 16, int 32, long 32, long long 64, float 32, double 64, native 32, pointer 32 |
| <b>Largest atomic size: integer</b> | No impact                  | No impact    | Target specific | No recommendation for simulation without code generation. For simulation with code generation, select your <b>Device vendor</b> and <b>Device type</b> if they are available in the drop-down list. If your <b>Device vendor</b> and <b>Device type</b> are not available, set device-specific values by using Custom Processor. | integer Char, floating-point Float                                                          |

| Configuration Parameter                  | Settings for Building Code                                                                      |                                                                                                     |                                                                                            |                                                                                                                                                                                                                                                                                                                                  | Factory Default |
|------------------------------------------|-------------------------------------------------------------------------------------------------|-----------------------------------------------------------------------------------------------------|--------------------------------------------------------------------------------------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-----------------|
|                                          | Debugging                                                                                       | Traceability                                                                                        | Efficiency                                                                                 | Safety precaution                                                                                                                                                                                                                                                                                                                |                 |
| <b>Byte ordering</b>                     | No impact                                                                                       | No impact                                                                                           | No impact                                                                                  | No recommendation for simulation without code generation. For simulation with code generation, select your <b>Device vendor</b> and <b>Device type</b> if they are available in the drop-down list. If your <b>Device vendor</b> and <b>Device type</b> are not available, set device-specific values by using Custom Processor. | Little Endian   |
| <b>Signed integer division rounds to</b> | No impact for simulation and during development<br><br>Undefined for production code generation | No impact for simulation and during development<br><br>Zero or Floor for production code generation | No impact for simulation and during development<br><br>Zero for production code generation | No recommendation for simulation without code generation. For simulation with code generation, select your <b>Device vendor</b> and <b>Device type</b> if they are available in the drop-down list. If your <b>Device vendor</b> and <b>Device type</b> are not available, set device-specific values by using Custom Processor. | Zero            |

| Configuration Parameter                                    | Settings for Building Code |              |                     |                                                                                                                                                                                                                                                                                                                                  | Factory Default |
|------------------------------------------------------------|----------------------------|--------------|---------------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-----------------|
|                                                            | Debugging                  | Traceability | Efficiency          | Safety precaution                                                                                                                                                                                                                                                                                                                |                 |
| <b>Shift right on a signed integer as arithmetic shift</b> | No impact                  | No impact    | On                  | No recommendation for simulation without code generation. For simulation with code generation, select your <b>Device vendor</b> and <b>Device type</b> if they are available in the drop-down list. If your <b>Device vendor</b> and <b>Device type</b> are not available, set device-specific values by using Custom Processor. | On              |
| <b>Support long long</b>                                   | No impact                  | No impact    | On (execution, ROM) | No recommendation for simulation without code generation. For simulation with code generation, select your <b>Device vendor</b> and <b>Device type</b> if they are available in the drop-down list. If your <b>Device vendor</b> and <b>Device type</b> are not available, set device-specific values by using Custom Processor. | Off             |

## Mapping Application Requirements to the Model Referencing Pane

| Configuration Parameter                                | Settings for Building Code |              |            |                                                                                                                                                           | Factory Default            |
|--------------------------------------------------------|----------------------------|--------------|------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------|----------------------------|
|                                                        | Debugging                  | Traceability | Efficiency | Safety precaution                                                                                                                                         |                            |
| <b>Rebuild options</b>                                 | No impact                  | No impact    | No impact  | If any changes detected or Never<br><br>If you use the Never setting, then set the <b>Never rebuild diagnostic</b> parameter to Error if rebuild required | If any changes detected    |
| <b>Never rebuild diagnostic</b>                        | No impact                  | No impact    | No impact  | error if rebuild required                                                                                                                                 | error if rebuild required  |
| <b>Enable parallel model reference builds</b>          | No impact                  | No impact    | No impact  | No impact                                                                                                                                                 | Off                        |
| <b>MATLAB worker initialization for builds</b>         | No impact                  | No impact    | No impact  | No impact                                                                                                                                                 | None                       |
| <b>Total number of instances allowed per top model</b> | No impact                  | No impact    | No impact  | No recommendation                                                                                                                                         | Multiple                   |
| <b>Pass scalar root inputs by value</b>                | No impact                  | No impact    | No impact  | No recommendation                                                                                                                                         | Off                        |
| <b>Minimize algebraic loop occurrences</b>             | No impact                  | No impact    | No impact  | No recommendation                                                                                                                                         | Off                        |
| <b>Propagate sizes of variable-size signals</b>        | No impact                  | No impact    | No impact  | No recommendation                                                                                                                                         | Infer from blocks in model |
| <b>Model dependencies</b>                              | No impact                  | No impact    | No impact  | No recommendation                                                                                                                                         | ' '                        |

**Mapping Application Requirements to the Simulation Target Pane: General Tab**

| Configuration Parameter                           | Settings for Building Code |                   |                   |                   | Factory Default |
|---------------------------------------------------|----------------------------|-------------------|-------------------|-------------------|-----------------|
|                                                   | Debugging                  | Traceability      | Efficiency        | Safety precaution |                 |
| <b>Ensure memory integrity</b>                    | On                         | No impact         | No recommendation | On                | On              |
| <b>Echo expressions without semicolons" /&gt;</b> | On                         | No impact         | Off               | No impact         | On              |
| <b>Ensure responsiveness</b>                      | On                         | No recommendation | No recommendation | No recommendation | On              |

**Mapping Application Requirements to the Simulation Target Pane: Symbols Tab**

| Configuration Parameter | Settings for Building Code |              |            |                   | Factory Default |
|-------------------------|----------------------------|--------------|------------|-------------------|-----------------|
|                         | Debugging                  | Traceability | Efficiency | Safety precaution |                 |
| <b>Reserved names</b>   | No impact                  | No impact    | No impact  | No recommendation | {}              |

**Mapping Application Requirements to the Simulation Target Pane: Custom Code Tab**

| Configuration Parameter          | Settings for Building Code |                   |                   |                   | Factory Default |
|----------------------------------|----------------------------|-------------------|-------------------|-------------------|-----------------|
|                                  | Debugging                  | Traceability      | Efficiency        | Safety precaution |                 |
| <b>Parse custom code symbols</b> | On                         | No impact         | No impact         | On                | On              |
| <b>Source file</b>               | No recommendation          | No recommendation | No recommendation | No recommendation | ' '             |
| <b>Header file</b>               | No recommendation          | No recommendation | No recommendation | No recommendation | ' '             |
| <b>Initialize function</b>       | No recommendation          | No recommendation | No recommendation | No recommendation | ' '             |
| <b>Terminate function</b>        | No recommendation          | No recommendation | No recommendation | No recommendation | ' '             |
| <b>Include directories</b>       | No impact                  | No impact         | No impact         | No recommendation | ' '             |
| <b>Source files</b>              | No impact                  | No impact         | No impact         | No recommendation | ' '             |
| <b>Libraries</b>                 | No impact                  | No impact         | No impact         | No recommendation | ' '             |
| <b>Defines</b>                   | No impact                  | No impact         | No impact         | No recommendation | ' '             |

## Mapping Application Requirements to the Code Generation Pane: General Tab

| Configuration Parameter                        | Settings for Building Code                                       |                                                                  |                                                                                     |                                                                  | Factory Default                         |
|------------------------------------------------|------------------------------------------------------------------|------------------------------------------------------------------|-------------------------------------------------------------------------------------|------------------------------------------------------------------|-----------------------------------------|
|                                                | Debugging                                                        | Traceability                                                     | Efficiency                                                                          | Safety precaution                                                |                                         |
| <b>System target file</b>                      | No impact                                                        | No impact                                                        | No impact                                                                           | No impact (GRT)<br>ERT based (ERT)                               | grt.tlc                                 |
| <b>Language</b>                                | No impact                                                        | No impact                                                        | No impact                                                                           | No impact                                                        | C                                       |
| <b>Compiler optimization level</b>             | Optimization<br>s off<br>(faster<br>builds)                      | Optimization<br>s off<br>(faster<br>builds)                      | Optimization<br>s on (faster<br>runs)<br>(execution)<br><br>No impact<br>(ROM, RAM) | No impact                                                        | Optimizations<br>off (faster<br>builds) |
| <b>Custom compiler optimization flags</b>      | Optimization<br>s off<br>(faster<br>builds)                      | Optimization<br>s off<br>(faster<br>builds)                      | Optimization<br>s on (faster<br>runs)                                               | No impact                                                        | Optimizations<br>off (faster<br>builds) |
| <b>Generate makefile</b>                       | No impact                                                        | No impact                                                        | No impact                                                                           | No impact                                                        | On                                      |
| <b>Make command</b>                            | No impact                                                        | No impact                                                        | No impact                                                                           | No<br>recommendation                                             | make_rtw                                |
| <b>Template makefile</b>                       | No impact                                                        | No impact                                                        | No impact                                                                           | No impact                                                        | grt_default_t<br>mf                     |
| <b>Select objective</b>                        | Debugging                                                        | Not applicable<br>for GRT-based<br>targets                       | Execution<br>efficiency                                                             | No<br>recommendation                                             | Unspecified                             |
| <b>Check model before generating code</b>      | On (proceed<br>with<br>warnings) or<br>On (stop for<br>warnings) | On (proceed<br>with<br>warnings) or<br>On (stop for<br>warnings) | On (proceed<br>with<br>warnings) or<br>On (stop for<br>warnings)                    | On (proceed<br>with<br>warnings) or<br>On (stop for<br>warnings) | Off                                     |
| <b>Generate code only</b>                      | Off                                                              | No impact                                                        | No impact                                                                           | No impact                                                        | Off                                     |
| <b>Verbose build</b>                           | On                                                               | No impact                                                        | No impact                                                                           | No<br>recommendation                                             | On                                      |
| <b>Retain .rtw file</b>                        | On                                                               | No impact                                                        | No impact                                                                           | No impact                                                        | Off                                     |
| <b>Profile TLC</b>                             | On                                                               | No impact                                                        | No impact                                                                           | No impact                                                        | Off                                     |
| <b>Start TLC debugger when generating code</b> | On                                                               | No impact                                                        | No impact                                                                           | No impact                                                        | Off                                     |
| <b>Start TLC coverage when generating code</b> | On                                                               | No impact                                                        | No impact                                                                           | No impact                                                        | Off                                     |
| <b>Enable TLC assertion</b>                    | On                                                               | No impact                                                        | No impact                                                                           | No<br>recommendation                                             | Off                                     |

**Mapping Application Requirements to the Code Generation Pane: Report Tab**

| Configuration Parameter              | Settings for Building Code |              |            |                   | Factory Default |
|--------------------------------------|----------------------------|--------------|------------|-------------------|-----------------|
|                                      | Debugging                  | Traceability | Efficiency | Safety precaution |                 |
| <b>Create Code Generation report</b> | On                         | On           | No impact  | No recommendation | Off             |
| <b>Launch report automatically</b>   | On                         | On           | No impact  | No impact         | Off             |

**Mapping Application Requirements to the Code Generation Pane: Comments Tab**

| Configuration Parameter                                   | Settings for Building Code |              |            |                   | Factory Default |
|-----------------------------------------------------------|----------------------------|--------------|------------|-------------------|-----------------|
|                                                           | Debugging                  | Traceability | Efficiency | Safety precaution |                 |
| <b>Include comments</b>                                   | On                         | On           | No impact  | No recommendation | On              |
| <b>Simulink block comments</b>                            | On                         | On           | No impact  | No recommendation | On              |
| <b>Stateflow object comments</b>                          | On                         | On           | No impact  | No recommendation | Off             |
| <b>Show eliminated blocks</b>                             | On                         | On           | No impact  | No recommendation | On              |
| <b>Verbose comments for 'Model default' storage class</b> | On                         | On           | No impact  | No recommendation | On              |
| <b>Operator Annotations</b>                               | No impact                  | On           | No impact  | No recommendation | On              |

**Mapping Application Requirements to the Code Generation Pane: Identifiers Tab**

| Configuration Parameter                                 | Settings for Building Code |              |            |                   | Factory Default |
|---------------------------------------------------------|----------------------------|--------------|------------|-------------------|-----------------|
|                                                         | Debugging                  | Traceability | Efficiency | Safety precaution |                 |
| <b>Maximum identifier length</b>                        | Valid value                | >30          | No impact  | >30               | 31              |
| <b>Use the same reserved names as Simulation Target</b> | No impact                  | No impact    | No impact  | No impact         | Off             |
| <b>Reserved names</b>                                   | No impact                  | No impact    | No impact  | No impact         | { }             |



**Mapping Application Requirements to the Code Generation Pane: Custom Code Tab**

| Configuration Parameter                                       | Settings for Building Code |              |            |                   | Factory Default |
|---------------------------------------------------------------|----------------------------|--------------|------------|-------------------|-----------------|
|                                                               | Debugging                  | Traceability | Efficiency | Safety precaution |                 |
| <b>Use the same custom code settings as Simulation Target</b> | No impact                  | No impact    | No impact  | No impact         | Off             |
| <b>Source file</b>                                            | No impact                  | No impact    | No impact  | No impact         | ' '             |
| <b>Header file</b>                                            | No impact                  | No impact    | No impact  | No impact         | ' '             |
| <b>Initialize function</b>                                    | No impact                  | No impact    | No impact  | No impact         | ' '             |
| <b>Terminate function</b>                                     | No impact                  | No impact    | No impact  | No impact         | ' '             |
| <b>Include directories</b>                                    | No impact                  | No impact    | No impact  | No impact         | ' '             |
| <b>Source files</b>                                           | No impact                  | No impact    | No impact  | No impact         | ' '             |
| <b>Libraries</b>                                              | No impact                  | No impact    | No impact  | No impact         | ' '             |
| <b>Libraries</b>                                              | No impact                  | No impact    | No impact  | No impact         | ' '             |

Mapping Application Requirements to the Code Generation Pane: Interface Tab

| Configuration Parameter                     | Settings for Building Code |                       |                                         |                                             | Factory Default                                                                                 |
|---------------------------------------------|----------------------------|-----------------------|-----------------------------------------|---------------------------------------------|-------------------------------------------------------------------------------------------------|
|                                             | Debugging                  | Traceability          | Efficiency                              | Safety precaution                           |                                                                                                 |
| <b>Standard math library</b>                | No impact                  | No impact             | Valid library                           | No impact                                   | C99 (ISO)                                                                                       |
| <b>Code replacement library</b>             | No impact                  | No impact             | Valid library                           | No impact                                   | None                                                                                            |
| <b>Utility function generation</b>          | Shared location (GRT)      | Shared location (GRT) | No impact (execution, RAM)              | No impact                                   | Auto                                                                                            |
|                                             | No impact (ERT)            | No impact (ERT)       | Shared location (ROM)                   |                                             |                                                                                                 |
| <b>Support: non-finite numbers</b>          | No impact                  | No impact             | Off (Execution, ROM)<br>No impact (RAM) | Norecommendation                            | On                                                                                              |
| <b>Code interface packaging</b>             | No impact                  | No impact             | Reusable function or C++ class          | No impact                                   | Nonreusable function if <b>Language</b> is set to C; C++ class if <b>Language</b> is set to C++ |
| <b>Multi-instance code error diagnostic</b> | Warning or Error           | No impact             | None                                    | No impact                                   | Error                                                                                           |
| <b>Classic call interface</b>               | No impact                  | Off                   | Off (execution, ROM), No impact (RAM)   | No recommendation                           | Off (except On for GRT models created before R2012a)                                            |
| <b>Single output/update function</b>        | On                         | On                    | On                                      | No recommendation                           | On                                                                                              |
| <b>MAT-file logging</b>                     | On                         | No impact             | Off                                     | Off                                         | On (GRT)<br>Off (ERT)                                                                           |
| <b>MAT-file variable name modifier</b>      | No impact                  | No impact             | No impact                               | No impact                                   | rt_                                                                                             |
| <b>Signals in C API</b>                     | No impact                  | No impact             | No impact                               | No impact (development)<br>Off (production) | Off                                                                                             |

| Configuration Parameter                   | Settings for Building Code |              |            |                                             | Factory Default |
|-------------------------------------------|----------------------------|--------------|------------|---------------------------------------------|-----------------|
|                                           | Debugging                  | Traceability | Efficiency | Safety precaution                           |                 |
| <b>Parameters in C API</b>                | No impact                  | No impact    | No impact  | No impact (development)<br>Off (production) | Off             |
| <b>Generate C API for: states</b>         | No impact                  | No impact    | No impact  | No impact (development)<br>Off (production) | Off             |
| <b>Generate C API for: root-level I/O</b> | No impact                  | No impact    | No impact  | No impact (development)<br>Off (production) | Off             |
| <b>ASAP2 interface</b>                    | No impact                  | No impact    | No impact  | No impact (development)<br>Off (production) | Off             |
| <b>External mode</b>                      | No impact                  | No impact    | No impact  | No impact (development)<br>Off (production) | Off             |
| <b>Transport layer</b>                    | No impact                  | No impact    | No impact  | No impact                                   | tcpip           |
| <b>MEX-file arguments</b>                 | No impact                  | No impact    | No impact  | No impact                                   | ' '             |
| <b>Static memory allocation</b>           | No impact                  | No impact    | No impact  | No impact                                   | Off             |
| <b>Static memory allocation</b>           | No impact                  | No impact    | No impact  | No impact                                   | 1000000         |



# Model Advisor Checks

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- “Simulink Coder Checks” on page 16-2
- “Code Generation Advisor Checks” on page 16-21

## Simulink Coder Checks

### In this section...

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“Check reuse of subsystem code” on page 16-2  
“Identify blocks using one-based indexing” on page 16-3  
“Check solver for code generation” on page 16-4  
“Check for blocks not supported by code generation” on page 16-4  
“Check and update model to use toolchain approach to build generated code” on page 16-5  
“Check and update embedded target model to use ert.tlc system target file” on page 16-7  
“Check and update models that are using targets that have changed significantly across different releases of MATLAB” on page 16-8  
“Check for blocks that have constraints on tunable parameters” on page 16-9  
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“Available Checks for Code Generation Objectives” on page 16-12  
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“Check model configuration settings against code generation objectives” on page 16-20

### Simulink Coder Checks Overview

Use Simulink Coder Model Advisor checks to configure your model for code generation.

#### See Also

- “Run Model Advisor Checks”
- “Simulink Checks”
- “Embedded Coder Checks” (Embedded Coder)

### Check reuse of subsystem code

**Check ID:** `mathworks.codegen.SubsysCodeReuse`

Identify `CodeReuseSubsystem` blocks that are not reusing code.

## Results and Recommended Actions

| Condition                                                             | Recommended Action                                                     |
|-----------------------------------------------------------------------|------------------------------------------------------------------------|
| One or more CodeReuseSubsystem blocks in the model do not reuse code. | Modify CodeReuseSubsystem blocks in the model so that they reuse code. |

## Capabilities and Limitations

You can:

- Run this check on your library models.
- Look under masks,
- Exclude blocks and charts from this check if you have a Simulink Check™ license.

## See Also

- “Model Advisor Exclusion Overview” (Simulink Check)

## Identify blocks using one-based indexing

**Check ID:** `mathworks.codegen.cgsl_0101`

Identify blocks using one-based indexing.

### Description

Zero-based indexing is more efficient in the generated code than one-based indexing.

Using zero-based indexing increases execution efficiency of the generated code.

Available with Simulink Coder.

## Results and Recommended Actions

| Condition                                                                 | Recommended Action                                                          |
|---------------------------------------------------------------------------|-----------------------------------------------------------------------------|
| The model or subsystem contains blocks configured for one-based indexing. | Configure the blocks for zero-based indexing. Update the supporting blocks. |

## Capabilities and Limitations

You can:

- Run this check on your library models.
- Exclude blocks and charts from this check if you have a Simulink Check license.

## See Also

- “cgsl\_0101: Zero-based indexing”.
- “Model Advisor Exclusion Overview” (Simulink Check)

## Check solver for code generation

**Check ID:** `mathworks.codegen.SolverCodeGen`

Check model solver and sample time configuration settings.

### Description

Incorrect configuration settings can stop the code generator from producing code. Underspecifying sample times can lead to undesired results. Avoid generating code that might corrupt data or produce unpredictable behavior.

Available with Simulink Coder.

### Results and Recommended Actions

| Condition                                                           | Recommended Action                                                                                                                                                                                                                                                                                                                                     |
|---------------------------------------------------------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| The solver type is set incorrectly for model level code generation. | In the Configuration Parameters dialog box, on the <b>Solver</b> pane, set <b>Type</b> to <b>Fixed-step</b> .                                                                                                                                                                                                                                          |
| Multitasking diagnostic options are not set to error.               | In the Configuration Parameters dialog box, on the <b>Diagnostics</b> pane, set <ul style="list-style-type: none"> <li>• <b>Sample Time &gt; Multitask conditionally executed subsystem</b> to error</li> <li>• <b>Sample Time &gt; Multitask data transfer</b> to error</li> <li>• <b>Data Validity &gt; Multitask data store</b> to error</li> </ul> |

### Tips

You do not have to modify the solver settings to generate code from a subsystem. The build process automatically changes **Solver type** to **fixed-step** when you right-click on the subsystem and select **C/C++ Code > Build This Subsystem** or **C/C++ Code > Generate S-Function** from the subsystem context menu.

### See Also

- “Configure Time-Based Scheduling”
- “Execute Multitasking Models”

## Check for blocks not supported by code generation

**Check ID:** `mathworks.codegen.codeGenSupport`

Identify blocks not supported by code generation.



## Description

This check partially identifies model constructs that are not suited for code generation as identified in the Simulink Block Support tables for Simulink Coder and Embedded Coder. If you are using blocks with support notes for code generation, review the information and follow the given advice.

Available with Simulink Coder.

## Results and Recommended Actions

| Condition                                                                           | Recommended Action                                                                                                             |
|-------------------------------------------------------------------------------------|--------------------------------------------------------------------------------------------------------------------------------|
| The model or subsystem contains blocks that should not be used for code generation. | Consider replacing the blocks listed in the results. Click an element from the list of questionable items to locate condition. |

## Capabilities and Limitations

You can:

- Run this check on your library models.
- Analyzes content of library linked blocks.
- Analyzes content in masked subsystems.
- Exclude blocks and charts from this check if you have a Simulink Check license.

## See Also

- “Use Blocks and Products Supported for Code Generation”
- “Model Advisor Exclusion Overview” (Simulink Check)

## Check and update model to use toolchain approach to build generated code

**Check ID:** `mathworks.codegen.toolchainInfoUpgradeAdvisor.check`

Check if model uses Toolchain settings to build generated code.

## Description

Checks whether the model uses the template makefile approach or the toolchain approach to build the generated code.

Available with Simulink Coder.

When you open a model created before R2013b that has **System target file** set to `ert.tlc`, `ert_shrlib.tlc`, or `grt.tlc` the software automatically tries to upgrade the model from using the template makefile approach to using the toolchain approach.

If the software did not upgrade the model, this check determines the cause, and if available, recommends actions you can perform to upgrade the model.

To determine which approach your model is using, you can also look at the Code Generation pane in the Configuration Parameters dialog box. The toolchain approach uses the following parameters to build generated code:

- Toolchain
- Build configuration

The template makefile approach uses the following settings to build generated code:

- **Compiler optimization level**
- **Custom compiler optimization flags**
- **Generate makefile**
- **Template makefile**

**Results and Recommended Actions**

| Condition                                                                                             | Recommended Action                                                                             | Comment                                                                                                                                                                                                                                                                                                                                                                                                                                                                        |
|-------------------------------------------------------------------------------------------------------|------------------------------------------------------------------------------------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Model is configured to use the toolchain approach.                                                    | No action.                                                                                     | The model was automatically upgraded.                                                                                                                                                                                                                                                                                                                                                                                                                                          |
| Model is not configured to use the toolchain approach.                                                | Model cannot be automatically upgraded to use the toolchain approach.                          | The system target file is not toolchain-compliant. Set <b>System target file</b> to a toolchain-compliant target, such as <code>ert.tlc</code> , <code>ert_shrlib.tlc</code> , or <code>grt.tlc</code> .                                                                                                                                                                                                                                                                       |
| Model is not configured to use the toolchain approach. (Parameter values are not the default values.) | Model can be automatically upgraded to use the toolchain approach. Click <b>Update Model</b> . | The parameters are set to their default values, except <b>Compiler Optimization Level</b> , which is set Optimizations on (faster runs). Clicking <b>Update Model</b> sets <b>Compiler Optimization Level</b> to its default value, Optimizations off (faster builds), and then upgrades the model. The upgraded model has <b>Build Configuration</b> set to Faster Builds. Saving the model makes these changes permanent.                                                    |
| Model is not configured to use the toolchain approach. (Parameter values are not the default values.) | Model cannot be automatically upgraded to use the toolchain approach.                          | One or more of the following parameters is not set to its default value: <ul style="list-style-type: none"> <li>• <b>Generate makefile</b> (default: Enabled)</li> <li>• <b>Template makefile</b> (default: Target-specific default TMF)</li> <li>• <b>Compiler optimization level</b> (default: Optimizations off (faster builds))</li> <li>• <b>Make command</b> (default: <code>make_rtw</code> without arguments)</li> </ul> See "Upgrade Model to Use Toolchain Approach" |

**Action Results**

Clicking **Update model** upgrades the model to use the toolchain approach to build generated code.

**See Also**

- “Upgrade Model to Use Toolchain Approach”

**Check and update embedded target model to use ert.tlc system target file**

**Check ID:** mathworks.codegen.codertarget.check

Check and update the embedded target model to use ert.tlc system target file.

**Description**

Check and update models whose **System target file** is set to a file other than ert.tlc and whose target hardware is one of the supported Texas Instruments C2000™ processors to use ert.tlc and similar settings.

Available with Simulink Coder.

**Results and Recommended Actions**

| Condition                                                                                                                                                                                                               | Recommended Action                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   |
|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| <b>System target file</b> is set to ert.tlc - Embedded Coder.                                                                                                                                                           | No action                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            |
| <b>System target file</b> is set to a file other than ert.tlc and <b>Hardware board</b> parameter is set to a processor that is supported by the Embedded Coder Support Package for Texas Instruments C2000 Processors. | <p>Run the corresponding check in Upgrade Advisor:</p> <ol style="list-style-type: none"> <li><b>1</b> In the <b>Modeling</b> tab of Simulink Editor, click <b>Model Advisor</b>.</li> <li><b>2</b> Open the <b>Upgrade Advisor</b> pane and select check <b>Check and update embedded target model to use ert.tlc system target file</b>.</li> <li><b>3</b> Right-click on the check and select <b>Run This Check</b>.</li> <li><b>4</b> After the check passes, open the Configuration Parameters dialog box, go to <b>Hardware Implementation</b> pane and confirm that the correct <b>Hardware board</b> is selected.</li> </ol> |

**Action Results**

Clicking **Run This Check** automatically sets the following parameters on the **Code Generation** pane in the model Configuration Parameters dialog box:

- **System target file** parameter to ert.tlc.
- **Toolchain** parameter to match the previous toolchain.

- **Build configuration** parameter to match the build configuration.

### Capabilities and Limitations

The new workflow uses the toolchain approach, which relies on enhanced makefiles to build generated code. It does not provide an equivalent to setting the **Build format** parameter to Project in the previous configuration. Therefore, the new workflow cannot automatically generate IDE projects within the CCS 3.3 IDE.

### See Also

“Toolchain Configuration”

## Check and update models that are using targets that have changed significantly across different releases of MATLAB

**Check ID:** `mathworks.codegen.realtime2CoderTargetInfoUpgradeAdvisor.check`

Check and update models with Simulink targets that have changed significantly across different releases of MATLAB.

### Description

Save a model that you have updated to work with the current installation of MATLAB.

Available with Simulink Coder.

### Results and Recommended Actions

| Condition                                                                                                        | Recommended Action                                                                                                                                               |
|------------------------------------------------------------------------------------------------------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Model uses a target that has changed significantly since the release of MATLAB in which it was originally saved. | Save model                                                                                                                                                       |
| Model does not use a Simulink target or is using the latest version of the target.                               | No action                                                                                                                                                        |
| Model is automatically updated.                                                                                  | Save model                                                                                                                                                       |
| Invalid external mode configuration.                                                                             | In the <b>Configuration Parameters &gt; Interface</b> pane, update the external mode parameter settings to match characteristics of your host-target connection. |
| Model is corrupted.                                                                                              | Close and reopen the model. If the issue persists, reset <b>Configuration Parameters &gt; Hardware Implementation &gt; Hardware board</b> .                      |

### Action Results

Clicking **Save model** updates the model to work with the current installation of MATLAB and saves the model.

**See Also**

“Configure Production and Test Hardware”

**Check for blocks that have constraints on tunable parameters**

**Check ID:** `mathworks.codegen.ConstraintsTunableParam`

Identify blocks with constraints on tunable parameters.

**Description**

Lookup Table blocks have strict constraints when they are tunable. If you violate lookup table block restrictions, the generated code produces incorrect answers.

Available with Simulink Coder.

**Results and Recommended Actions**

| <b>Condition</b>                                   | <b>Recommended Action</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                |
|----------------------------------------------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Lookup Table blocks have tunable parameters.       | When tuning parameters during simulation or when running the generated code, you must: <ul style="list-style-type: none"> <li>• Preserve monotonicity of the setting for the <b>Vector of input values</b> parameter.</li> <li>• Preserve the number and location of zero values that you specify for <b>Vector of input values</b> and <b>Vector of output values</b> parameters if you specify multiple zero values for the <b>Vector of input values</b> parameter.</li> </ul>                                                                                                                        |
| Lookup Table (2-D) blocks have tunable parameters. | When tuning parameters during simulation or when running the generated code, you must: <ul style="list-style-type: none"> <li>• Preserve monotonicity of the setting for the <b>Row index input values</b> and <b>Column index of input values</b> parameters.</li> <li>• Preserve the number and location of zero values that you specify for <b>Row index input values</b>, <b>Column index of input values</b>, and <b>Vector of output values</b> parameters if you specify multiple zero values for the <b>Row index input values</b> or <b>Column index of input values</b> parameters.</li> </ul> |
| Lookup Table (n-D) blocks have tunable parameters. | When tuning parameters during simulation or when running the generated code, you must preserve the increasing monotonicity of the breakpoint values for each table dimension <b>Breakpoints n</b> .                                                                                                                                                                                                                                                                                                                                                                                                      |

## Capabilities and Limitations

If you have a Simulink Check license, you can exclude blocks and charts from this check.

### See Also

- 1-D Lookup Table
- 2-D Lookup Table
- “Model Advisor Exclusion Overview” (Simulink Check)

## Check for model reference configuration mismatch

**Check ID:** `mathworks.codegen.MdlrefConfigMismatch`

Identify referenced model configuration parameter settings that do not match the top model configuration parameter settings.

### Description

The code generator cannot create code for top models that contain referenced models with different, incompatible configuration parameter settings.

Available with Simulink Coder.

### Results and Recommended Actions

| Condition                                                                                        | Recommended Action                                 |
|--------------------------------------------------------------------------------------------------|----------------------------------------------------|
| The top model and the referenced model have inconsistent model configuration parameter settings. | Modify the specified model configuration settings. |

### See Also

- “Model Reference Basics”
- “Set Configuration Parameters for Model Hierarchies”

## Check sample times and tasking mode

**Check ID:** `mathworks.codegen.SampleTimesTaskingMode`

Set up the sample time and tasking mode for your system.

### Description

Incorrect tasking mode can result in inefficient code execution or incorrect generated code.

Available with Simulink Coder.

## Results and Recommended Actions

| Condition                                                                                                                                                                                                                                                                                                                  | Recommended Action                                                                                                                                                                                                                                         |
|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| The model represents a multirate system but is not configured for multitasking.                                                                                                                                                                                                                                            | Select model configuration parameter <b>“Treat each discrete rate as a separate task”</b> . When you select the parameter, multitasking execution is applied for a multirate model. For more information, see “Time-Based Scheduling and Code Generation”. |
| The model is configured for multitasking, but multitasking is not desirable on the target hardware. For example, the operating system does not support multiprocessing or the target hardware is bare metal (is not running an operating system) and the application does not provide for a multitasking execution scheme. | Clear model configuration parameter <b>“Treat each discrete rate as a separate task”</b> . When you clear the parameter, single-tasking execution is applied. For more information, see “Time-Based Scheduling and Code Generation”.                       |

### See Also

“Time-Based Scheduling and Code Generation”

## Check for code generation identifier formats used for model reference

**Check ID:** `mathworks.codegen.ModelRefRTWConfigCompliance`

Checks for referenced models in a model referencing hierarchy for which code generation changes configuration parameter settings that involve identifier formats.

### Description

In referenced models, if the following **Configuration Parameters > Code Generation > Identifiers** parameters have settings that do not contain a \$R token (which represents the name of the reference model), code generation prepends the \$R token to the identifier format.

- **Global variables**
- **Global types**
- **Subsystem methods**
- **Constant macros**

Available with Simulink Coder.

## Results and Recommended Actions

| Condition                                                                               | Recommended Action                                                                  |
|-----------------------------------------------------------------------------------------|-------------------------------------------------------------------------------------|
| A script that operates on generated code uses model names that code generation changes. | Update the script to use the generated name (which includes an appended \$R token). |

## Check for relative execution order change for Data Store Read and Data Store Write blocks

**Check ID:** `mathworks.design.datastoresimrtwcmp`

Checks that the execution order of Data Store Read and Data Store Write blocks does not change when a model is compiled for code generation.

### Description

The execution order defines the sequence in which the Data Store Read and Data Store Write blocks access the Data Store Memory block. The Model Advisor check compares the execution order from prior to running the check (normal simulation mode) to the execution order after compiling the check (code generation mode). The check passes when the execution order is the same. When there are differences, the check issues a **Warning** and identifies the discrepancies in the results.

Available with Simulink Coder.

### Results and Recommended Actions

| Condition                                                                                                                             | Recommended Action                                                                                                                                                                                                      |
|---------------------------------------------------------------------------------------------------------------------------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| The execution order of the Data Store Read and Data Store Write blocks is different between simulation mode and code generation mode. | In the Model Advisor results, under <b>Action</b> , click <b>Modify block priorities</b> . The Model Advisor modifies the blocks so the execution order in simulation mode is the same as that in code generation mode. |

### See Also

- “Control and Display Execution Order”
- “Data Store Basics”
- “Order Data Store Access”

## Available Checks for Code Generation Objectives

Code generation objectives checks facilitate designing and troubleshooting Simulink models and subsystems that you want to use to generate code. For more information about code generation objectives, see “Application Objectives Using Code Generation Advisor”.

The Code Generation Advisor includes the following checks from Simulink, Simulink Coder, and Embedded Coder for each of the code generation objectives. Two checks unique to the Code Generation Advisor are included below the list.



| Check                                                                                 | Execution efficiency (all targets)                                                  | ROM efficiency (ERT-based targets)                                                  | RAM efficiency (ERT-based targets) | Safety precaution (ERT-based targets) | Traceability (ERT-based targets) | Debugging (all targets) | MISRA C:2012 guidelines (ERT-based targets) | Polyspace (ERT-based targets) |
|---------------------------------------------------------------------------------------|-------------------------------------------------------------------------------------|-------------------------------------------------------------------------------------|------------------------------------|---------------------------------------|----------------------------------|-------------------------|---------------------------------------------|-------------------------------|
| “Check model configuration settings against code generation objectives” on page 16-20 | Included                                                                            | Included                                                                            | Included                           | Included                              | Included                         | Included                | Included (see <b>Note</b> below)            | Included                      |
| “Check for optimal bus virtuality”                                                    | Included                                                                            | Included                                                                            | Included                           | N/A                                   | N/A                              | N/A                     | N/A                                         | N/A                           |
| “Identify questionable blocks within the specified system” on page 16-19              | Included                                                                            | Included                                                                            | Included                           | N/A                                   | N/A                              | N/A                     | N/A                                         | N/A                           |
| “Check the hardware implementation” (Embedded Coder)                                  | Included if Embedded Coder is available                                             | Included if Embedded Coder is available                                             | N/A                                | N/A                                   | N/A                              | N/A                     | N/A                                         | N/A                           |
| “Identify questionable software environment specifications” (Embedded Coder)          | Included when Traceability is not a higher priority and Embedded Coder is available | Included when Traceability is not a higher priority and Embedded Coder is available | N/A                                | N/A                                   | N/A                              | N/A                     | N/A                                         | N/A                           |

| Check                                                                    | Execution efficiency (all targets)                                                                | ROM efficiency (ERT-based targets)                                                                | RAM efficiency (ERT-based targets)                                                                | Safety precaution (ERT-based targets) | Traceability (ERT-based targets) | Debugging (all targets) | MISRA C:2012 guidelines (ERT-based targets) | Polyspace (ERT-based targets) |
|--------------------------------------------------------------------------|---------------------------------------------------------------------------------------------------|---------------------------------------------------------------------------------------------------|---------------------------------------------------------------------------------------------------|---------------------------------------|----------------------------------|-------------------------|---------------------------------------------|-------------------------------|
| “Identify questionable code instrumentation (data I/O)” (Embedded Coder) | Included when Traceability or Debugging are not higher priorities and Embedded Coder is available | Included when Traceability or Debugging are not higher priorities and Embedded Coder is available | Included when Traceability or Debugging are not higher priorities and Embedded Coder is available | N/A                                   | N/A                              | N/A                     | N/A                                         | N/A                           |
| “Identify questionable subsystem settings” (Embedded Coder)              | N/A                                                                                               | Included if Embedded Coder is available                                                           | Included if Embedded Coder is available                                                           | N/A                                   | N/A                              | N/A                     | N/A                                         | N/A                           |
| “Identify blocks that generate expensive rounding code” (Embedded Coder) | Included if Embedded Coder is available                                                           | Included if Embedded Coder is available                                                           | N/A                                                                                               | N/A                                   | N/A                              | N/A                     | N/A                                         | N/A                           |
| “Identify questionable fixed-point operations” (Embedded Coder)          | Included if Embedded Coder or Fixed-Point Designer™ is available                                  | Included if Embedded Coder or Fixed-Point Designer is available                                   | N/A                                                                                               | N/A                                   | N/A                              | N/A                     | N/A                                         | N/A                           |
| “Identify blocks using one-based indexing” on page 16-3                  | Included                                                                                          | Included                                                                                          | N/A                                                                                               | N/A                                   | N/A                              | N/A                     | N/A                                         | N/A                           |

| Check                                                                                              | Execution efficiency (all targets)      | ROM efficiency (ERT-based targets)      | RAM efficiency (ERT-based targets) | Safety precaution (ERT-based targets) | Traceability (ERT-based targets) | Debugging (all targets) | MISRA C:2012 guidelines (ERT-based targets) | Polyspace (ERT-based targets) |
|----------------------------------------------------------------------------------------------------|-----------------------------------------|-----------------------------------------|------------------------------------|---------------------------------------|----------------------------------|-------------------------|---------------------------------------------|-------------------------------|
| “Identify lookup table blocks that generate expensive out-of-range checking code” (Embedded Coder) | Included if Embedded Coder is available | Included if Embedded Coder is available | N/A                                | N/A                                   | N/A                              | N/A                     | N/A                                         | N/A                           |
| “Check output types of logic blocks” (Embedded Coder)                                              | Included if Embedded Coder is available | N/A                                     | N/A                                | N/A                                   | N/A                              | N/A                     | N/A                                         | N/A                           |
| “Identify unconnected lines, input ports, and output ports”                                        | N/A                                     | N/A                                     | N/A                                | Included                              | N/A                              | N/A                     | N/A                                         | N/A                           |
| “Check Data Store Memory blocks for multitasking, strong typing, and shadowing issues”             | N/A                                     | N/A                                     | N/A                                | Included                              | N/A                              | N/A                     | N/A                                         | N/A                           |
| “Identify block output signals with continuous sample time and non-floating point data type”       | N/A                                     | N/A                                     | N/A                                | Included                              | N/A                              | N/A                     | N/A                                         | N/A                           |

| Check                                                                       | Execution efficiency (all targets) | ROM efficiency (ERT-based targets) | RAM efficiency (ERT-based targets) | Safety precaution (ERT-based targets) | Traceability (ERT-based targets) | Debugging (all targets) | MISRA C:2012 guidelines (ERT-based targets) | Polyspace (ERT-based targets) |
|-----------------------------------------------------------------------------|------------------------------------|------------------------------------|------------------------------------|---------------------------------------|----------------------------------|-------------------------|---------------------------------------------|-------------------------------|
| “Check for blocks that have constraints on tunable parameters” on page 16-9 | N/A                                | N/A                                | N/A                                | Included                              | N/A                              | N/A                     | N/A                                         | N/A                           |
| “Check if read/write diagnostics are enabled for data store blocks”         | N/A                                | N/A                                | N/A                                | Included                              | N/A                              | N/A                     | N/A                                         | N/A                           |
| “Check structure parameter usage with bus signals”                          | N/A                                | N/A                                | N/A                                | Included                              | N/A                              | N/A                     | N/A                                         | N/A                           |
| “Check data store block sample times for modeling errors”                   | N/A                                | N/A                                | N/A                                | Included                              | N/A                              | N/A                     | N/A                                         | N/A                           |
| “Check for potential ordering issues involving data store access”           | N/A                                | N/A                                | N/A                                | Included                              | N/A                              | N/A                     | N/A                                         | N/A                           |

| Check                                                                                    | Execution efficiency (all targets) | ROM efficiency (ERT-based targets) | RAM efficiency (ERT-based targets) | Safety precaution (ERT-based targets) | Traceability (ERT-based targets) | Debugging (all targets) | MISRA C:2012 guidelines (ERT-based targets) | Polyspace (ERT-based targets) |
|------------------------------------------------------------------------------------------|------------------------------------|------------------------------------|------------------------------------|---------------------------------------|----------------------------------|-------------------------|---------------------------------------------|-------------------------------|
| “Check for blocks not recommended for C/C++ production code deployment” (Embedded Coder) | N/A                                | N/A                                | N/A                                | N/A                                   | N/A                              | N/A                     | Included if Embedded Coder is available     | N/A                           |
| “Check for blocks not recommended for MISRA C:2012” (Embedded Coder)                     | N/A                                | N/A                                | N/A                                | N/A                                   | N/A                              | N/A                     | Included if Embedded Coder is available     | N/A                           |
| “Check for unsupported block names” (Embedded Coder)                                     | N/A                                | N/A                                | N/A                                | N/A                                   | N/A                              | N/A                     | Included if Embedded Coder is available     | N/A                           |
| “Check usage of Assignment blocks” (Embedded Coder)                                      | N/A                                | N/A                                | N/A                                | N/A                                   | N/A                              | N/A                     | Included if Embedded Coder is available     | N/A                           |
| “Check for bitwise operations on signed integers” (Embedded Coder)                       | N/A                                | N/A                                | N/A                                | N/A                                   | N/A                              | N/A                     | Included if Embedded Coder is available     | N/A                           |

| Check                                                                                           | Execution efficiency (all targets)      | ROM efficiency (ERT-based targets)      | RAM efficiency (ERT-based targets) | Safety precaution (ERT-based targets)   | Traceability (ERT-based targets) | Debugging (all targets) | MISRA C:2012 guidelines (ERT-based targets) | Polyspace (ERT-based targets) |
|-------------------------------------------------------------------------------------------------|-----------------------------------------|-----------------------------------------|------------------------------------|-----------------------------------------|----------------------------------|-------------------------|---------------------------------------------|-------------------------------|
| “Check for recursive function calls” (Embedded Coder)                                           | N/A                                     | N/A                                     | N/A                                | N/A                                     | N/A                              | N/A                     | Included if Embedded Coder is available     | N/A                           |
| “Check for equality and inequality operations on floating-point values” (Embedded Coder)        | N/A                                     | N/A                                     | N/A                                | N/A                                     | N/A                              | N/A                     | Included if Embedded Coder is available     | N/A                           |
| “Check for switch case expressions without a default case” (Embedded Coder)                     | N/A                                     | N/A                                     | N/A                                | N/A                                     | N/A                              | N/A                     | Included if Embedded Coder is available     | N/A                           |
| “Check configuration parameters for generation of inefficient saturation code” (Embedded Coder) | Included if Embedded Coder is available | Included if Embedded Coder is available | N/A                                | Included if Embedded Coder is available | N/A                              | N/A                     | N/A                                         | N/A                           |

**Note** When the Code Generation Advisor checks your model against the MISRA C:2012 guidelines objective, the tool does not consider all of the configuration parameter settings that are checked by the MISRA C:2012 guidelines checks in the Model Advisor. For a complete check of configuration parameter settings:

- 1 Open the Model Advisor.
- 2 Navigate to **By Task > Modeling Guidelines for MISRA C:2012**.

- 3 Run the checks in the folder.

For more information on using the Model Advisor, see “Check Your Model Using the Model Advisor”.

### See Also

- “Application Objectives Using Code Generation Advisor”
- “Configure Model for Code Generation Objectives by Using Code Generation Advisor” (Embedded Coder)
- “Run Model Advisor Checks”
- “Simulink Checks”
- “Simulink Coder Checks” on page 16-2
- “Simulink Check Checks” (Simulink Check)

## Identify questionable blocks within the specified system

Identify blocks not supported by code generation or not recommended for deployment.

### Description

The code generator creates code only for the blocks that it supports. Some blocks are not recommended for production code deployment.

### Results and Recommended Actions

| Condition                                                  | Recommended Action                                                                         |
|------------------------------------------------------------|--------------------------------------------------------------------------------------------|
| A block is not supported by the code generator.            | Remove the specified block from the model or replace the block with the recommended block. |
| A block is not recommended for production code deployment. | Remove the specified block from the model or replace the block with the recommended block. |
| Check for Gain blocks whose value equals 1.                | Replace Gain blocks with Signal Conversion blocks.                                         |

### Capabilities and Limitations

You can:

- Run this check on your library models.
- Exclude blocks and charts from this check if you have a Simulink Check license.

### See Also

“Use Blocks and Products Supported for Code Generation”

“Model Advisor Exclusion Overview” (Simulink Check)

## Check model configuration settings against code generation objectives

Check the configuration parameter settings for the model against the code generation objectives.

### Description

Each parameter in the Configuration Parameters dialog box might have different recommended settings for code generation based on your objectives. This check helps you identify the recommended setting for each parameter so that you can achieve optimized code based on your objective.

### Results and Recommended Actions

| Condition                                                                                   | Recommended Action                                                                                                                                                              |
|---------------------------------------------------------------------------------------------|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Parameters are set to values other than the value recommended for the specified objectives. | Set the parameters to the recommended values.<br><br><b>Note</b> A change to one parameter value can impact other parameters. Passing the check might take multiple iterations. |

### Action Results

Clicking **Modify Parameters** under **Action** in the check window changes the parameter values to the recommended values.

### See Also

- “Recommended Settings Summary for Model Configuration Parameters” (Embedded Coder)
- “Application Objectives Using Code Generation Advisor”
- “Configure Model for Code Generation Objectives by Using Code Generation Advisor” (Embedded Coder)



## Code Generation Advisor Checks

### In this section...

“Available Checks for Code Generation Objectives” on page 16-21

“Identify questionable blocks within the specified system” on page 16-27

“Check model configuration settings against code generation objectives” on page 16-28

### Available Checks for Code Generation Objectives

Code generation objectives checks facilitate designing and troubleshooting Simulink models and subsystems that you want to use to generate code. For more information about code generation objectives, see “Application Objectives Using Code Generation Advisor”.

The Code Generation Advisor includes the following checks from Simulink, Simulink Coder, and Embedded Coder for each of the code generation objectives. Two checks unique to the Code Generation Advisor are included below the list.

| Check                                                                                 | Execution efficiency (all targets) | ROM efficiency (ERT-based targets) | RAM efficiency (ERT-based targets) | Safety precaution (ERT-based targets) | Traceability (ERT-based targets) | Debugging (all targets) | MISRA C:2012 guidelines (ERT-based targets) | Polyspace (ERT-based targets) |
|---------------------------------------------------------------------------------------|------------------------------------|------------------------------------|------------------------------------|---------------------------------------|----------------------------------|-------------------------|---------------------------------------------|-------------------------------|
| “Check model configuration settings against code generation objectives” on page 16-28 | Included                           | Included                           | Included                           | Included                              | Included                         | Included                | Included (see <b>Note</b> below)            | Included                      |
| “Check for optimal bus virtuality”                                                    | Included                           | Included                           | Included                           | N/A                                   | N/A                              | N/A                     | N/A                                         | N/A                           |
| “Identify questionable blocks within the specified system” on page 16-27              | Included                           | Included                           | Included                           | N/A                                   | N/A                              | N/A                     | N/A                                         | N/A                           |

| Check                                                                        | Execution efficiency (all targets)                                                                | ROM efficiency (ERT-based targets)                                                                | RAM efficiency (ERT-based targets)                                                                | Safety precaution (ERT-based targets) | Traceability (ERT-based targets) | Debugging (all targets) | MISRA C:2012 guidelines (ERT-based targets) | Polyspace (ERT-based targets) |
|------------------------------------------------------------------------------|---------------------------------------------------------------------------------------------------|---------------------------------------------------------------------------------------------------|---------------------------------------------------------------------------------------------------|---------------------------------------|----------------------------------|-------------------------|---------------------------------------------|-------------------------------|
| “Check the hardware implementation” (Embedded Coder)                         | Included if Embedded Coder is available                                                           | Included if Embedded Coder is available                                                           | N/A                                                                                               | N/A                                   | N/A                              | N/A                     | N/A                                         | N/A                           |
| “Identify questionable software environment specifications” (Embedded Coder) | Included when Traceability is not a higher priority and Embedded Coder is available               | Included when Traceability is not a higher priority and Embedded Coder is available               | N/A                                                                                               | N/A                                   | N/A                              | N/A                     | N/A                                         | N/A                           |
| “Identify questionable code instrumentation (data I/O)” (Embedded Coder)     | Included when Traceability or Debugging are not higher priorities and Embedded Coder is available | Included when Traceability or Debugging are not higher priorities and Embedded Coder is available | Included when Traceability or Debugging are not higher priorities and Embedded Coder is available | N/A                                   | N/A                              | N/A                     | N/A                                         | N/A                           |
| “Identify questionable subsystem settings” (Embedded Coder)                  | N/A                                                                                               | Included if Embedded Coder is available                                                           | Included if Embedded Coder is available                                                           | N/A                                   | N/A                              | N/A                     | N/A                                         | N/A                           |
| “Identify blocks that generate expensive rounding code” (Embedded Coder)     | Included if Embedded Coder is available                                                           | Included if Embedded Coder is available                                                           | N/A                                                                                               | N/A                                   | N/A                              | N/A                     | N/A                                         | N/A                           |

| Check                                                                                              | Execution efficiency (all targets)                              | ROM efficiency (ERT-based targets)                              | RAM efficiency (ERT-based targets) | Safety precaution (ERT-based targets) | Traceability (ERT-based targets) | Debugging (all targets) | MISRA C:2012 guidelines (ERT-based targets) | Polyspace (ERT-based targets) |
|----------------------------------------------------------------------------------------------------|-----------------------------------------------------------------|-----------------------------------------------------------------|------------------------------------|---------------------------------------|----------------------------------|-------------------------|---------------------------------------------|-------------------------------|
| “Identify questionable fixed-point operations” (Embedded Coder)                                    | Included if Embedded Coder or Fixed-Point Designer is available | Included if Embedded Coder or Fixed-Point Designer is available | N/A                                | N/A                                   | N/A                              | N/A                     | N/A                                         | N/A                           |
| “Identify blocks using one-based indexing” on page 16-3                                            | Included                                                        | Included                                                        | N/A                                | N/A                                   | N/A                              | N/A                     | N/A                                         | N/A                           |
| “Identify lookup table blocks that generate expensive out-of-range checking code” (Embedded Coder) | Included if Embedded Coder is available                         | Included if Embedded Coder is available                         | N/A                                | N/A                                   | N/A                              | N/A                     | N/A                                         | N/A                           |
| “Check output types of logic blocks” (Embedded Coder)                                              | Included if Embedded Coder is available                         | N/A                                                             | N/A                                | N/A                                   | N/A                              | N/A                     | N/A                                         | N/A                           |
| “Identify unconnected lines, input ports, and output ports”                                        | N/A                                                             | N/A                                                             | N/A                                | Included                              | N/A                              | N/A                     | N/A                                         | N/A                           |

| Check                                                                                        | Execution efficiency (all targets) | ROM efficiency (ERT-based targets) | RAM efficiency (ERT-based targets) | Safety precaution (ERT-based targets) | Traceability (ERT-based targets) | Debugging (all targets) | MISRA C:2012 guidelines (ERT-based targets) | Polyspace (ERT-based targets) |
|----------------------------------------------------------------------------------------------|------------------------------------|------------------------------------|------------------------------------|---------------------------------------|----------------------------------|-------------------------|---------------------------------------------|-------------------------------|
| “Check Data Store Memory blocks for multitasking, strong typing, and shadowing issues”       | N/A                                | N/A                                | N/A                                | Included                              | N/A                              | N/A                     | N/A                                         | N/A                           |
| “Identify block output signals with continuous sample time and non-floating point data type” | N/A                                | N/A                                | N/A                                | Included                              | N/A                              | N/A                     | N/A                                         | N/A                           |
| “Check for blocks that have constraints on tunable parameters” on page 16-9                  | N/A                                | N/A                                | N/A                                | Included                              | N/A                              | N/A                     | N/A                                         | N/A                           |
| “Check if read/write diagnostics are enabled for data store blocks”                          | N/A                                | N/A                                | N/A                                | Included                              | N/A                              | N/A                     | N/A                                         | N/A                           |
| “Check structure parameter usage with bus signals”                                           | N/A                                | N/A                                | N/A                                | Included                              | N/A                              | N/A                     | N/A                                         | N/A                           |

| Check                                                                                    | Execution efficiency (all targets) | ROM efficiency (ERT-based targets) | RAM efficiency (ERT-based targets) | Safety precaution (ERT-based targets) | Traceability (ERT-based targets) | Debugging (all targets) | MISRA C:2012 guidelines (ERT-based targets) | Polyspace (ERT-based targets) |
|------------------------------------------------------------------------------------------|------------------------------------|------------------------------------|------------------------------------|---------------------------------------|----------------------------------|-------------------------|---------------------------------------------|-------------------------------|
| “Check data store block sample times for modeling errors”                                | N/A                                | N/A                                | N/A                                | Included                              | N/A                              | N/A                     | N/A                                         | N/A                           |
| “Check for potential ordering issues involving data store access”                        | N/A                                | N/A                                | N/A                                | Included                              | N/A                              | N/A                     | N/A                                         | N/A                           |
| “Check for blocks not recommended for C/C++ production code deployment” (Embedded Coder) | N/A                                | N/A                                | N/A                                | N/A                                   | N/A                              | N/A                     | Included if Embedded Coder is available     | N/A                           |
| “Check for blocks not recommended for MISRA C:2012” (Embedded Coder)                     | N/A                                | N/A                                | N/A                                | N/A                                   | N/A                              | N/A                     | Included if Embedded Coder is available     | N/A                           |
| “Check for unsupported block names” (Embedded Coder)                                     | N/A                                | N/A                                | N/A                                | N/A                                   | N/A                              | N/A                     | Included if Embedded Coder is available     | N/A                           |

| Check                                                                                    | Execution efficiency (all targets) | ROM efficiency (ERT-based targets) | RAM efficiency (ERT-based targets) | Safety precaution (ERT-based targets) | Traceability (ERT-based targets) | Debugging (all targets) | MISRA C:2012 guidelines (ERT-based targets) | Polyspace (ERT-based targets) |
|------------------------------------------------------------------------------------------|------------------------------------|------------------------------------|------------------------------------|---------------------------------------|----------------------------------|-------------------------|---------------------------------------------|-------------------------------|
| “Check usage of Assignment blocks” (Embedded Coder)                                      | N/A                                | N/A                                | N/A                                | N/A                                   | N/A                              | N/A                     | Included if Embedded Coder is available     | N/A                           |
| “Check for bitwise operations on signed integers” (Embedded Coder)                       | N/A                                | N/A                                | N/A                                | N/A                                   | N/A                              | N/A                     | Included if Embedded Coder is available     | N/A                           |
| “Check for recursive function calls” (Embedded Coder)                                    | N/A                                | N/A                                | N/A                                | N/A                                   | N/A                              | N/A                     | Included if Embedded Coder is available     | N/A                           |
| “Check for equality and inequality operations on floating-point values” (Embedded Coder) | N/A                                | N/A                                | N/A                                | N/A                                   | N/A                              | N/A                     | Included if Embedded Coder is available     | N/A                           |
| “Check for switch case expressions without a default case” (Embedded Coder)              | N/A                                | N/A                                | N/A                                | N/A                                   | N/A                              | N/A                     | Included if Embedded Coder is available     | N/A                           |

| Check                                                                                           | Execution efficiency (all targets)      | ROM efficiency (ERT-based targets)      | RAM efficiency (ERT-based targets) | Safety precaution (ERT-based targets)   | Traceability (ERT-based targets) | Debugging (all targets) | MISRA C:2012 guidelines (ERT-based targets) | Polyspace (ERT-based targets) |
|-------------------------------------------------------------------------------------------------|-----------------------------------------|-----------------------------------------|------------------------------------|-----------------------------------------|----------------------------------|-------------------------|---------------------------------------------|-------------------------------|
| “Check configuration parameters for generation of inefficient saturation code” (Embedded Coder) | Included if Embedded Coder is available | Included if Embedded Coder is available | N/A                                | Included if Embedded Coder is available | N/A                              | N/A                     | N/A                                         | N/A                           |

**Note** When the Code Generation Advisor checks your model against the MISRA C:2012 guidelines objective, the tool does not consider all of the configuration parameter settings that are checked by the MISRA C:2012 guidelines checks in the Model Advisor. For a complete check of configuration parameter settings:

- 1 Open the Model Advisor.
- 2 Navigate to **By Task > Modeling Guidelines for MISRA C:2012**.
- 3 Run the checks in the folder.

For more information on using the Model Advisor, see “Check Your Model Using the Model Advisor”.

### See Also

- “Application Objectives Using Code Generation Advisor”
- “Configure Model for Code Generation Objectives by Using Code Generation Advisor” (Embedded Coder)
- “Run Model Advisor Checks”
- “Simulink Checks”
- “Simulink Coder Checks” on page 16-2
- “Simulink Check Checks” (Simulink Check)

## Identify questionable blocks within the specified system

Identify blocks not supported by code generation or not recommended for deployment.

### Description

The code generator creates code only for the blocks that it supports. Some blocks are not recommended for production code deployment.

**Results and Recommended Actions**

| Condition                                                  | Recommended Action                                                                         |
|------------------------------------------------------------|--------------------------------------------------------------------------------------------|
| A block is not supported by the code generator.            | Remove the specified block from the model or replace the block with the recommended block. |
| A block is not recommended for production code deployment. | Remove the specified block from the model or replace the block with the recommended block. |
| Check for Gain blocks whose value equals 1.                | Replace Gain blocks with Signal Conversion blocks.                                         |

**Capabilities and Limitations**

You can:

- Run this check on your library models.
- Exclude blocks and charts from this check if you have a Simulink Check license.

**See Also**

“Use Blocks and Products Supported for Code Generation”

“Model Advisor Exclusion Overview” (Simulink Check)

**Check model configuration settings against code generation objectives**

Check the configuration parameter settings for the model against the code generation objectives.

**Description**

Each parameter in the Configuration Parameters dialog box might have different recommended settings for code generation based on your objectives. This check helps you identify the recommended setting for each parameter so that you can achieve optimized code based on your objective.

**Results and Recommended Actions**

| Condition                                                                                   | Recommended Action                                                                                                         |
|---------------------------------------------------------------------------------------------|----------------------------------------------------------------------------------------------------------------------------|
| Parameters are set to values other than the value recommended for the specified objectives. | Set the parameters to the recommended values.                                                                              |
|                                                                                             | <b>Note</b> A change to one parameter value can impact other parameters. Passing the check might take multiple iterations. |

**Action Results**

Clicking **Modify Parameters** under **Action** in the check window changes the parameter values to the recommended values.



**See Also**

- “Recommended Settings Summary for Model Configuration Parameters” (Embedded Coder)
- “Application Objectives Using Code Generation Advisor”
- “Configure Model for Code Generation Objectives by Using Code Generation Advisor” (Embedded Coder)

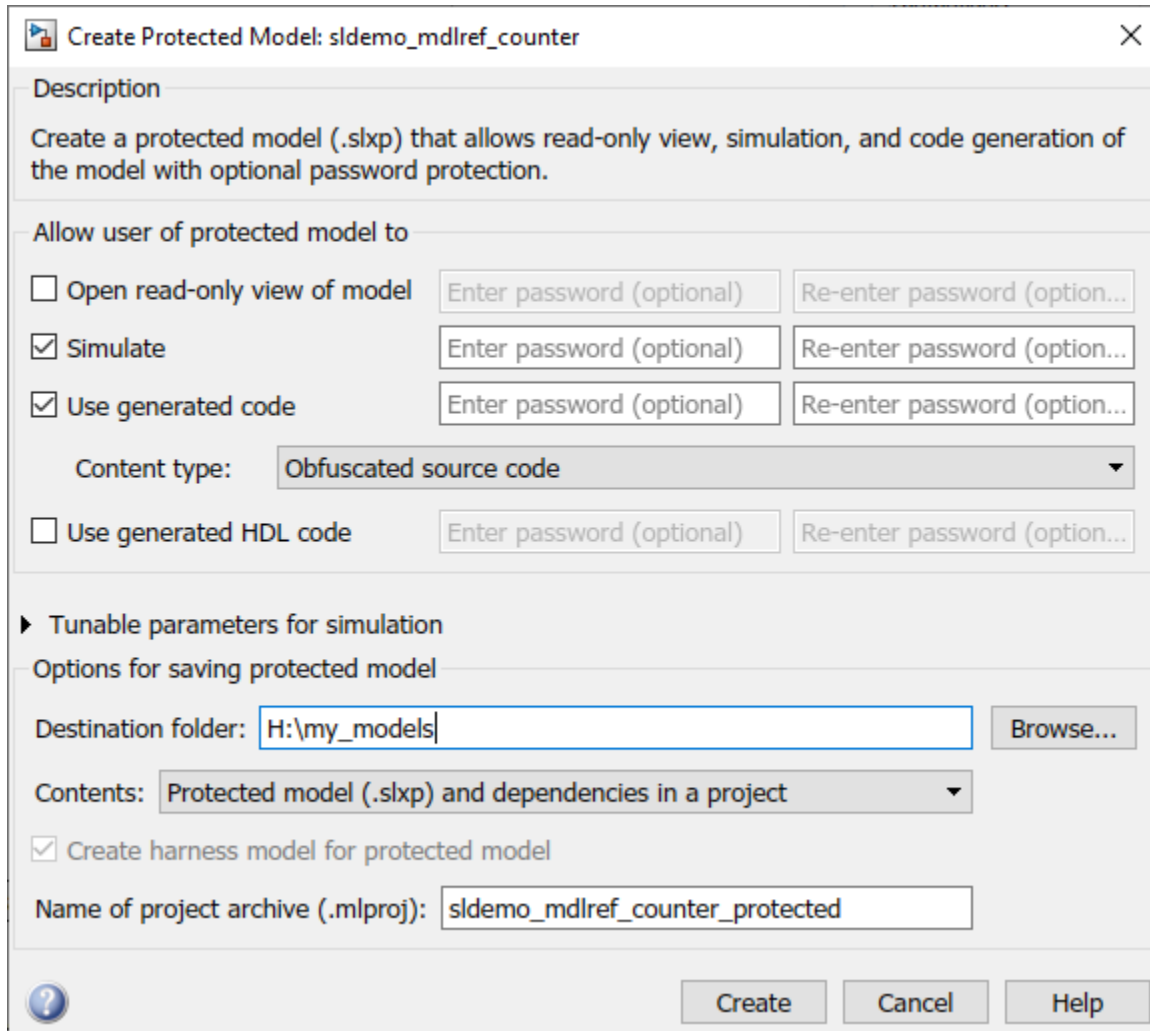


# Parameters for Creating Protected Models

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## Create Protected Model

This figure illustrates the various options in the Create Protected Model dialog box.



### Create Protected Model: Overview

Create a protected model (.slxp) that allows read-only view, simulation, and code generation of the model with optional password protection.

To open the Create Protected Model dialog box, right-click the model block that references the model for which you want to generate protected model code. From the context menu, select **Subsystem & Model Reference > Create Protected Model for Selected Model Block**.

#### See Also

- "Reference Protected Models from Third Parties"
- "Protect Models to Conceal Contents"

## Open read-only view of model

Share a view-only version of your protected model with optional password protection. View-only version includes the contents and block parameters of the model.

### Settings

**Default:** Off

On

Share a Web view of the protected model. For password protection, create and verify a password with a minimum of four characters.

Off

Do not share a Web view of the protected model.

### Alternatives

`Simulink.ModelReference.protect`

### See Also

- “Protect Models to Conceal Contents” (Embedded Coder)

## Simulate

Enable user to simulate a protected model with optional password-protection. Selecting **Simulate**:

- Enables protected model Simulation Report.
- Sets Mode to Accelerator. You can run normal, accelerator, and rapid accelerator mode simulations.
- Displays only binaries and headers.
- Enables code obfuscation.

### Settings

**Default:** On

On

User can simulate the protected model. For password protection, create and verify a password with a minimum of four characters.

Off

User cannot simulate the protected model.

### Alternatives

`Simulink.ModelReference.protect`

**See Also**

- “Protect Models to Conceal Contents” (Embedded Coder)

**Use generated code**

Allows user to generate code for the protected model with optional password protection. Selecting **Use generated code**:

- Enables Simulation Report and Code Generation Report for the protected model.
- Enables code generation.
- Enables support for simulation.

**Settings**

**Default:** Off

On

User can generate code for the protected model. For password protection, create and verify a password with a minimum of four characters.

Off

User cannot generate code for the protected model.

**Dependencies**

- To generate code, you must also select the **Simulate** check box.
- This parameter enables **Code interface** and **Content type**.

**Alternatives**

`Simulink.ModelReference.protect`

**See Also**

- “Code Generation Requirements and Limitations” (Embedded Coder)
- “Protect Models to Conceal Contents” (Embedded Coder)

**Code interface**

Specify the interface for the generated code.

**Settings**

**Default:** Model reference

Model reference

Specifies the model reference interface, which allows use of the protected model within a model reference hierarchy. Users of the protected model can generate code from a parent model that

contains the protected model. In addition, users can run Model block software-in-the-loop (SIL) or processor-in-the-loop (PIL) simulations to verify code.

#### Top model

Specifies the standalone interface. Users of the protected model can run Model block SIL or PIL simulations to verify the protected model code.

#### Dependencies

- Requires an Embedded Coder license
- This parameter is enabled if you:
  - Specify an ERT (`ert.tlc`) system target file.
  - Select the **Use generated code** check box.

#### Alternatives

`Simulink.ModelReference.protect`

#### See Also

- “Code Generation Requirements and Limitations” (Embedded Coder)
- “Protect Models to Conceal Contents” (Embedded Coder)

## Content type

Select the appearance of the generated code.

#### Settings

**Default:** Obfuscated source code

#### Binaries

Includes only compiled binaries for the generated code.

#### Obfuscated source code

Includes obfuscated source code.

#### Readable source code

Includes readable source code and readable code comments.

The options `Obfuscated source code` and `Readable source code` by default include only the minimal header files required to build the code with the chosen build settings. These options correspond to using the `Simulink.ModelReference.protect` with the `'OutputFormat'` option set to `'MinimalCode'`. To include header files found on the include path in the protected model, use the `Simulink.ModelReference.protect` function and set the `'OutputFormat'` option to `'AllReferencedHeaders'`.

The `Binaries` option corresponds to using the `Simulink.ModelReference.protect` function with the `'OutputFormat'` option set to `'CompiledBinaries'`.

#### Dependencies

This parameter is enabled by selecting the **Use generated code** check box.

**Alternatives**

Simulink.ModelReference.protect

**See Also**

- “Protect Models to Conceal Contents” (Embedded Coder)

**Use generated HDL code**

Allows user to generate HDL code for the protected model with optional password protection. Selecting **Use generated HDL code**:

- Enables Simulation Report and HDL Code Generation Report for the protected model.
- Enables support for HDL code generation.
- Enables support for simulation.

**Settings**

**Default:** Off

On

User can generate HDL code for the protected model. For password protection, create and verify a password with a minimum of eight characters.

Off

User can simulate but cannot generate HDL code for the protected model.

**Dependencies**

To generate HDL code, you must also select the **Simulate** check box.

**Alternatives**

Simulink.ModelReference.protect

**See Also**

- “Code Generation Requirements and Limitations” (Embedded Coder)
- “Protect Models to Conceal Contents” (Embedded Coder)

**Destination folder**

Specify the path of the folder to contain the protected model.

**Settings**

**Default:** Current working folder



## Dependencies

A model that you protect must be available on the MATLAB path.

## Alternatives

`Simulink.ModelReference.protect`

## See Also

- “Protect Models to Conceal Contents” (Embedded Coder)

## Contents

Option to package supporting files, including a harness model, with the protected model in a project archive. The type and number of supporting files depends on the model being protected. Examples of supporting files are a MAT-file with base workspace definitions and a data dictionary pruned to relevant definitions. The supporting files are not protected.

---

**Note** Before sharing the project, check whether the project contains the necessary supporting files. If supporting files are missing, simulating or generating code for the related harness model can help identify them. Add the missing dependencies to the project and update the harness model as needed.

---

## Settings

**Default:** Protected model (.slxp) and dependencies in a project

Protected model (.slxp) and dependencies in a project

Create a project archive that contains the protected model, its dependencies, and its harness model. The supporting files are not protected. The project archive is a single file that allows for easy sharing.

Protected model (.slxp) only

Create only the protected model. If the protected model has dependencies, you must share them separately. Similarly, if you create a harness model for the protected model, you must share the harness model separately.

## Alternatives

`Simulink.ModelReference.protect`

## See Also

- “Protect Models to Conceal Contents” (Embedded Coder)

## Create harness model for protected model

Create a harness model for the protected model. The harness model provides an isolated environment for the protected model, which is referenced by a Model block.

**Settings****Default:** Off

On

Create a harness model for the protected model.



Off

Do not create a harness model for the protected model.

**Dependencies**To clear the check box for this parameter, set **Contents** to Protected model (.slxp) only.**Alternatives**

Simulink.ModelReference.protect

**See Also**

- “Protect Models to Conceal Contents” (Embedded Coder)

**Name of project archive (.mlproj)**

Name of the project archive that contains the generated files. The project inside the archive uses the same name.

**Settings****Default:** *modelname\_protected***Dependencies**To enable this parameter, set **Contents** to Protected model (.slxp) and dependencies in a project.**Alternatives**

Simulink.ModelReference.protect

**See Also**

- “Protect Models to Conceal Contents” (Embedded Coder)

# Simulink Coder Tools

---

## Code Mappings Editor - C

Associate model elements with code interface definitions


### Description

The Code Mappings editor is a graphical interface where you can configure data elements in a model for code generation. Each model in a model reference hierarchy has its own code mappings. Associate each category of model data element with a specific storage class throughout a model. Then, override those settings, as needed, for specific data elements.

A storage class defines properties such as appearance and location, which the code generator uses when producing code for associated data.

To configure data elements and functions for code generation, use the tables in the Code Mappings editor display:

- **Data Defaults**
- **Inports**
- **Outports**
- **Parameters**
- **Data Stores**
- **Signals/States**

When there are additional code mapping properties that can be configured for a model element, you can configure these properties by selecting a row in the active table and clicking the  icon.

Before you can configure a signal for code generation, add the signal to the model code mappings. Add and remove signals from the code mappings by pausing on the ellipsis that appears above or below a signal line to open the action bar. Click the **Add Signal** or **Remove Signal** button. These buttons are also available in the Code Mappings editor on the **Signals/States** tab.

The screenshot displays the Simulink Code Mappings Editor - C interface. The top section shows a Simulink block diagram with inputs In1, In2, In3, In4 and output Out1. The diagram includes blocks like RelOp1, RelOp2, OR, LogOp, Gain, Delay, Table1, Table2, and Switch. The bottom section shows the 'Code Mappings - C' window with tabs for Data Defaults, Imports, Outputs, Parameters, Data Stores, and Signals/States. The 'Signals' tab is active, showing a list of signal categories and their storage classes.

| Model Element Category             | Storage Class         |
|------------------------------------|-----------------------|
| Inports and Outputs                |                       |
| Inports                            | ImportedExternPointer |
| Outputs                            | ExportedGlobal        |
| Signals                            |                       |
| Signals, states, and internal data | Default               |
|                                    | ExportedGlobal        |
|                                    | ImportedExtern        |
|                                    | ImportedExternPointer |
|                                    | ExportedGlobal        |
|                                    | FixedStepDiscrete     |

## Open the Code Mappings Editor - C

Do one of the following:

- Open the Simulink Coder app. On the **C Code** tab, select **Code Interface** > **Default Code Mappings** or **Code Interface** > **Individual Element Code Mappings**.
- Open the Simulink Coder app. On the **C Code** tab, in the bottom left corner of the Simulink Editor window, click the **Code Mappings** tab.
- In the model canvas of the Simulink Editor window, click the perspective control in the lower-right corner and select **Code**. Then, click the **Code Mappings** tab.

## Examples

### Configure Code Generation for Root-Level Inport and Output Blocks

Configure code generation for the root-level Inport and Output blocks throughout a model. Applying default configurations can save time, especially for large-scale models that use a significant amount of data. After applying default mappings, you can adjust mappings for individual data elements.

#### Set Up Example Environment

- 1 Copy external code file `exDblFloat.h` into a writable folder.  

```
copyfile(fullfile(matlabroot, 'toolbox', 'rtw', 'rtwdemos', 'exDblFloat.h'));
```
- 2 Open model `rtwdemo_configrpinterface`. Save a copy of the model into the same location as file `exDblFloat.h`.
- 3 Open the Simulink Coder app. The **C Code** tab includes the Code Mappings editor.

#### Configure Default Mappings

Configure the code generator to declare and define global variables for inports and outputs in generated files `rtwdemo_configrpinterface.h` and `rtwdemo_configrpinterface.c`.

- 1 In the **C Code** tab, select **Code Interface > Default Code Mappings**.
- 2 In the **Data Defaults** tab, under **Inports and Outputs**, select the row for **Inports**. Then, set the storage class to `ImportedExternPointer`. Set the storage class for **Outputs** to `ExportedGlobal`. The editor updates the default storage class setting for the two selected data element categories.

The screenshot displays the Code Mappings Editor interface. The top part shows a Simulink model for 'rtwdemo\_configpinterface'. The model has three input ports: In1 (1), In2 (2), and In3 (3). In1 is connected to 'UPPER Constant1' and 'LOWER Constant2', which feed into 'RelOp1' and 'RelOp2' respectively. These outputs go to an 'OR' block, which then feeds into 'LogOp'. In2 is connected to 'Table1' (1-D T(u)), which feeds into a 'Gain' block (K1). In3 and In4 are connected to 'Table2' (2-D T(u)), which feeds into a 'Delay' block (1/z). The outputs of 'LogOp', 'Gain', and 'Delay' feed into a 'Switch' block. The 'Switch' block has a 'Data Store Read' block and a 'Data Store Write' block. The 'Switch' block outputs to 'Out1' (1). The 'Code Mappings - C' window is open, showing the 'Inports' and 'Outports' tabs. The 'Inports' tab is selected, and the storage class for 'In1' is set to 'ImportedExternPointer'. The 'Outports' tab is also visible, and the storage class for 'Out1' is set to 'ExportedGlobal'.

| Model Element Category             | Storage Class         |
|------------------------------------|-----------------------|
| Inports                            | ImportedExternPointer |
| Outports                           | ExportedGlobal        |
| Signals                            | Default               |
| Signals, states, and internal data | ExportedGlobal        |
|                                    | ImportedExternPointer |



### Configure Individual Inports and Outports for Default Configuration

- 1 In the Code Mappings editor, click the **Inports** tab. The storage class for each inport is set to Auto, which means that the code generator might eliminate or change the representation of relevant code for optimization purposes. If optimizations are not possible, the code generator applies the model default configuration.
- 2 Force the code generator to use the default configuration for inports, which is storage class `ImportedExternPointer`. Press the **Ctrl** key and select the inports. For one of the selected inports, set the storage class to Model default: `ImportedExternPointer`. The editor updates the storage class setting for the selected inports.
- 3 Force the code generator to use storage class `ExportedGlobal` for the model root output. Click the **Outports** tab. Select the row for Out2. Then, set the storage class to Model default: `ExportedGlobal`.

### Configure Individual Data Elements

To configure properties for individual data elements, for example, if you need to override default configuration settings, use the tabs for the different data element types. For this example, override the default storage class setting for Inport block In1.

By default, the code generator names inport and output variables based on the Inport or Output block name in the model. When you configure data elements with a storage class setting other than **Auto**, you can override that default setting for individual elements by setting storage class property **Identifier**. This property enables you to specify an identifier for the code without modifying the model design. For this example, set **Identifier** for the Inport and Output blocks.

- 1 In the Code Mappings editor, click the **Inports** tab.
- 2 For In1, set the storage class to ImportedExtern.
- 3 For each inport, select the row. Then, click the  icon. Set the **Identifier** property as follows:
  - Set In1 to input1.
  - Set In2 to input2.
  - Set In3 to input3.
  - Set In4 to input4.
- 4 Click **Outputs**.
- 5 Select output Out1. Click the  icon and set the **Identifier** property to output.

### Generate and Verify Code

Generate code and verify that the code generated for the Inport and Output blocks appears as you expect. For example:

- `rtwdemo_configrpinterface_private.h` includes these declarations:

```
/* Exported data declaration */

/* Data with Imported storage */
extern real_T input1; /* '<Root>/In1' */
extern real_T input2; /* '<Root>/In2' */
extern real_T input3; /* '<Root>/In3' */
extern real_T input4; /* '<Root>/In4' */
```

- `rtwdemo_configrpinterface.h` lists output as field in output structure `ExtY_rtwdemo_configrpinterfac_T`.

```
/* External outputs (root outputs fed by signals with default storage) */
typedef struct {
 real_T output; /* '<Root>/Out1' */
} ExtY_rtwdemo_configrpinterfac_T;
```

- This code fragment shows the variable that represents In2, `input2`, being used in the generated entry-point step function for sample rate of 1 second.

```
/* Model step function for TID1 */
void rtwdemo_configrpinterface_step1(void) /* Sample time: [1.0s, 0.0s] */
{
 /* Lookup_n-D: '<Root>/Table1D' incorporates:
 * Inport: '<Root>/In2'
 */
 rtwdemo_configrpinterface_B.Table1D = look1_binlcpw(input2,
rtwdemo_configrpinterfac_ConstP.Table1D_bp0IData,
rtwdemo_configrpinterfac_ConstP.Table1D_tableData, 10U);
 .
 .
 .
}
```



## Parameters

### Data Defaults

#### Model Element Category — Category of model data elements

character vector

Names a category of Simulink model data elements. The storage class that you set for a category applies to elements in that category throughout the model.

| Model Element Category             | Description                                                                                                                                                                                                                                                                                                                                     |
|------------------------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Inports                            | Root-level input ports of a model, such as Inport and In Bus Element blocks.                                                                                                                                                                                                                                                                    |
| Outports                           | Root-level output ports of a model, such as Outport and Out Bus Element blocks.                                                                                                                                                                                                                                                                 |
| Signals, states, and internal data | Data elements that are internal to the model, such as block output signals, discrete block states, data stores, and zero-crossing signals.                                                                                                                                                                                                      |
| Shared local data stores           | Data Store Memory blocks that have the block parameter <b>Share across model instances</b> set. These data stores are accessible only in the model where they are defined. The data store value is shared across instances of the model.                                                                                                        |
| Global data stores                 | Data stores that are defined by a signal object in the base workspace or in a data dictionary. Multiple models in an application can use these data stores. To view and configure these data stores in the Code Mappings editor, click the <b>Refresh</b> link to the right of the category name. Clicking this link updates the model diagram. |
| Model parameters                   | Parameters that are defined within a model, such as parameters in the model workspace. Excludes model arguments.                                                                                                                                                                                                                                |
| External parameters                | Parameters that you define as objects in the base workspace or in a data dictionary. Multiple models in an application can use these parameters. To view and configure these parameters in the Code Mappings editor, click the <b>Refresh</b> link to the right of the category name. Clicking this link updates the model diagram.             |

The Code Mappings editor presents valid storage class options for a given category. The options can include:

- Unspecified storage class (**Default**). The code generator places the code for the category of data elements in standard structures, such as `B_`, `ExtY_`, `ExtU_`, `DW_`, and `P_`. See “Data Structures in the Generated Code”.
- Relevant predefined storage classes, such as `ExportedGlobal`.
- Relevant storage classes in an available package, such as `ImportFromFile` (requires Embedded Coder) .
- Storage class defined in an Embedded Coder Dictionary (requires Embedded Coder) .

#### Storage Class — Code definition for model data elements

character vector

Definition (specification) that the code generator uses to determine properties, such as appearance and location, for code that it produces for model data elements. Valid settings are `Default`, `ExportedGlobal`, `ImportedExtern`, and `ImportedExternPointer`. See “Choose Storage Class for Controlling Data Representation in Generated Code”.

### Inports

#### **Source — Name of root-level Inport block or bus element**

character vector

Identifies a root Inport block or an element of an In Bus Element block (for example, `InBus1.signal1`) in the model. If the element resolves to a data object, the Code Mappings editor displays a resolve-to-signal-object icon to the right of the source name and resolves the configuration based on whether the storage class setting for the element is `Auto`. If the storage class is `Auto`, the data element assumes the code configuration that the data object specifies. The editor changes the display text in the **Storage Class** column to `From signal object`: followed by the name of the storage class of the data object. If the storage class is not `Auto`, the data element assumes the configuration that you specify in the Code Mappings editor.

#### **Storage Class — Code definition for root inport**

character vector

Definition that the code generator uses to determine properties, such as appearance and location, for code that it produces for the root inport. Valid settings are `Auto`, `Model default`, `ExportedGlobal`, `ImportedExtern`, and `ImportedExternPointer`. See “Choose Storage Class for Controlling Data Representation in Generated Code”.

#### **Identifier — Name of variable**

character vector

Name for the variable that represents the inport in the generated code.

#### **CalibrationAccess — Enable or disable calibration of the inport**

`NoCalibration` (default) | `Calibration`

Select `Calibration` for the inport to enable the calibration. Select `NoCalibration` to view the value of the inport and disable the calibration.

#### **CompuMethod — Name of conversion method**

character vector

Name of the method for converting the ECU-internal value to a physical value for easy readability.

#### **DisplayIdentifier — Display name of the inport**

character vector

Optional display name of the inport for the measurement purpose in the calibration tool, which is different than the inport name in the Simulink model.

#### **Format — Display format of the inport value**

`%[length].[layout]`

Special display format to be specified for measurement in the calibration tool. This format specification overrules the display format specified in `CompuMethod` of the inport.

**Outputs****Source — Name of root Output block or bus element**

character vector

Identifies a root-level Output block or an element of an Out Bus Element block (for example, `OutBus1.signal1`) in the model. If the element resolves to a data object, the Code Mappings editor displays a resolve-to-signal-object icon to the right of the source name and resolves the configuration based on whether the storage class setting for the element is `Auto`. If the storage class is `Auto`, the data element assumes the code configuration that the data object specifies. The editor changes the display text in the **Storage Class** column to `From signal object:` followed by the name of the storage class of the data object. If the storage class is not `Auto`, the data element assumes the configuration that you specify in the Code Mappings editor.

**Storage Class — Code definition for root output**

character vector

Definition that the code generator uses to determine properties, such as appearance and location, for code that it produces for the root output. Valid settings are `Auto`, `Model default`, `ExportedGlobal`, `ImportedExtern`, and `ImportedExternPointer`. See “Choose Storage Class for Controlling Data Representation in Generated Code”.

**Identifier — Name of variable**

character vector

Name for the variable that represents the output in the generated code.

**CalibrationAccess — Enable or disable calibration of the output**`NoCalibration` (default) | `Calibration`

Select `Calibration` for the output to enable the calibration. Select `NoCalibration` to view the value of the output and disable the calibration.

**CompuMethod — Name of conversion method**

character vector

Name of the method for converting the ECU-internal value to a physical value for easy readability.

**DisplayIdentifier — Display name of the output**

character vector

Optional display name of the output for the measurement purpose in the calibration tool, which is different than the output name in the Simulink model.

**Format — Display format of the output value**`%[length].[layout]`

Special display format to be specified for measurement in the calibration tool. This format specification overrides the display format specified in `CompuMethod` of the output.

**Parameters****Source — Name of model parameter argument, model parameter, or external parameter**

character vector

Identifies a parameter in the model. If the element resolves to a data object, the Code Mappings editor displays a resolve-to-parameter-object icon to the right of the source name and resolves the configuration based on whether the storage class setting for the element is **Auto**. If the storage class is **Auto**, the data element assumes the code configuration that the data object specifies. The editor changes the display text in the **Storage Class** column to **From parameter object:** followed by the name of the storage class of the data object. If the storage class is not **Auto**, the data element assumes the configuration that you specify in the code mappings.

Types of parameter elements are listed in this table.

| Type of Parameter Element | Description                                                                                                                                                                                                                                                                                                                                                                                                                    |
|---------------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Model parameter           | Parameter that is defined within a model, such as a parameter in the model workspace. Excludes model arguments.                                                                                                                                                                                                                                                                                                                |
| External parameter        | Parameter that you define as an object in the base workspace or in a data dictionary. Multiple models in an application can use these parameters. This grouping of parameters appears in the editor only if the model uses such an element. To view and configure these parameters in the Code Mappings editor, click the <b>Refresh</b> link to the right of the category name. Clicking this link updates the model diagram. |

#### **Storage Class — Code definition for parameter**

character vector

Definition that the code generator uses to determine properties, such as appearance and location, for code that it produces for the parameter. For external parameters, after you click the **Refresh** link to the right of the category name, the compiled storage class (for example, the storage class configured for an external parameter) appears on the right side of the **Storage Class** column. Valid settings are **Auto**, **Model default**, **ExportedGlobal**, **ImportedExtern**, and **ImportedExternPointer**. See “Choose Storage Class for Controlling Data Representation in Generated Code”.

#### **Identifier — Name of variable**

character vector

Name for the variable that represents the model parameter or model parameter argument in the generated code.

#### **CalibrationAccess — Enable or disable calibration of the model parameter**

NoCalibration (default) | Calibration

Select **Calibration** for the model parameter to enable the calibration. Select **NoCalibration** to view the value of the model parameter and disable the calibration.

#### **CompuMethod — Name of conversion method**

character vector

Name of the method for converting the ECU-internal value to a physical value for easy readability.

#### **DisplayIdentifier — Display name of the model parameter**

character vector

Optional display name of the model parameter for the measurement purpose in the calibration tool, which is different than the output name in the Simulink model.

**Format — Display format of the model parameter value**

`%[length].[layout]`

Special display format to be specified for measurement in the calibration tool. This format specification overrules the display format specified in `CompuMethod` of the model parameter.

**Data Stores****Source — Name of local data store, shared local data store, or global data store**

character vector

Identifies a data store in the model. If the element resolves to a data object, the Code Mappings editor displays a resolve-to-signal-object icon to the right of the source name and resolves the configuration based on whether the storage class setting for the element is `Auto`. If the storage class is `Auto`, the data element assumes the code configuration that the data object specifies. The editor changes the display text in the **Storage Class** column to `From signal object:` followed by the name of the storage class of the data object. If the storage class is not `Auto`, the data element assumes the configuration that you specify in the code mappings.

Types of data store elements are listed in this table.

| Type of Data Store Element | Description                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      |
|----------------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Local data store           | Data store that is accessible from anywhere in the model hierarchy that is at or below the level at which you define the data store. You can define a local data store graphically in a model by including a Data Store Memory block or by creating a signal object (synthesized data store) in the model workspace.                                                                                                                                                                                                                                                                                                                             |
| Shared local data store    | Data Store Memory block that has the block parameter <b>Share across model instances</b> set. These data stores are accessible only in the model where they are defined. The data store value is shared across instances of the model. This grouping of data stores appears in the editor only if such an element exists in the model.                                                                                                                                                                                                                                                                                                           |
| Global data store          | Data store that is defined by a signal object in the base workspace or in a data dictionary. Multiple models in an application can use these data stores. These data stores are not configurable in the code mappings. After you click the refresh button, they appear in the Code Mappings editor in a read-only state for viewing or accounting purposes. This grouping of data stores appears in the editor only if the model uses such an element. To view and configure these data stores in the Code Mappings editor, click the <code>Refresh</code> link to the right of the category name. Clicking this link updates the model diagram. |

Names of local and shared local data stores appear in the format *block-name: data-store-name*.

Depending on how the data store element is represented and configured in the model, local and shared local data stores can resolve to a signal object in the model workspace, based workspace, or a data dictionary. Global data stores resolve to a signal object in the base workspace or a data dictionary.

**Storage Class — Code definition for data store**

character vector

Definition that the code generator uses to determine properties, such as appearance and location, for code that it produces for the data store. For global data stores, after you click the Refresh link to the right of the category name, the compiled storage class (for example, the storage class configured for a global data store) appears on the right side of the **Storage Class** column. Valid settings are `Auto`, `Model default`, `ExportedGlobal`, `ImportedExtern`, and `ImportedExternPointer`. See “Choose Storage Class for Controlling Data Representation in Generated Code”.

**Path — Path to data store in model**

character vector

Link that you can click to highlight the data store in the model diagram.

**Identifier — Name of variable**

character vector

Name for the variable that represents the data store in the generated code.

**CalibrationAccess — Enable or disable calibration of the data store**

`NoCalibration` (default) | `Calibration`

Select `Calibration` for the data store to enable the calibration. Select `NoCalibration` to view the value of the data store and disable the calibration.

**CompuMethod — Name of conversion method**

character vector

Name of the method for converting the ECU-internal value to a physical value for easy readability.

**DisplayIdentifier — Display name of the data store**

character vector

Optional display name of the data store for the measurement purpose in the calibration tool, which is different than the output name in the Simulink model.

**Format — Display format of the data store value**

`%[length].[layout]`

Special display format to be specified for measurement in the calibration tool. This format specification overrides the display format specified in `CompuMethod` of the data store.

**Signals/States****Source — Name of signal or state**

character vector

Identifies a signal line or state in the model. If the element resolves to a data object, the Code Mappings editor displays a resolve-to-signal-object icon to the right of the source name and resolves the configuration based on whether the storage class setting for the element is `Auto`. If the storage class is `Auto`, the data element assumes the code configuration that the data object specifies. The editor changes the display text in the **Storage Class** column to `From signal object:` followed by the name of the storage class of the data object. If the storage class is not `Auto`, the data element assumes the configuration that you specify in the Code Mappings editor.

The Code Mappings editor lists:

- Named signals and states by using the data element name
- Unnamed signals by using the format *source-block: port-number*
- States used in multiple blocks by using the format *block-name: state-name*

To configure an individual signal line in the Code Mappings editor for a model, first you must add the signal to the mappings. See “Configure Signal Data for C Code Generation”.

### **Storage Class – Code definition for signal**

character vector

Definition that the code generator uses to determine properties, such as appearance and location, for code that it produces for the signal line or state. Valid settings are `Auto`, `Model default`, `ExportedGlobal`, `ImportedExtern`, and `ImportedExternPointer`. See “Choose Storage Class for Controlling Data Representation in Generated Code”.

### **Path – Path to signal line or state in model**

character vector

Link that you can click to highlight the signal line or block that uses the state in the model diagram.

### **Identifier – Name of variable**

character vector

Name for the variable that represents the signal or state in the generated code.

### **CalibrationAccess – Enable or disable calibration of the signal or state**

`NoCalibration` (default) | `Calibration`

Select `Calibration` for the signal or state to enable the calibration. Select `NoCalibration` to view the value of the signal or state and disable the calibration.

### **CompuMethod – Name of conversion method**

character vector

Name of the method for converting the ECU-internal value to a physical value for easy readability.

### **DisplayIdentifier – Display name of the signal or state**

character vector

Optional display name of the signal or state for the measurement purpose in the calibration tool, which is different than the output name in the Simulink model.

### **Format – Display format of the signal or state value**

`%[length].[layout]`

Special display format to be specified for measurement in the calibration tool. This format specification overrules the display format specified in `CompuMethod` of the signal or state.

## **Version History**

**Introduced in R2020b**

## **See Also**

### **Topics**

“C Code Generation Configuration for Model Interface Elements”

“Choose Data Configuration Approach”

“Choose Storage Class for Controlling Data Representation in Generated Code”

“Configure Generated C Function Interface for Model Entry-Point Functions”



# Code Replacement Viewer

Explore content of code replacement libraries

## Description

The Code Replacement Viewer displays the content of code replacement libraries and tables. You can use this tool to explore and choose a code replacement library or to view a predefined code replacement table. If you develop a custom code replacement library, you can use this viewer to verify table entries for the following properties:

- Argument order is correct.
- Conceptual argument names match code generator naming conventions.
- Implementation argument names are correct.
- Header or source file specification is not missing.
- I/O types are correct.
- Relative priority of entries is correct (highest priority is 0, and lowest priority is 100).
- Saturation or rounding mode specifications are not missing.

If you specify a library name when you open the viewer, the viewer displays the code replacement tables for that library. If you specify a table name when you open the viewer, the viewer displays the function and operator code replacement entries for that table. The viewer can only display code replacement tables that are defined. For more information on creating code replacement tables, see “Define Code Replacement Library Optimizations” (Embedded Coder).

## Abbreviated Entry Information

In the middle pane, the viewer displays entries that are in the selected code replacement table, along with abbreviated information for each entry.

| Field                 | Description                                                                                                                                                                                                                                                                                                                                                                                                        |
|-----------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| <b>Name</b>           | Name or identifier of the function or operator being replaced (for example, <code>cos</code> or <code>RTW_OP_ADD</code> ).                                                                                                                                                                                                                                                                                         |
| <b>Implementation</b> | Name of the implementation function, which can match or differ from <b>Name</b> .                                                                                                                                                                                                                                                                                                                                  |
| <b>NumIn</b>          | Number of input arguments.                                                                                                                                                                                                                                                                                                                                                                                         |
| <b>In1Type</b>        | Data type of the first conceptual input argument.                                                                                                                                                                                                                                                                                                                                                                  |
| <b>In2Type</b>        | Data type of the second conceptual input argument.                                                                                                                                                                                                                                                                                                                                                                 |
| <b>OutType</b>        | Data type of the conceptual output argument.                                                                                                                                                                                                                                                                                                                                                                       |
| <b>Priority</b>       | The entry's match priority, relative to other entries of the same name and to the conceptual argument list within the selected code replacement library. The priority can range from 0 to 100, with 0 being the highest priority. The default is 100. If the library provides two implementations for a function or operator, the implementation with the higher priority shadows the one with the lower priority. |

| Field      | Description |
|------------|-------------|
| UsageCount | Not used.   |

### Detailed Entry Information

In the middle pane, when you select an entry, the viewer displays entry details.

| Field                        | Description                                                                                                                                                                                                                                                                                                                                                                                                        |
|------------------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| <b>Description</b>           | Text description of the table entry (can be empty).                                                                                                                                                                                                                                                                                                                                                                |
| <b>Key</b>                   | Name or identifier of the function or operator being replaced (for example, <code>cos</code> or <code>RTW_OP_ADD</code> ), and the number of conceptual input arguments.                                                                                                                                                                                                                                           |
| <b>Implementation</b>        | Name of the implementation function, and the number of implementation input arguments.                                                                                                                                                                                                                                                                                                                             |
| <b>Implementation type</b>   | Type of implementation: <code>FCN_IMPL_FUNCT</code> for function or <code>FCN_IMPL_MACRO</code> for macro.                                                                                                                                                                                                                                                                                                         |
| <b>Saturation mode</b>       | Saturation mode that the implementation function supports. One of:<br><code>RTW_SATURATE_ON_OVERFLOW</code><br><code>RTW_WRAP_ON_OVERFLOW</code><br><code>RTW_SATURATE_UNSPECIFIED</code>                                                                                                                                                                                                                          |
| <b>Rounding modes</b>        | Rounding modes that the implementation function supports. One or more of:<br><code>RTW_ROUND_FLOOR</code><br><code>RTW_ROUND_CEILING</code><br><code>RTW_ROUND_ZERO</code><br><code>RTW_ROUND_NEAREST</code><br><code>RTW_ROUND_NEAREST_ML</code><br><code>RTW_ROUND_SIMPLEST</code><br><code>RTW_ROUND_CONV</code><br><code>RTW_ROUND_UNSPECIFIED</code>                                                          |
| <b>GenCallback file</b>      | Not used.                                                                                                                                                                                                                                                                                                                                                                                                          |
| <b>Implementation header</b> | Name of the header file that declares the implementation function.                                                                                                                                                                                                                                                                                                                                                 |
| <b>Implementation source</b> | Name of the implementation source file.                                                                                                                                                                                                                                                                                                                                                                            |
| <b>Priority</b>              | The entry's match priority, relative to other entries of the same name and to the conceptual argument list within the selected code replacement library. The priority can range from 0 to 100, with 0 being the highest priority. The default is 100. If the library provides two implementations for a function or operator, the implementation with the higher priority shadows the one with the lower priority. |
| <b>Total Usage Count</b>     | Not used.                                                                                                                                                                                                                                                                                                                                                                                                          |
| <b>Entry class</b>           | Class from which the current table entry is instantiated.                                                                                                                                                                                                                                                                                                                                                          |
| <b>Conceptual arguments</b>  | Name, I/O type ( <code>RTW_IO_OUTPUT</code> or <code>RTW_IO_INPUT</code> ), and data type for each conceptual argument.                                                                                                                                                                                                                                                                                            |
| <b>Implementation</b>        | Name, I/O type ( <code>RTW_IO_OUTPUT</code> or <code>RTW_IO_INPUT</code> ), data type, and alignment requirement for each implementation argument.                                                                                                                                                                                                                                                                 |

## Fixed-Point Entry Information

When you select an operator entry that specifies net slope fixed-point parameters, the viewer displays fixed-point information.

| Field                                | Description                                                                                                                                                                                                                                                                                                               |
|--------------------------------------|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| <b>Net slope adjustment factor F</b> | Slope adjustment factor (F) part of the net slope factor, $F2^E$ , for net slope table entries. You use this factor with fixed-point multiplication and division replacement to map a range of slope and bias values to a replacement function.                                                                           |
| <b>Net fixed exponent E</b>          | Fixed exponent (E) part of the net slope factor, $F2^E$ , for net slope table entries. You use this fixed exponent with fixed-point multiplication and division replacement to map a range of slope and bias values to a replacement function.                                                                            |
| <b>Slopes must be the same</b>       | Indicates whether code replacement request processing must check that the slopes on arguments (input and output) are equal. You use this information with fixed-point addition and subtraction replacement to disregard specific slope and bias values, and map relative slope and bias values to a replacement function. |
| <b>Must have zero net bias</b>       | Indicates whether code replacement request processing must check that the net bias on arguments is zero. You use this information with fixed-point addition and subtraction replacement to disregard specific slope and bias values, and map relative slope and bias values to a replacement function.                    |

## Open the Code Replacement Viewer

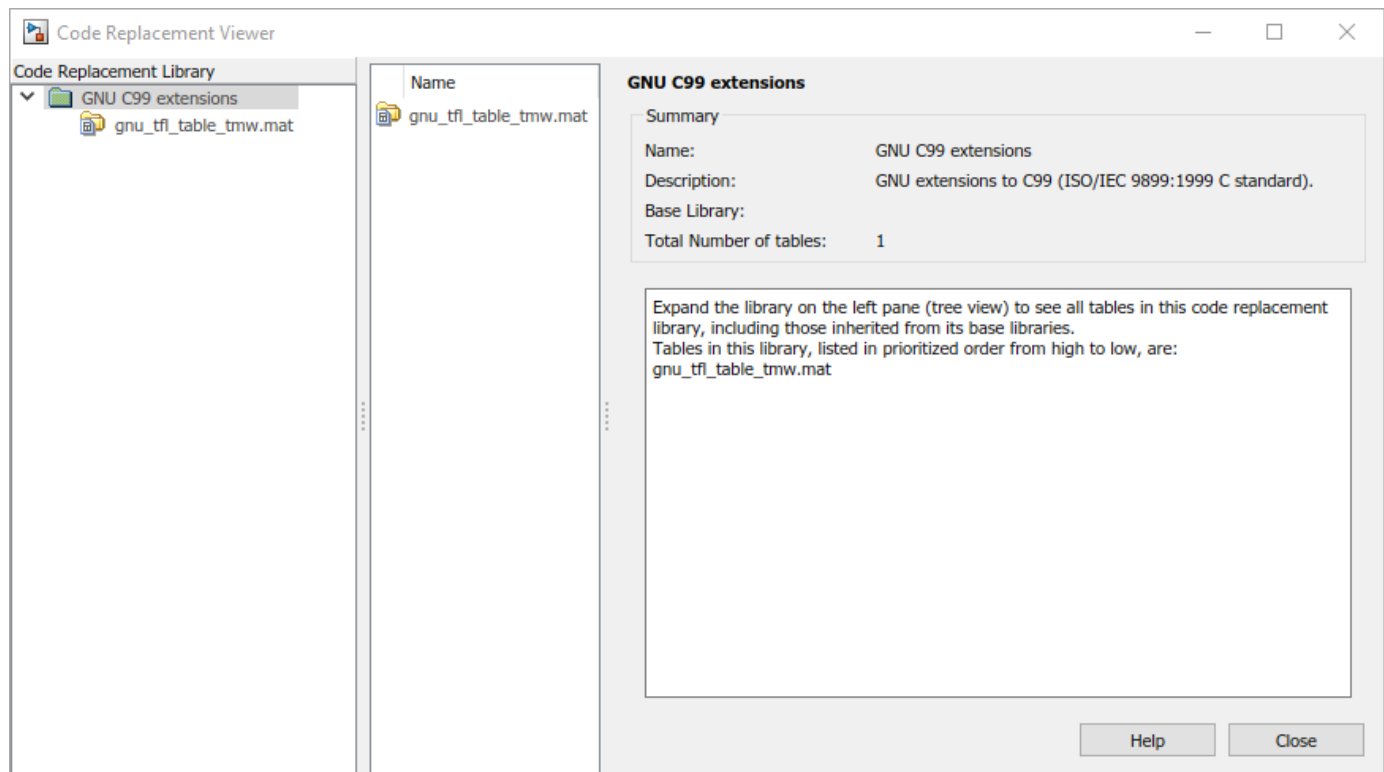
Open from the MATLAB command prompt using `crviewer`.

### Examples

#### Display Contents of Code Replacement Library

This example opens the registered code replacement library GNU C99 extensions.

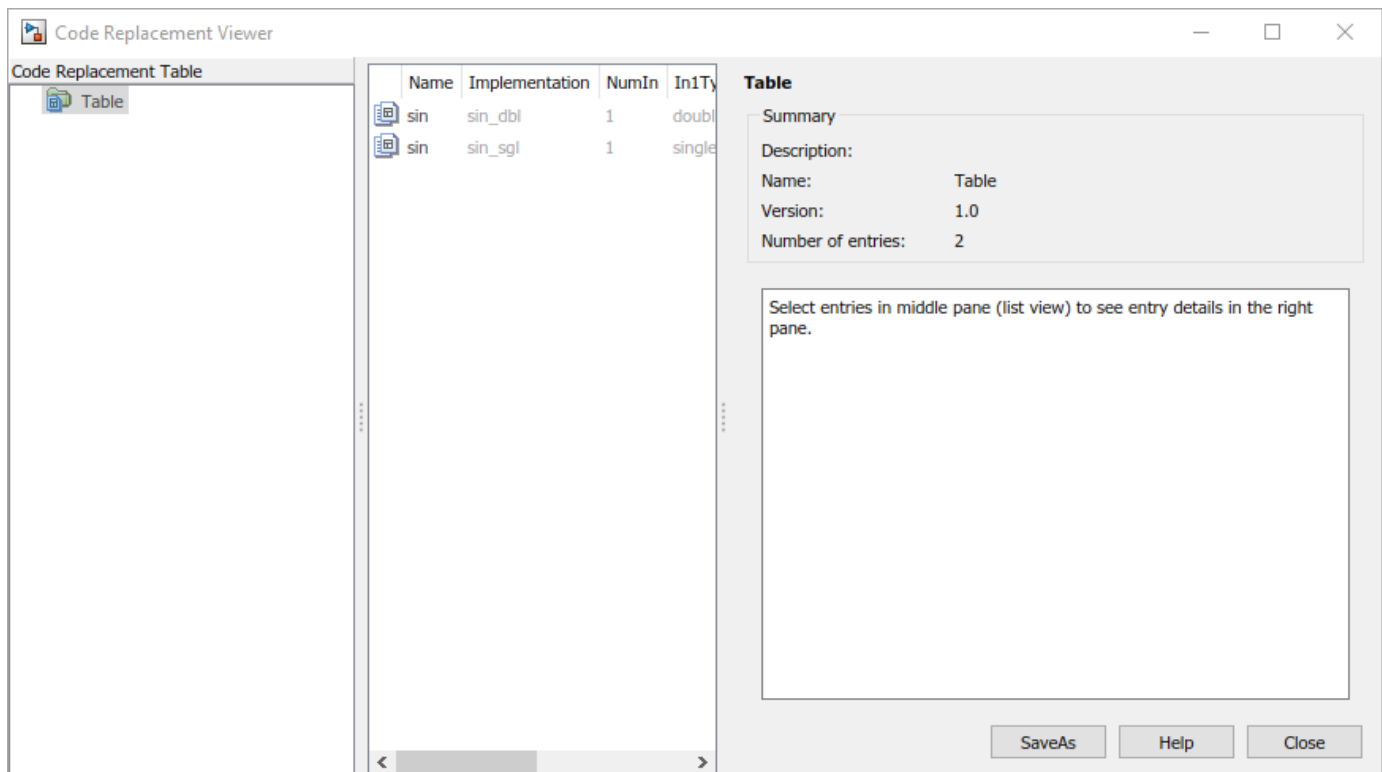
```
crviewer('GNU C99 extensions')
```



### Display Contents of Code Replacement Table

This example opens a predefined code replacement table `crl_table_sinfcn`. To learn how to create this example table, see “Define Code Replacement Library Optimizations” (Embedded Coder).

```
crviewer(crl_table_sinfcn)
```



- “Configure a Code Replacement Library”

## Programmatic Use

`crviewer('library')` opens the Code Replacement Viewer and displays the contents of `library`, where `library` is a character vector that names a registered code replacement library.

`crviewer(table)` opens the Code Replacement Viewer and displays the contents of a predefined table, where `table` is a MATLAB file that defines code replacement tables. The table must be user predefined and the file must be in the current folder or on the MATLAB path.

## Version History

Introduced in R2014b

## See Also

### Topics

“Configure a Code Replacement Library”

“What Is Code Replacement?”

“Code Replacement Libraries”

“Code Replacement Terminology”



# Optimization Parameters

---

## Model Configuration Parameters: Code Generation Optimization

The **Code Generation > Optimization** category includes parameters for improving the simulation speed of your models and improving the performance of the generated code. Model configuration parameters to improve the generated code require Simulink Coder or Embedded Coder.

| Parameter                                                  | Description                                                                                                                                                                                      |
|------------------------------------------------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Default parameter behavior                                 | Transform numeric block parameters into constant inlined values in the generated code.                                                                                                           |
| Leverage target hardware instruction set extensions        | Select instruction sets to generate SIMD (single instruction, multiple data) code for target hardware.                                                                                           |
| Optimize reductions                                        | Generate single instruction, multiple data (SIMD) code for reduction operation loops.                                                                                                            |
| Pass reusable subsystem outputs as (Embedded Coder)        | Specify how a reusable subsystem passes outputs.                                                                                                                                                 |
| Remove root level I/O zero initialization (Embedded Coder) | Specify whether to generate initialization code for root-level inports and outports set to zero.                                                                                                 |
| Remove internal data zero initialization (Embedded Coder)  | Specify whether to generate initialization code for internal work structures, such as block states and block outputs, to zero.                                                                   |
| Level (Embedded Coder)                                     | Choose the optimization level that you want to apply to the generated code.                                                                                                                      |
| Priority (Embedded Coder)                                  | Optimize the generated code for increased execution efficiency, decreased RAM consumption, or a balance between the two.                                                                         |
| Specify custom optimizations (Embedded Coder)              | Instead of applying an optimization level, select this parameter to select the optimization parameters in the <b>Details</b> section.                                                            |
| Use memcpy for vector assignment                           | Optimize code generated for vector assignment by replacing <code>for</code> loops with <code>memcpy</code> .                                                                                     |
| Memcpy threshold (bytes)                                   | Specify the minimum array size in bytes for which <code>memcpy</code> and <code>memset</code> function calls should replace <code>for</code> loops for vector assignments in the generated code. |
| Enable local block outputs                                 | Specify whether block signals are declared locally or globally.                                                                                                                                  |
| Reuse local block outputs                                  | Specify whether Simulink Coder software reuses signal memory.                                                                                                                                    |
| Eliminate superfluous local variables (Expression folding) | Collapse block computations into single expressions.                                                                                                                                             |
| Reuse global block outputs (Embedded Coder)                | Reuse global memory for block outputs.                                                                                                                                                           |



| Parameter                                                                                    | Description                                                                                                                     |
|----------------------------------------------------------------------------------------------|---------------------------------------------------------------------------------------------------------------------------------|
| Reuse output buffers of Model blocks (Embedded Coder)                                        | Reuse referenced model buffers if possible.                                                                                     |
| Perform in-place updates for Assignment and Bus Assignment blocks (Embedded Coder)           | Reuse the input and output variables of Bus Assignment and Assignment blocks if possible.                                       |
| Reuse buffers for Data Store Read and Data Store Write blocks (Embedded Coder)               | Remove temporary buffers for Data Store Read and Data Store Write blocks. Use the Data Store Memory block directly if possible. |
| Simplify array indexing (Embedded Coder)                                                     | Replace multiply operations in array indices when accessing arrays in a loop.                                                   |
| Pack Boolean data into bitfields (Embedded Coder)                                            | Specify whether Boolean signals are stored as one-bit bitfields or as a Boolean data type.                                      |
| Bitfield declarator type specifier (Embedded Coder)                                          | Specify the bitfield type when selecting configuration parameter Pack Boolean data into bitfields (Embedded Coder).             |
| Reuse buffers of different sizes and dimensions (Embedded Coder)                             | Reduce memory consumption by reusing buffers to store data of different sizes and dimensions.                                   |
| Optimize global data access (Embedded Coder)                                                 | Select global variable optimization.                                                                                            |
| Optimize block operation order in the generated code (Embedded Coder)                        | Reorder block operations in the generated code for improved code execution speed.                                               |
| Use bitsets for storing state configuration                                                  | Use bitsets to reduce the amount of memory required to store state configuration variables.                                     |
| Use bitsets for storing Boolean data                                                         | Use bitsets to reduce the amount of memory required to store Boolean data.                                                      |
| Maximum stack size (bytes)                                                                   | Specify the maximum stack size in bytes for your model.                                                                         |
| Loop unrolling threshold                                                                     | Specify the minimum signal or parameter width for which a for loop is generated.                                                |
| Optimize using the specified minimum and maximum values (Embedded Coder)                     | Optimize generated code using the specified minimum and maximum values for signals and parameters in the model.                 |
| <b>Maximum number of arguments for subsystem outputs</b>                                     | Set maximum number of subsystem outputs to pass individually.                                                                   |
| Inline invariant signals                                                                     | Transform symbolic names of invariant signals into constant values.                                                             |
| Remove code from floating-point to integer conversions with saturation that maps NaN to zero | Remove code that handles floating-point to integer conversion results for NaN values.                                           |
| Use memset to initialize floats and doubles to 0.0                                           | Specify whether to generate code that explicitly initializes floating-point data to 0.0.                                        |
| Remove code from floating-point to integer conversions that wraps out-of-range values        | Remove wrapping code that handles out-of-range floating-point to integer conversion results.                                    |

| Parameter                                                                                         | Description                                                                                                                                    |
|---------------------------------------------------------------------------------------------------|------------------------------------------------------------------------------------------------------------------------------------------------|
| Remove Code from Tunable Parameter Expressions That Saturate Out-of-Range Values (Embedded Coder) | Remove wrapping code of tunable parameters.                                                                                                    |
| Remove code that protects against division arithmetic exceptions (Embedded Coder)                 | Specify whether to generate code that guards against division by zero and INT_MIN/ -1 operations for integers and fixed-point data.            |
| Buffer for reusable subsystems                                                                    | Improve reuse by inserting buffers at reusable subsystem boundaries.                                                                           |
| <b>Disable incompatible optimizations</b>                                                         | Specify whether to disable optimizations that are incompatible with Simulink Code Inspector.                                                   |
| Base storage type for automatically created enumerations                                          | Set the storage type and size for enumerations created with active state output.                                                               |
| Use signal labels to guide buffer reuse (Embedded Coder)                                          | For signals with the same label, the code generator attempts to use the same signal memory.                                                    |
| Generate parallel for-loops (Embedded Coder)                                                      | Specify whether for-loops in the generated code shall be implement in parallel for Matlab Function, Matlab System or a For Each block.         |
| Signal storage reuse                                                                              | Specify reuse of memory buffers allocated to store block input and output signals thereby reducing the memory requirement of real-time program |
| Operator to represent Bitwise and Logical Operator blocks (Embedded Coder)                        | Specify whether the generated code contains bitwise or logical operators or both.                                                              |

## See Also

## Related Examples

- “Performance”

## Optimization Pane: Tab Overview

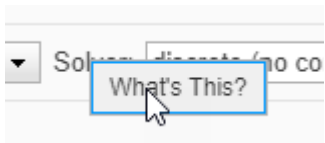
Set up optimizations for a model's active configuration set. Optimizations are set for both simulation and code generation.

### Tips

- To open the Optimization pane For ERT-based targets, in the Simulink Editor, select **Apps > Embedded Coder > Settings > Configuration Parameters > Optimization**.
- To open the Optimization pane For GRT-based targets, in the Simulink Editor, select **Apps > Simulink Coder > Settings > Configuration Parameters > Optimization**.
- Simulink Coder optimizations appear only when the Simulink Coder product is installed on your system. Selecting a GRT-based or ERT-based system target file changes the available options. ERT-based target optimizations require a Embedded Coder license when generating code. See the **Dependencies** sections below for licensing information for each parameter.

### To get help on an option

- 1 Right-click the option text label.
- 2 From the context menu, select **What's This**.



### See Also

#### Related Examples

- "Model Configuration Parameters: Code Generation Optimization" on page 19-2
- "Perform Acceleration"
- "Performance"

## Remove code from floating-point to integer conversions that wraps out-of-range values

Control generation of wrapping code that handles out-of-range floating-point to integer conversion values

**Model Configuration Pane:** Code Generation / Optimization

### Description

The **Remove code from floating-point to integer conversions that wraps out-of-range values** parameter specifies whether to generate wrapping code that handles out-of-range floating-point to integer conversion results.

### Settings

off (default) | on

#### On

Removes code when out-of-range conversions occur. Select this check box if code efficiency is critical to your application and the following conditions are true for at least one block in the model:

- Computing the outputs or parameters of a block involves converting floating-point data to integer or fixed-point data.
- The **Saturate on integer overflow** check box is cleared in the Block Parameters dialog box.

---

**Caution** Execution of generated code might not produce the same results as simulation.

---

#### Off

Results for simulation and execution of generated code match when out-of-range conversions occur. The generated code is larger than when you select this check box.

### Tips

- Selecting this check box reduces the size and increases the speed of the generated code at the cost of potentially producing results that do not match simulation in the case of out-of-range values.
- Selecting this check box affects code generation results only for out-of-range values and cannot cause code generation results to differ from simulation results for in-range values.

### Recommended Settings

| Application | Setting |
|-------------|---------|
| Debugging   | Off     |

| <b>Application</b> | <b>Setting</b>                       |
|--------------------|--------------------------------------|
| Traceability       | Off                                  |
| Efficiency         | On (execution, ROM), No impact (RAM) |
| Safety precaution  | No impact                            |

## **Programmatic Use**

**Parameter:** EfficientFloat2IntCast

**Type:** character vector

**Value:** 'on' | 'off'

**Default:** 'off'

## **Version History**

**Introduced in R2006a**

## **See Also**

### **Topics**

“Remove Code for Out-of-Range Floating Point to Integer Conversions”

“Model Configuration Parameters: Code Generation Optimization” on page 19-2

## Buffer for reusable subsystems

Buffers to enhance reuse of subsystems

**Model Configuration Pane:** Code Generation / Optimization

### Description

The **Buffer for reusable subsystems** parameter specifies whether to generate code that has buffers to enhance the reuse of subsystems.

### Settings

on (default) | off

On

Generates code that has extra buffers that enable the reuse of subsystems in the generated code which enhances ROM efficiency.

Off

Generates code that does not have extra buffers that could have potentially increased the reuse of a subsystem in the generated code. This code generation reduces ROM efficiency. The absence of the extra buffers might avoid extra data copies in the generated code, which improves code execution speed.

### Recommended Settings

| Application       | Setting                         |
|-------------------|---------------------------------|
| Debugging         | No Impact                       |
| Traceability      | No Impact                       |
| Efficiency        | Off (Execution Speed), On (ROM) |
| Safety precaution | No Impact                       |

### Programmatic Use

**Parameter:** BufferReusableBoundary

**Type:** character vector

**Value:** 'on' | 'off'

**Default:** 'on'

### Version History

Introduced in R2006a

### See Also

#### Topics

“Model Configuration Parameters: Code Generation Optimization” on page 19-2

“Specify Buffer Reuse for Signals in a Path” (Embedded Coder)

## Default parameter behavior

Represent numeric block parameters in generated code

**Model Configuration Pane:** Code Generation / Optimization

### Description

The **Default parameter behavior** parameter specifies how to represent numeric block parameters in the generated code. When using Embedded Coder for a component model that is configured with a service interface, this parameter must be set to **Inlined**.

### Dependencies

When you set **Default parameter behavior** to **Inlined**, you enable Inline invariant signals configuration parameter.

### Settings

Tunable for GRT targets (default) Inlined for ERT targets (default)

#### Inlined

Set **Default parameter behavior** to **Inlined** to reduce global RAM usage and increase efficiency of the generated code. The code does not allocate memory to represent numeric block parameters such as the **Gain** parameter of a Gain block. Instead, the code inlines the literal numeric values of these block parameters.

#### Tunable

Set **Default parameter behavior** to **Tunable** to enable tunability of numeric block parameters in the generated code. The code represents numeric block parameters and variables that use the storage class **Auto**, including numeric MATLAB variables, as tunable fields of a global parameters structure.

### Tips

- Whether you set **Default parameter behavior** to **Inlined** or to **Tunable**, create parameter data objects to preserve tunability for block parameters. For more information, see “Create Tunable Calibration Parameter in the Generated Code”.
- When you switch from a system target file that is not ERT-based to one that is ERT-based, **Default parameter behavior** sets to **Inlined** by default. However, you can change the setting of **Default parameter behavior** later.
- When a top model uses referenced models or if a model is referenced by another model:
  - Referenced models must set **Default parameter behavior** to **Inlined** if the top model has **Default parameter behavior** set to **Inlined**.
  - The top model can specify **Default parameter behavior** as **Tunable** or **Inlined**.
- If your model contains an Environment Controller block, you can suppress code generation for the branch connected to the Sim port if you set **Default parameter behavior** to **Inlined** and the branch does not contain external signals.



## Recommended Settings

| Application       | Setting                                                              |
|-------------------|----------------------------------------------------------------------|
| Debugging         | Tunable during development<br>Inlined for production code generation |
| Traceability      | Tunable                                                              |
| Efficiency        | Inlined                                                              |
| Safety precaution | No impact                                                            |

## Programmatic Use

**Parameter:** DefaultParameterBehavior

**Type:** character vector

**Value:** 'Inlined' | 'Tunable'

**Default:** 'Tunable' for GRT targets | 'Inlined' for ERT targets

## Version History

Introduced in R2015b

## See Also

### Topics

“Model Configuration Parameters: Code Generation Optimization” on page 19-2

“Inline Numeric Values of Block Parameters”

“How Generated Code Stores Internal Signal, State, and Parameter Data”

## Leverage target hardware instruction set extensions

Instruction sets to generate single instruction, multiple data (SIMD) code

**Model Configuration Pane:** Code Generation / Optimization

### Description

The **Leverage target hardware instruction set extensions** parameter specifies the instruction sets to use to generate single instruction, multiple data (SIMD) code for target hardware.

### Dependencies

To use this parameter, you must set **Device vendor** to Intel, AMD, or Generic and **Device type** to x86-64 (Windows 64), x86-64 (Linux 64), Athlon 64, or MATLAB Host Computer. If you use MATLAB Host Computer, you can choose only instruction sets that are supported by your computer.

### Settings

SSE2 (default) | None | SSE | SSE4.1 | AVX | AVX2 | FMA | AVX512F

For all targets:

- None — Does not generate SIMD code.

Instruction sets for GRT-based targets:

- SSE2

Instruction sets for ERT-based targets:

- SSE
- SSE2
- SSE4.1
- AVX
- AVX2
- FMA
- AVX512F

The list of instruction sets for ERT-based targets shows the dependency of the instruction sets, where each instruction set depends on the instruction sets that precede it. The code generator loads the selected instruction set and the instruction sets that it depends on. For example, if you select AVX, the code generator loads AVX, SSE4.1, SSE2, and SSE. If you select SSE2 for a GRT-based target or an ERT-based target, the code generator loads SSE2 and SSE.

## Recommended Settings

| Application       | Setting   |
|-------------------|-----------|
| Debugging         | No impact |
| Traceability      | No impact |
| Efficiency        | No impact |
| Safety precaution | No impact |

## Programmatic Use

**Parameter:** InstructionSetExtensions

**Type:** character vector

**Value:** 'None' | 'SSE' | 'SSE2' | 'SSE4.1' | 'AVX' | 'AVX2' | 'FMA' | 'AVX512F'

**Default:** 'SSE2'

## Limitations

- If you use a custom toolchain for your generated code, you must set **Instruction set extensions** to None. Instruction set extensions do not support the use of custom toolchains.

## Version History

Introduced in R2021b

## See Also

### Topics

“Generate SIMD Code from Simulink Blocks”

## Optimize reductions

Single instruction, multiple data (SIMD) code for reduction operation loops

**Model Configuration Pane:** Code Generation / Optimization

### Description

The **Optimize reductions** parameter instructs the code generator to generate single instruction, multiple data (SIMD) code for reduction operation loops. A reduction is an operation that reduces a set of elements, such as an array, to a single value using an associative binary operator. For example, calculating the sum of the elements in an array is a reduction operation that uses the addition operator.

### Dependencies

To use this parameter, you must set **Instruction set extensions** to a valid instruction set.

### Settings

off (default) | on

#### On

Generates single instruction, multiple data (SIMD) code for reduction operation loops.

#### Off

Generates non-parallel for loops for reduction operations.

### Recommended Settings

| Application       | Setting   |
|-------------------|-----------|
| Debugging         | No impact |
| Traceability      | No impact |
| Efficiency        | No impact |
| Safety precaution | No impact |

### Programmatic Use

**Parameter:** OptimizeReductions

**Type:** character vector

**Value:** 'on' | 'off'

**Default:** 'off'

### Version History

Introduced in R2022a

## **See Also**

### **Topics**

“Generate SIMD Code from Simulink Blocks”

## Inline invariant signals

Transform symbolic names of Invariant signals in generated code

**Model Configuration Pane:** Code Generation / Optimization

### Description

The **Inline invariant signals** parameter instructs the code generator to transform symbolic names of invariant signals into constant values.

**Category:** Optimization

### Dependencies

This parameter is enabled when you set **Default parameter behavior** to Inlined.

### Settings

off (default) | on

#### On

Simulink Coder software uses the numerical values of model parameters, instead of their symbolic names, in generated code. An invariant signal is not inline if it is nonscalar, complex, or the block inport the signal is attached to takes the address of the signal.

#### Off

Uses symbolic names of model parameters in generated code.

### Recommended Settings

| Application       | Setting   |
|-------------------|-----------|
| Debugging         | Off       |
| Traceability      | Off       |
| Efficiency        | On        |
| Safety precaution | No impact |

### Programmatic Use

**Parameter:** InlineInvariantSignals

**Type:** character vector

**Value:** 'on' | 'off'

**Default:** 'off'

### Version History

Introduced before R2006a

## **See Also**

### **Topics**

“Model Configuration Parameters: Code Generation Optimization” on page 19-2

“Inline Invariant Signals”

“Performance”

## Use memcpy for vector assignment

Optimize code generated for vector assignments

**Model Configuration Pane:** Code Generation / Optimization

### Description

The **Use memcpy for vector assignment** parameter specifies whether to optimize code generated for vector assignment by replacing for loops with memcpy.

### Dependencies

When you select this parameter, the associated parameter **Memcpy threshold (bytes)** is enabled.

### Settings

on | off

On

Enables use of memcpy for vector assignment based on the associated threshold parameter **Memcpy threshold (bytes)**. memcpy is used in the generated code if the number of array elements times the number of bytes per element is greater than or equal to the specified value for **Memcpy threshold (bytes)**. One byte equals the width of a character in this context.

Off

Disables use of memcpy for vector assignment.

### Tips

- If the destination of a memcpy is not changed, the code generator can further optimize the code by replacing the memcpy function call with pointer assignments. For more information, see “Convert Data Copies to Pointer Assignments” (Embedded Coder).

### Recommended Settings

| Application       | Setting   |
|-------------------|-----------|
| Debugging         | No impact |
| Traceability      | No impact |
| Efficiency        | On        |
| Safety precaution | No impact |

### Programmatic Use

**Parameter:** EnableMemcpy

**Type:** character vector

**Value:** 'on' | 'off'

**Default:** 'on'



## **Version History**

**Introduced in R2008b**

### **See Also**

#### **Topics**

“Model Configuration Parameters: Code Generation Optimization” on page 19-2

“Use memcpy Function to Optimize Generated Code for Vector Assignments”

“Performance”

## Memcpy threshold (bytes)

Specify minimum array size for which memcpy and memset function calls replace for loops for vector assignments

**Model Configuration Pane:** Code Generation / Optimization

### Description

The **Memcpy threshold (bytes)** specifies the minimum array size in bytes for which memcpy and memset function calls should replace for loops for vector assignments in the generated code.

### Dependencies

For the memcpy optimization, this parameter is enabled when you select **Use memcpy for vector assignment**.

### Settings

64 (default) | ' '

The code generator by default sets the parameter value **64** which you can change based on your optimization requirements. However, the maximum value for the **Memcpy threshold (bytes)** is 2147483647 bytes. If you set the parameter value at more than the maximum value, it automatically changes back to 2147483647 bytes.

### Recommended Settings

| Application       | Setting                                                   |
|-------------------|-----------------------------------------------------------|
| Debugging         | No impact                                                 |
| Traceability      | No impact                                                 |
| Efficiency        | Accept default or determine target-specific optimal value |
| Safety precaution | No impact                                                 |

### Programmatic Use

**Parameter:** MemcpyThreshold

**Type:** integer

**Value:** valid quantity of bytes

**Default:** 64

### Version History

Introduced in R2008b

## **See Also**

### **Topics**

“Model Configuration Parameters: Code Generation Optimization” on page 19-2

“Use memcpy Function to Optimize Generated Code for Vector Assignments”

“Performance”

## Loop unrolling threshold

Specify minimum array size width for generating for loops

**Model Configuration Pane:** Code Generation / Optimization

### Description

The **Loop unrolling threshold** specifies the minimum array size width for which a for loop is generated.

### Dependencies

If you want to use this parameter for specifying the minimum array size width for parallel for-loops, Embedded Coder is required.

### Settings

5 (default)

Specify the array size at which the code generator begins to use a for loop instead of separate assignment statements to assign values.

When there are perfectly nested loops, the code generator uses a for loop if the product of the loop counts for loops in the perfect loop nest is greater than or equal to the threshold.

### Recommended Settings

| Application       | Setting   |
|-------------------|-----------|
| Debugging         | No impact |
| Traceability      | No impact |
| Efficiency        | >0        |
| Safety precaution | No impact |

### Programmatic Use

**Parameter:** RollThreshold

**Type:** character vector

**Value:** valid value

**Default:** '5'

### Version History

Introduced before R2006a

### See Also

#### Topics

“Model Configuration Parameters: Code Generation Optimization” on page 19-2

“Configure Loop Unrolling Threshold”  
“Performance”

## Maximum stack size (bytes)

Specify maximum stack size for model

**Model Configuration Pane:** Code Generation / Optimization

### Description

The **Maximum stack size (bytes)** parameter specifies the maximum stack size in bytes for your model.

### Settings

Inherit from target (default) | <Specify a value>

Inherit from target

The Simulink Coder software assigns the maximum stack size to the smaller value of the following:

- The default value (200,000 bytes) set by the Simulink Coder software
- Value of the TLC variable `MaxStackSize` in the system target file

<Specify a value>

Specify a positive integer value. Simulink Coder software assigns the maximum stack size to the specified value.

---

**Note** If you specify a maximum stack size for a model, the estimated required stack size of a referenced model must be less than the specified maximum stack size of the parent model.

---

### Tips

- If you specify the maximum stack size to be zero, then the generated code implements all variables as global data.
- If you specify the maximum stack to be `inf`, then the generated code contains the least number of global variables.
- If your model contains a variable that is larger than 4096 bytes, the code generator implements it in global memory by default. You can increase the size of variables that the code generator places in local memory by changing the value of the TLC variable `MaxStackVariableSize`. You can change this value by typing the following command in MATLAB Command Window:  
`set_param(modelName, 'TLCOptions', '-aMaxStackVariableSize=N')`

### Recommended Settings

| Application  | Setting   |
|--------------|-----------|
| Debugging    | No impact |
| Traceability | No impact |

| Application       | Setting   |
|-------------------|-----------|
| Efficiency        | No impact |
| Safety precaution | No impact |

## Programmatic Use

**Parameter:** MaxStackSize

**Type:** int

**Value:** valid value

**Default:** Inherit from target

## Version History

Introduced in R2010a

## See Also

### Topics

“Model Configuration Parameters: Code Generation Optimization” on page 19-2

“Customize Stack Space Allocation”

“Performance”

## Use bitsets for storing state configuration

Bitsets for storing state configuration variables

**Model Configuration Pane:** Code Generation / Optimization

### Description

The **Use bitsets for storing state configuration** specifies whether to use bitsets to reduce the amount of memory required to store state configuration variables.

### Settings

off (default) | on

**Default:** Off

On

Stores state configuration variables in bitsets. Potentially reduces the amount of memory required to store the variables. Potentially requires more instructions to access state configuration, which can result in less optimal code.

Off

Stores state configuration variables in unsigned bytes. Potentially increases the amount of memory required to store the variables. Potentially requires fewer instructions to access state configuration, which can result in more optimal code.

### Tips

- Selecting this check box can significantly reduce the amount of memory required to store the variables. However, it can increase the amount of memory required to store target code if the target processor does not include instructions for manipulating bitsets.
- Select this check box for Stateflow charts that have a large number of sibling states at a given level of the hierarchy.
- Clear this check box for Stateflow charts with a small number of sibling states at a given level of the hierarchy.

### Recommended Settings

| Application       | Setting                        |
|-------------------|--------------------------------|
| Debugging         | Off                            |
| Traceability      | Off                            |
| Efficiency        | Off (execution, ROM), On (RAM) |
| Safety precaution | No impact                      |

### Programmatic Use

**Parameter:** StateBitsets



**Type:** character vector

**Value:** 'on' | 'off'

**Default:** 'off'

## **Version History**

**Introduced before R2006a**

## **See Also**

### **Topics**

“Reduce Memory Usage for Boolean and State Configuration Variables”

“Design Tips for Optimizing Generated Code for Stateflow Objects”

## Use bitsets for storing Boolean data

Bitsets to store Boolean data

**Model Configuration Pane:** Code Generation / Optimization

### Description

The **Use bitsets for storing Boolean data** parameter specifies whether to use bitsets to reduce the amount of memory required for storing Boolean data.

### Settings

off (default) | on

**Default:** Off

On

Stores Boolean data in bitsets. Potentially reduces the amount of memory required to store the data. Potentially requires more instructions to access the data, which can result in less optimal code.

Off

Stores Boolean data in unsigned bytes. Potentially increases the amount of memory required to store the data. Potentially requires fewer instructions to access the data, which can result in more optimal code.

### Tips

- Select this check box for Stateflow charts that reference Boolean data infrequently.
- Clear this check box for Stateflow charts that reference Boolean data frequently.

### Recommended Settings

| Application       | Setting                        |
|-------------------|--------------------------------|
| Debugging         | Off                            |
| Traceability      | Off                            |
| Efficiency        | Off (execution, ROM), On (RAM) |
| Safety precaution | No impact                      |

### Programmatic Use

**Parameter:** DataBitsets

**Type:** character vector

**Value:** 'on' | 'off'

**Default:** 'off'

## **Version History**

**Introduced before R2006a**

### **See Also**

#### **Topics**

“Reduce Memory Usage for Boolean and State Configuration Variables”

“Design Tips for Optimizing Generated Code for Stateflow Objects”

## Base storage type for automatically created enumerations

Specify storage type and size of enumerations for state outputs

**Model Configuration Pane:** Code Generation / Optimization

### Description

The **Base storage type for automatically created enumerations** parameter specifies the storage type and size for enumerations created with active state output.

### Settings

'Native Integer' (default) | int32 | int16 | int8 | uint16 | uint8

'Native Integer'

Default target integer type

int32

32 bit signed integer type

int16

16 bit signed integer type

int8

8 bit signed integer type

uint16

16 bit unsigned integer type

uint8

8 bit unsigned integer type

### Tips

- The default 'Native Integer' is recommended for most models.
- If you need a smaller memory footprint for the generated enumerations, set the storage type to a smaller size. The size must be large enough to hold the number of states in the chart.

### Recommended Settings

| Application       | Setting |
|-------------------|---------|
| Debugging         |         |
| Traceability      |         |
| Efficiency        |         |
| Safety precaution |         |

## **Programmatic Use**

**Parameter:** ActiveStateOutputEnumStorageType

**Type:** character vector

**Value:** 'Native Integer' | 'int32' | 'int16' | 'int8' | 'uint16' | 'uint8'

**Default:** 'Native Integer'

## **Version History**

**Introduced in R2014b**

## **See Also**

### **Topics**

“Monitor State Activity Through Active State Data” (Stateflow)

“Design Tips for Optimizing Generated Code for Stateflow Objects”

## Enable local block outputs

Declare block signals locally or globally

**Model Configuration Pane:** Code Generation / Optimization

### Description

The **Enable local block outputs** parameter specifies whether block signals are declared locally or globally.

### Dependencies

This parameter is enabled by **Signal storage reuse**.

### Settings

on (default) | off

#### On

Block signals are declared locally in functions.

#### Off

Block signals are declared globally.

### Tips

- If it is not possible to declare an output as a local variable, the generated code declares the output as a global variable.
- If you are constrained by limited stack space, you can turn **Enable local block outputs** off and still benefit from memory reuse.

### Recommended Settings

| Application       | Setting   |
|-------------------|-----------|
| Debugging         | Off       |
| Traceability      | Off       |
| Efficiency        | On        |
| Safety precaution | No impact |

### Programmatic Use

**Parameter:** LocalBlockOutputs

**Type:** character vector

**Value:** 'on' | 'off'

**Default:** 'on'

## **Version History**

**Introduced before R2006a**

### **See Also**

#### **Topics**

“Enable and Reuse Local Block Outputs in Generated Code”

“Performance”

“Model Configuration Parameters: Code Generation Optimization” on page 19-2

## Reuse local block outputs

Reuse local output variables

**Model Configuration Pane:** Code Generation / Optimization

### Description

The **Reuse local block outputs** parameter specifies whether Simulink Coder reuses signal memory.

### Dependencies

This parameter is enabled by **Signal storage reuse**.

### Settings

on (default) | off

#### On

- Simulink Coder software tries to reuse signal memory, reducing stack size where signals are being buffered in local variables.
- Selecting this parameter trades code traceability for code efficiency.

#### Off

Signals are stored in unique locations.

### Recommended Settings

| Application       | Setting   |
|-------------------|-----------|
| Debugging         | Off       |
| Traceability      | Off       |
| Efficiency        | On        |
| Safety precaution | No impact |

### Programmatic Use

**Parameter:** BufferReuse

**Type:** character vector

**Value:** 'on' | 'off'

**Default:** 'on'

### Version History

Introduced before R2006a



## **See Also**

### **Topics**

“Enable and Reuse Local Block Outputs in Generated Code”

“Performance”

“Model Configuration Parameters: Code Generation Optimization” on page 19-2

## Eliminate superfluous local variables (Expression folding)

Specify to fold expressions into single expression

**Model Configuration Pane:** Code Generation / Optimization

### Description

The **Eliminate superfluous local variables (Expression folding)** parameter specifies whether to collapse block computations into single expressions.

**Category:** Optimization

### Dependencies

This parameter is enabled by **Signal storage reuse**.

### Settings

on (default) | off

#### On

- Enables expression folding.
- Eliminates local variables, incorporating the information into the main code statement.
- Improves code readability and efficiency.

#### Off

Disables expression folding.

### Recommended Settings

| Application       | Setting                                                                              |
|-------------------|--------------------------------------------------------------------------------------|
| Debugging         | Off                                                                                  |
| Traceability      | No impact for simulation or during development<br>Off for production code generation |
| Efficiency        | On                                                                                   |
| Safety precaution | No impact                                                                            |

### Programmatic Use

**Parameter:** ExpressionFolding

**Type:** character vector

**Value:** 'on' | 'off'

**Default:** 'on'

## **Version History**

**Introduced before R2006a**

### **See Also**

#### **Topics**

“Minimize Computations and Storage for Intermediate Results at Block Outputs”

“Performance”

“Model Configuration Parameters: Code Generation Optimization” on page 19-2

## Remove code from floating-point to integer conversions with saturation that maps NaN to zero

Control generation of protective code that handles floating-point to integer conversion for NaN values

**Model Configuration Pane:** Code Generation / Optimization

### Description

The **Remove code from floating-point to integer conversions with saturation that maps NaN to zero** parameter instructs the code generator to remove code that handles floating-point to integer conversion results for NaN values.

### Dependencies

For ERT-based targets, this parameter is enabled when you select the **floating-point numbers** and **non-finite numbers** check boxes in the **Code Generation > Interface** pane.

### Settings

on (default) | off

#### On

Removes code when mapping from NaN to integer zero occurs. Select this check box if code efficiency is critical to your application and the following conditions are true for at least one block in the model:

- Computing outputs or parameters of a block involves converting floating-point data to integer or fixed-point data.
- The **Saturate on integer overflow** check box is selected in the Block Parameters dialog box.

---

**Caution** Execution of generated code might not produce the same results as simulation.

---

#### Off

Results for simulation and execution of generated code match when mapping from NaN to integer zero occurs. The generated code is larger than when you select this check box.

### Tips

- Selecting this check box reduces the size and increases the speed of the generated code at the cost of producing results that do not match simulation in the case of NaN values.
- Selecting this check box affects code generation results only for NaN values and cannot cause code generation results to differ from simulation results for other values.

## Recommended Settings

| Application       | Setting           |
|-------------------|-------------------|
| Debugging         | Off               |
| Traceability      | Off               |
| Efficiency        | On                |
| Safety precaution | No recommendation |

## Programmatic Use

**Parameter:** EfficientMapNaN2IntZero

**Type:** character vector

**Value:** 'on' | 'off'

**Default:** 'on'

## Version History

Introduced in R2008b

## See Also

### Topics

“Remove Code That Maps NaN to Integer Zero”

“Model Configuration Parameters: Code Generation Optimization” on page 19-2

## Use memset to initialize floats and doubles to 0.0

Control generation of code that explicitly initializes floating-point data to 0.0

**Model Configuration Pane:** Code Generation / Optimization

### Description

The **Use memset to initialize floats and doubles to 0.0** parameter specifies whether to generate code that explicitly initializes floating-point data to 0.0.

### Settings

On (GUI), 'off' (command line) (default) | off (GUI), 'on' (command line)

On

Uses `memset` to clear internal storage for floating-point data to integer bit pattern 0 (all bits 0), regardless of type. If your compiler and target CPU both represent floating-point zero with the integer bit pattern 0, use this parameter to gain execution and ROM efficiency.

This parameter requires that you turn on the configuration parameter **Memcpy threshold** to enable the `memset` functionality. Check that the value of the threshold is set high enough.

Off

Generates code to explicitly initialize storage for data of types `float` and `double` to 0.0. The resulting code is slightly less efficient than code generated when you select the option.

---

**Note** The command-line values are reverse of the settings values. Therefore, 'on' in the command line corresponds to the description of "Off" in the settings section, and 'off' in the command line corresponds to the description of "On" in the settings section.

---

### Recommended Settings

| Application       | Setting                                                          |
|-------------------|------------------------------------------------------------------|
| Debugging         | No impact                                                        |
| Traceability      | No impact                                                        |
| Efficiency        | On (GUI), 'off' (command line) (execution, ROM), No impact (RAM) |
| Safety precaution | No impact                                                        |

### Programmatic Use

**Parameter:** `InitFltsAndDblsToZero`

**Type:** character vector

**Value:** 'on' | 'off'

**Default:** 'off'

## **Version History**

**Introduced before R2006a**

### **See Also**

#### **Topics**

“Optimize Generated Code Using memset Function”

“Model Configuration Parameters: Code Generation Optimization” on page 19-2

## Signal storage reuse

Reuse signal memory

**Model Configuration Pane:** Code Generation / Optimization

### Description

The **Signal storage reuse** parameter instructs the code generator to reuse buffers allocated to store block input and output signals whenever possible.

### Dependencies

This parameter enables:

- **Enable local block outputs** on page 19-32
- **Reuse local block outputs** on page 19-34
- **Eliminate superfluous local variables (Expression folding)** on page 19-36

If you have an Embedded Coder license, this parameter enables:

- **Optimize global data access** (Embedded Coder)
- **Perform in-place updates for Assignment and Bus Assignment blocks** (Embedded Coder)
- **Reuse global block outputs** (Embedded Coder)
- **Optimize block operation order in the generated code** (Embedded Coder)
- **Reuse buffers for Data Store Read and Data Store Write blocks** (Embedded Coder)

### Settings

on (default) | off

#### On

Simulink software reuses memory buffers allocated to store block input and output signals, reducing the memory requirement of your real-time program.

#### Off

Simulink software allocates a separate memory buffer for each block's outputs. This makes all block outputs global and unique, which in many cases significantly increases RAM and ROM usage.

### Tips

- This option applies only to signals with storage class **Auto**.
- Signal storage reuse can occur only among signals that have the same data type.
- Clearing this option can substantially increase the amount of memory required to simulate large models.
- Clear this option if you need to:



- Debug a C-MEX S-function
- Use a Floating Scope or a Floating Scope block with the **Floating display** option selected to inspect signals in a model that you are debugging
- Simulink software opens an error dialog if **Signal storage reuse** is enabled and you attempt to use a Floating Scope or floating Display block to display a signal whose buffer has been reused.

## Recommended Settings

| Application       | Setting   |
|-------------------|-----------|
| Debugging         | Off       |
| Traceability      | Off       |
| Efficiency        | On        |
| Safety precaution | No impact |

## Programmatic Use

**Parameter:** OptimizeBlockIOStorage

**Type:** character vector

**Value:** 'on' | 'off'

**Default:** 'on'

## Version History

Introduced in R2007a

## See Also

### Topics

“Minimize Computations and Storage for Intermediate Results at Block Outputs”

“Performance”

“Model Configuration Parameters: Code Generation Optimization” on page 19-2

